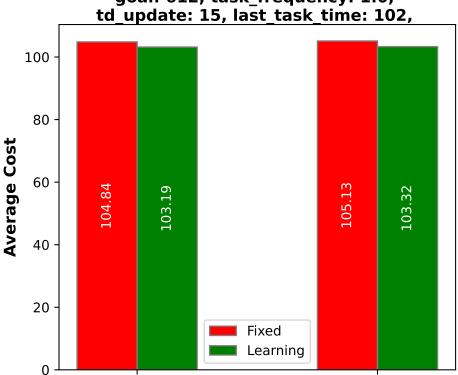
Map: den312d agents: 5,

tasks: 100, pickup: 609, goal: 612, task\_frequency: 1.0,



Real

**Estimated**