CS GY 6513 BIG DATA

Efficient Repository for fine-tuning Self-driving vehicles using Big Data

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Point of this project...

- 1. Use Case Data inflow rate + Storage size (Motivation slide)
- 2. Python drawbacks and limitations (KNN)
- 3. Hadoop Algorithm metrics + Limitations
- 4. Pyspark Algorithm (Template matching + Hog Filter) + Limitations
- Pyspark + Resnet50 + LSH
- Architecture bird's eye view
- 7. Architecture component view data flow
- 8. Optimizations (next slide)
- 9. Limitations
- 10. Future Work

Pending Work

- What optimization can be done in Big Data?
 - a. New Images date wise prediction caching
 - b. Freeze the last layer
- 2. Quantitative Analysis Metrics
- 3. Graphs/Charts
 - a. Time improvement across algorithms
 - b. Time improvement across datasets
- 4. Dataset
- 5. Storage

Motivation

- One car One day 4GB Data points -160,000 cars for now with Beta FSD
- We can only imagine how much data flows into their system on a daily basis.
- Now adding all this to your training data will take more than 2 years to train for the smallest model

https://www.youtube.com/watch?v=y57wwucbXR8



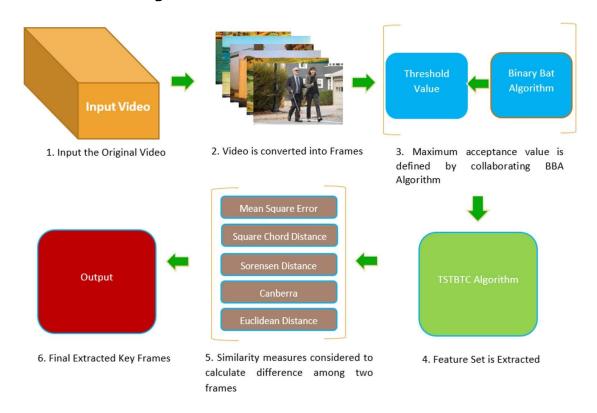


Dataset and Scale

https://www.kaggle.com/datasets/andrewmvd/road-sign-detection , https://public.roboflow.com/object-detection/self-driving-car

- Data reaches upto 4TB per day from self-driving cars (<u>source</u>)
- Autonomous test vehicles generate 5TB 20TB of data per day per vehicle (source)
- Need pre-processing of video data which is an expensive operation

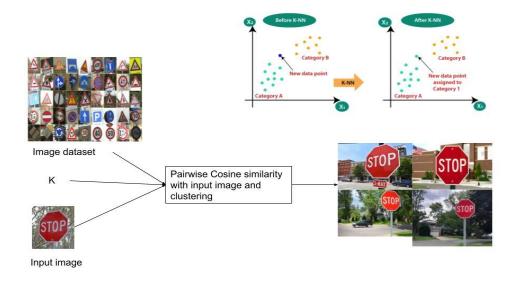
Video Key-Frame extraction algorithm



Python based approach - Observations & limitations

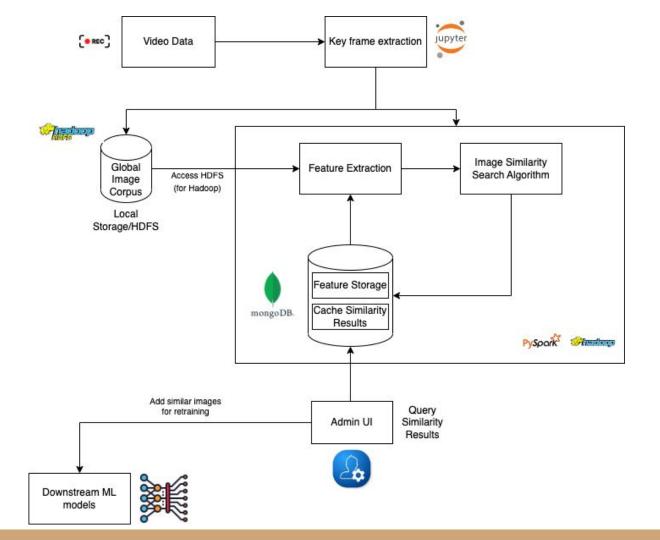
Time complexity:

O(Number of images * Number of features)



