Data Science and Artificial Intelligence

Machine Learning

Support Vector Machine

Lecture No. 4



Recap of Previous Lecture







Topics to be Covered









Topic Sym

Topic

Topic

Topic Kerners

Topic Theorem on Kornels

Soft-margin sym

Questions



blurmark.com







SVM (algorithm) Things to Remember

$$\omega = [\omega, \omega_2 - -$$

min max
$$\frac{1}{2} ||\omega||^2 + \sum_{i=1}^{N} \lambda_i \left(1 - y_i (\omega x_i + b)\right)$$
 $\lambda_i \geqslant 0$







3.
$$\omega = \sum \lambda i y i x \Omega$$

$$\sum \lambda i y i = 0$$

4. dual max
$$\begin{cases} \sum_{i=1}^{N} \lambda_i - \frac{1}{2i} \sum_{j=1}^{N} \lambda_i \lambda_j y_i y_j x_j x_j \\ \lambda_i \ge 0 \end{cases}$$

$$\sum_{i=1}^{N} \lambda_i y_i = 0$$





SVM (algorithm)

5.
$$\chi_i \chi_j^T \Rightarrow \left(\chi_i^{\perp} \chi_i^2 - - - \chi_i^D\right)$$

Innerproduct

higherdimension
$$X_i \longrightarrow \phi(x_i)$$

 $X_i \longrightarrow \phi(x_i)$







7. dual max
$$\sum_{i=1}^{N} \lambda_i - \frac{1}{2} \sum \lambda_i \lambda_j y_i y_j \phi(x_i) \phi(x_j)^T$$

K(xi,xj)

8. actual Conversion of points into higherdimensions
Is not needed that the kind of the state of

$$x_i \neq \phi(x_i)$$

$$\phi(x_i)\phi(x_j) \neq k(x_i,x_j)$$





Why the kernels are successful in classifications

Kernels in <u>Support Vector Machines</u> (SVMs) are functions that <u>calculate</u> the similarity <u>of pairs</u> of data points in a high-dimensional space. They <u>allow</u> SVMs to <u>discover</u> complex, non-linear patterns in data by implicitly <u>relating</u> the input data <u>to</u> a higher-dimensional feature space where the data <u>can</u> be linearly <u>extracted</u>..

Backend





The linear kernel can be defined as:





One definition of the polynomial kernel is:

Where x and y are the input feature vectors, c is a constant term, and d is the degree of the polynomial, K(x, y) = (x, y + c)d. The constant term is added to, and the dot product of the input vectors elevated to the degree of the polynomial.

$$(x.y+c)$$

$$\langle \chi, y \rangle^2 = K(\chi, y)$$
 $3 \rightarrow 9$





The Gaussian kernel can be defined as: most used kerner fxn.

