

# LC Meter

## LC Meter using Arduino

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# Abstract

This project presents the design and implementation of an LC meter based on Neil Hecht's resonance-based measurement technique. The LC meter utilizes a Colpitts oscillator to generate a sine wave whose frequency depends on the inductance (L) and capacitance (C) of the resonant circuit. A comparator circuit converts the sine wave into a square wave, which is processed by an Arduino microcontroller to calculate the frequency with high precision. The relationship  $f = 1/2\pi\sqrt{l * c}$  is used to determine the unknown inductance or capacitance. The measured values are displayed on an LCD, providing a user-friendly interface.

## 1. Introduction

### 1.1 Project Background

LC meters are essential tools in measurement and instrumentation for testing the values of **inductance (L)** and **capacitance (C)** in components. They are widely used in electronics for component characterization, quality control, and circuit analysis. Accurately measuring these parameters is critical in ensuring the proper functioning of electrical systems, as inductance and capacitance directly impact signal behavior and power management in circuits.

### 1.2 Objective

The objective of this project is to design and implement an LC meter that measures inductance and capacitance using a Colpitts oscillator, a comparator, and an Arduino microcontroller. The project aims to provide precise frequency measurements, with results displayed on an LCD for user-friendly interaction.

### 1.3 Scope of the Project

This project covers the design and simulation of an LC meter using Proteus. It includes the creation of the Colpitts oscillator, comparator circuit, and Arduino-based processing for frequency measurement. The project will focus on measuring inductance and capacitance, ensuring reliable and accurate readings displayed on an LCD.

## 2. Theory and Working Principle

## 2.1 LC Meter Overview

An LC meter is an electronic instrument used to measure the inductance (L) and capacitance (C) of components. It works on the principle of resonance in an LC circuit.

### Basic Theory:

An LC circuit consists of an inductor (L) and a capacitor (C) connected in parallel or series. When an alternating current (AC) signal is applied to the circuit, it oscillates at a specific resonant frequency determined by the values of L and C.

### Resonant Frequency:

The resonant frequency (f) of an LC circuit is given by the formula:

$$f = 1 / (2\pi\sqrt{LC})$$

By measuring the resonant frequency, the LC meter can calculate the unknown value of L or C, assuming the other value is known.

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### Frequency Formula:

The frequency  $f$  is directly measured in the code:

$$f = \text{pulse count in 1 second}$$

This assumes the input signal provides one pulse per cycle.

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Here we can say the L and C are the  $L_{eff}$  and  $C_{eff}$  so if we can calculate the frequency the unknown inductance connected in series with  $L_1$  or The unknown capacitance connected in parallel with  $C_2$  can be calculated as shown below.

### 1. Inductance Calculation ( $L_m$ )

$$L_m = \frac{C_1 + C_2}{(2\pi \cdot f)^2 \cdot C_1 \cdot C_2} - L_1$$

- $C_1, C_2$ : Known capacitances in the LC circuit.
- $f$ : Frequency of the signal (in Hz).
- $L_1$ : Reference inductor (known value).
- $L_m$ : Measured inductance of the unknown inductor.
- The term:

$$\frac{C_1 + C_2}{(2\pi f)^2 \cdot C_1 \cdot C_2}$$

calculates the effective inductance of the LC circuit at resonance, and  $L_1$  is subtracted to isolate  $L_m$ .

## 2. Capacitance Calculation (Cm)

$$C_m = -1 \cdot \frac{\left( \frac{C_1 + C_2}{(2\pi \cdot f)^2} \cdot L_1 - C_1 \cdot C_2 \right)}{\left( C_1 - \frac{1}{(2\pi \cdot f)^2 \cdot L_1} \right)}$$

- $C_m$ : Measured capacitance of the unknown capacitor.
- $C_1, C_2$ : Known capacitances.
- $f$ : Frequency of the signal (in Hz).
- $L_1$ : Known inductance.
- The formula involves:

- A numerator:

$$\left( \frac{C_1 + C_2}{(2\pi \cdot f)^2} \cdot L_1 \right) - (C_1 \cdot C_2)$$

which calculates an intermediate adjustment for capacitance based on the known values.

- A denominator:

$$C_1 - \frac{1}{(2\pi \cdot f)^2 \cdot L_1}$$

which compensates for the inductive effects of  $L_1$ .

