

13/11/20

class Node:

def __init__(self, state, level):

self.grid = state

self.level = level

self.cost = 0

~~def~~ def G(state):

return state.level

def H(state, target):

grid = state.grid

dist = 0

for i in grid:

d1, d2 = grid.index(i), target.index(i)

x1, y1 = d1 % 3

x2, y2 = d2 % 3

~~dist~~ dist += abs(x1 - x2) + abs(y1 - y2)

return dist

def F(state, target):

return G(state) + H(state, target)

~~def~~ def printGrid(state):

state = state.grid.copy()

state[state.index(-1)] = ''

print(state[0], state[1], state[2])

print(state[3], state[4], state[5])

print(state[6], state[7], state[8])

print()

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```
def isfrontier(frontier, neighbour)
```

```
    return len([state for state in neighbour frontier if  
                 state.grid == neighbour.grid]) > 0
```

```
def astar(state, target):
```

```
    frontier = [Node(state[1])]
```

```
    print("Fail")
```

```
def possible_moves(state):
```

```
    b = state.grid.index(0)
```

```
    d = []
```

```
    pos_moves = []
```

```
    pos_moves.append(gen, state, move, b)
```

```
    return
```

```
def gen(state, move, blank):
```

```
    temp = state.grid.copy()
```

```
    return temp
```

```
astar(src, target)
```