

```

> #ex1
> with(plots);with(DEtools);
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d,
conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot,
display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot,
implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot,
listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple,
odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d,
polyhedra_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions,
setoptions3d, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]
[AreSimilar, Closure, DENormal, DEplot, DEplot3d, DEplot_polygon, DFactor,
DFactorLCLM, DFactorsols, Dchangevar, Desingularize, FunctionDecomposition, GCRD,
Gosper, Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols,
MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm,
RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge,
Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot,
casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys,
dalembertsol, dcoeffs, de2diffop, dfieldplot, diff_table, diffop2de, dperiodic_sols, dpolyform,
dsols, eigenring, endomorphism_charpoly, equinv, eta_k, eulersols, exactsol, expsols,
exterior_power, firint, firtest, formal_sol, gen_exp, generate_ic, genhomosols, gensys,
hamilton_eqs, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate_sols,
infactor, invariants, kovacicols, leftdivision, liesol, line_int, linearsol, matrixDE,
matrix_riccati, maxdimsystems, moser_reduce, muchange, mult, mutest, newton_polygon,
normalG2, ode_int_y, ode_y1, odeadvisor, odepde, parametricsol, particularsol,
phaseportrait, poincare, polysols, power_equivalent, rational_equivalent, ratsols, redode,
reduceOrder, reduce_order, regular_parts, regularsp, remove_RootOf, riccati_system,
riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities, solve_group,
super_reduce, symgen, symmetric_power, symmetric_product, symtest, transinv, translate,
untranslate, varparam, zoom]

```

(1)

```

> ec:=diff(y(x),x)+y(x)*tan(x)=1/cos(x);

```

$$ec := \frac{d}{dx} y(x) + y(x) \tan(x) = \frac{1}{\cos(x)}$$

(2)

```

> sol:=dsolve(ec,y(x));

```

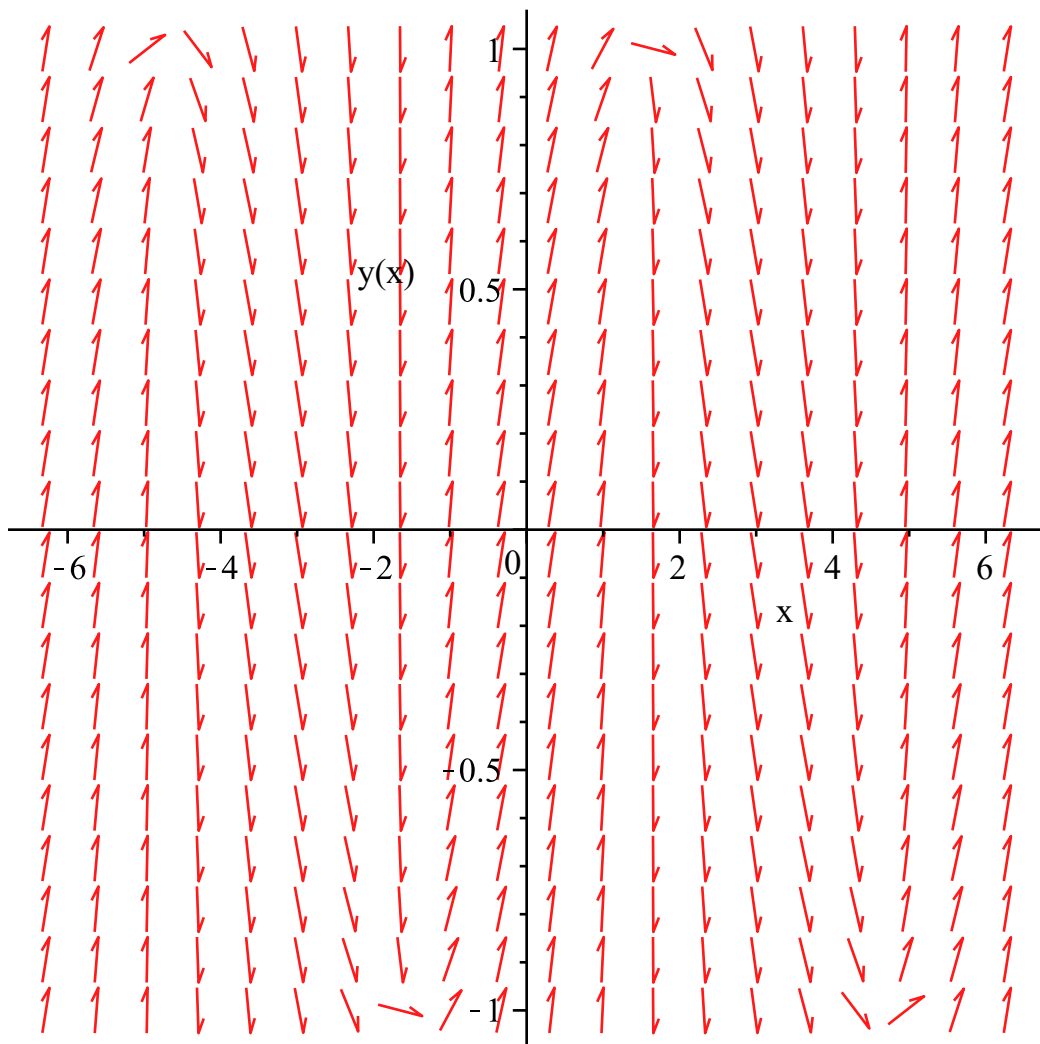
$$sol := y(x) = \cos(x) \tan(x) + \cos(x) \_C1$$