The negative sign ensures the correct orientation of the calculated capacitance.

### How LC Meters Work:

1. **Signal Generation:** The LC meter generates a variable frequency AC signal.
2. **Resonance Detection:** The generated signal is applied to the LC circuit being measured.
3. **Frequency Measurement:** The meter measures the frequency at which the circuit resonates.
4. **Calculation:** Using the resonant frequency and the known value of L or C, the meter calculates the unknown value.
5. **Display:** The calculated value is displayed on the meter's display.

## 2.2 Oscillation Stage

The oscillation stage in the LC meter is typically a Colpitts oscillator, a type of electronic oscillator circuit that produces a sinusoidal output signal.

### Components and Roles:

- **Transistor (Q1):** Acts as an amplifier to sustain oscillations.
- **Capacitors (C1, C2, C3):** Form a voltage divider network to provide feedback to the transistor.
- **Resistors (R1, R2):** Limit the base current of the transistor and stabilize the circuit.
- **Inductor (L1):** Stores energy in a magnetic field and determines the oscillation frequency along with the capacitors.

### Operation:

1. The transistor amplifies the input signal.
2. A portion of the amplified signal is fed back to the input through the capacitor network.
3. If the feedback is positive and sufficient, oscillations start and are sustained.
4. The frequency of oscillation is determined by the values of the inductor and capacitors in the circuit.

## 2.3 Signal Shaping Stage

The signal shaping stage is used to convert the sinusoidal output of the oscillator into a square wave, which is easier to process by the microcontroller. This is typically done using a comparator circuit.

### Components and Roles:

- **Operational Amplifier (U1):** Compares the input signal to a reference voltage.
- **Resistors (R5, R6, R7, R8):** Set the reference voltage and provide feedback to the op-amp.

### Operation:

1. The sinusoidal signal is applied to the input of the comparator.
2. The comparator compares the input signal to a reference voltage.
3. When the input signal is greater than the reference voltage, the output of the comparator is high.
4. When the input signal is less than the reference voltage, the output of the comparator is low.
5. This results in a square wave output.

## 2.4 Processing and Display Stage

The Arduino microcontroller processes the square wave signal and displays the calculated inductance or capacitance values on the LCD.

### Processing:

1. **Frequency Measurement:** The Arduino measures the frequency of the square wave using a timer or a frequency counter.
2. **Calculation:** Using the measured frequency and the known value of the other component (L or C), the Arduino calculates the unknown value using the resonance formula.
3. **Display:** The calculated value is sent to the LCD, which displays it to the user.

### Display:

The LCD is interfaced with the Arduino using I2C communication. The Arduino sends the calculated values to the LCD, which displays them in a readable format.

