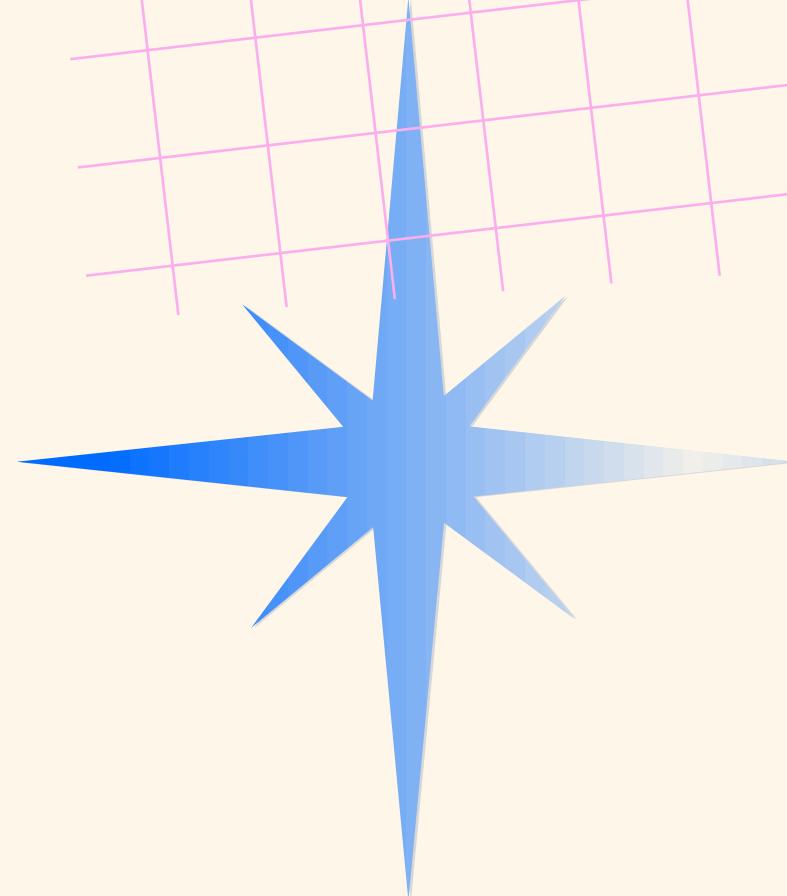
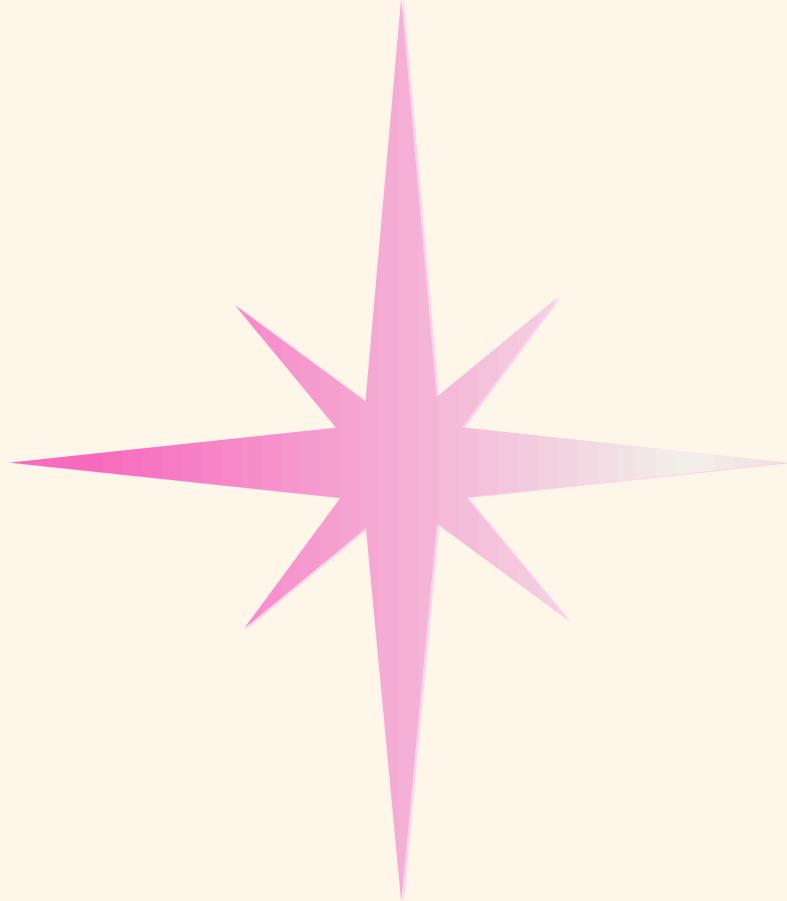