(3)

```

> DEplot(ec,y(x),x=-2*Pi..2*Pi,y=-1..1);

```



```
> cond:=y(Pi)=1;
```

$$cond := y(\pi) = 1$$

(4)

```
> sol_c:=dsolve({ec,cond},y(x));
```

$$sol\_c := y(x) = \cos(x) \tan(x) - \cos(x)$$

(5)

```
> #ex2
```

```
> ec:=(1+x^2)*diff(y(x),x,x)+4*x*diff(y(x),x)+2*y(x)-sin(x)=0;
```

$$ec := (1 + x^2) \left( \frac{d^2}{dx^2} y(x) \right) + 4x \left( \frac{d}{dx} y(x) \right) + 2y(x) - \sin(x) = 0$$

(6)

```
> sol:=dsolve(ec,y(x));
```

$$sol := y(x) = \frac{C2}{1 + x^2} + \frac{C1 x}{1 + x^2} - \frac{\sin(x)}{1 + x^2}$$

(7)

```
> cond:=y(0)=3,D(y)(0)=2;
```

$$cond := y(0) = 3, D(y)(0) = 2$$

(8)

```
> sol_c:=dsolve({ec,cond},y(x));
```

$$sol\_c := y(x) = \frac{3}{1 + x^2} + \frac{3x}{1 + x^2} - \frac{\sin(x)}{1 + x^2}$$

