```
In [1]: import numpy as np
    from matplotlib import pyplot as plt
    import mltools as ml

In [2]: from mltools.transforms import rescale

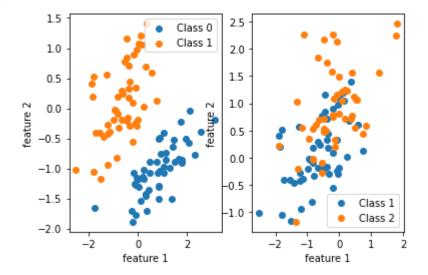
In [3]: iris = np.genfromtxt("data/iris.txt",delimiter=None)
    X, Y = iris[:,0:2], iris[:,-1] # get first two features & target
    X,Y = ml.shuffleData(X,Y) # reorder randomly (important later)
    X,_ = rescale(X) # works much better on rescaled data

XA, YA = X[Y<2,:], Y[Y<2] # get class 0 vs 1
    XB, YB = X[Y>0,:], Y[Y>0] # get class 1 vs 2
```

1. Show the two classes in a scatter plot (one for each data set) and verify that one data set is linearly separable while the other is not. (5 points)

```
In [4]:
         # Class 0 vs Class 1
         fig, ax = plt.subplots(1, 2)
         ax[0].scatter(XA[YA==0,0], XA[YA==0,1], label = 'Class 0')
         ax[0].legend()
         ax[0].scatter(XA[YA==1,0], XA[YA==1,1], label = 'Class 1')
         ax[0].legend()
         ax[0].set xlabel('feature 1')
         ax[0].set ylabel('feature 2')
         # Class 1 vs Class 2
         ax[1].scatter(XB[YB==1,0], XB[YB==1,1], label = 'Class 1')
         ax[1].legend()
         ax[1].scatter(XB[YB==2,0], XB[YB==2,1], label = 'Class 2')
         ax[1].legend()
         ax[1].set_xlabel('feature 1')
         ax[1].set ylabel('feature 2')
```

Out[4]: Text(0, 0.5, 'feature 2')



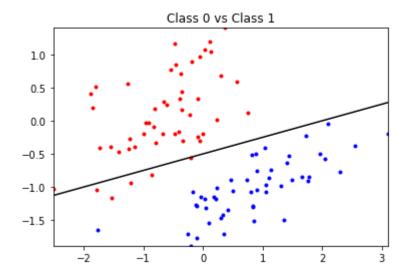
Class 0 and Class 1 are linearly separable, whereas Class 1 and Class 2 are not.

2. Include the lines of code you added to the function, and the two generated plots.

x2b = (-self.theta[0]-self.theta[1]*x1b)/self.theta[2]; # TODO find x2 values as a function of x1's values

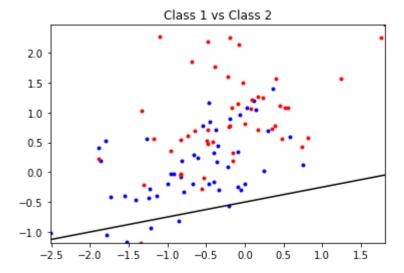
```
In [5]:
    from logisticClassify2 import *
    learner1 = logisticClassify2(); # create "blank" learner
    learner1.classes = np.unique(YA) # define class labels using YA or YB
    wts = np.array([0.5,-0.25,1]); # TODO: fill in values
    learner1.theta = wts; # fill in the theta values
    learner1.plotBoundary(XA,YA)
    plt.title('Class 0 vs Class 1')
```

Out[5]: Text(0.5, 1.0, 'Class 0 vs Class 1')



```
In [6]:
    learner2 = logisticClassify2();
    learner2.classes = np.unique(YB) # define class labels using YA or YB
    wts = np.array([0.5,-0.25,1]); # TODO: fill in values
    learner2.theta = wts; # set the learner's parameters
    learner2.plotBoundary(XB,YB)
    plt.title('Class 1 vs Class 2')
```

Out[6]: Text(0.5, 1.0, 'Class 1 vs Class 2')



3.Include the function definition and the two computed errors.

Definition:

For each point in X, computer the linear response $r = 0.5 - 0.25x_1 + 1x_2$

If r > 0, we know that the data point lies above the decision line. We will predict Class 1.