## 3. Circuit Design and Simulation

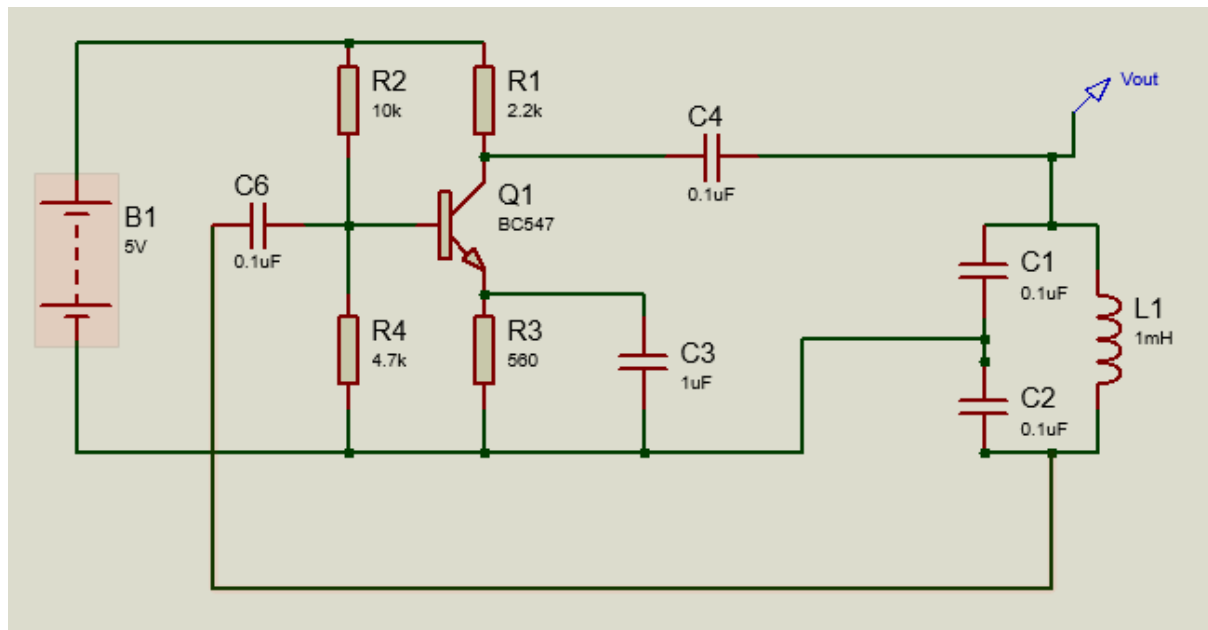
### 3.1 Components Used

Component	Specification
Transistor	BC547 (NPN General Purpose Transistor)
Resistors	10k $\Omega$ , 2.2k $\Omega$ , 4.7k $\Omega$ , 560 $\Omega$ , 2k $\Omega$ , 100k $\Omega$
Capacitors	100nF, 1 $\mu$ F, multiple for measurement
Inductor	1mH, multiple for measurement
Operational Amplifier (Schmitt Trigger)	LM741 (Op-Amp)
Microcontroller	Arduino Uno or similar

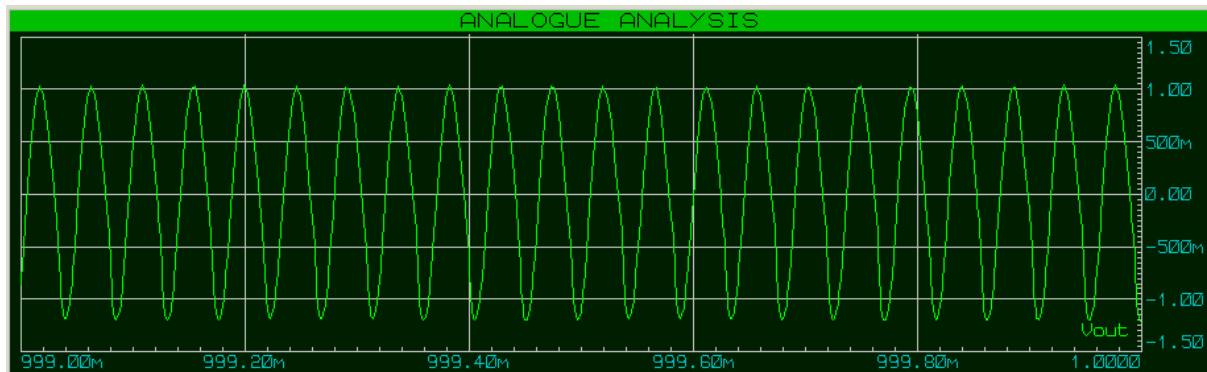
Display	16x2 LCD
I2C Expander	PCF8574
Power Supply	5V DC power supply