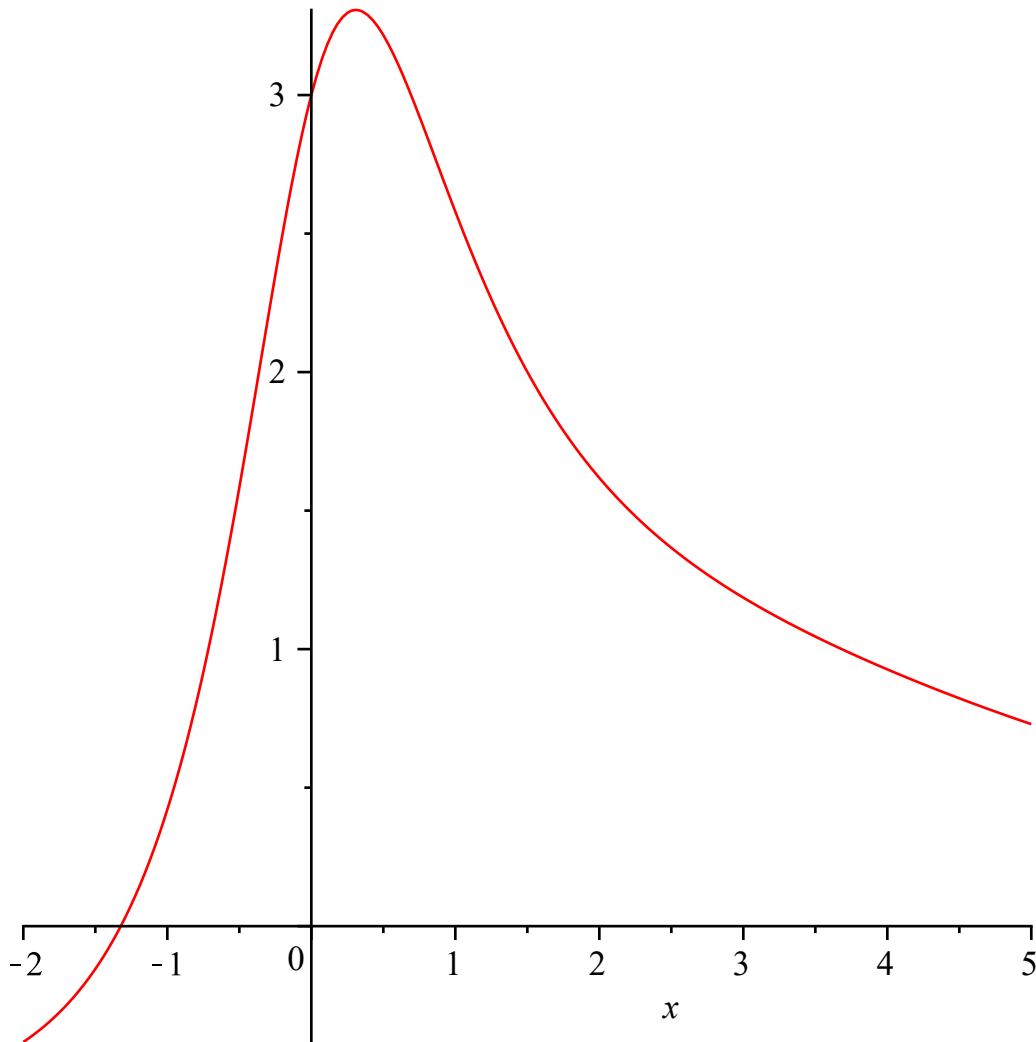
(9)

```
> y1:=unapply(rhs(sol_c),x);
```

$$y1 := x \rightarrow \frac{3}{1+x^2} + \frac{3x}{1+x^2} - \frac{\sin(x)}{1+x^2}$$

(10)

```
> plot(y1(x), x=-2..5);
```



```
> #ex3
```

```
> ec1:=diff(x(t), t)=x(t);
```

$$ec1 := \frac{d}{dt} x(t) = x(t)$$

(11)

```
> ec2:=diff(y(t), t)=x(t)+2*y(t);
```

$$ec2 := \frac{d}{dt} y(t) = x(t) + 2y(t)$$

(12)

```
> sist:=ec1, ec2;
```

$$sist := \frac{d}{dt} x(t) = x(t), \frac{d}{dt} y(t) = x(t) + 2y(t)$$

(13)

```
> sol:=dsolve({sist}, {x(t), y(t)});
```

$$sol := \{x(t) = \_C2 e^t, y(t) = -\_C2 e^t + e^{2t} \_C1\}$$

(14)

```
> cond:=x(0)=1, y(0)=4;
```

$$cond := x(0) = 1, y(0) = 4$$

(15)

