

## HMM

Conditional Probability:  $P(A|B) = P(B)P(A \cap B)$

Joint Probability:  $P(A \cap B)$

Marginal Probability:  $P(A) = \sum B P(A \cap B)$  (for discrete variables)

$P(A) = \int B P(A \cap B) dB$  (for continuous variables)

Bayes' Theorem:  $P(A|B) = P(B)P(B|A) \cdot P(A)$

Expectation (Mean):  $E[X] = \sum x \cdot P(X=x)$  (for discrete variables)

$E[X] = \int -\infty^{\infty} x \cdot f(x) dx$  (for continuous variables)

Variance:  $\text{Var}(X) = E[(X - E[X])^2]$

## Marcov model

transition probabilities  $a_{ij} = P(S_i | S_j)$   $a_{ij} = P(s_i | s_j)$

initial probabilities  $P_i(i) = P(S_i)$   $\pi_i = P(s_i)$

$P(\{'Dry', 'Dry', 'Rain', 'Rain'\}) = P('Rain'|'Rain') P('Rain'|'Dry') P('Dry'|'Dry') P('Dry') =$

## hidden Markov model

matrix of transition probabilities  $A=(a_{ij})$ ,  $a_{ij} = P(s_i | s_j)$

matrix of observation probabilities  $B=(b_i(v_m))$ ,  $b_i(v_m) = P(v_m | s_i)$

a vector of initial probabilities  $\pi_i = P(s_i)$ ,  $\pi_i = P(s_i)$  .  $\pi_i = P(s_i)$ ,  $\pi_i = P(s_i)$

$P(\{'Dry', 'Rain'\}) = P(\{'Dry', 'Rain'\}, \{'Low', 'Low'\}) + P(\{'Dry', 'Rain'\}, \{'Low', 'High'\}) +$   
 $P(\{'Dry', 'Rain'\}, \{'High', 'Low'\}) + P(\{'Dry', 'Rain'\}, \{'High', 'High'\})$

$P(\{'Dry', 'Rain'\}, \{'Low', 'Low'\}) = P(\{'Dry', 'Rain'\} | \{'Low', 'Low'\}) P(\{'Low', 'Low'\}) =$   
 $P('Dry'|'Low') P('Rain'|'Low') P('Low') P('Low'|'Low')$

## Using HMMs :

### Evaluation problem.

HMM  $M=(A, B, \pi)$ ,  $O=o_1 o_2 \dots o_K$ , probability that model  $M$  has generated sequence  $O$ .

### Decoding problem.

HMM  $M=(A, B, \pi)$ ,  $O=o_1 o_2 \dots o_K$ , most likely sequence of hidden states  $s_i$  that produced  $O$ .

### Learning problem.

$O=o_1 o_2 \dots o_K$ , HMM (numbers of hidden and visible states), determine HMM parameters

$M=(A, B, \pi)$  that best fit training data.

## Evaluation Problem. Forward-Backward HMM algorithms

### Forward recursion for HMM

forward variable  $\alpha_k(i)$

hidden state at time  $k$   $s_i : \alpha_k(i) = P(o_1 o_2 \dots o_k, q_k = s_i)$

Initialization:

$$\alpha_1(i) = P(o_1, q_1 = s_i) = \pi_i b_i(o_1), \quad 1 \leq i \leq N.$$

Forward recursion:

$$\begin{aligned} \alpha_{k+1}(j) &= P(o_1 o_2 \dots o_{k+1}, q_{k+1} = s_j) = \\ &= \sum_i P(o_1 o_2 \dots o_{k+1}, q_k = s_i, q_{k+1} = s_j) = \\ &= \sum_i P(o_1 o_2 \dots o_k, q_k = s_i) a_{ij} b_j(o_{k+1}) = \\ &= [\sum_i \alpha_k(i) a_{ij}] b_j(o_{k+1}), \quad 1 \leq j \leq N, 1 \leq k \leq K-1. \end{aligned}$$

Termination:

$$P(o_1 o_2 \dots o_K) = \sum_i P(o_1 o_2 \dots o_K, q_K = s_i) = \sum_i \alpha_K(i)$$

Complexity :  $N^2K$  operations.

