

# Tessellating The Go Stone

## Generating a triangle mesh for the go stone

Posted by Glenn Fiedler (<http://web.archive.org/web/20181107181438/https://gafferongames.com/about>) on Wednesday, February 20, 2013

## Introduction

Hi, I'm Glenn Fiedler. Welcome to **Virtual Go** (<http://web.archive.org/web/20181107181438/https://gafferongames.com/categories/virtual-go/>), my project to create a physically accurate computer simulation of a Go board and stones.

In this article we want to draw the go stone using **OpenGL** (<http://web.archive.org/web/20181107181438/https://www.opengl.org/>).

Unfortunately we can't just tell the graphics card, "Hey! Please draw the intersection of two spheres with radius  $r$  and  $d$  apart with a bevel torus  $r_1$  and  $r_2$ !", because modern 3D graphics cards work by drawing triangles. We have to take our mathematical definition of the go stone and turn it into a set of triangles that the graphics card can render.

This is called tessellation and there are several different ways to do it.

## Longitude And Latitude

The first way that I tried was to consider sphere rendering like a globe with longitude/latitude. I started with a ring around the 'equator' of the go stone, stepping these rings up to the top of the sphere like the north pole on a globe.

[https://gafferongames.com/post/tessellating\\_the\\_go\\_stone/](https://gafferongames.com/post/tessellating_the_go_stone/)

Go

AUG

NOV

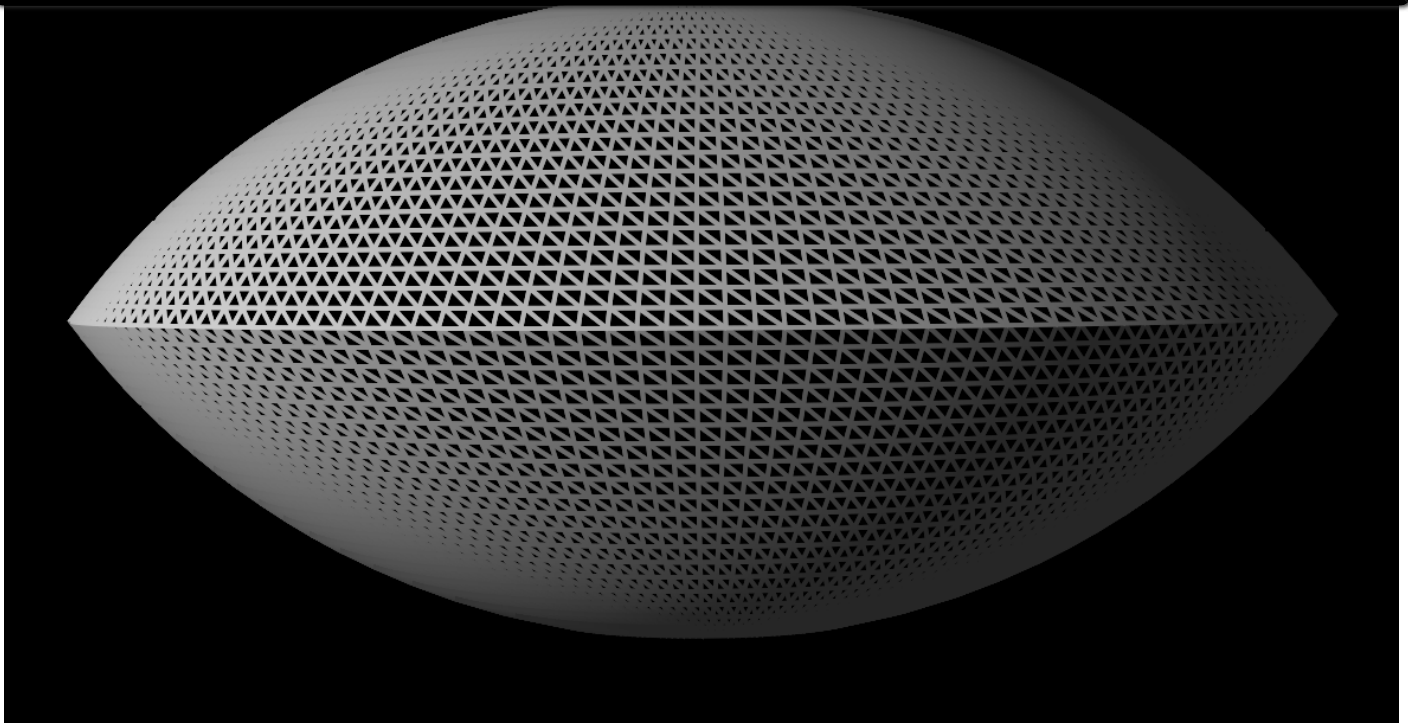
DEC

[3 captures](#)