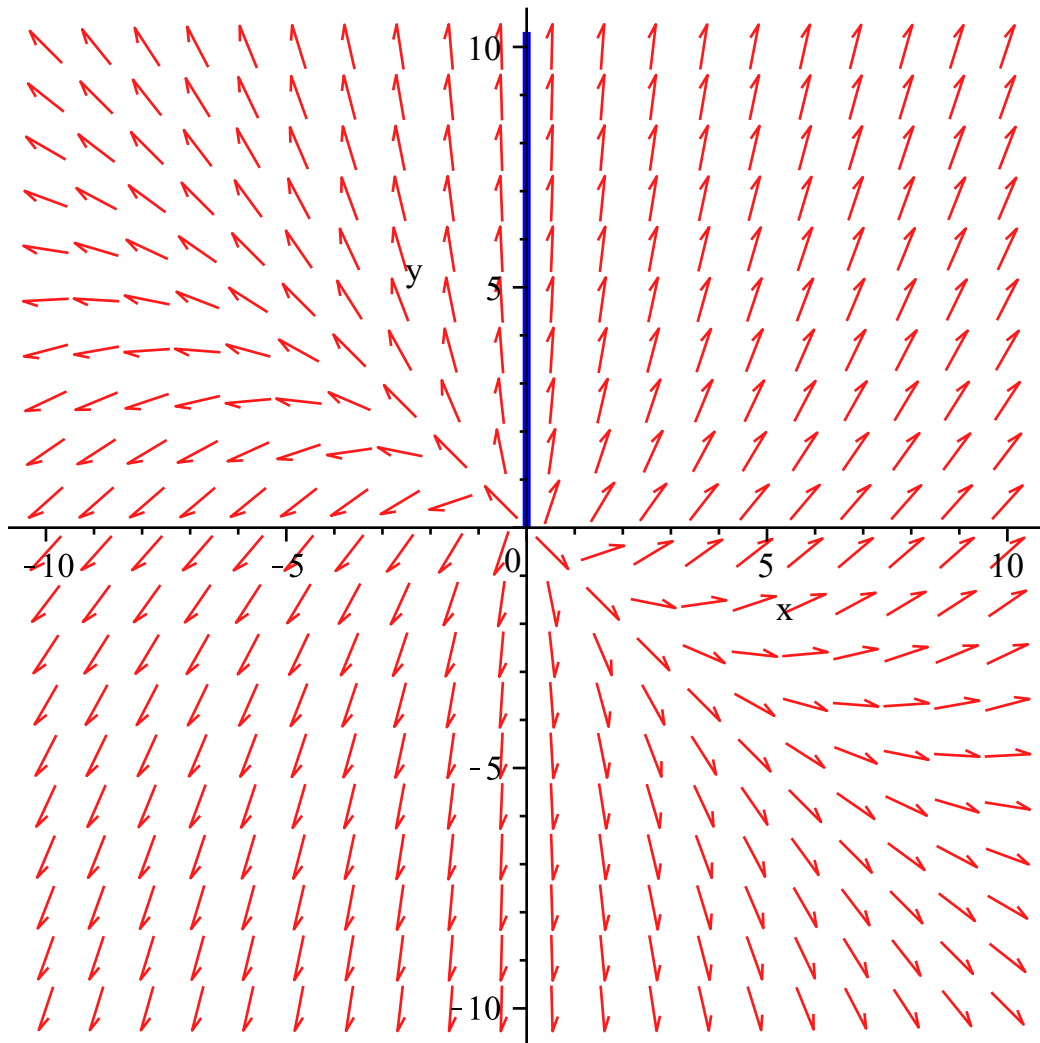
```
> sol_c:=dsolve({sist, cond}, {x(t), y(t)});
```