## Backward recursion

Initialization:

$$\beta_K(i) = 1, \quad 1 \leq i \leq N.$$

Backward recursion:

$$\begin{aligned} \beta_k(j) &= P(o_{k+1} o_{k+2} \dots o_K | q_k = s_j) = \\ &= \sum_i P(o_{k+1} o_{k+2} \dots o_K, q_{k+1} = s_i | q_k = s_j) = \\ &= \sum_i P(o_{k+2} o_{k+3} \dots o_K | q_{k+1} = s_i) a_{ji} b_j(o_{k+1}) = \\ &= \sum_i \beta_{k+1}(i) a_{ji} b_j(o_{k+1}), \quad 1 \leq j \leq N, 1 \leq k \leq K-1. \end{aligned}$$

Termination:

$$\begin{aligned} P(o_1 o_2 \dots o_K) &= \sum_i P(o_1 o_2 \dots o_K, q_1 = s_i) = \\ &= \sum_i P(o_1 o_2 \dots o_K | q_1 = s_i) P(q_1 = s_i) = \sum_i \beta_1(i) b_i(o_1) \pi_i \end{aligned}$$

$$P(X_t = i | O) = \frac{\alpha_t(i) \cdot \beta_t(i)}{P(O)}$$

## Decoding problem

Brute force— exponential time.

Use efficient Viterbi algorithm instead.

## Viterbi algorithm

if best path ending in  $q_k = s_j$  goes through  $q_{k-1} = s_i$  then it should coincide with best path ending in  $q_{k-1} = s_i$ .

## Learning problem

iterative expectation-maximization algorithm to find local maximum of  $P(O | M)$  - Baum-Welch algorithm.

$a_{ij} = P(s_i | s_j)$  = No of transitions from state  $s_j$  to state  $s_i$  / no of transitions out of state  $s_j$

$b_i(v_m) = P(v_m | s_i)$  = no of times observation  $v_m$  occurs in state  $s_i$  / no of times in state  $s_i$

## Baum-Welch algorithm

$a_{ij} = P(s_i | s_j) = \text{expected No of transitions from state } s_j \text{ to state } s_i / \text{expected no of transitions}$

$$\frac{\sum_k \xi_{k(i,j)}}{\sum_k \gamma_{k(i)}}$$

out of state  $s_j$

$b_i(v_m) = P(v_m | s_i) = \text{expected no of times observation } v_m \text{ occurs in state } s_i / \text{expected no of}$

$$\frac{\sum_{k, o_k = v_m} \gamma_{k(i)}}{\sum_k \gamma_{k(i)}}$$

times in state  $s_i$

$\pi_i = P(s_i) = \text{Expected frequency in state } s_i \text{ at time } k=1. \gamma_{1(i)}$

### Code Morphing

transposition, substitution, insertion, and deletion

“strong” metamorphic generator relies only on transposition

### “Strong” metamorphic generator

Initialize with a seed virus ( form assembly code )

Split into small blocks (6 lines of code)( subject to some conditions )

To generate a malware sample... Shuffle code blocks, add conditional jumps

Shuffling blocks – break signatures

include dead code insertion ( “opaque predicates” )

Why insert dead code? – Makes statistical analysis more difficult

### Experiments

Seed with NGVCK virus

Generate 200 morphed copies

Assemble each morphed asm into exe

Verify that seed virus detected by AV...

morphed copies not detected by AV

Disassemble exes, extract opcodes

Train HMMs, – 5-fold cross validation

Score each model vs 40 benign samples

### Why can we detect this morphed malware using HMMs... ..but not using signatures?

Signatures – disrupted by transposition

HMM not affected by transposition, “sees” differences between viruses and benign

Transposition – highly effective anti-signature strategy, ineffective for machine learning

### User behavior monitoring

observing, analyzing, and understanding the actions and activities

• login attempts • file accesses • application usage • system commands (login, file, app, command)

## **Significance in Cyber security (Early Detection, Insider Threats, Enhanced Response, Compliance)**

### **Early Threat Detection:**

unusual login times, access to unauthorized resources, abnormal data transfer volumes  
Early detection allows security teams to investigate early, identify the root cause, and take action to mitigate the threat before it escalates

### **Prevention of Insider Threats:**

come from employees, contractors, trusted entities with access to sensitive data/ systems.  
User behavior monitoring ,flagging suspicious activities  
unusual access patterns, data exfiltration attempts, privilege abuse,

### **Enhanced Incident Response:**

analyzing user activity logs, access logs,  
identify affected systems, determine extent of unauthorized access/data breaches, tracing the actions of threat actors.

