

# Ashutosh Purohit

Last updated on August 21, 2017

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## EDUCATION

### BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE

BE(Hons) Manufacturing Engineering  
Junior | Pilani, India  
CGPA: 8.38/10

### NAVRACHANA HIGHER SECONDARY SCHOOL

12th Graduation  
March 2015 | Baroda, India  
Percentage: 93%

### BHARTIYA VIDYA BHAVANS

10th Graduation  
March 2013 | Baroda, India  
CGPA: 10/10

## LINKS

Facebook://AshutoshP24  
LinkedIn://AshutoshP  
Twitter://@AP  
Quora://Ashu

## COURSEWORK

### UNDERGRADUATE

Manufacturing Processes  
Manufacturing Management  
Supply Chain Management  
Fluid Mechanics  
Kinematics and Dynamics of Mechanisms  
Machine Design and Drawing  
Neural Networks and Fuzzy Logic  
Object Oriented Programing

### MOOCS

Neural Networks by Jefery Hinton  
Algorithms by California Institute of Technology

## SKILLS

### PROGRAMMING

Over 5000 lines  
• Java • C • Python

### SOFTWARES

• Solidworks • Linkage • COMSOL  
• Arduino

## EXPERIENCE

### INDIAN SPACE RESEARCH ORGANIZATION | RESEARCH INTERN

May 2017 - July 2017 | Jodhpur, India

- Created a **neural network implementing the googLENET algorithm** to detect windmills in a given satellite image and achieved an **accuracy of 95%**
- Mentored by **Dr Rakesh Paliwal, Sr Scientist, ISRO**
- The program so developed **will be used by ISRO for further research**

### DUBAI PRECAST CONCRETE | SUMMER INTERN

June 2016 - July 2016 | Dubai

- **Paid intern** in the Design department
- Introduced the design team to the **benefits of SolidWorks in performing stress-strain as well as other simulations** on hollow core slabs and other precast elements

## PROJECTS

### EFFECT OF CUTTING TOOL PARAMETERS ON SURFACE ROUGHNESS USING NEURAL NETWORKS | BITS PILANI

Feb 2017 | Pilani, India

Worked in a **2 membered team** to evaluate cutting tool parameters to obtain minimal surface roughness in a mild steel rod using neural networks.

### DESIGNING AND MANUFACTURING AN AUTONOMOUS ROBOT AND A SEMI-AUTONOMOUS ROBOT | ABU ROBOCON 2016

Mar 2016 | Pune, India

Designed and Manufactured the Hybrid bot which is a **semi-autonomous robot** capable of **line following, climbing poles and also powering the Eco bot**, a small autonomous bot adept in line following, to compete in a pan Asia Competition.

### DESIGNING AND MANUFACTURING A MANUAL DISK PROPELLING BOT | ABU ROBOCON 2017

Mar 2017 | Pune, India

Designed and manufactured a bot proficient in not only **throwing disks at a given distance and height**, but also **line following**, to compete in a pan Asia Competition.

## AWARDS

2012 **City topper** and state rank **105<sup>th</sup>** National Science Talent Search Examination

2012 **City topper** and state rank **22<sup>nd</sup>** International English Olympiad

## POSITIONS OF RESPONSIBILITY

- [1] One of the six **core members** of the **Junior Placement Committee**
- [2] **Event Coordinator** in the Manufacturing division
- [3] **Mechanical subsystem lead** for Team Robocon