

School of Computer Science and Engineering

Winter Semester 2023-24 Continuous Assessment Test – I

SLOT: B2+TB2

Programme Name & Branch: B.Tech & SCOPE

Course Name & Code: Artificial Intelligence & BCSE306L

Class Number (s): Common to all batches

Faculty Name (s): All

Exam Duration: 90 Min. Maximum Marks: 50

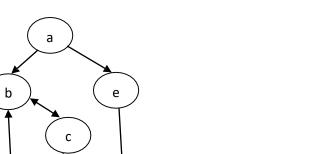
| Q. No. | Question | | | | | Max Marks | СО | BL |
|------------|--|--|---|---|---|--------------|-----|----|
| 1. | Design PEAS for the following artificial intelligent agents. i) Taxi driver agent ii) Automated robot in a manufacturing plant. iii) Playing soccer iv) Bidding an item on an auction v) Shopping for used AI books on the Internet | | | | 10 | CO1 | BL2 | |
| Ans wer | Agent | Performance measure | Environment | Actuators | Sensors | | | |
| | Playing soccer | Scoring goals, defending, winning, injuries and teamwork | Soccer playground, Players, ball, goals, referee | Player`s legs, head and hands | Camera, orientation sensor, players locator | | | |
| | Shopping for used AI books on the Internet | Price, authors, book review, interested books, cost minimization | Websites, vendors, shippers | Keyboard, mouse (hands | Camera, price monitor | | | |
| | Bidding an item on auction | The winning bid amount | Auctioneer Bidders BiddersItems which are to be bid | Speakers Microphon es Display items Budget | Camera Price monitor, where prices are being displayed. | | | |
| | Taxi driver agent | Safe Fast Legal | Roads, Traffic, Pedestrians | Steering, Accelerator , Brake, | Cameras, Sonar, Speedometer, | | | |

| | Automated robot in a manufacturing plant. | Comfortable trip Maximize profits Percentage of parts correctly manufactured | Conveyor | signal, horn, Jointed arm hand | GPS, odometer, engine sensors, keyboard Camera, joint angle sensors | | | |
|-----|--|---|----------|--|---|-----|-----|--|
| 2. | Consider the project developed by Google, codenamed Waymo. Waymo has successfully deployed self-driving cars with advanced sensors and implemented AI-based model algorithms in their decision-making process. These autonomous vehicles navigate the roads, making decisions based on percept history and real-time sensory input — the ability to make informed decisions based on historical data and real-time perceptual input received from the environments. Identify the most suitable model and explain how it fits this scenario where a decision has been made based on the perception of events that happened. | | | | 10 | CO1 | BL3 | |
| Ans | | | | | | | | |

10

CO₂

BL3



Which sequences of paths are explored by BFS and DFS in this problem? Show the complete intermediate state space for DFS and BFS with a neat sketch. Would you prefer DFS or BFS for this problem? Justify?

Note: Nodes are revisited as per the direction mentioned.