### **Compliance and Governance:**

User behavior monitoring  
monitor and audit user activities to protect sensitive data, prevent unauthorized access

## **Key Components of User Behavior Monitoring (activity, auth, escalation, patterns, endpoint)**

### **User Activity Logs:**

recording actions - login attempts, file accesses, application usage, and system commands.  
Logging login attempts  
Recording file access events

### **User Authentication Patterns**

Analyzing user authenticate, login times, locations, devices used.  
Identifying frequent logins from unusual locations/devices.  
Monitoring use of multi-factor authentication methods.

### **Privilege Escalation Monitoring**

where users attempt to gain elevated privileges or access unauthorized resources.  
Monitoring changes to user permissions or roles  
Tracking the commands/scripts that may indicate privilege escalation attempts

### **Access Patterns and Permissions**

Analyzing the frequency and nature of access requests  
frequent access to confidential files  
Monitoring changes to access permissions for critical resources.

### **Endpoint Behavior Analysis**

Examining behavior of users on endpoints (devices), desktops, laptops, and mobile devices.  
installation of unauthorized software or accessing restricted websites.  
Analyzing user behavior for signs of malware infection or data exfiltration attempts.

### **Tools and Methods**

**Log Management and Analysis Tools:** Splunk, ELK Stack  
monitor user activities, detect anomalies, and investigate security incidents.

**User Activity Monitoring Solutions :** Varonis, SolarWinds User Device Tracker  
real-time monitoring of user activities, file access, email communications, application usage,

### **Varonis -**

Data Access Governance:

Behavior Analytics:

Data Protection:

**SolarWinds User Device Tracker** - network monitoring, track user activity, device connections  
User Tracking: logins and logouts, activities across devices, user activity reports.  
Device Mapping: Maps devices to users  
Real-time Alerts: alerts for suspicious activities

### **User and Entity Behavior Analytics (UEBA) - Exabeam, Rapid7 InsightIDR**

Users:

1.Devices 2.Applications 3.Accounts and Identities 4.Data and Resources 5.Network Traffic: use machine learning algorithms, analyze user behavior, detect anomalous activities

### **Exabeam**

Behavioral Analytics:

Threat Hunting: search and investigate potential security threats

Incident Response Automation: Automates the investigation and response to security incidents

### **Rapid7 InsightIDR**

cloud-based

User Behavior Analysis:

Automated Threat Detection:

Endpoint Detection and Response (EDR):

### **What is Cluster Analysis?**

applications

stand-alone tool to get insight into data distribution

preprocessing step for other algorithm

### **Density-based Approaches**

Discover clusters of arbitrary shape.

DBSCAN – first density based clustering

OPTICS – density based cluster-ordering

DENCLUE – density-based description of cluster and clustering

### **DBSCAN: Density Based Spatial Clustering of Applications with Noise**

clusters of arbitrary shape in spatial databases with noise

#### **Core, Border & Outlier**

**Core** - it has more than a specified number of points (MinPts) within Eps, at the interior of a cluster.

**border** - has fewer than MinPts within Eps, in the neighborhood of a core point.

**noise** - not a core point nor a border point

**Directly density-reachable** - not symmetric

p is a core object and q is in p's ε neighborhood.

**Density-Connected** - symmetric

pair of points p and q are density-connected if they are commonly density-reachable from a point o

#### **DBSCAN: The Algorithm**

select a p

Retrieve all points density-reachable from p wrt Eps and MinPts.

If p is a core point, a cluster is formed.

If p is a border point, no points are density-reachable from p and visits the next point

#### **Density Based Clustering:**

##### **Advantages**

Clusters can have arbitrary shape and size

Number of clusters is determined automatically

Can separate clusters from surrounding noise

Can be supported by spatial index structures

##### **Disadvantages**

Input parameters may be difficult to determine

In some situations very sensitive to input parameter setting