BreadBoard Guitar

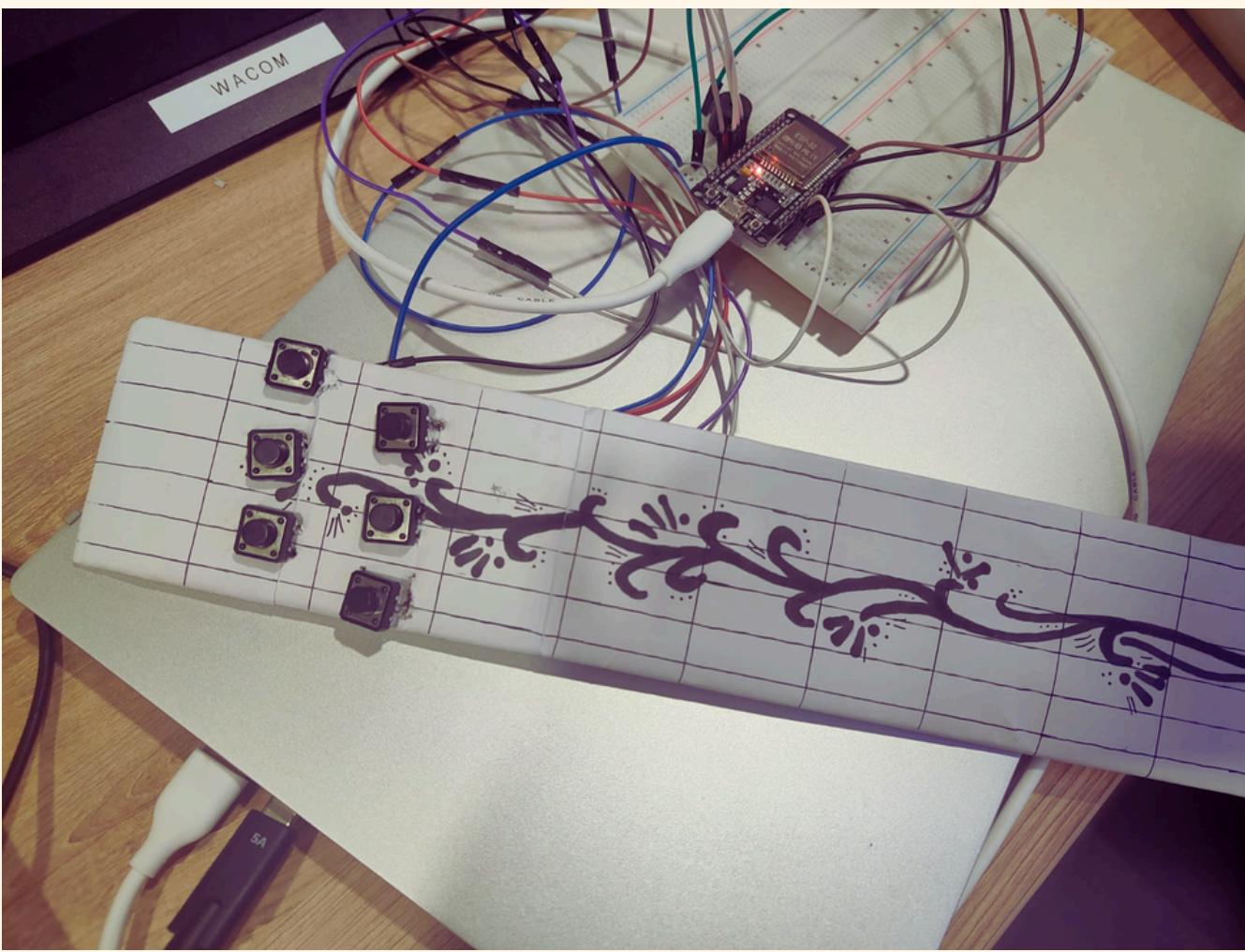