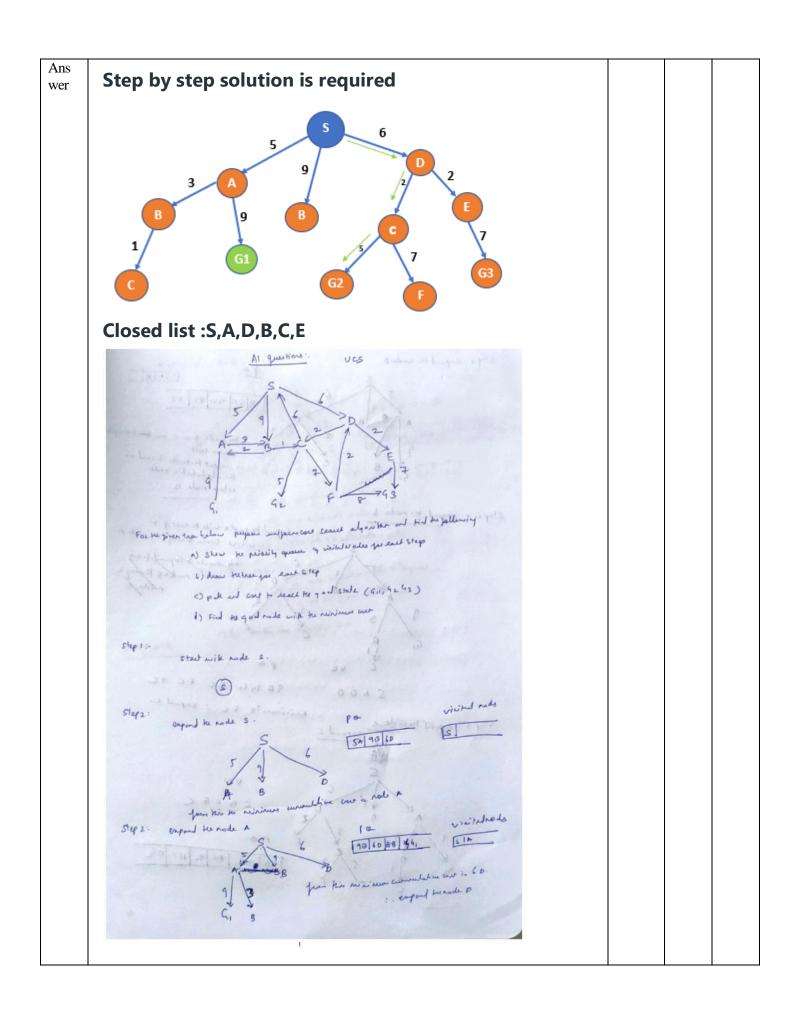
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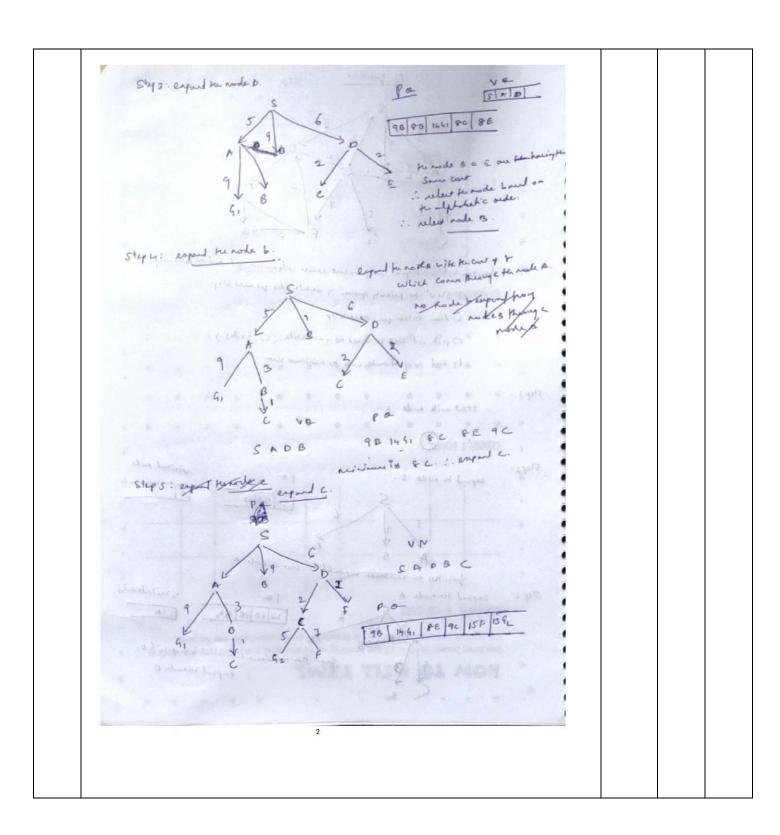
If we were just running vanilla DFS(nopruningor loopchecking) then we would prefer BFS, because DFS could get stuck in an **infiniteloop**. Note that DFS is sensitive to the ordering of the nodes. If it explores to the left first it will get stuck in the loop, whereas if it explores to the right first it will find the goal very quickly.