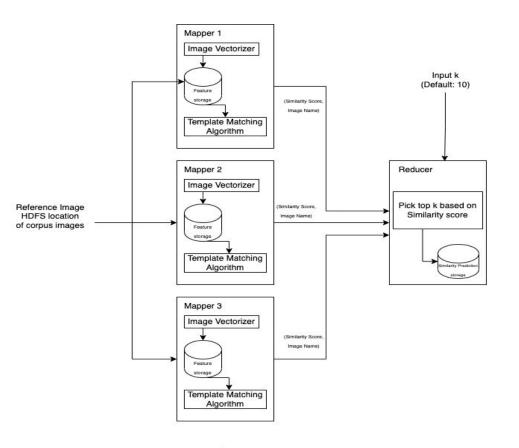
- Time taken for 1.1GB = approx. 2 hours

Bird's Eye View



Mapper and Reducer in Hadoop

- Parallelize Feature Extraction in Mapper
- Store image features in MongoDB
- Performance enhancement due to parallel processing
- Limitations to employ advanced ML algorithms



Architecture Diagram

Hadoop + SIFT - Results



Input



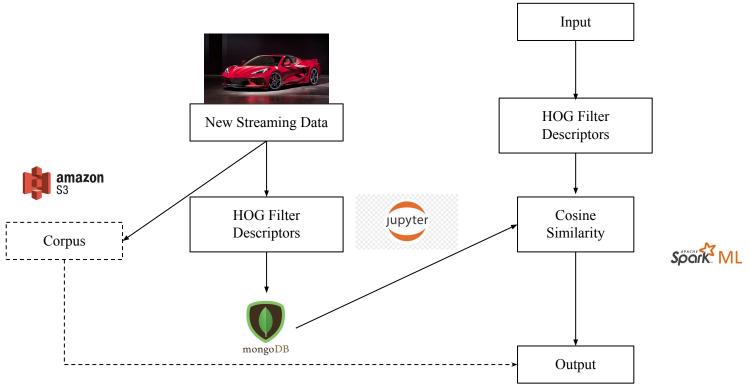


Output

Pyspark + Different Algorithms

- Architecture
- Limitations
- Performance Discussion

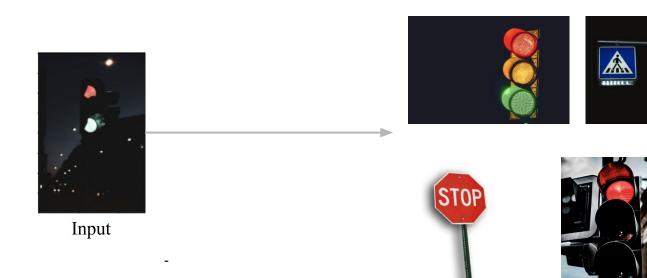
Pyspark + HOG Filter



Time taken for 1.1GB = approx. 25 mins
Features are too sparse
(200,000) and hence slow computation

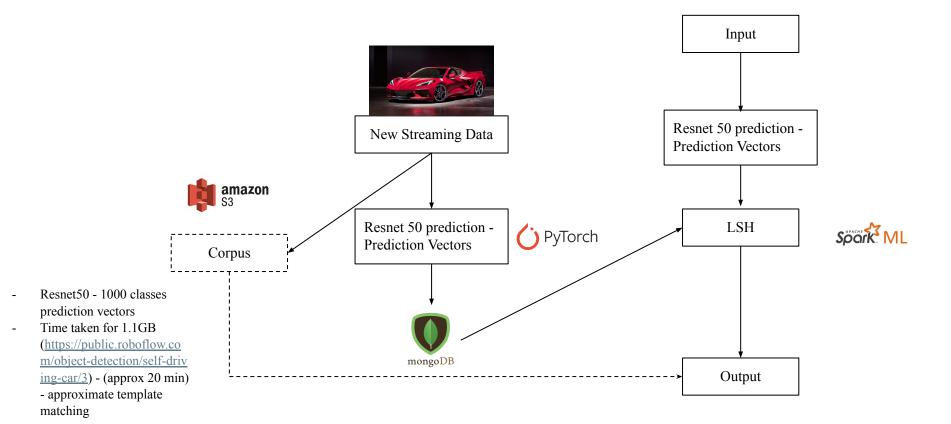
*Saving in MongoDB helps reduce time taken for model to run on the entire corpus again and again