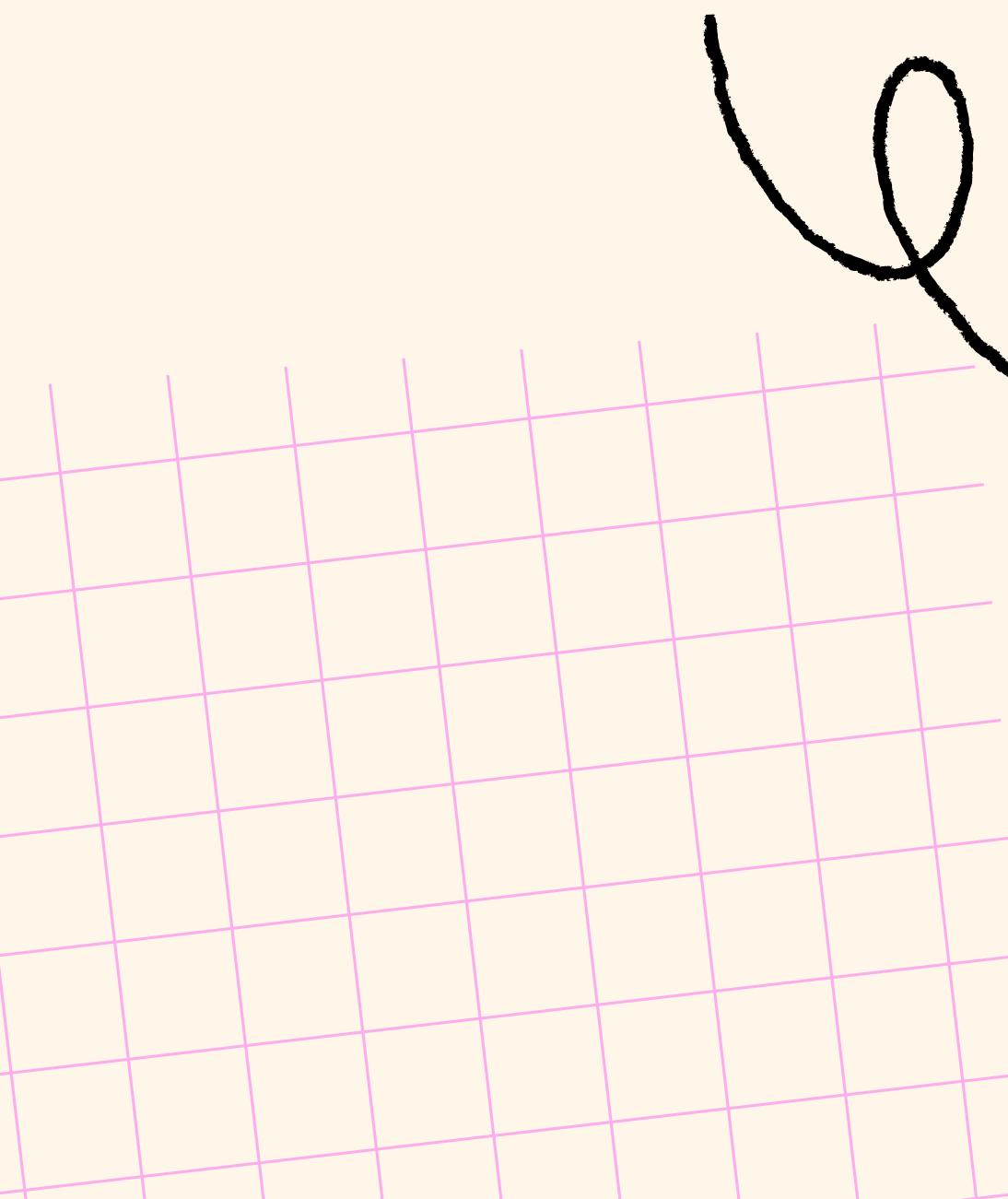
ur fav team btw