If r < 0, we know that the data point lies under the decision line. We will predict Class 0.

```
In [7]:
    learner = logisticClassify2(); # create "blank" learner
    learner.classes = np.unique(YA) # define class labels using YA or YB
    wts = np.array([0.5,-0.25,1]); # TODO: fill in values
    learner.theta = wts;

    ErrorA = learner.err(XA,YA)
    print('Errors for set A:', ErrorA)

    ErrorB = learner.err(XB,YB-1)
    print('Errors for set B:', ErrorB)
```

Errors for set A: 0.050505050505050504 Errors for set B: 0.46464646464646464

4. Verify that your predict code matches your boundary plot by using plotClassify2D with your manually constructed learner on the two data sets. This will call predict on a dense grid of points, and you should find that the resulting decision boundary matches the one you computed analytically.

```
In [8]:
# Class 0 vs Class 1
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
```

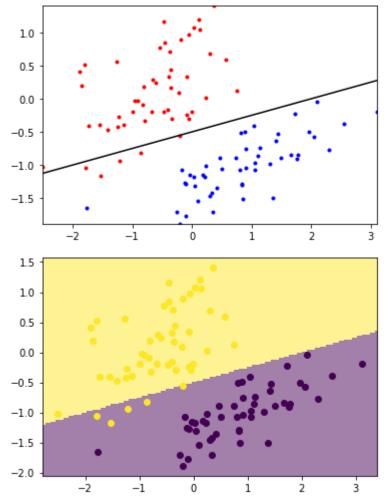
```
learner.theta = wts;
learner.plotBoundary(XA,YA)
plt.figure()
ml.plotClassify2D(learner, XA, YA)
```

C:\Users\pendr\Documents\CS273\Assignment $3\mbox{mltools\plot.py:61:}$ UserWarning: color is redundantly defined by the 'color' keyword argument and the fmt string "ko" (-> color ='k'). The keyword argument will take precedence.

axis.plot(X[Y==c,0],X[Y==c,1], 'ko', color=cmap(cvals[i]), **kwargs)

C:\Users\pendr\Documents\CS273\Assignment 3\mltools\plot.py:61: UserWarning: color is re dundantly defined by the 'color' keyword argument and the fmt string "ko" (-> color ='k'). The keyword argument will take precedence.

axis.plot(X[Y==c,0],X[Y==c,1], 'ko', color=cmap(cvals[i]), **kwargs)

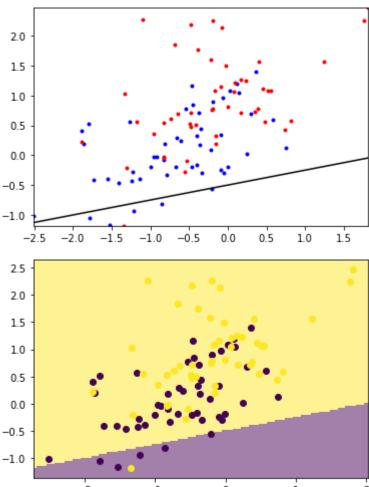


```
In [9]: # Class 1 vs Class 2
  learner.theta = wts;
  learner.plotBoundary(XB,YB-1)
  plt.figure()
  ml.plotClassify2D(learner, XB, YB-1)
```

C:\Users\pendr\Documents\CS273\Assignment 3\mltools\plot.py:61: UserWarning: color is re
dundantly defined by the 'color' keyword argument and the fmt string "ko" (-> color
='k'). The keyword argument will take precedence.
 axis.plot(X[Y==c,0],X[Y==c,1], 'ko', color=cmap(cvals[i]), **kwargs)

C:\Users\pendr\Documents\CS273\Assignment 3\mltools\plot.py:61: UserWarning: color is re dundantly defined by the 'color' keyword argument and the fmt string "ko" (-> color

='k'). The keyword argument will take precedence.
axis.plot(X[Y==c,0],X[Y==c,1], 'ko', color=cmap(cvals[i]), **kwargs)



