## **FAQ**

| Module-5    |   |
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| Question 1. | What is the fundamental difference between                |
|             | HashTables and HashMaps?                                  |
| Answer      | HashTables are known for their synchronisation and        |
|             | thread-safety properties, which contribute to their       |
|             | somewhat slower performance compared to                   |
|             | HashMaps. In contrast, HashMaps lack                      |
|             | synchronisation and thread safety, hence providing        |
|             | enhanced efficiency in single-threaded contexts.          |
| Question 2. | In what ways do Binary Trees exhibit distinctions         |
|             | from Binary SearchTrees (BSTs)?                           |
| Answer      | Binary trees are a kind of hierarchical data structure    |
|             | that consist of nodes, each of which may have a           |
|             | maximum of two offspring. These trees do notimpose        |
|             | any restrictions on the values of the nodes. Binary       |
|             | Search Trees (BSTs) are a kind of binary tree that        |
|             | exhibit an ordered or sorted structure. In a BST, the     |
|             | left child node is assigned a value that is less than its |
|             | parent node, while the right child node is assigned a     |

|             | value that is higher than its parent node.               |
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| Question 3. | What are the advantages of using an AVL Tree over a      |
|             | standard BinarySearch Tree (BST)?                        |
| Answer      | AVL Trees, a variant of Binary Search Trees designed for |
|             | self-balancing, guarantee the preservation of balance in |
|             | the tree after each insertion or deletion operation. The |
|             | presence of balance in trees ensures that all tree       |
|             | operations have logarithmic limitations, hence           |
|             | preventing the occurrence of worst-case situations seen  |
|             | in binary search trees, where they may deteriorateinto   |
|             | linked lists.  |
| Question 4. | What is the underlying objective of using Priority       |
|             | Queues?  |
| Answer      | Priority queues are a kind of data structure that        |
|             | organises components according to their respective       |
|             | priority. These data structures enable the retrieval     |
|             | of the highest (or lowest) priority element in           |
|             | constant time, irrespective of the sequence in           |
|             | which elements were inserted.                            |

| Question 5. | In which situations would Heaps be considered an optimal choice for adata structure? |
|-------------|--|
|             |  |
| Answer      | Heaps are well-suited for use in applications that need                              |
|             | regular management of an item with the greatest or                                   |
|             | lowest priority. Common applications of this include the                             |
|             | implementation of algorithms like Dijkstra's shortest                                |
|             | route algorithm, Prim's Minimum Spanning Tree method,                                |
|             | or any situation that necessitates the efficient retrieval of                        |
|             | the highest or lowest value, such as inPriority Queues.                              |