101

Punya & Zalak

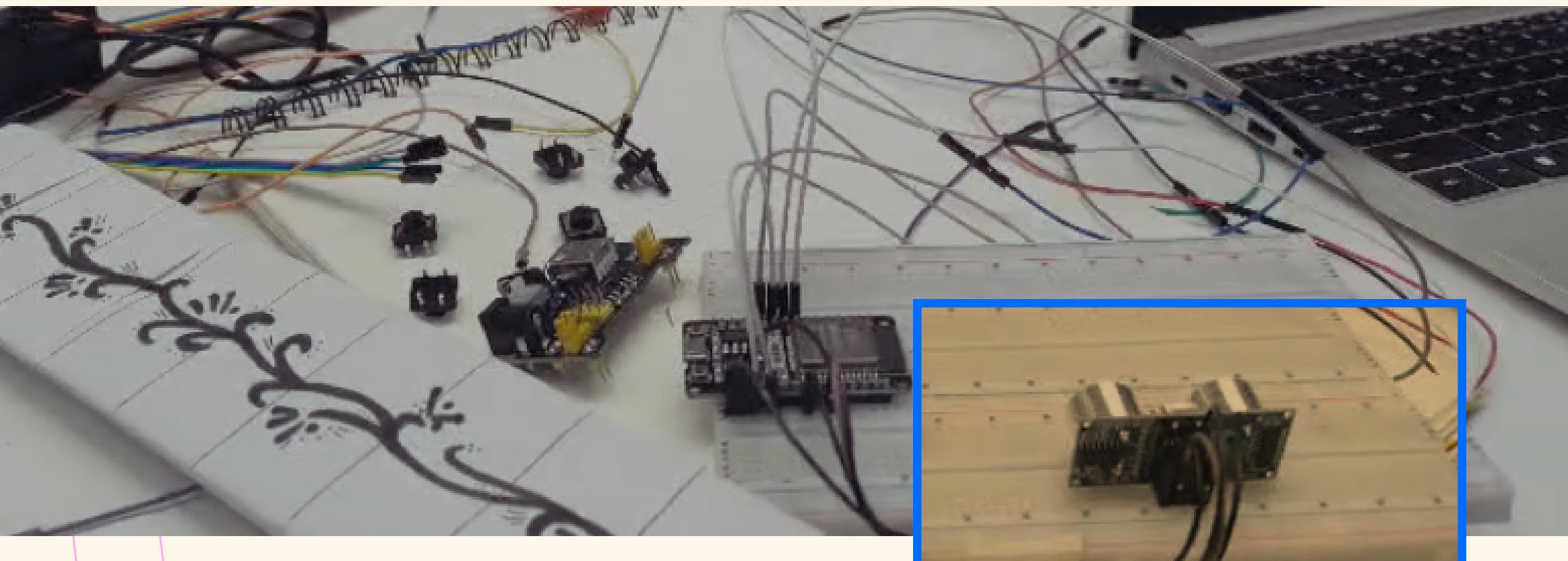
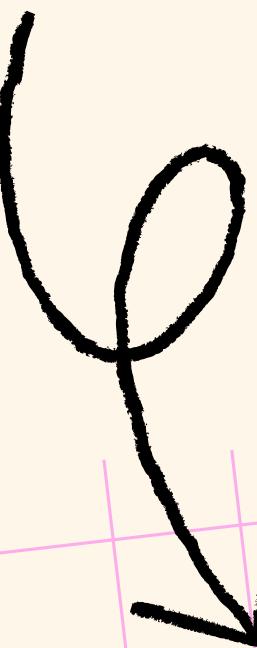
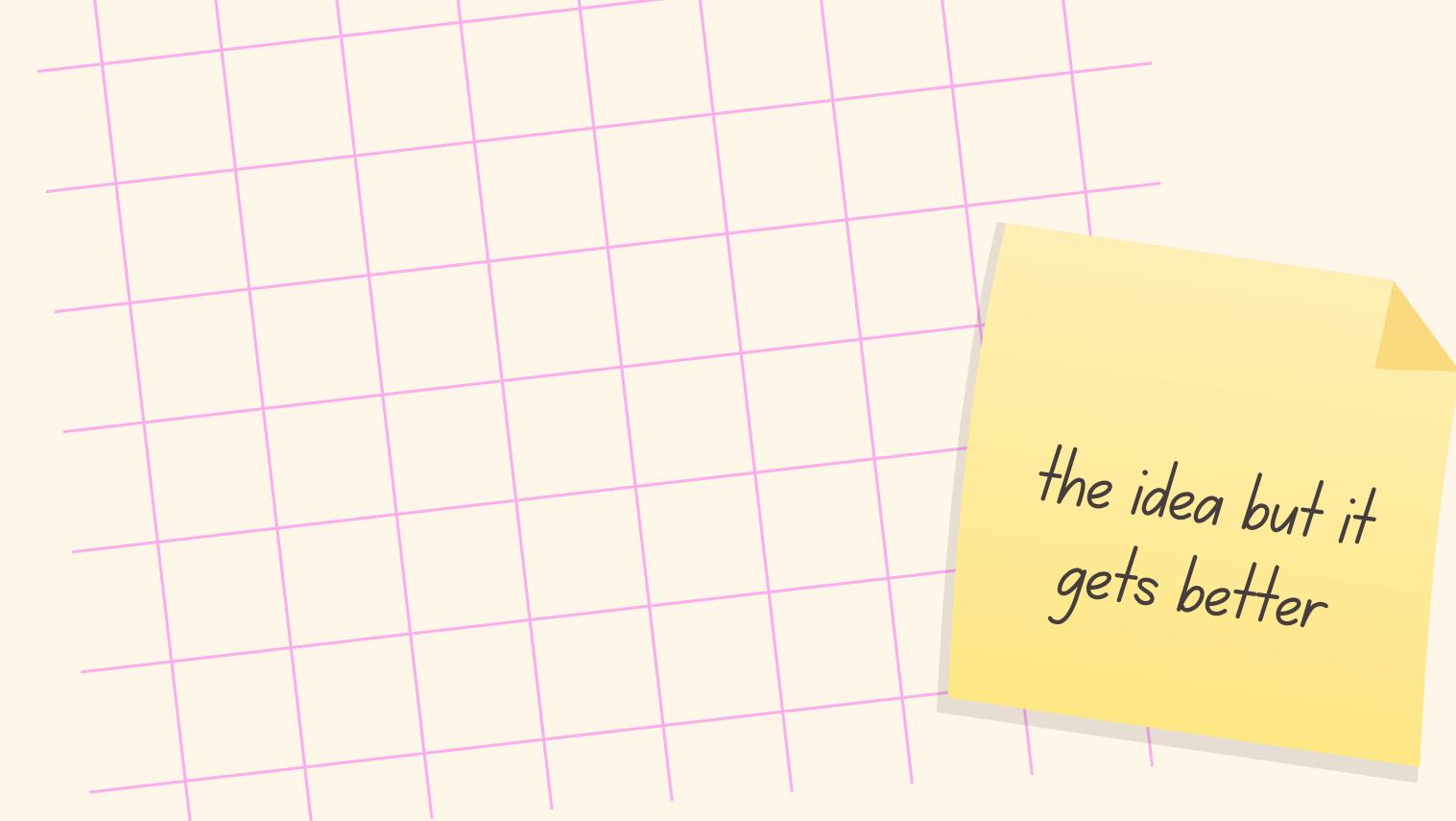