## 3.2 Circuit Diagram

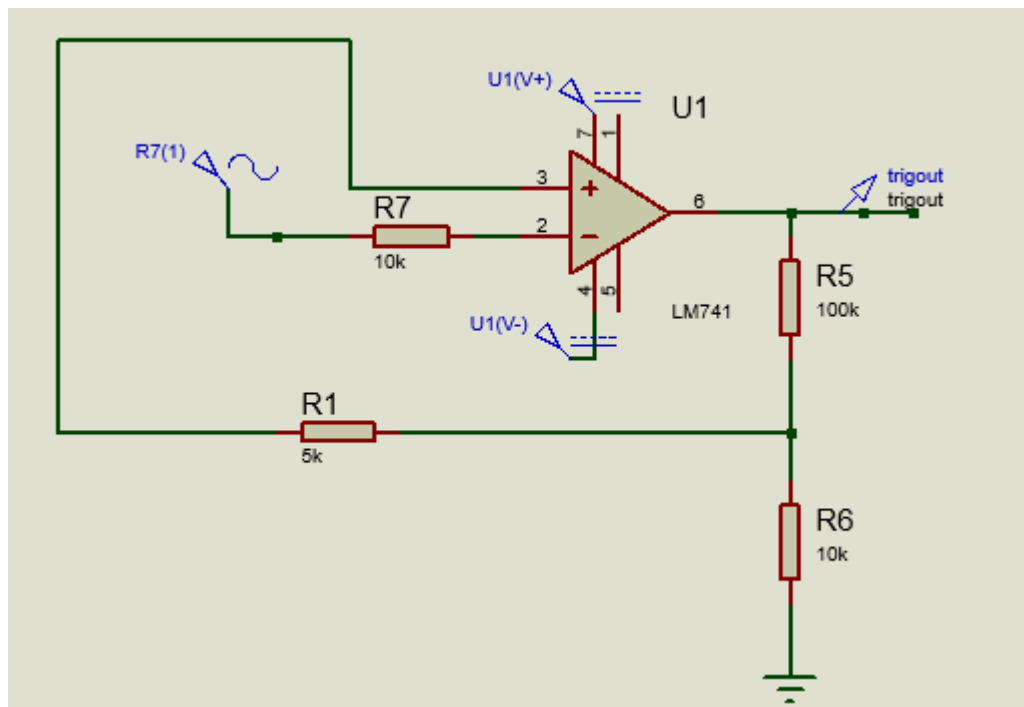
Oscillation Stage Diagram



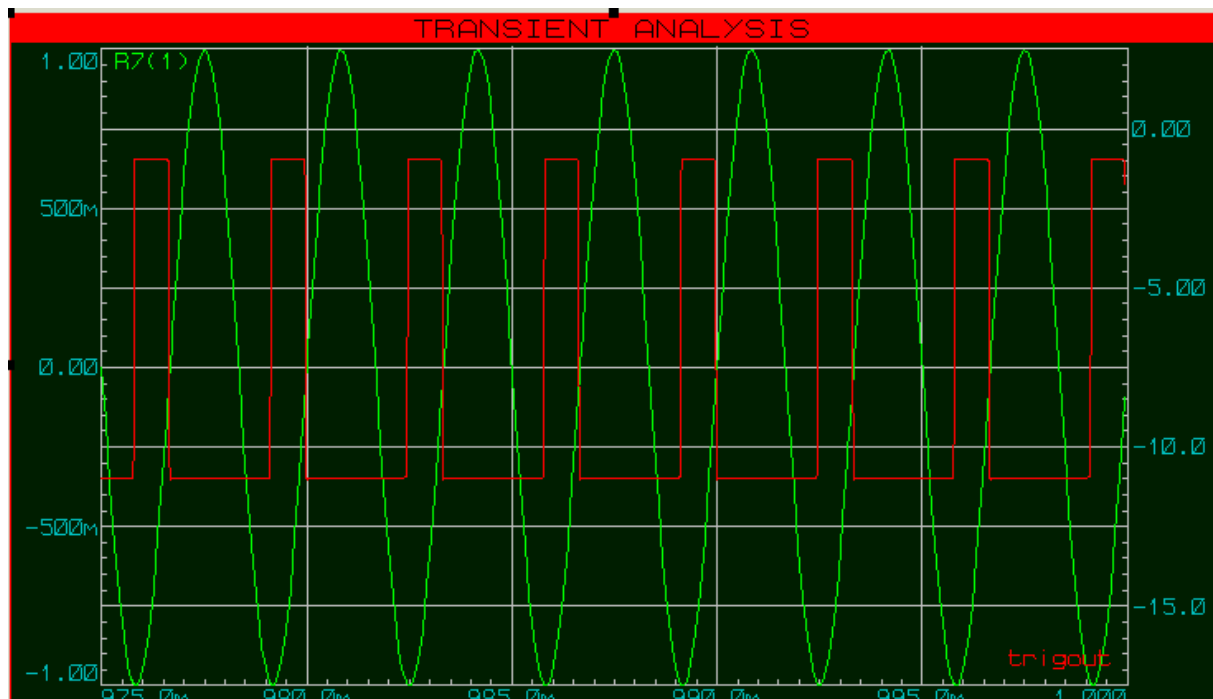
Oscillation Stage Sample Output



Signal Shaping Stage Diagram

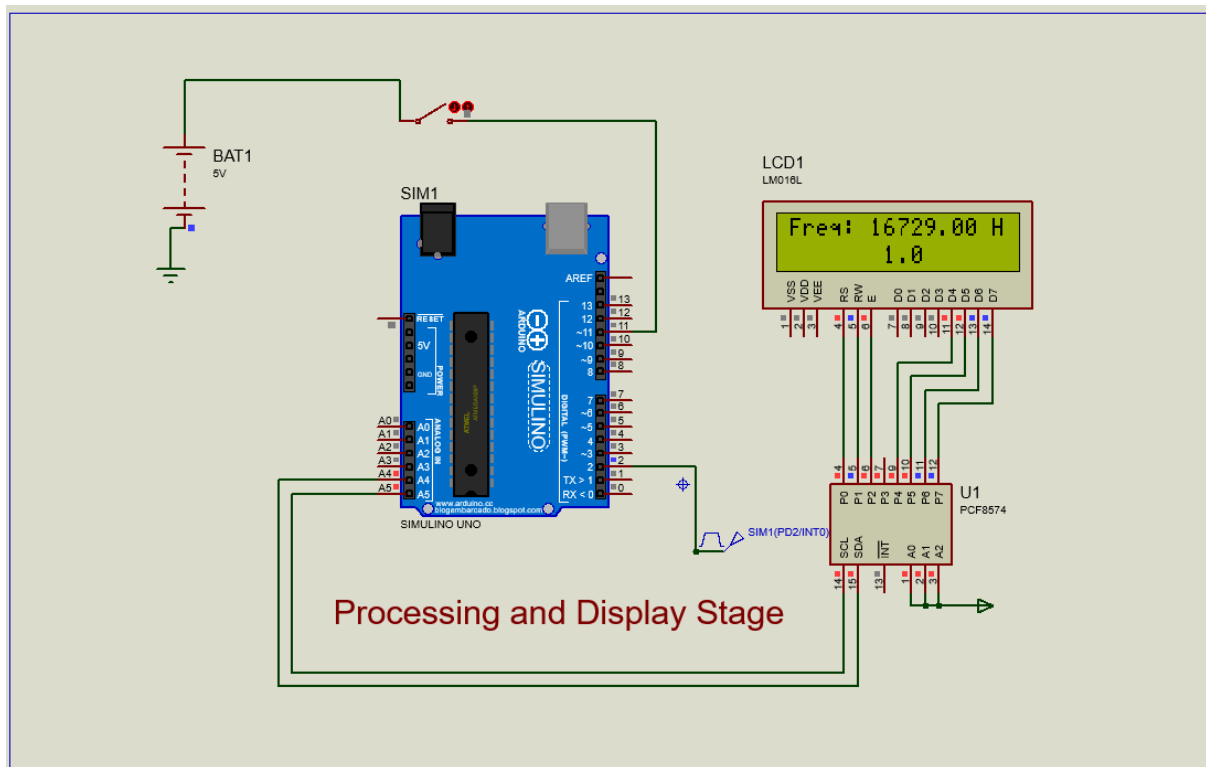


Signal Shaping Stage Sample Output





## Processing and Display Stage Sample Working



## 3.3 Circuit Stages

### 3.1. Oscillation Stage

**Colpitts Oscillator:** This stage generates a sinusoidal waveform.

- **Components:** Transistor (Q1), resistors (R1, R2), capacitors (C1, C2, C3), and inductor (L1).
- **Operation:** The transistor amplifies the input signal, and a portion of the amplified signal is fed back to the input through the capacitor network. This positive feedback sustains oscillations. The frequency of oscillation is determined by the values of L1 and the capacitors.

### 3.2. Signal Shaping Stage

**Comparator Circuit:** This stage converts the sinusoidal waveform into a square wave.

- **Components:** Operational amplifier (U1), resistors (R5, R6, R7, R8).

