view frames Result Recorded at time: 1652394870.7205732 world Broadcaster: /virtual joint broadcaster zero Average rate: $1\overline{0}000.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda link0 Broadcaster: /d455 broadcaster Broadcaster: /robot state publisher Average rate: $\overline{10000.0}$ Average rate: $30.2\overline{04}$ Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 1652394870.669 Oldest transform: 1652394865.769 Oldest transform: 0.0 d455_link panda_link1 Broadcaster: /d455/camera/realsense2 camera manager Broadcaster: /d455/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: 10000.0 Average rate: 10000.0 Average rate: $30.2\overline{04}$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1652394870.669 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1652394865.769 d455_depth_frame panda_link2 d455_color_frame Broadcaster: /d455/camera/realsense2 camera manager Broadcaster: /d455/camera/realsense2 camera manager Broadcaster: /robot state publisher Average rate: $30.\overline{204}$ Average rate: 10000.0 Average rate: 10000.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1652394870.669 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1652394865.769 d455_depth_optical_frame d455_color_optical_frame panda link3 Broadcaster: /robot state publisher Average rate: 30.204 Buffer length: 4.9 Most recent transform: 1652394870.669 Oldest transform: 1652394865.769 panda_link4 Broadcaster: /robot_state_publisher Average rate: $30.\overline{204}$ Buffer length: 4.9 Most recent transform: 1652394870.669 Oldest transform: 1652394865.769 panda link5 Broadcaster: /robot state publisher Average rate: 30.204 Buffer length: 4.9 Most recent transform: 1652394870.669 Oldest transform: 1652394865.769 panda link6 Broadcaster: /robot state publisher Average rate: 30.204 Buffer length: 4.9 Most recent transform: 1652394870.669 Oldest transform: 1652394865.769 panda link7 Broadcaster: /robot state publisher Average rate: $1000\overline{0}.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 panda link8 Broadcaster: /d405 broadcaster Broadcaster: /robot_state_publisher Broadcaster: /franka control Average rate: $29.\overline{5}25$ Average rate: $\overline{10000.0}$ Average rate: $1000\overline{0}.0$ Buffer length: 4.979
Most recent transform: 1652394870.705 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1652394865.726 Oldest transform: 0.0 Oldest transform: 0.0 d405_link panda_NE panda hand Broadcaster: /d405/camera/realsense2 camera manager | Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /franka control Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $29.\overline{5}25$ Average rate: $1000\overline{0}.0$ Average rate: 10000.0 Average rate: 10000.0 Average rate: $30.2\overline{04}$ Average rate: $30.2\overline{04}$ Buffer length: 4.979 Buffer length: 4.9 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.9 Most recent transform: 1652394870.705 Most recent transform: 1652394870.669 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 1652394870.669 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 1652394865.726 Oldest transform: 0.0 Oldest transform: 1652394865.769 Oldest transform: 1652394865.769 d405_depth_frame d405_color_frame panda_EE panda_rightfinger panda hand tcp panda_leftfinger Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /d405/camera/realsense2 camera manager Broadcaster: /franka control Average rate: 10000.0 Average rate: 10000.0 Average rate: $29.\overline{5}25$ Buffer length: 4.979 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 1652394870.705 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 1652394865.726 Oldest transform: 0.0 d405_depth_optical_frame d405_color_optical_frame panda_K