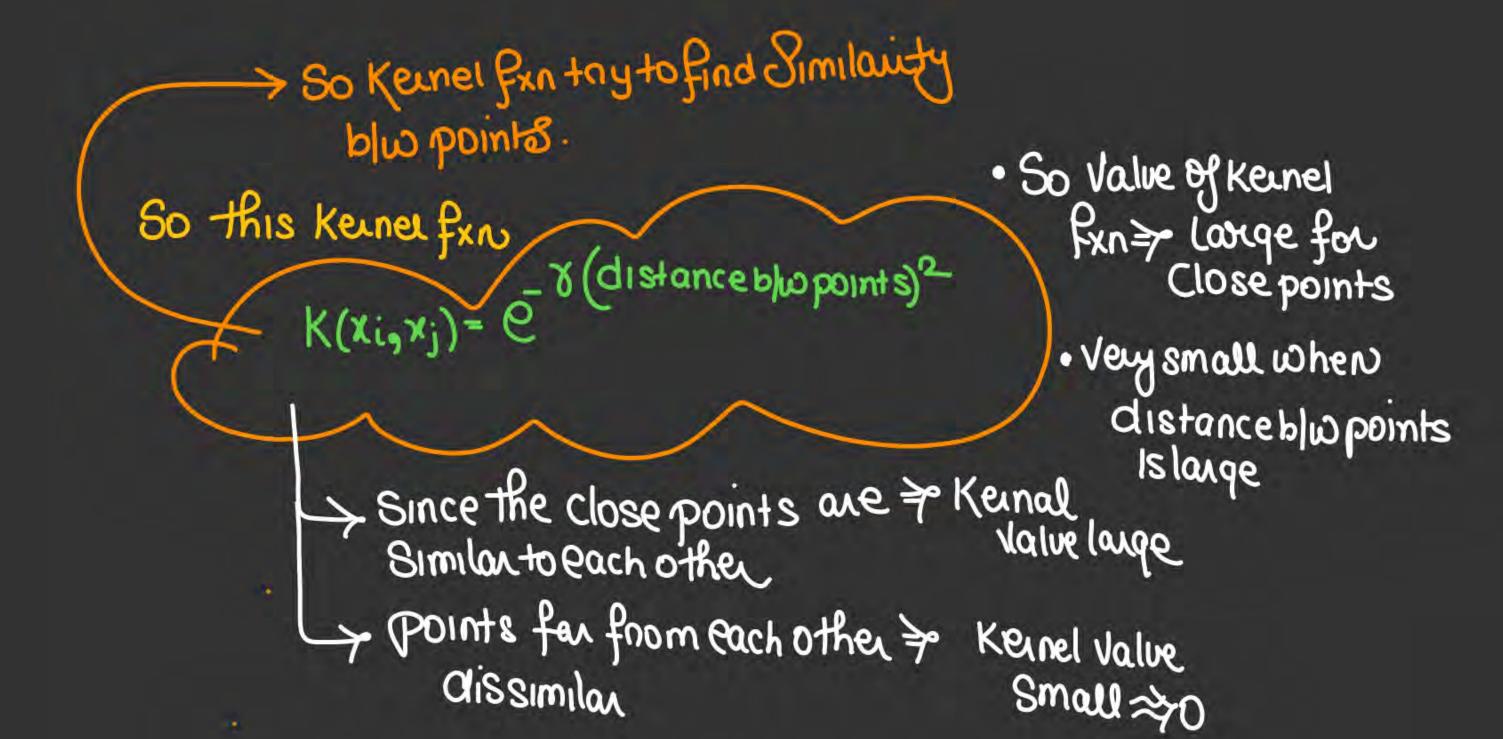
RBF Kernel

 $K(x, y) = \exp(-gamma * ||x - y||^2)$

Radial Basisfan.

$$K(x_0^2, x_0^2) = \exp(-x||x_0^2 - x_0^2|^2) \rightarrow (x_0^2 - x_0^2)^2 + (x_0^2 - x_0^2)^2 + (x_0^2 - x_0^2)^2 + (x_0^2 - x_0^2)^2$$

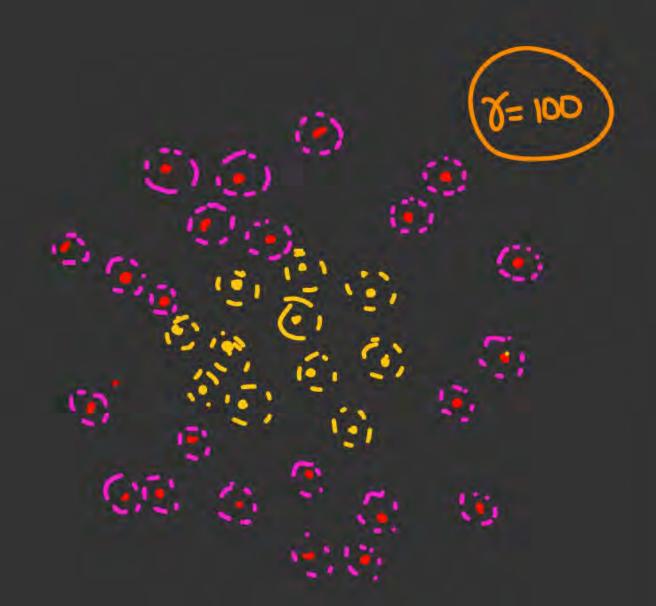
Constance by 2 points



So Keunel fxn > e V (distance blue)2 (1=00), So If I is small then

The neighbourhood of any

Point is wide spread. Vis a hyper Parameter 8=100, if 8 is large then neighbourhood.
Of any point is compact.



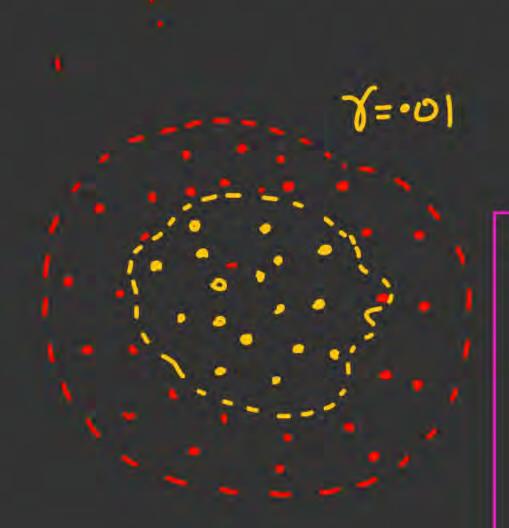
· If Visv. v. small = under fit

- · If Yislange >>

 ** **Complexity high

 ** **Bias=0

 ** Volunce=high
 - If Vis small Ly Perfect fit.



- the order of Non linewaty in exp term $e^{-x} = \infty$ $e^{-x} = (1 - x + xe/2! - x^3 - \dots)$
 - So the RBF Keiner Can Convert

 The feature space into a dimension

 Space.