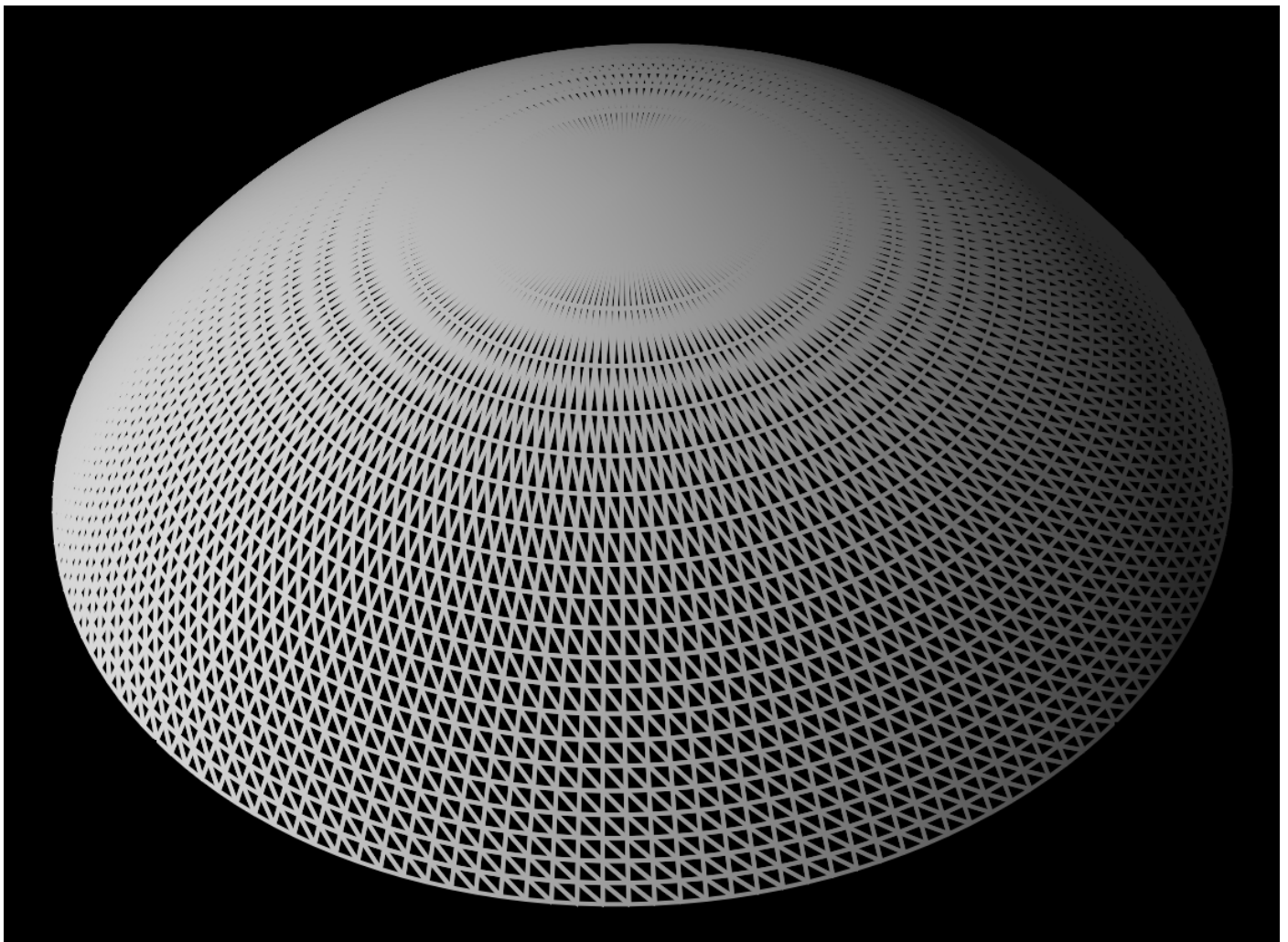
21 Oct 2017 - 7 Nov 2018

2017 2018 2019

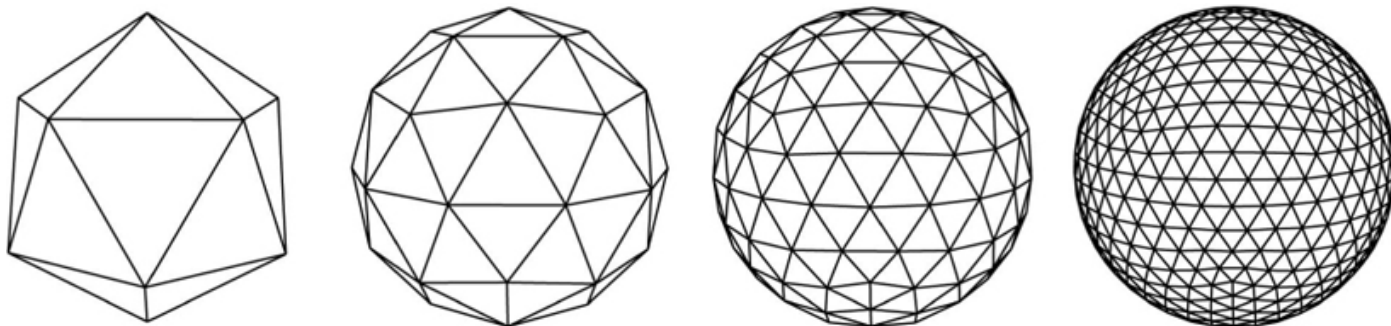
About this capture



Unfortunately, just like longitude/latitude on a globe, tessellating this way leads to very distorted mapping around the pole and a lot of wasted triangles:

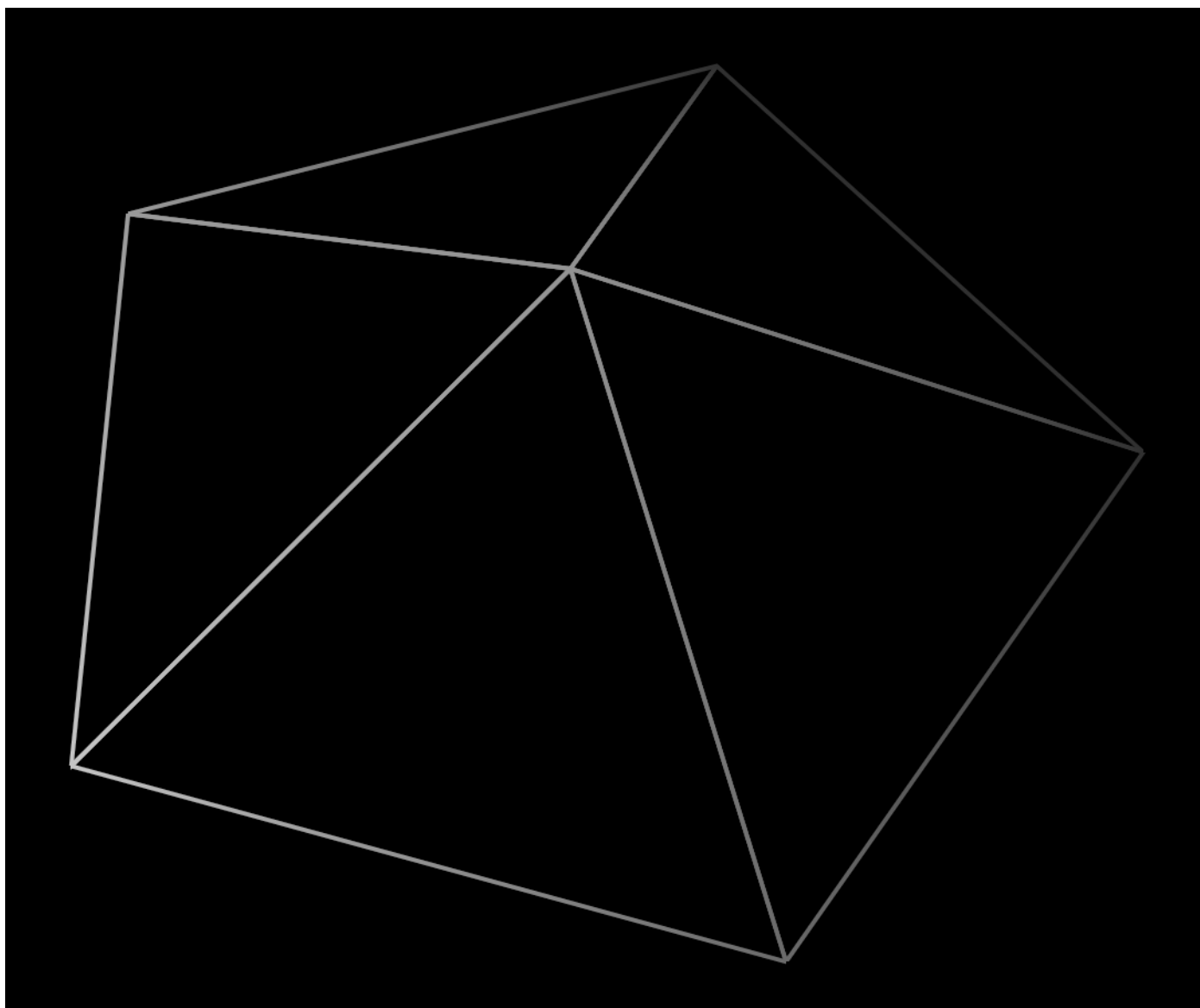


## Triangle Subdivision



Since the go stone only needs the top  $\frac{1}{3}$  or  $\frac{1}{4}$  of a sphere, I didn't want to subdivide a whole sphere only to throw most of it away. So I designed my own subdivision algorithm to generate only the top section of a sphere.

After some trial and error I found that a pentagon plus a center vertex at the pole of the sphere was a good initial generator that minimized the distortion that occurs during subdivision. The only tricky part is that when subdividing you need to keep track of whether the edge is a sphere edge or a circle edge, as the subdivided vertex must be projected differently.





[https://gafferongames.com/post/tessellating\\_the\\_go\\_stone/](https://gafferongames.com/post/tessellating_the_go_stone/)