the idea was to create a **toy**
guitar that mimics the 3
chords: **D, A, and G** through
the pushbuttons on the
fretboard.



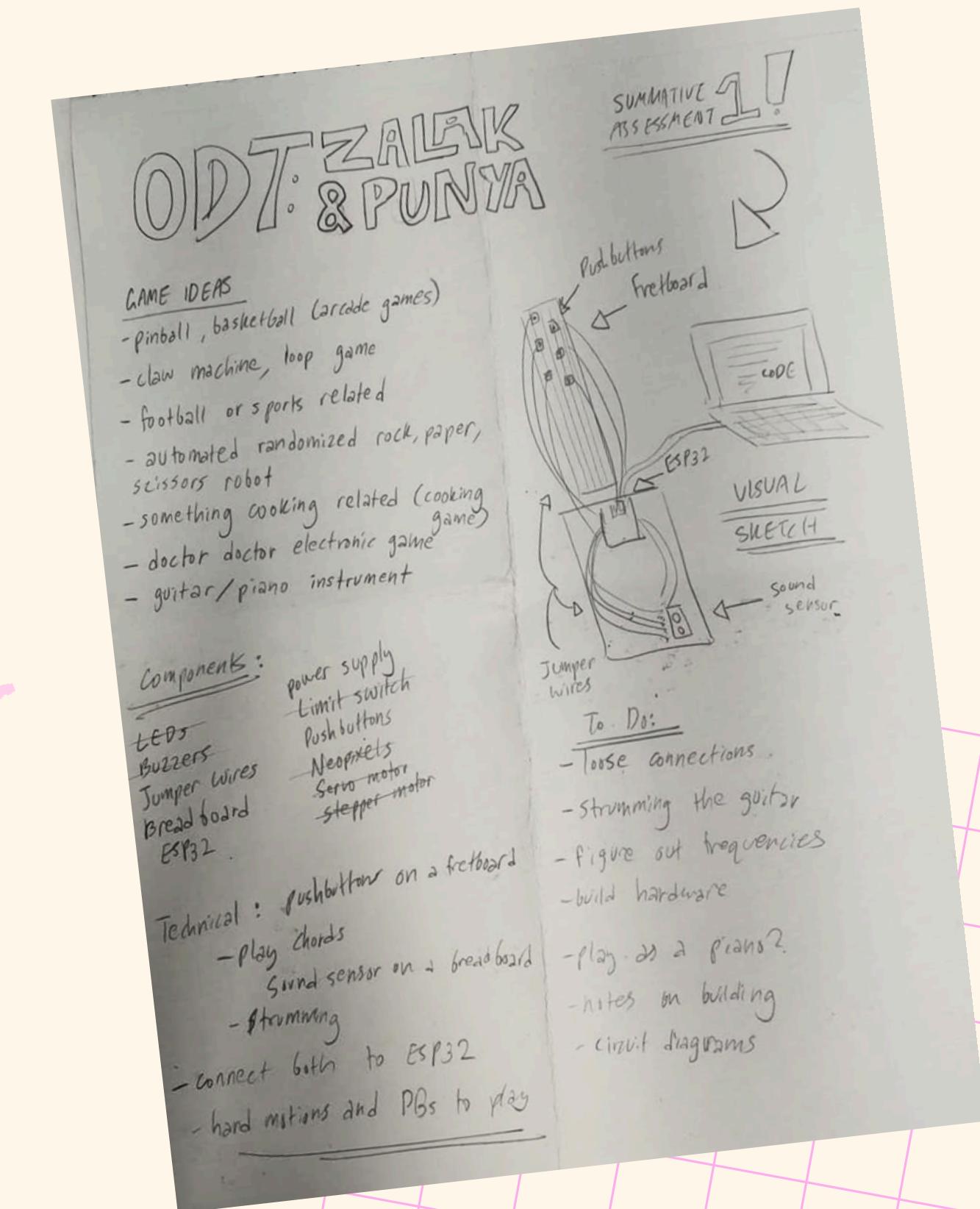
#fire

to make it even more closer to an actual guitar, I decided to introduce the **ultrasonic sensor** for the strumming.