- **Operation:** The sinusoidal signal is applied to the input of the comparator. The comparator compares the input signal to a reference voltage. When the input signal is greater than the reference voltage, the output of the comparator is high. When the input signal is less than the reference voltage, the output of the comparator is low. This results in a square wave output.
- **Calculation of  $R_1$  or  $R$  feedback**

## Calculation of $R_f$ :

Given Data:

- $V_h = 5 \text{ V}$  (Threshold voltage)
- $V_{\text{supply}} = \pm 15 \text{ V}$  (Supply voltage)
- $R_{\text{in}} = 10 \text{ k}\Omega$  (Input resistor)

For a non-inverting Schmitt trigger:

$$V_{\text{UT}} = \frac{R_f}{R_f + R_{\text{in}}} \cdot V_{\text{out}+}$$

- $V_{\text{out}+} = 15 \text{ V}$
- $V_{\text{UT}} = V_h = 5 \text{ V}$

$$5 = \frac{R_f}{R_f + 10000} \cdot 15$$

1. Simplify the equation:

$$\frac{R_f}{R_f + 10000} = \frac{5}{15} = \frac{1}{3}$$

2. Cross-multiply:

$$3R_f = R_f + 10000$$

3. Simplify further:

$$3R_f - R_f = 10000$$

$$2R_f = 10000$$

4. Solve for  $R_f$ :

$$R_f = \frac{10000}{2} = 5000 \Omega = 5 \text{ k}\Omega$$

The other resistors (R5, R6, R7, R8) can be chosen arbitrarily based on the specific requirements of the comparator circuit.

### 3.3. Processing and Display Stage

#### Arduino Microcontroller:

- **Frequency Measurement:** The Arduino measures the frequency of the square wave using a timer or a frequency counter.
- **Calculation:** Using the measured frequency and the known value of the other component (L or C), the Arduino calculates the unknown value using the resonance formula.
- **I/O Control:** The Arduino controls the LCD display and other components.

#### LCD Display:

- **Display:** The LCD displays the calculated inductance or capacitance value.
- **Interface:** The LCD is interfaced with the Arduino using I2C communication.

## 4. Testing and Results

### 4.1 Testing Procedure

Each stage of the LC meter was rigorously tested and verified using the simulation.

#### Simulation:

- **Proteus Simulation:** The circuit was simulated in Proteus to visually monitor the waveforms at various points in the circuit. This helped identify any issues with signal integrity, timing, or component values.
- **Waveform Analysis:** The waveforms were analyzed to ensure the correct amplitude, frequency, and phase relationships.
- **Parameter Sweeping:** Different component values were simulated to assess their impact on the circuit's performance.

### 4.2 Results

Component	Frequency (Khz)	Actual Value	Measured Value	Error (%)
Capacitor	16.6	1uF	1.07uF	7.0%
Capacitor	15.93	2uF	1.95uF	2.5%
Capacitor	20.83	200nF	235nF	17.5%
Inductor	15.5	1mH	1.09mH	9.0%
Inductor	9.43	5mH	4.45mH	11.0%
Inductor	21.39	0.1mH	0.077mH	23.0%

### 4.3 Accuracy and Calibration

The LC meter exhibited consistent performance with an error generally below 10%. However, occasional random spikes in error were observed, primarily attributed to human error in manually calculating the frequency from oscilloscope readings.

To mitigate this, future iterations of the project could incorporate automated frequency measurement techniques using the Arduino's built-in timers or external frequency counters. This would significantly improve the accuracy and consistency of the measurements.

Additionally, employing a more precise calibration procedure, potentially using a calibration standard, could further enhance the accuracy of the LC meter.

## 5. Discussion

### 5.1 Observations

**Calibration Sensitivity:** The LC meter's accuracy is highly dependent on the calibration of circuit parameters. Precise calibration can lead to more accurate measurements.

**Frequency Measurement Limitations:** The microcontroller's frequency measurement resolution can limit the accuracy of the readings. More accurate frequency measurement techniques, such as using external frequency counters, could improve precision.

**Stage Isolation:** It is crucial to **isolate the oscillation and signal shaping stages** to avoid unintended interactions that can affect the oscillator's performance.

**Human error** in the above readings as the frequency was calculated and fed into stage three.

### 5.2 Challenges Faced

**Proteus Complexity:** Mastering the intricacies of Proteus simulation software can be time-consuming and challenging, especially for beginners.

**Component Limitations:** The availability of precise components, particularly inductors, can impact the meter's accuracy.