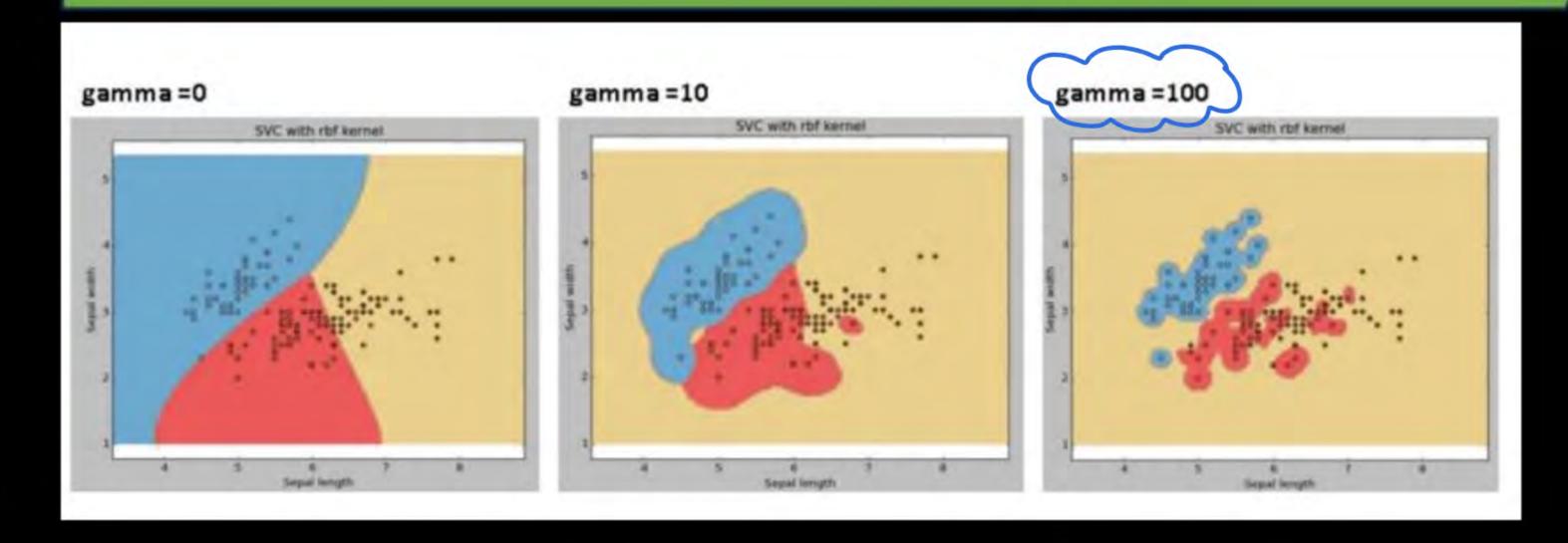
The Laplacian kernel can be defined as:

$$K(x,y) = e^{-x||x-y||}$$





RBF or Gaussian Kernel







RBF or Gaussian Kernel







Sigmoid Kernel

It is defined as

K(x,y) = tanh(alpha * x * y + beta), where x and y are the input vectors, alpha and beta are parameters, and tanh is the hyperbolic tangent function.

$$k(x,y) = tanh(x(x,y) + B)$$

$$\frac{1}{(2\theta + e^{-\theta})} \Rightarrow \frac{e^{2\theta} - e^{-\theta}}{e^{2\theta} + e^{-\theta}} \Rightarrow \frac{e^{2\theta} - e^{-\theta}}{e^{2\theta} + e^{-\theta}}$$

$$\Rightarrow k(x,y) = knh(x,y+k)$$

Linear kernels:

- Suitable for high-dimensional data or linearly separable data.
- Computes the dot product of input vectors, efficient for large feature sets.
- Simple and often used as a baseline for comparison.

RBF kernel:

- Default choice for non-linear problems in SVMs.
 - Captures complex relationships without prior knowledge of data.
- Sensitive to hyperparameter tuning, especially gamma.

not much imp, only nead it.

Polynomial kernels:

Effective for problems with polynomial patterns.

Commonly used in computer vision and image recognition.

Degree parameter controls the complexity of the polynomial.

Sigmoid kernel:

Useful for neural network applications.

Appropriate when data distribution resembles a sigmoid.

Requires careful tuning of parameters for best performance.