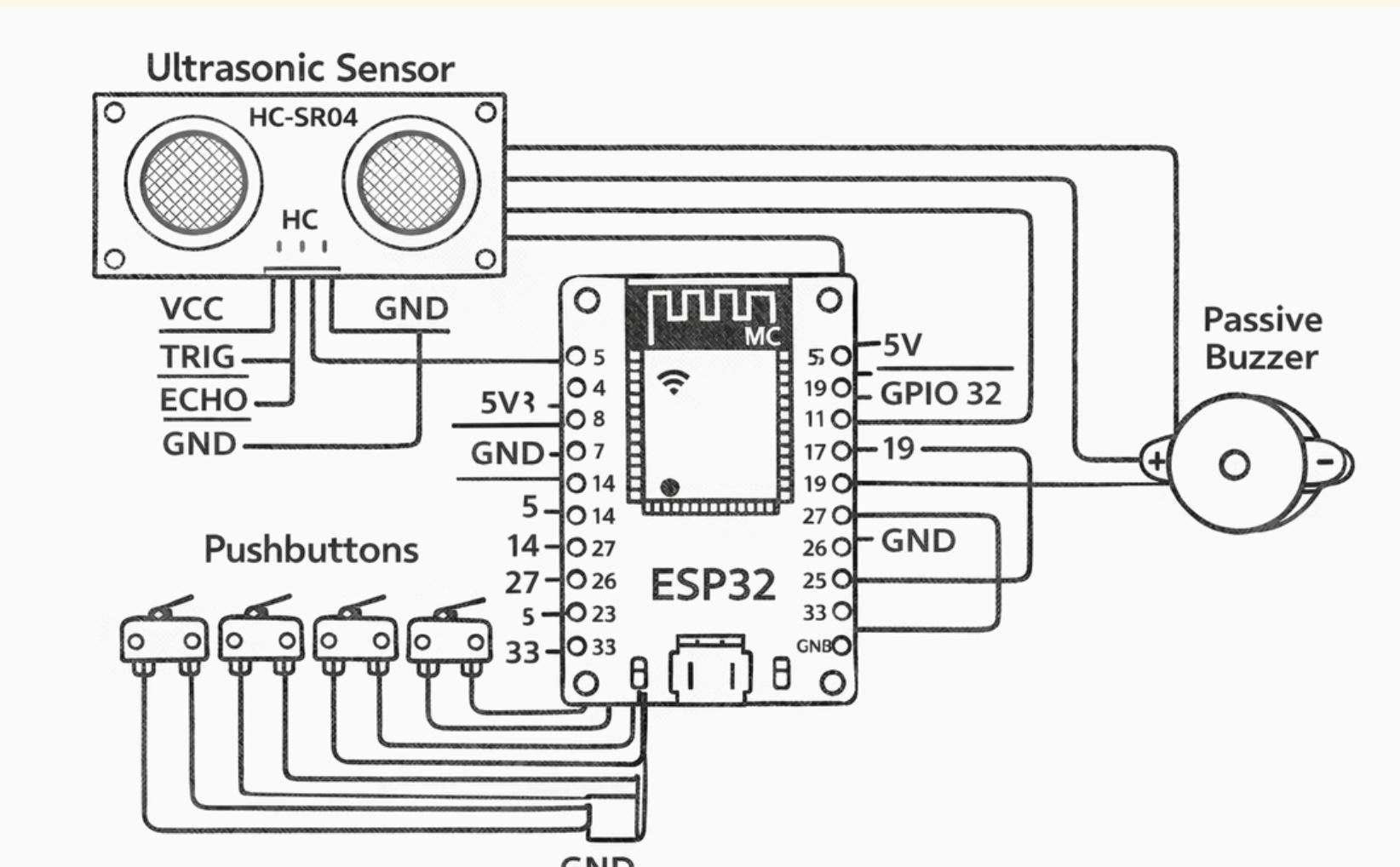


#evenfirer

IDEA TION



CIRCUIT DIAGRAM



AI GENERATED

```
from machine import Pin, PWM, time_pulse_us
import time

audio = PWM(Pin(32))
audio.duty(0)

s1= Pin(15,Pin.IN,Pin.PULL_UP)
s2= Pin(4,Pin.IN,Pin.PULL_UP)
s3= Pin(14,Pin.IN,Pin.PULL_UP)
s4= Pin(27,Pin.IN,Pin.PULL_UP)
s5= Pin(26,Pin.IN,Pin.PULL_UP)
s6= Pin(25,Pin.IN,Pin.PULL_UP)

trig= Pin(5,Pin.OUT)
echo= Pin(19,Pin.IN)

D_chord = [294, 370, 440]
A_chord = [220, 277, 330]
G_chord = [196, 247, 294]

def get_distance():
    trig.off()
    time.sleep_us(2)
    trig.on()
    time.sleep_us(10)
    trig.off()

    duration = time_pulse_us(echo, 1, 30000)

    if duration < 0:
        return None

    distance = duration / 58
    return distance
```

```
def play_down(chord):
    for note in chord:
        audio.freq(note)
        audio.duty(500)
        time.sleep(0.08)
        audio.duty(0)
        time.sleep(0.02)

def play_up(chord):
    for note in reversed(chord):