(16)

$$sol\_c := \{x(t) = e^t, y(t) = -e^t + 5e^{2t}\}$$

(16)

```
> DEplot([sist],[x(t),y(t)],t=-4..4,x=-10..10,y=-10..10,[[x(0)=0,
y(0)=1]],linecolor=blue);
```



```
> #nu este adevarata conditia deoarece sagetiile ies din 0,daca ar
intra atunci limitele ar fi egale cu 0
```

```
> #ex4
```

```
> ec:=diff(N(t),t)=k*N(t);
```

$$ec := \frac{d}{dt} N(t) = k N(t)$$

(17)

```
> sist:=ec,N(0)=n0;
```

$$sist := \frac{d}{dt} N(t) = k N(t), N(0) = n0$$

(18)

```
> k:=2.5;n0:=500;
```

$$k := 2.5000000000$$

$$n0 := 500$$

(19)

```
> dsolve({sist},N(t));
```

$$N(t) = 500 e^{\frac{5}{2}t}$$

(20)

```
> restart; with(plots); with(DEtools);
```

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[AreSimilar, Closure, DENormal, DEplot, DEplot3d, DEplot\_polygon, DFactor, DFactorLCLM, DFactorsols, Dchangevar, Desingularize, FunctionDecomposition, GCRD, Gosper, Heunsols, Homomorphisms, IVPsol, IsHyperexponential, LCLM, MeijerGsols, MultiplicativeDecomposition, ODEInvariants, PDEchangecoords, PolynomialNormalForm, RationalCanonicalForm, ReduceHyperexp, RiemannPsols, Xchange, Xcommutator, Xgauge, Zeilberger, abelsol, adjoint, autonomous, bernoullisol, buildsol, buildsym, canoni, caseplot, casesplit, checkrank, chinisol, clairautsol, constcoeffsols, convertAlg, convertsys, dalembertsol, dcoeffs, de2diffop, dfieldplot, diff\_table, diffop2de, dperiodic\_sols, dpolyform, dsubs, eigenring, endomorphism\_charpoly, equinv, eta\_k, eulersols, exactsol, expsols, exterior\_power, firint, firtest, formal\_sol, gen\_exp, generate\_ic, genhomosol, gensys, hamilton\_eqs, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate\_sols, intfactor, invariants, kovacicsols, leftdivision, liesol, line\_int, linearsol, matrixDE, matrix\_riccati, maxdimsystems, moser\_reduce, muchange, mult, mutest, newton\_polygon, normalG2, ode\_int\_y, ode\_y1, odeadvisor, odepde, parametricsol, particularsol, phaseportrait, poincare, polysols, power\_equivalent, rational\_equivalent, ratsols, redode, reduceOrder, reduce\_order, regular\_parts, regularsp, remove\_RootOf, riccati\_system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities, solve\_group, super\_reduce, symgen, symmetric\_power, symmetric\_product, symtest, transinv, translate, untranslate, varparam, zoom]

> **ec:=diff(N(t),t)=k\*N(t);**

$$ec := \frac{d}{dt} N(t) = k N(t) \quad (22)$$

> **cond:=N(0)=n0;**

$$cond := N(0) = n0 \quad (23)$$

> **sol:=dsolve({ec,cond},N(t));**

$$sol := N(t) = n0 e^{kt} \quad (24)$$

> **e:=unapply(rhs(sol),n0,k,t);**

$$e := (n0, k, t) \rightarrow n0 e^{kt} \quad (25)$$

> **timee:=solve(e(n0,1.5,t)=2\*n0,t);**

$$timee := 0.4620981204 \quad (26)$$

> **evalf(timee);**

$$0.4620981204 \quad (27)$$

> **#ex5**

> **f1:=(x,y)->x^2\*y+y^2\*x;**

$$f1 := (x, y) \rightarrow x^2 y + y^2 x \quad (28)$$

$$\begin{aligned} &> f2 := (x, y) \rightarrow x - y^2 - x*y + 1; \\ &f2 := (x, y) \rightarrow x - y^2 - x*y + 1 \end{aligned} \quad (29)$$