Pyspark + HOG Filter - Results

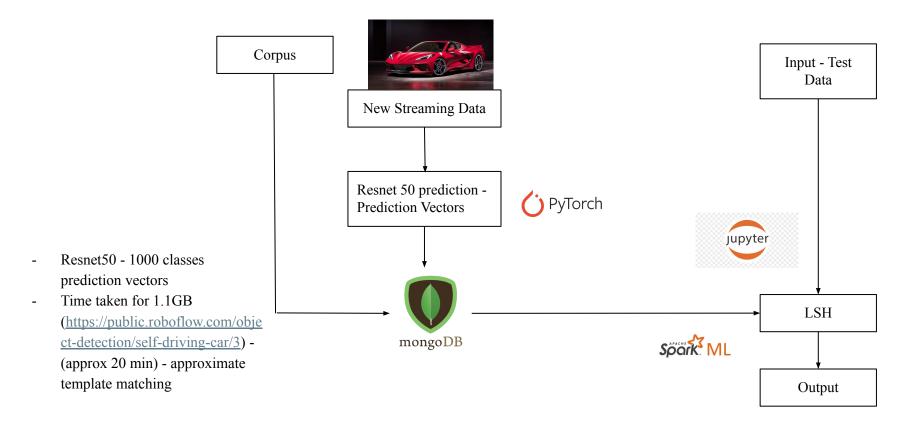




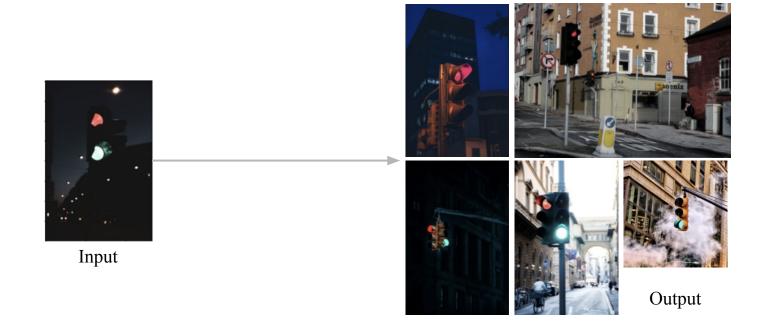
Pyspark + Resnet50 + LSH



Pyspark + Resnet50 + LSH



Pyspark + Resnet50 + LSH - Results



Why MongoDB?

- Document Oriented to store feature vectors of images

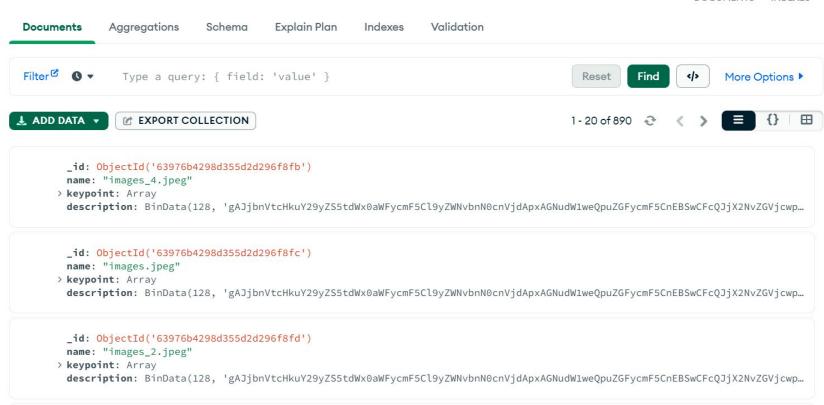
- For storing similar images for each input to avoid recomputation

- Why not SQL?

image_features_db.features

890 1

DOCUMENTS INDEXES



Future Work

- Process the key frame extraction using spark streaming module and Kafka.

 Object detection (another big data problem by itself) during preprocessing using spark streaming reduces noisy unrelated frames from entering the system. (<u>source</u>)

The journey and lessons learnt along the way...

- Native python scripts for huge streaming data compute intensive
- Issues with adding additional packages in *HDFS* environment
- Hadoop interface is not good for visualizing intermediate outputs and debugging algorithmic errors
- Template matching, HOG filter algorithms in *Pyspark* achieve faster results than hadoop
- Approximate image search (**LSH**) reduces time complexity
- Eliminating recomputation of feature extraction MongoDB
- **Dask** A brilliant framework with a very similar usage to Python

Thank you!

We are sincerely grateful to Prof. Rodriguez for taking this course. We are also thankful to the TAs!

References

<u>https://towardsdatascience.com/deep-learning-with-apache-spark-part-1-6d39</u> <u>7c16abd</u> - Spark Deep Learning packages

<u>https://365datascience.com/trending/techniques-for-processing-traditional-and-big-data/</u> - Python limitations

https://docs.dask.org/en/stable/ - Dask