How the kernels do the transformation

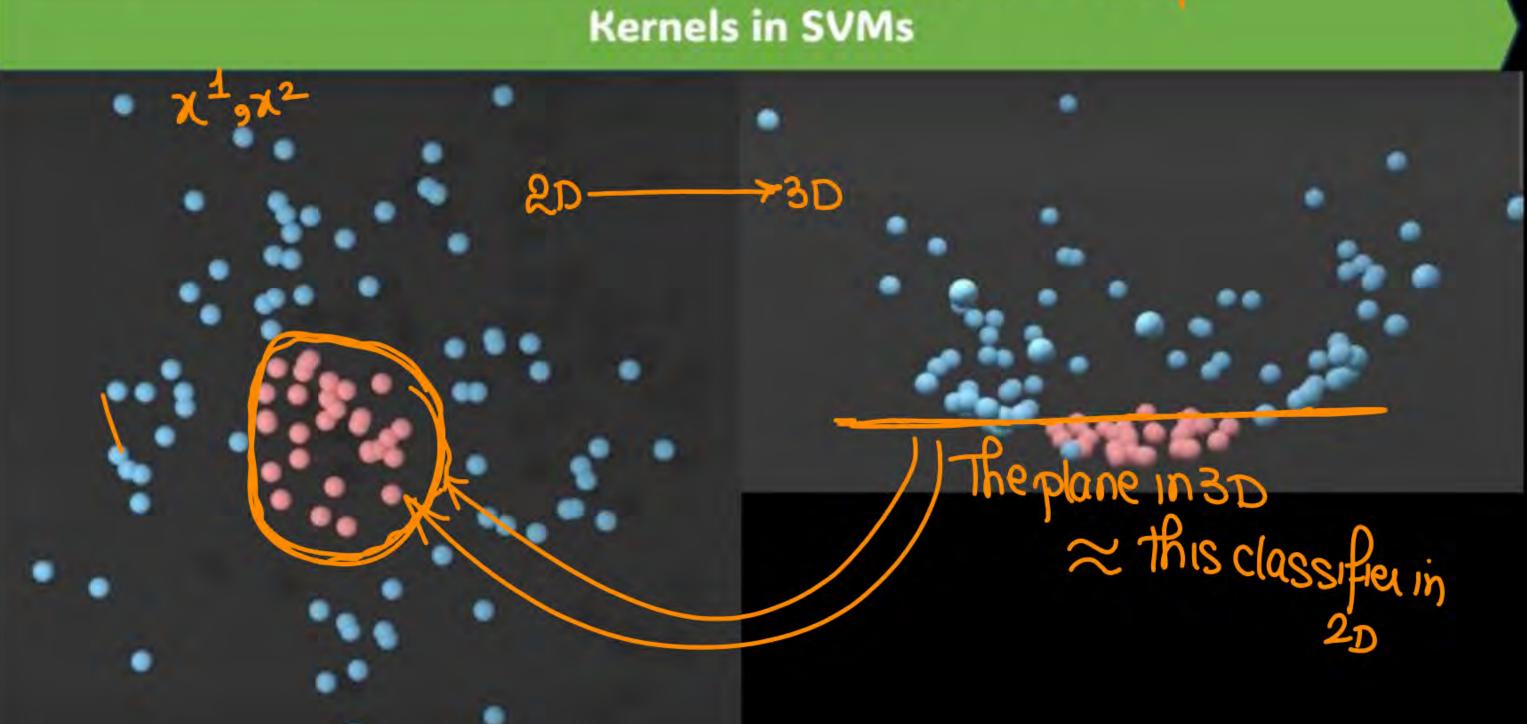
Mathematical definition: $K(x, y) = \langle f(x), f(y) \rangle$. Here K is the kernel function, x, y are n dimensional inputs. f is a map from n-dimension to m-dimension space. $\langle x,y \rangle$ denotes the dot product. usually m is much larger than n.