$$\begin{aligned} &> ec1 := \text{diff}(x(t), t) = f1(x(t), y(t)); \\ &ec1 := \frac{d}{dt} x(t) = x(t)^2 y(t) + y(t)^2 x(t) \end{aligned} \quad (30)$$

$$\begin{aligned} &> ec2 := \text{diff}(y(t), t) = f2(x(t), y(t)); \\ &ec2 := \frac{d}{dt} y(t) = x(t) - y(t)^2 - x(t) y(t) + 1 \end{aligned} \quad (31)$$

$$\begin{aligned} &> sist := ec1, ec2; \\ &sist := \frac{d}{dt} x(t) = x(t)^2 y(t) + y(t)^2 x(t), \frac{d}{dt} y(t) = x(t) - y(t)^2 - x(t) y(t) + 1 \end{aligned} \quad (32)$$

$$\begin{aligned} &> pct := \text{solve}(\{f1(x, y) = 0, f2(x, y) = 0\}, \{x, y\}); \\ &pct := \{x = -1, y = 0\}, \{x = 0, y = 1\}, \{x = 0, y = -1\}, \{x = -1, y = 1\} \end{aligned} \quad (33)$$

$$\begin{aligned} &> J := \text{jacobian}([f1(x, y), f2(x, y)], [x, y]); \\ &J := \begin{bmatrix} 2xy + y^2 & x^2 + 2xy \\ -y + 1 & -2y - x \end{bmatrix} \end{aligned} \quad (34)$$

$$\begin{aligned} &> \text{with}(\text{linalg}); \\ &[\text{BlockDiagonal}, \text{GramSchmidt}, \text{JordanBlock}, \text{LUdecomp}, \text{QRdecomp}, \text{Wronskian}, \text{addcol}, \\ &\text{addrow}, \text{adj}, \text{adjoint}, \text{angle}, \text{augment}, \text{backsub}, \text{band}, \text{basis}, \text{bezout}, \text{blockmatrix}, \text{charmat}, \\ &\text{charpoly}, \text{cholesky}, \text{col}, \text{coldim}, \text{colspace}, \text{colspan}, \text{companion}, \text{concat}, \text{cond}, \text{copyinto}, \\ &\text{crossprod}, \text{curl}, \text{definite}, \text{delcols}, \text{delrows}, \text{det}, \text{diag}, \text{diverge}, \text{dotprod}, \text{eigenvals}, \\ &\text{eigenvalues}, \text{eigenvectors}, \text{eigenvects}, \text{entermatrix}, \text{equal}, \text{exponential}, \text{extend}, \text{ffgausselim}, \\ &\text{fibonacci}, \text{forwardsub}, \text{frobenius}, \text{gausselim}, \text{gaussjord}, \text{geneqns}, \text{genmatrix}, \text{grad}, \\ &\text{hadamard}, \text{hermite}, \text{hessian}, \text{hilbert}, \text{htranspose}, \text{ihermite}, \text{indexfunc}, \text{innerprod}, \text{intbasis}, \\ &\text{inverse}, \text{ismith}, \text{issimilar}, \text{iszero}, \text{jacobian}, \text{jordan}, \text{kernel}, \text{laplacian}, \text{leastsqrs}, \text{linsolve}, \\ &\text{matadd}, \text{matrix}, \text{minor}, \text{minpoly}, \text{mulcol}, \text{mulrow}, \text{multiply}, \text{norm}, \text{normalize}, \text{nullspace}, \\ &\text{orthog}, \text{permanent}, \text{pivot}, \text{potential}, \text{randmatrix}, \text{randvector}, \text{rank}, \text{ratform}, \text{row}, \text{rowdim}, \\ &\text{rowspan}, \text{rowspan}, \text{rref}, \text{scalarmul}, \text{singularvals}, \text{smith}, \text{stackmatrix}, \text{submatrix}, \text{subvector}, \\ &\text{sumbasis}, \text{swapcol}, \text{swaprow}, \text{sylvester}, \text{toeplitz}, \text{trace}, \text{transpose}, \text{vandermonde}, \text{vecpotent}, \\ &\text{vectdim}, \text{vector}, \text{wronskian}] \end{aligned} \quad (35)$$

