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class MusketeerEnv:
 def __init__(self, true_ps, avg_impressions):
     self.true_ps = true_ps
     self.avg_impressions = avg_impressions
     self.nb_arms = len(true_ps)
     self.reset()
def reset(self):
     self.arms = [Arm(p) for p in self.true_ps]
     return self.get_state()
def get_state(self):
     return [self.arms[i].get_state() for i in range(self.nb_arms)]
 def get_rates(self):
     return [self.arms[i].get_rate() for i in range(self.nb_arms)]
 def get_impressions(self):
     return int(np.random.triangular(self.avg_impressions/2,
                                 self.avg_impressions,
                                 self.avg_impressions*1.5))
 def step(self, ps):
     self.t += 1
     impressions = self.get_impressions()
     for i in np.random.choice(a=self.nb_arms,size=impressions,p=ps):
         self.arms[i].pull()
     self.record()
     return self.get_state()
 def record(self):
     d = {'t':self.t, 'max_rate':0, 'opt_impressions':0}
     for i in range(self.nb_arms):
         d[f'impressions_{i}'],d[f'actions_{i}'] = self.arms[i].get_state()
         d[f'rate_{i}'] = self.arms[i].get_rate()
         if d[f'rate_{i}'] > d['max_rate']:
             d['max_rate'] = d[f'rate_{i}']
             d['opt_impressions'] = d[f'impressions_{i}']
     d['total_impressions'] = sum([self.arms[i].impressions for i in range(self.nb_arms)])
     d['opt_impressions_rate'] = d['opt_impressions'] / d['total_impressions']
     d['total_actions'] = sum([self.arms[i].actions for i in range(self.nb_arms)])
     d['total_rate'] = d['total_actions'] / d['total_impressions']
     d['regret_rate'] = d['max_rate'] - d['total_rate']
     d['regret'] = d['regret_rate'] * d['total_impressions']
     self.ds.append(d)
 def show df(self):
     df = pd.DataFrame(self.ds)
     cols = ['t'] + [f'rate_{i}' for i in range(self.nb_arms)]+ \
            [f'impressions_{i}' for i in range(self.nb_arms)]+ \
            [f'actions_{i}' for i in range(self.nb_arms)]+ \
            ['regret_rate','regret']
     df = df[cols]
     return df
```