Ddimension (d+xw) - DParameters



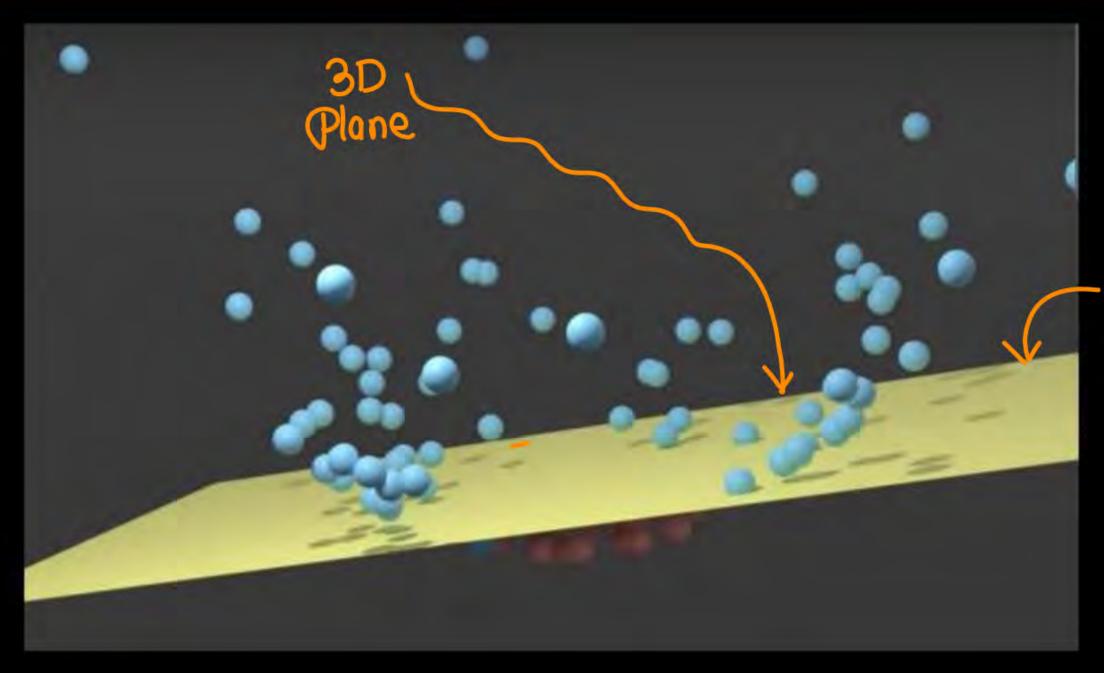








Kernels in SVMs

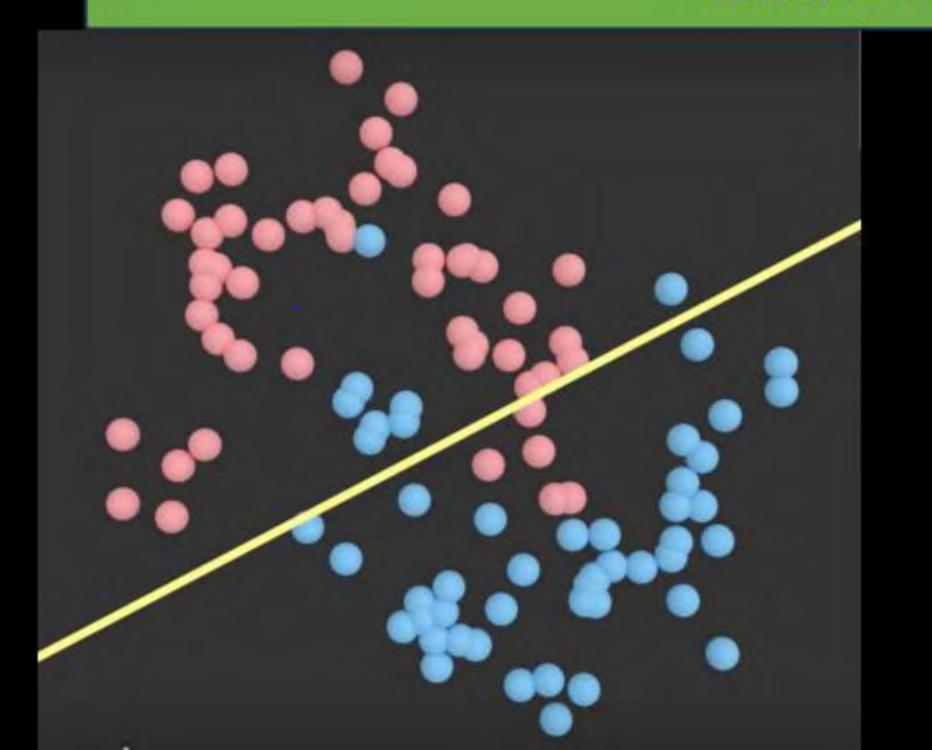


Linearly





Linear Kernel









Mercers Theorem

Mercer's theorem

Only those fin Can be used as Kernels if they satisfy >0

A function KK is a kernel function if it satisfies two conditions: $\frac{(x,y)=k(y,x)}{(y,x)}$

- Condition 1 The function KK must be symmetric.
- Condition 2 The function must be positive semidefinite.

we have iodatapoints

```
K(x19x2) - - - - K(x19x10)
> We have loxio matrix
                   K(X2,X1) K(X2,X2) - - - K(X2,X10)
> So keinel matrix 8hd
   be positive semi
   clefinite >
 K(X10,X10)
```





The Kernel trick will always work ??

NO, this wont work on noisy data...





uestion: You are training a linear SVM classifier with a binary classification problem. The SVM decision boundary is defined as 3x - 2y - 4 = 0. You want to classify a new data point with coordinates (5, 7). What is the signed distance of the data point to the decision boundary? 3x - 2y - 4 = 0

$$\frac{3(5)-2(7)-4}{\sqrt{3^2+2^2}} \Rightarrow \underbrace{15-14-4}_{\sqrt{9+4}} \Rightarrow \underbrace{-3/_{13}}_{\sqrt{9+4}}$$





Question: You are training a support vector machine with a polynomial kernel. The kernel function is defined as $K(x, y) = (x \cdot y + 1)^2$. You want to calculate K(3, 4). What is the value of K(3, 4)?

a) 25

Single o

≥ (13)2

b) 121

c) 144

d) 169





Question: You are using an RBF kernel in an SVM. The width parameter (gamma) is set to 0.1. What is the effect of increasing gamma on the SVM decision boundary?

It results in a more flexible (complex) decision boundary.



- b) It results in a less flexible (simpler) decision boundary.
- c) It does not affect the decision boundary.
- d) The effect on the decision boundary depends on the value of C.





Question: What is the primary objective of a Support Vector Machine (SVM)?

a) Minimize the number of support vectors.

Maximize the margin between classes.

- c) Minimize the number of features.
- d) Maximize the number of support vectors.





Question: In SVM, what is the role of a kernel function?

a) It determines the regularization parameter.

(f) It transforms data into a higher-dimensional space.

c) It computes the margin between classes.

d) It minimizes the number of support vectors.