Go

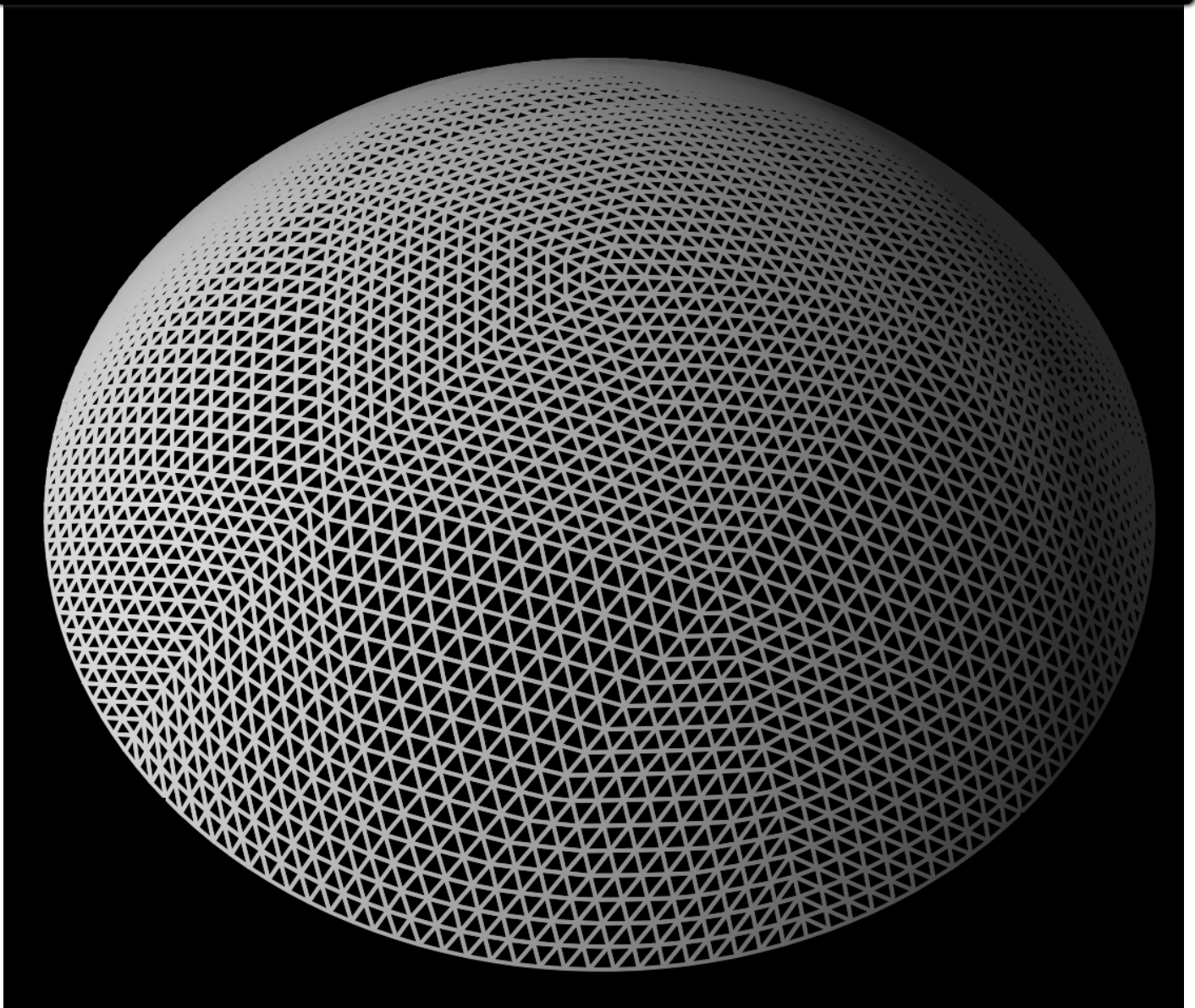
AUG NOV DEC

07

2017 2018 2019

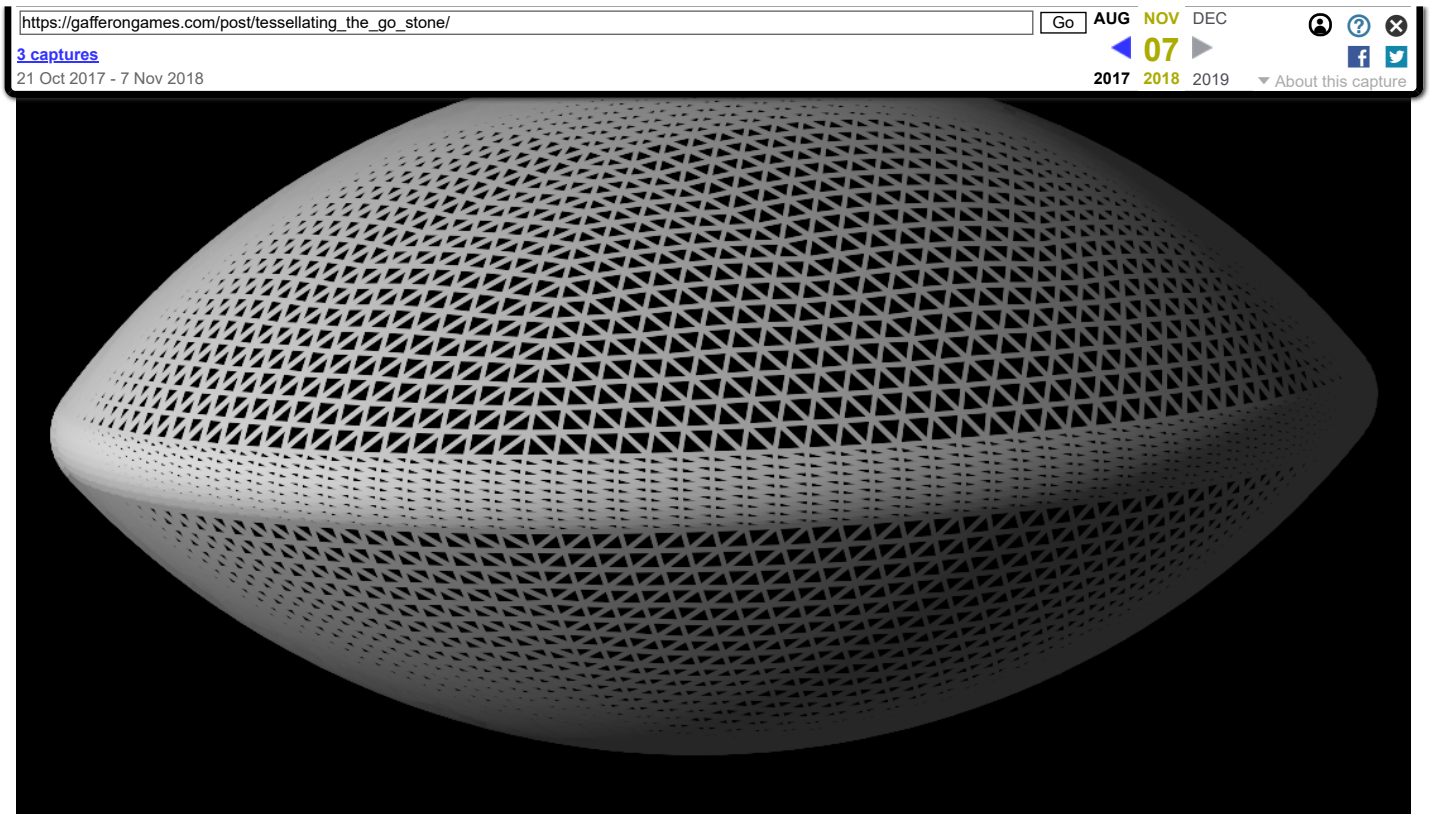


About this capture



## Tessellating The Bevel

Now we need to tessellate the bevel. To do this I take the vertices which form the circle edge at the bottom of the top sphere surface and calculate the angle of each vertex about the y axis. I then use these angles to sweep around the torus ensuring that the torus vertices weld perfectly with the top and bottom sphere sections.



## Vertex Welding

Due to how recursive subdivision works a lot of duplicate vertices are generated.

I'd rather not have the graphics card waste time transforming the same vertex over and over, so as I add vertices to the mesh I hash vertex positions into a 3D grid (~1mm cells) and reuse an existing vertex if the position and normals match within some small epsilon value.