$$\begin{aligned} &> A1 := \text{subs}(pct[1, 1], pct[1, 2], \text{eval}(J)); \\ &A1 := \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \end{aligned} \quad (36)$$

$$\begin{aligned} &> \text{eigenvals}(A1); \\ &\frac{1}{2} \sqrt{5} + \frac{1}{2}, \frac{1}{2} - \frac{1}{2} \sqrt{5} \end{aligned} \quad (37)$$

$$\begin{aligned} &> \text{\#pct de echilibru de tip focus instabil} \\ &> A2 := \text{subs}(pct[2, 1], pct[2, 2], \text{eval}(J)); \\ &A2 := \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix} \end{aligned} \quad (38)$$

$$\begin{aligned} &> \text{eigenvals}(A2); \\ &1, -2 \end{aligned} \quad (39)$$

```
> #pct de echilibru instabil de tip sa
> A3:=subs(pct[3,1],pct[3,2],eval(J));
```

$$A3 := \begin{bmatrix} 1 & 0 \\ 2 & 2 \end{bmatrix} \quad (40)$$

```
> eigenvals(A3);
```

1, 2 (41)

```
> #pct de echilibru instabil de tip nod
```

```
> A4:=subs(pct[4,1],pct[4,2],eval(J));
```

$$A4 := \begin{bmatrix} -1 & -1 \\ 0 & -1 \end{bmatrix} \quad (42)$$

```
> eigenvals(A4);
```