Question: In a binary SVM classification, how are data points represented on the correct side of the decision boundary (positive class) with respect to the margin?

a) Support vectors

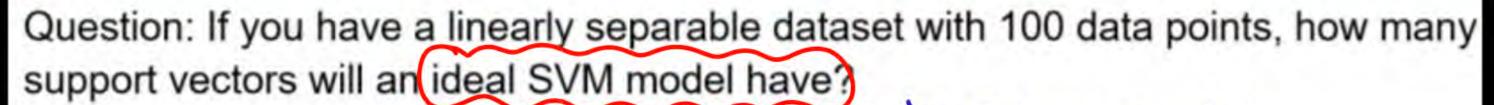


- b) Misclassified points
- c) Negative values









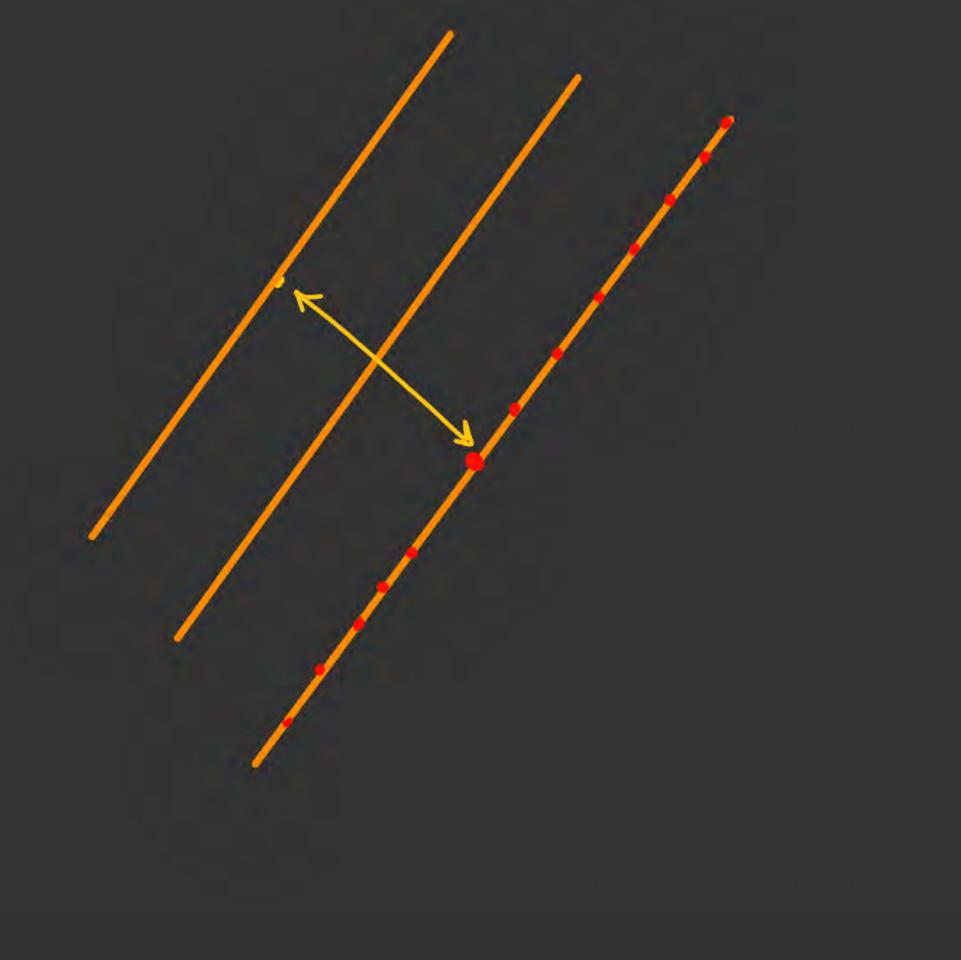
a) 100

b) 50

c) 10

d/2

Only 2' SVs are needed.







Question: In SVM, the term "support vectors" refers to:

Data points used to train the model. + tourning dato

Data points located far from the decision boundary.

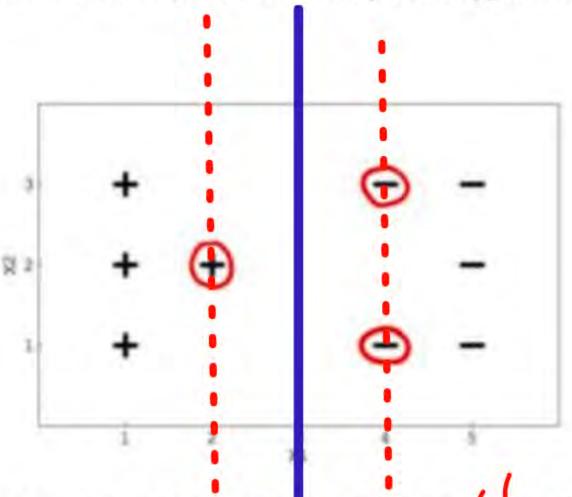
Data points on the correct side of the decision boundary.

Data points closest to the decision boundary.