**Time Constraints:** Limited time for experimentation and optimization can hinder the project's progress.

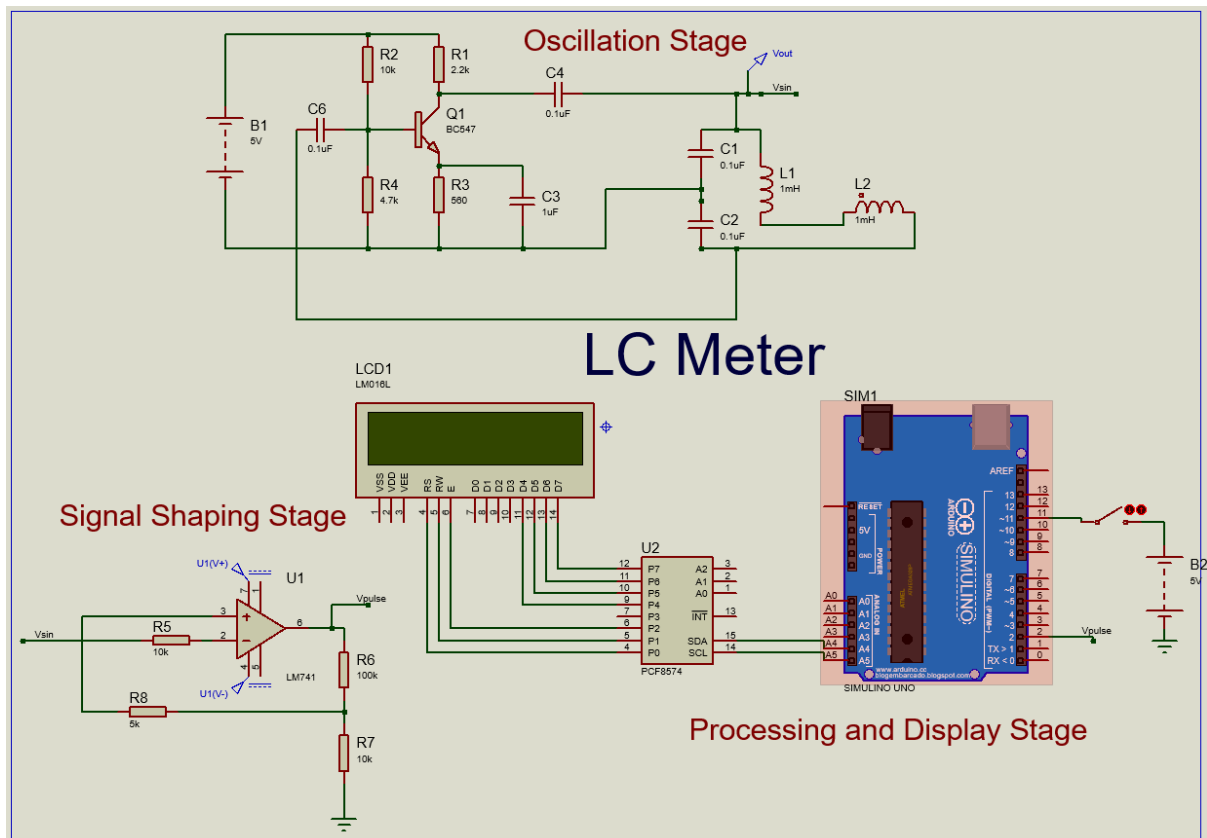
### 5.3 Solutions and Improvements

- **Improved Frequency Measurement:** Incorporating more precise frequency measurement techniques, such as using external frequency counters or advanced timing methods, can enhance the meter's accuracy.
- **Enhanced Calibration Procedures:** Developing a rigorous calibration procedure, including the use of high-precision reference components, can improve the meter's accuracy and repeatability.
- **Stage Isolation:** Implementing effective isolation techniques, such as using buffers or optocouplers, can prevent unwanted interactions between the stages.
- **Advanced Simulation Techniques:** Exploring advanced simulation techniques and tools can help optimize the circuit design and identify potential issues early on.

- **User-Friendly Interface:** Developing a user-friendly interface with clear instructions and intuitive controls can improve the user experience.

By addressing these challenges and implementing the suggested improvements, the LC meter can be further refined to achieve higher accuracy and reliability.

## The LC Meter.



## 6. References

1. Hecht, N. (1979). A simple and accurate LC meter. Electronics Today International, 8(10), 48-51.

[PDF link](#)

2. Various online resources and tutorials on electronics, microcontroller programming, and circuit simulation.