5

 $\frac{\partial}{\partial \theta_{i}} J_{j} = \frac{\partial}{\partial \theta_{i}} - y^{(j)} | og \theta(x^{(j)} \theta_{i}^{T}) - \frac{\partial}{\partial \theta_{i}} (1 - y^{(j)}) | og (1 - \theta(x^{(j)} \theta_{i}^{T})) \\
= \frac{-y^{(j)}}{6(x^{(j)} \theta_{i}^{T})} \cdot \frac{\partial}{\partial \theta} \theta(x^{(j)} \theta_{i}^{T}) - \frac{1 - y^{(j)}}{1 - \theta(x^{(j)} \theta_{i}^{T})} \cdot \frac{\partial}{\partial \theta_{i}} (1 - \theta(x^{(j)} \theta_{i}^{T})) \\
= [-y^{(j)} + \theta(\theta_{i}^{T} x_{i})] \cdot x_{i} \\
\frac{\partial}{\partial \theta_{i}} J_{j} = [-y^{(j)} + \theta(\theta_{i}^{T} x_{i})] \cdot x_{i} \\
\frac{\partial}{\partial \theta_{i}} J_{j} = [-y^{(j)} + \theta(\theta_{i}^{T} x_{i})] \cdot x_{i}$

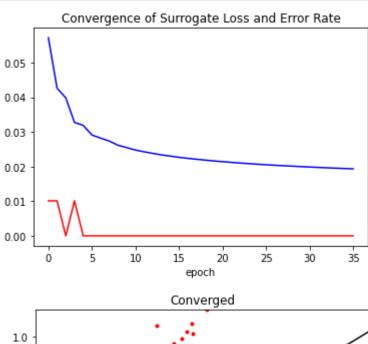
6. Include the complete implementation of train.

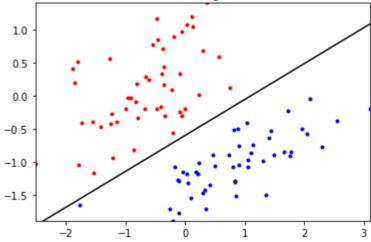
```
In [11]:
          def train(self, X, Y, initStep=1.0, stopTol=1e-4, stopEpochs=5000, plot=None):
                  """ Train the logistic regression using stochastic gradient descent """
                  M,N = X.shape;
                                                     # initialize the model if necessary:
                  self.classes = np.unique(Y); # Y may have two classes, any values
                  XX = np.hstack((np.ones((M,1)),X)) # XX is X, but with an extra column of ones
                  YY = ml.toIndex(Y,self.classes); # YY is Y, but with canonical values 0 or 1
                  if len(self.theta)!=N+1: self.theta=np.random.rand(N+1);
                  # init loop variables:
                  epoch=0; done=False; Jnll=[]; J01=[];
                  while not done:
                      stepsize, epoch = initStep*2.0/(2.0+epoch), epoch+1; # update stepsize
                      # Do an SGD pass through the entire data set:
                      for i in np.random.permutation(M):
                                = self.theta@XX[i,:];
                                                          # TODO: compute linear response r(x)
                          sigma_ri = 1/(1+np.exp(-ri))
                          gradi = (-YY[i] + sigma_ri) * XX[i,:]; # TODO: compute gradient of
                          self.theta -= stepsize * gradi; # take a gradient step
                      J01.append(self.err(X,Y)) # evaluate the current error rate
                      ## TODO: compute surrogate loss (logistic negative log-likelihood)
                      jsur = 0
                      for i in np.random.permutation(M):
                          sigma = 1/(1+np.exp(-self.theta@XX[i,:]))
                          jsur += -YY[i]*np.log(sigma)-(1-YY[i])*np.log(1-sigma)
                      Jsur = jsur/M
                      ## Jsur = sum_i [ (log si) if yi==1 else (log(1-si)) ]
                      Jnll.append( Jsur ) # TODO evaluate the current NLL loss
                      #plt.figure(1); plt.plot(Jnll, 'b-', J01, 'r-'); plt.draw();
                                                                                    # plot losses
                      #if N==2: plt.figure(2); self.plotBoundary(X,Y); plt.draw(); # & predictor
                      #plt.pause(.01);
                                                          # let OS draw the plot
                      ## For debugging: you may want to print current parameters & losses
                      # print self.theta, ' => ', Jnll[-1], ' / ', J01[-1]
                      # raw input() # pause for keystroke
                      # TODO check stopping criteria: exit if exceeded # of epochs ( > stopEpochs
                      if len(Jnll) == 1:
                          done = epoch > stopEpochs
                        done = epoch > stopEpochs or np.abs(Jnll[-1] - Jnll[-2]) < stopTol;</pre>
                      plt.figure(1)
                      plt.plot(Jnll, 'b-', J01, 'r-')
                      plt.xlabel("epoch")
                      plt.title("Convergence of Surrogate Loss and Error Rate")
                      plt.draw();
                      plt.figure(2);
                      plt.title('Converged');
                      self.plotBoundary(X,Y);
                      plt.draw();
```