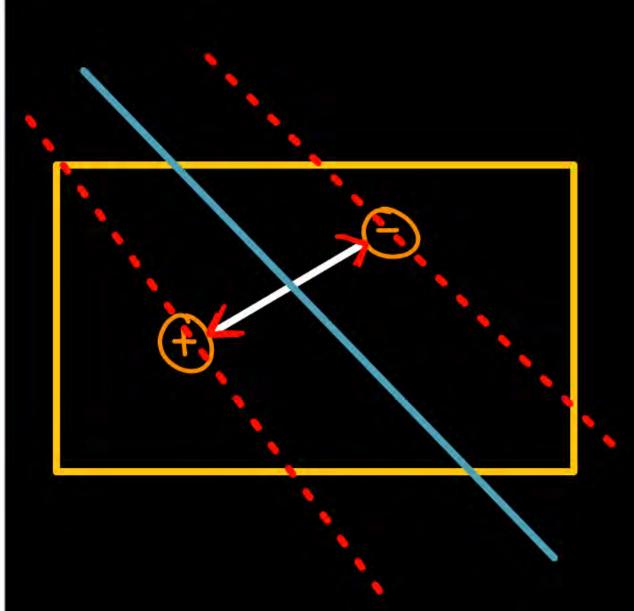
Suppose you are using a Linear SVM classifier with 2 class classification problem. Consider the following data in which the points circled red represent support vectors.

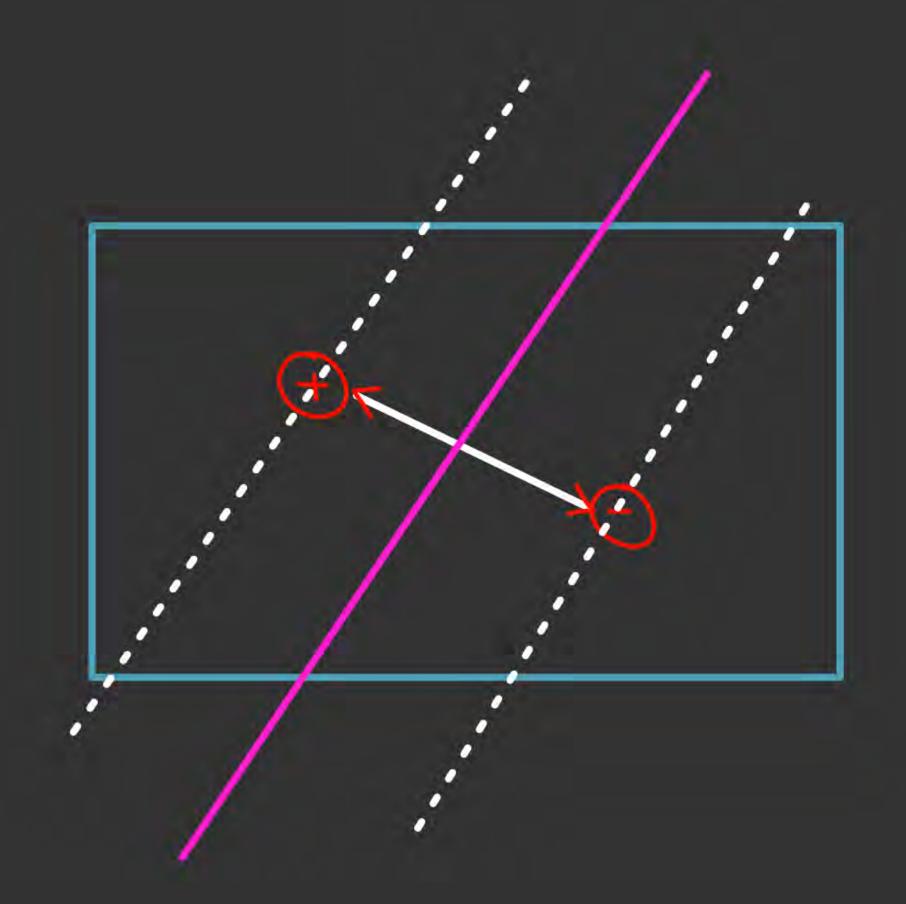


Will the decision boundary change if any of the red points are removed?



b. No









The soft margin SVM is more preferred than the hard-margin svm when:

- The data is linearly separable
- 2. The data is noisy and contains overlapping point





After training an SVM, we can discard all examples which are not support vectors and can still classify new examples?



True

b. False





In the linearly non-separable case, what effect does the C parameter have on the SVM mode.

- a. it determines how many data points lie within the margin
- it is a count of the number of data points which do not lie on their respective side of the hyperplane
- it allows us to trade-off the number of misclassified points in the training data and the size of the margin
- d. it counts the support vectors







Suppose that we use a RBF kernel with appropriate parameters to perform classification on a particular two class data set where the data is not linearly separable. In this scenario

- a. the decision boundary in the transformed feature space is non-linear
- b. the decision boundary in the transformed feature space is linear
 - c. the decision boundary in the original feature space is linear
 - d. the decision boundary in the original feature space is non-linear





- 1) Support vector machine may be termed as:
 - A. Maximum aprori classifier
- B. Maximum margin classifier
 - C. Minimum apriori classifier
 - D. Minimum margin classifier





- 3) If the hyperplane $W^TX+b=0$ correctly classifies all the training points (X_i, y_i) , where $y_i=\{+1, -1\}$, then:
 - A. ||W-1|| = 2
 - OB. X= 1
 - Oc. $W^T X_i + b \ge 0$ for all i
 - D. $y_i(W^TX_i+b) \ge 0$ for all i.