With vertex welding the reduction in vertices is dramatic: 53000 to just 6500.

For more information on vertex welding please refer to the discussion in [Real-Time Collision Detection](http://web.archive.org/web/20181107181438/https://www.amazon.com/Real-Time-Collision-Detection-Interactive-Technology/dp/1558607323/ref=sr_1_1?ie=UTF8&qid=1363029675&sr=8-1&keywords=real+time+collision+detection) ([http://web.archive.org/web/20181107181438/https://www.amazon.com/Real-Time-Collision-Detection-Interactive-Technology/dp/1558607323/ref=sr\\_1\\_1?ie=UTF8&qid=1363029675&sr=8-1&keywords=real+time+collision+detection](http://web.archive.org/web/20181107181438/https://www.amazon.com/Real-Time-Collision-Detection-Interactive-Technology/dp/1558607323/ref=sr_1_1?ie=UTF8&qid=1363029675&sr=8-1&keywords=real+time+collision+detection)) by [Christer Ericson](http://web.archive.org/web/20181107181438/http://realtimecollisiondetection.net/blog/) (<http://web.archive.org/web/20181107181438/http://realtimecollisiondetection.net/blog/>).

**NEXT ARTICLE:** [How The Go Stone Moves](http://web.archive.org/web/20181107181438/https://gafferongames.com/post/how_the_go_stone_moves/)

([http://web.archive.org/web/20181107181438/https://gafferongames.com/post/how\\_the\\_go\\_stone\\_moves/](http://web.archive.org/web/20181107181438/https://gafferongames.com/post/how_the_go_stone_moves/))

● (<http://web.archive.org/web/20181107181438/https://www.linkedin.com/in/glennfiedler/>)

● (<http://web.archive.org/web/20181107181438/https://twitter.com/gafferongames>)

● (<http://web.archive.org/web/20181107181438/https://github.com/gafferongames>)

Go

AUG

NOV

DEC

◀

07

▶

2017

2018

2019

👤

?

✕

f

t

About this capture

[3 captures](#)

21 Oct 2017 - 7 Nov 2018