7 Run train for your logistic regression classifier on both data sets (A and B). Describe your parameter choices for each dataset

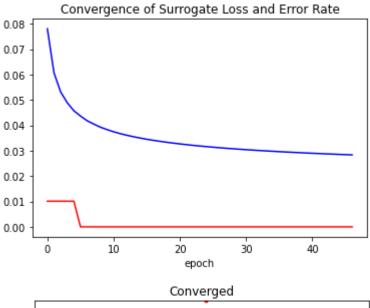
(stepsize, etc.) and include plots showing the convergence of the surrogate loss and error rate (e.g., the loss values as a function of epoch during gradient descent), and the final converged classifier with the data (the included train function does that for you already).

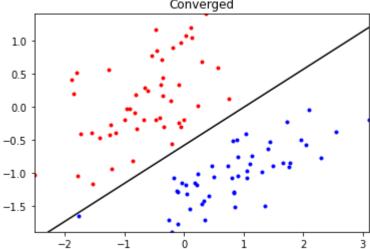
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XA,YA,initStep=1)
```



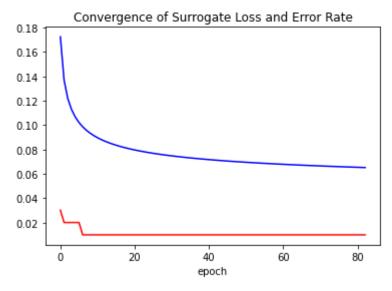


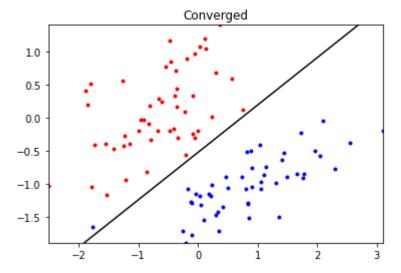
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XA,YA,initStep=0.5)
```



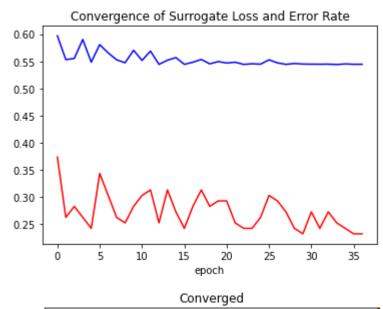


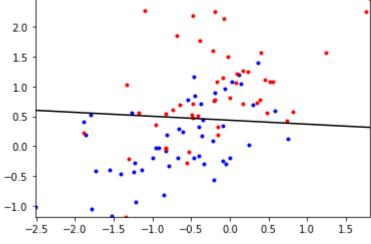
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XA,YA,initStep=0.1)