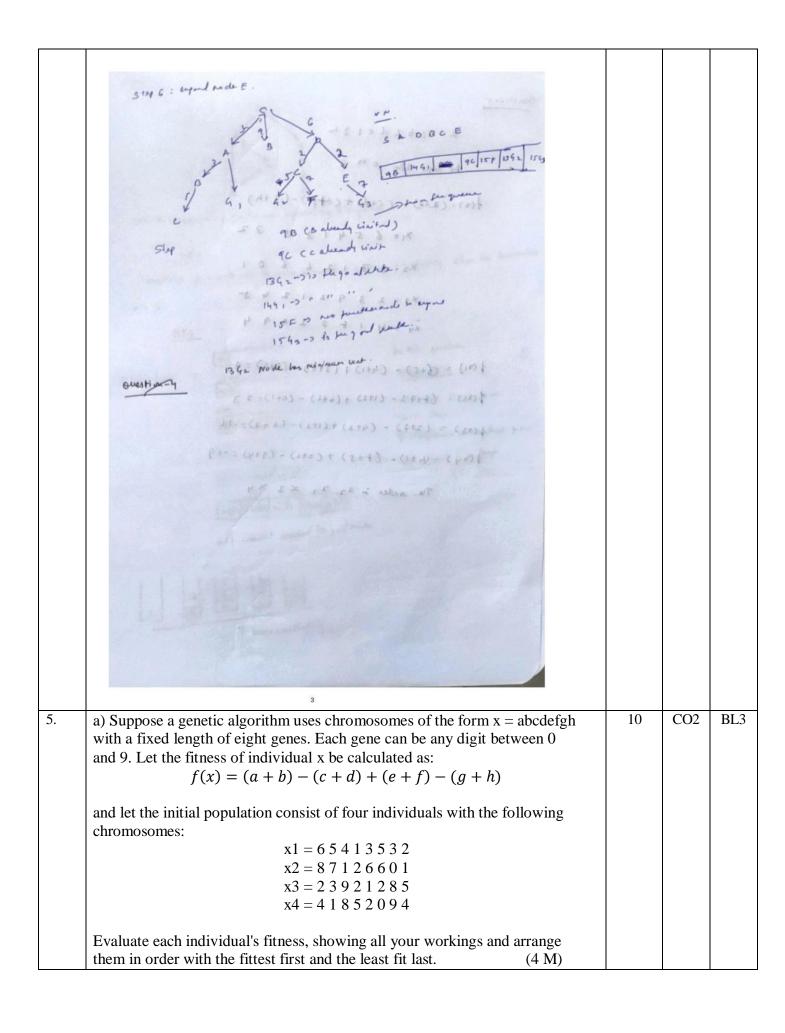
DFS explores a-->b-->d-->b BFS first adds a-->b and a-->e to the frontier.

It expands ab and adds abd and abc to the frontier. Path ae is then expanded, adding aef to the frontier. Path abd is selected and removed from the frontier, and expanded so that abdb and abdc are added to the frontier. Path abc is selected and expanded, adding abcb and abcd to the frontier.

| Ans wer | DFS explains a -> b -> d -> b -> d preens oscillating blow the two modes by d. | | | |
|------------|--|----|-----|-----|
| | DFS da His public hat about abc abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd abd | | | |
| | act selected secolar to god mode act se | | | |
| 4. | For the given directed graph (start node is S), perform the Uniform Cost Search (UCS). Expand the node based on the alphabetic order if the nodes have the same cumulative cost. 1. Show the priority queue and visited nodes for each step (4M) 2. Draw the tree for each step (3M) 3. Path and cost to reach the goal states (G1, G2, G3) (2M) 4. Find the goal node which has the minimum cost. (1M) | 10 | CO2 | BL3 |
| | S 6 D 2 E 7 9 S F 8 G3 | | | |
| | | | | |







| b) With a neat sketch of the hill-climbing algorithm's state-space landscape, explain why the hill-climbing search gets struck. List the variants of the hill climbing algorithm and describe how they overcome this problem. (6 M) | | |
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| Outhor: | | |

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Ans