        audio.freq(note)
        audio.duty(500)
        time.sleep(0.08)
        audio.duty(0)
        time.sleep(0.02)

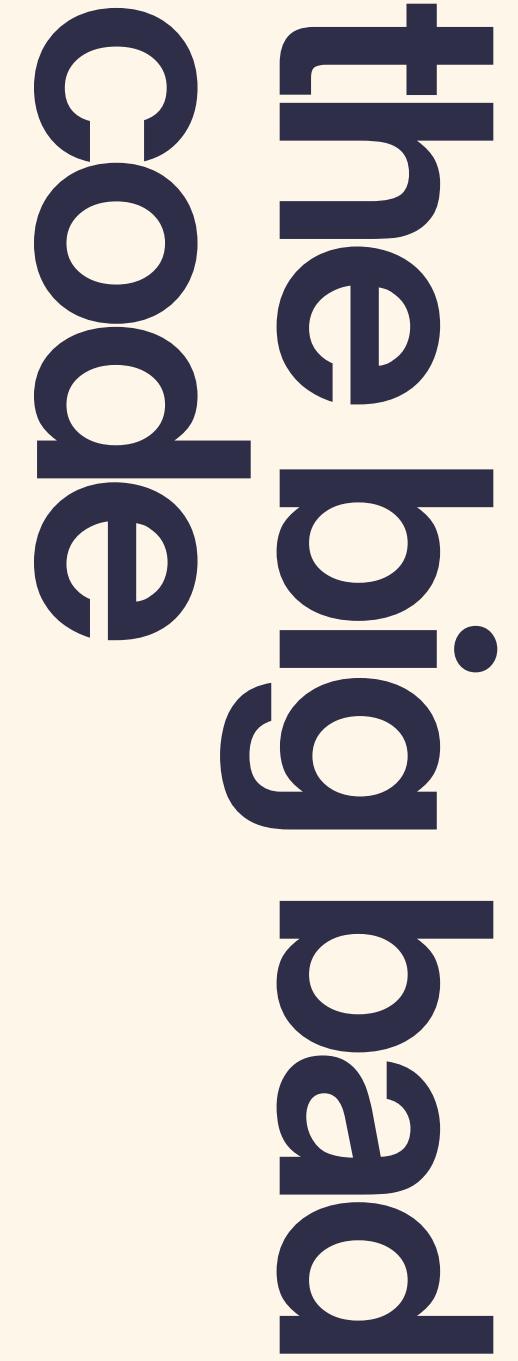
last_distance = get_distance()
current_chord = None

while True:

    c1= s1.value()
    c2= s2.value()
    c3= s3.value()
    c4= s4.value()
    c5= s5.value()
    c6= s6.value()

    if c1==0 and c2==0 and c3==0:
        current_chord= D_chord
    elif c1==0 and c5==0 and c6==0:
        current_chord= G_chord
    elif c5==0 and c4==0 and c3==0:
        current_chord= A_chord

    else:
        current_chord= None
        audio.duty(0)
```



coding shoding

```
distance = get_distance()

if distance is None:
    continue

change = distance - last_distance

if current_chord != None:
    audio.duty(0)

    if change < -6:
        play_down(current_chord)

    if change > 6:
        play_up(current_chord)

print("distance:", distance, " Change:", change)

last_distance = distance
time.sleep(0.05)
```