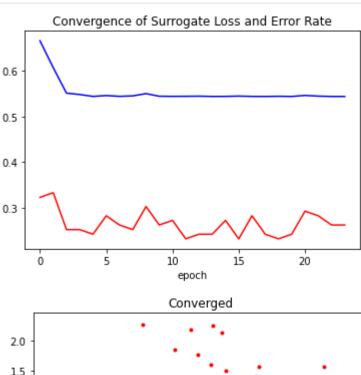
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XB,YB,initStep=1)
```

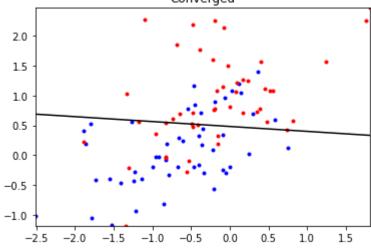




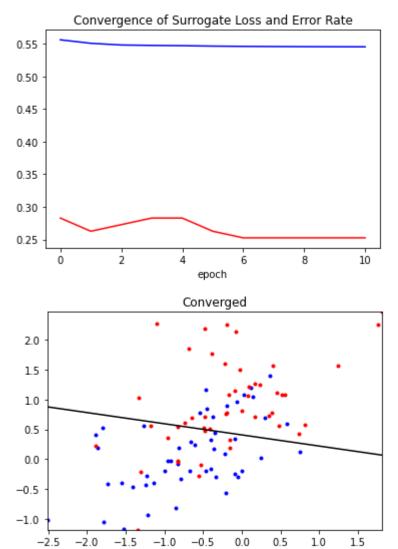
In [16]:

```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XB,YB,initStep=0.5)
```





```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train(XB,YB,initStep=0.1)
```

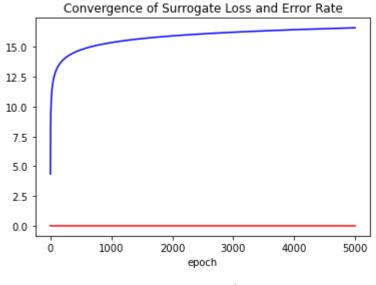


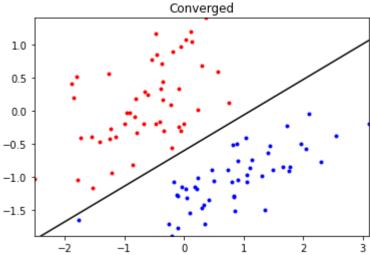
I chose initStep of 0.1 because it shows how surrogate loss converges and how the error rate changes. When the step size is equal to 1, the convergence curve is very steep and it is difficult to observe the training process.

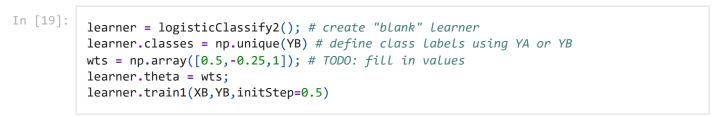
8. Add an L1 regularization term

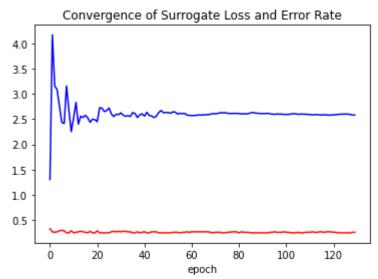
alpha = 2

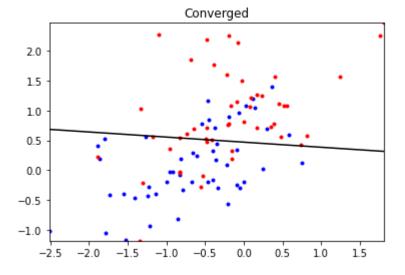
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train1(XA,YA,initStep=0.5)
```







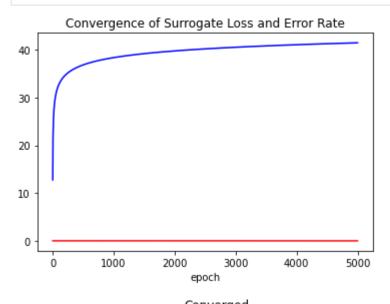


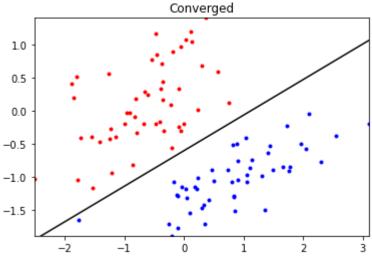


alpha = 5

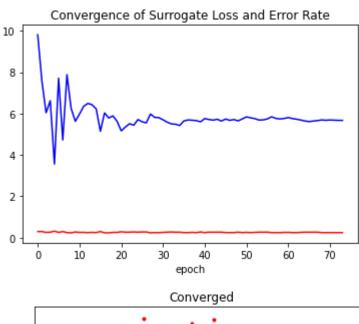
In [20]:

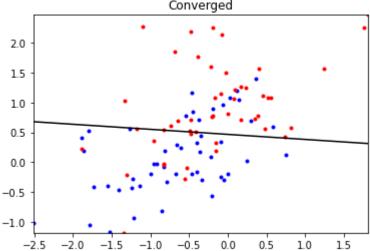
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train1(XA,YA,initStep=0.5,alpha = 5)
```





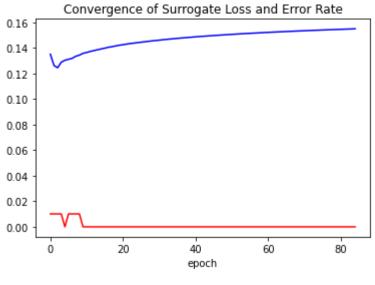
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train1(XB,YB,initStep=0.5,alpha = 5)
```

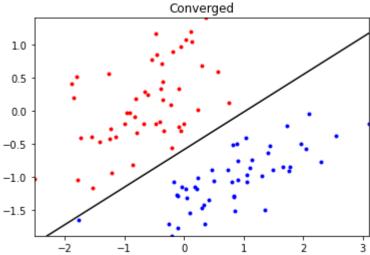




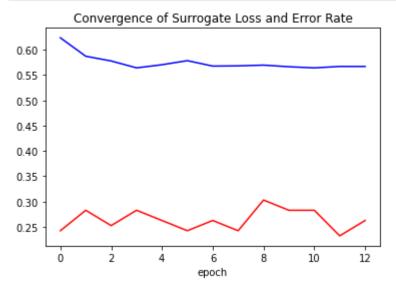
alpha = 0.01

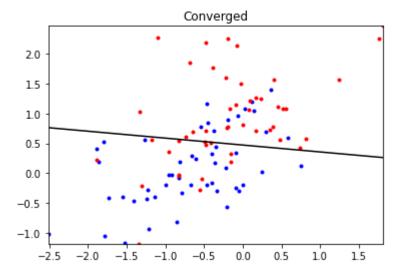
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XA,YA,initStep=0.5,alpha = 0.01)
```





learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XB,YB,initStep=0.5,alpha = 0.01)

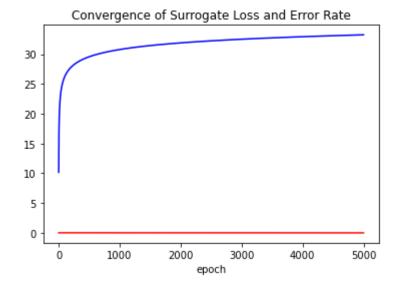


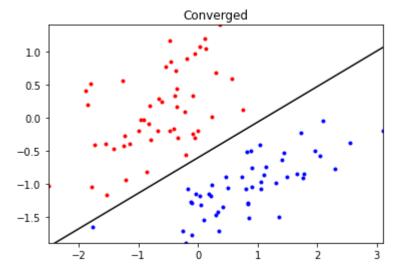


9. Add an L2 regularization term

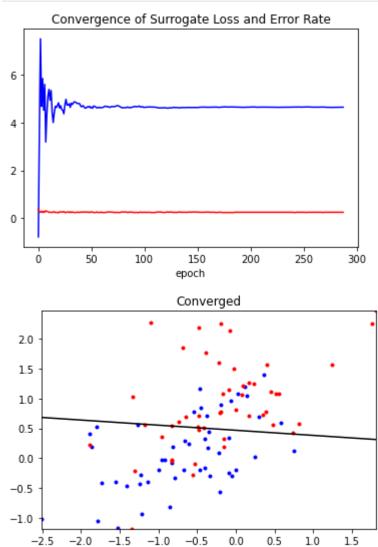
alpha = 2