- 2) In a hard margin support vector machine:
 - A. No training instances lie inside the margin
 - B. All the training instances lie inside the margin
 - C. Only few training instances lie inside the margin
 - D. None of the above





- 4) The constraint in the primal optimization problem solved to obtain the hard margin optimal separating hyperplane is:
- A. $y_i(W^TX_i+b) \ge 1$ for all i
 - \bigcirc B. $y_i(W^TX_i+b) \le 1$ for all i
- C. $(W^TX_i+b) \ge 1$ for all i
- D. $(W^TX_i+b) \le 1$ for all i





10) In a hard margin SVM $W^TX+b=0$, suppose X_j 's are the support vectors and α_j 's the corresponding Lagrange multipliers, then which of the following statements are correct:

O A.
$$W = \sum a_i y_i X_i$$

O B. $\sum a_i y_i = 0$

B.
$$\sum a_i y_i = 0$$





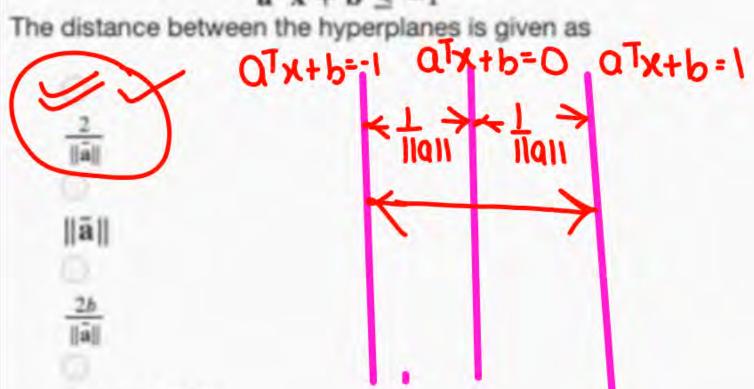


In a support vector machine (SVM) for classification of the points $\tilde{\mathbf{x}}$, let the hyperplanes be given as

$$\bar{\mathbf{a}}^T \bar{\mathbf{x}} + \bar{\mathbf{b}} \ge 1$$

 $\bar{\mathbf{a}}^T \bar{\mathbf{x}} + \bar{\mathbf{b}} \le -1$

 $2(b+1)||\tilde{\bf a}||$





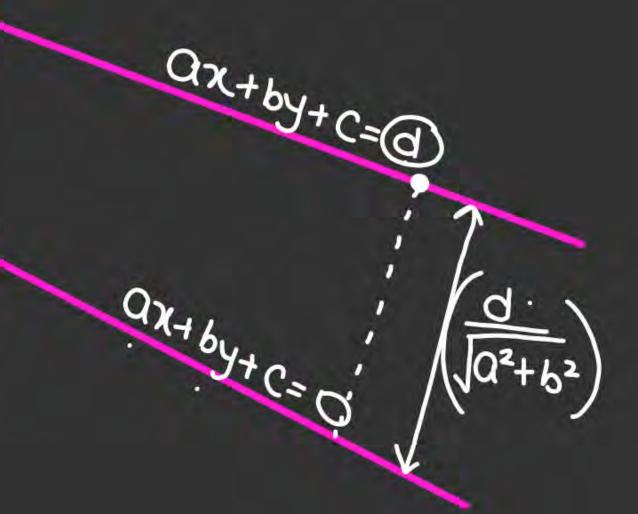


4) In a support vector machine (SVM) for classification of the points $\bar{\mathbf{x}}$, let the hyperplanes be given as

$$-8x_1 + 6x_2 + 3 \ge 5$$
$$-8x_1 + 6x_2 + 3 \le -5$$

The distance between the hyperplanes is given as $\begin{array}{c}
8 \times 1 + 6 \times 2 + 3 = 5 \\
-8 \times 1 + 6 \times 2 + 3 = 5
\end{array}$ $\begin{array}{c}
5 \\
\hline
\sqrt{8^2 + 6^2}
\end{array}$ $\begin{array}{c}
5 \\
\hline
\sqrt{8^2 + 6^2}
\end{array}$

$$-\frac{8}{5}x_{11} + \frac{6}{5}x_{11} + \frac{6}{5}x_{11} + \frac{6}{5}x_{11} + \frac{2}{5}x_{11} + \frac{2}{5}x_{1$$







SVM is a supervised Machine Learning can be used for Options :	
O Regression	O Classification
O both a or b	O None of These





Clo	sest Point to the hyperplane are support vectors	
0	True	O False
0	Unpredictable	O None of these





In SVM, the dimension of the hyperplane depends upon which one?		
O the number of features	O the number of samples	
O the number of target variables	O All of the above	



THANK - YOU