epoch
the
data
is
now



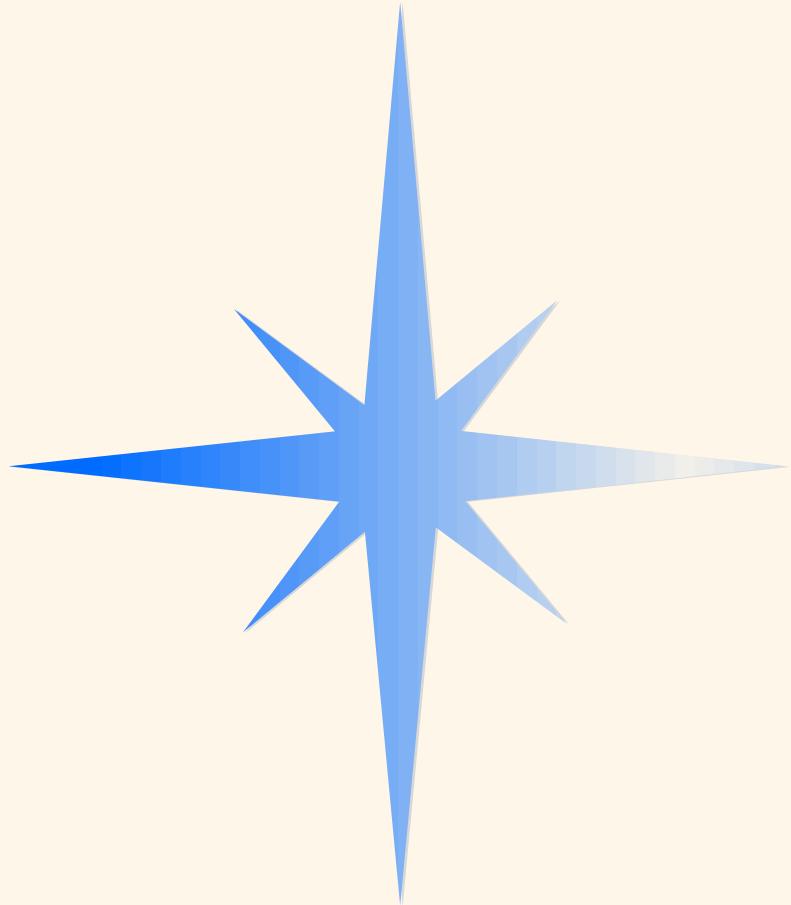
MY CONTRIBUTION

software development

- Wrote the complete MicroPython code for the ESP32.
- Programmed ultrasonic distance measurement using the HC-SR04.
- Implemented distance change detection to simulate guitar strumming.
- Created logic to detect up-strum and down-strum based on movement direction.
- Designed chord mappings using frequency arrays (D, A, G).
- Controlled a passive buzzer using PWM signals.
- Added fade-in and fade-out effects to reduce robotic sound.
- Debugged constant buzzing and undefined variable errors.
- Optimized timing and thresholds for smoother performance.

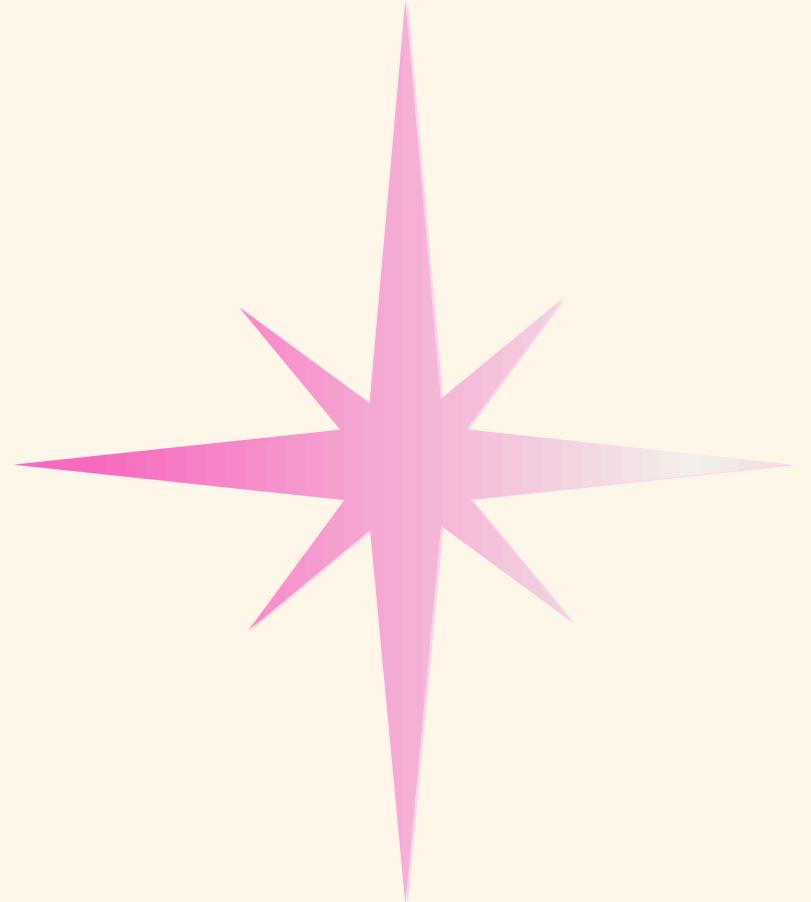
hardware configuration

- Connected and configured the ESP32 with:
 - Ultrasonic sensor (TRIG & ECHO pins)
 - Pushbuttons for chord selection
 - Passive buzzer for sound output
- Used GPIO pins efficiently for multiple inputs.
- Configured internal pull-up resistors for stable button readings.
- Ensured proper grounding and power distribution.
- Tested and corrected wiring issues.



The entire project returns to one central purpose: to celebrate the joy of building something wonderfully unnecessary. The breadboard guitar is not positioned as a revolutionary instrument or an essential tool.

It exists simply to spark [curiosity, laughter, and experimentation](#).



thanks