```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XA,YA,initStep=0.5)
```



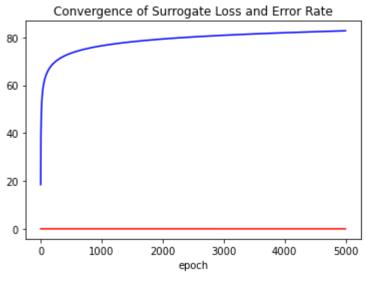


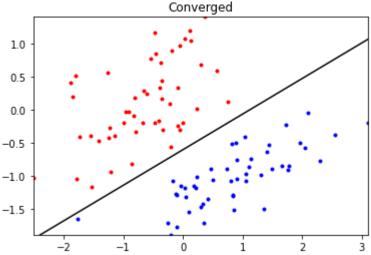
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XB,YB,initStep=0.5)
```



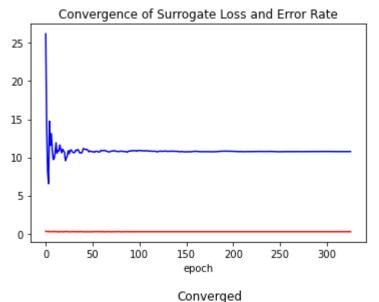
alpha = 5

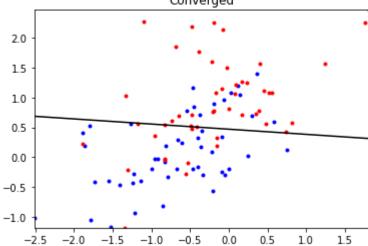
```
learner = logisticClassify2(); # create "blank" Learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XA,YA,initStep=0.5,alpha = 5)
```





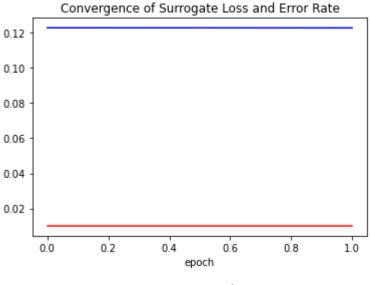
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XB,YB,initStep=0.5,alpha = 5)
```

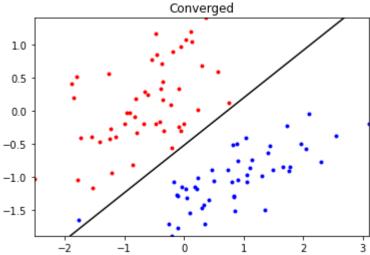




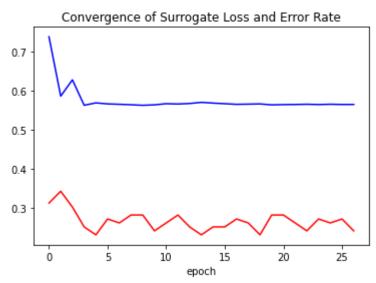
alpha = 0.01

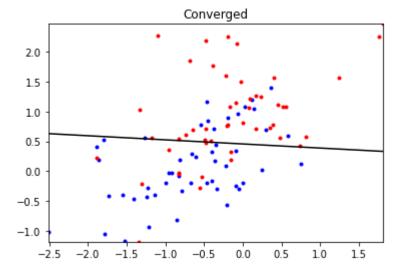
```
learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YA) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XA,YA,initStep=0.5,alpha = 0.01)
```





learner = logisticClassify2(); # create "blank" learner
learner.classes = np.unique(YB) # define class labels using YA or YB
wts = np.array([0.5,-0.25,1]); # TODO: fill in values
learner.theta = wts;
learner.train2(XB,YB,initStep=0.5,alpha = 0.01)





The L1 parametric loss function, also known as the mean absolute value error, minimizes the sum of the absolute differences between the target value and the estimated value. the L2 parametric loss function, also known as the mean squared error, minimizes the sum of the squares of the differences between the target value Yi and the estimated value f(xi). the L2 parametric loss averages the errors and the model will have a larger error than the L1 parametric, so the model will be more sensitive to the sample, which requires adjusting the model to minimize the This requires adjusting the model to minimize the error. If a sample is an outlier, the model will need to be adjusted to fit the single outlier, at the expense of many other normal samples whose errors are smaller than the single outlier's error. For this model, since we do not have that many outliners, L1 regulazation is enough.

Statement of Collaboration

Completed individually and searched Google for more datailed explanation for Question 10