-1, -1 (43)

```
> #pct de echilibru local asimptotic stabil de tip sa
```

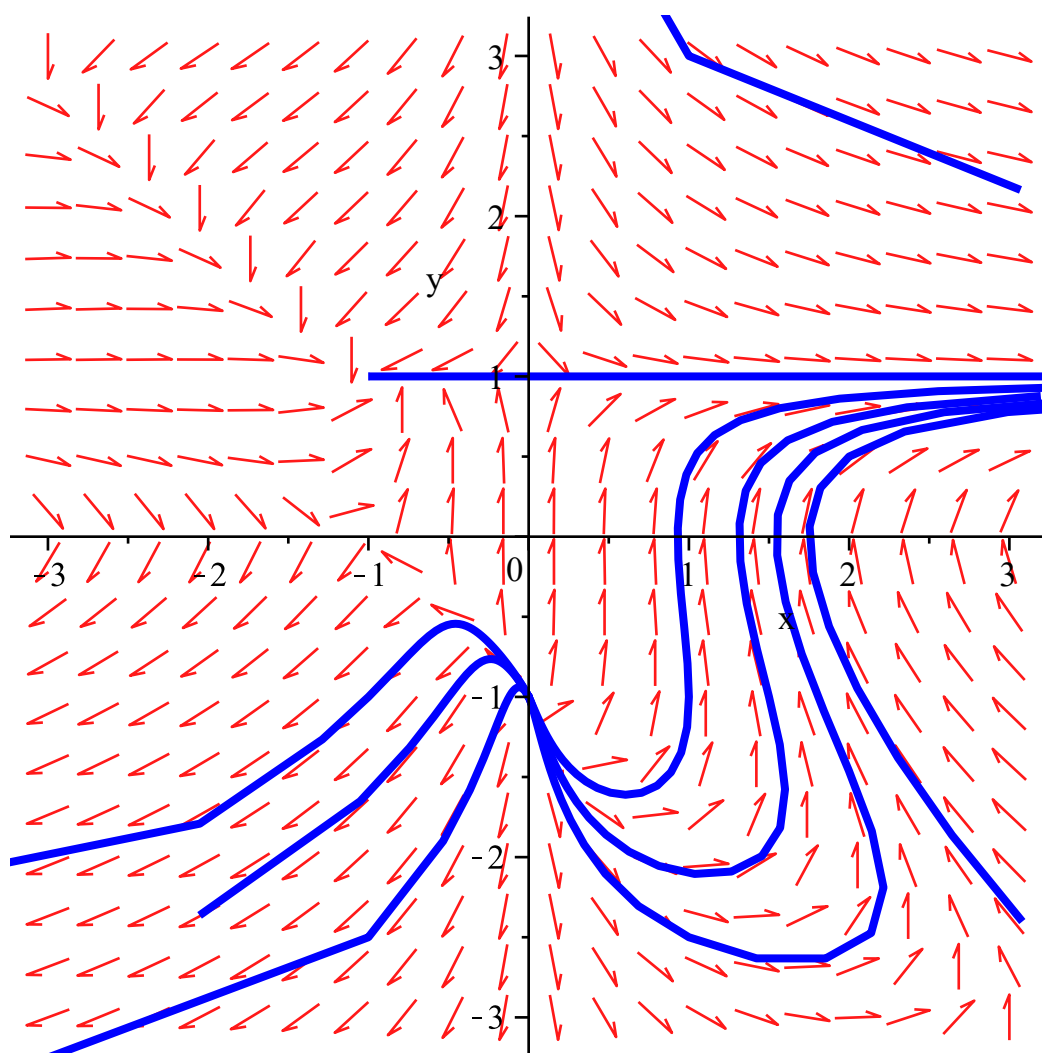
```
> condin:=[x(0)=-1,y(0)=1],[x(0)=-0.5,y(0)=1],[x(0)=1,y(0)=1],[x
> (0)=1,y(0)=3],[x(0)=2,y(0)=0.5],[x(0)=-1,y(0)=-1],[x(0)=-0.5,y
> (0)=-1],[x(0)=-1,y(0)=-2.5],[x(0)=1,y(0)=-1],[x(0)=1.5,y(0)=-1
> ],[x(0)=1,y(0)=-2.5];
```

```
condin := [x(0) = -1, y(0) = 1], [x(0) = -0.5000000000, y(0) = 1], [x(0) = 1, y(0) = 1],
[x(0) = 1, y(0) = 3], [x(0) = 2, y(0) = 0.5000000000], [x(0) = -1, y(0) = -1], [x(0) =
-0.5000000000, y(0) = -1], [x(0) = -1, y(0) = -2.5000000000], [x(0) = 1, y(0) = -1],
[x(0) = 1.5000000000, y(0) = -1], [x(0) = 1, y(0) = -2.5000000000] (44)
```

```
> DEplot([sist],[x(t),y(t)],t=-10..10,x=-3..3,y=-3..3,
> [condin],linecolor=blue,stepsize=0.1);
```

Warning, plot may be incomplete, the following errors(s) were issued:

cannot evaluate the solution further right of .48670809,  
probably a singularity



```
> restart; with(plots); with(DEtools);
```

```
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```

```
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dsubs, eigenring, endomorphism_charpoly, equinv, eta_k, eulersols, exactsol, expsols,
```

(45)



*exterior\_power, firint, firtest, formal\_sol, gen\_exp, generate\_ic, genhomosol, gensys, hamilton\_eqs, hypergeomsols, hyperode, indicialeq, infgen, initialdata, integrate\_sols, infactor, invariants, kovacicsols, leftdivision, liesol, line\_int, linearsol, matrixDE, matrix\_riccati, maxdimsystems, moser\_reduce, muchange, mult, mutest, newton\_polygon, normalG2, ode\_int\_y, ode\_y1, odeadvisor, odepde, parametricsol, particularsol, phaseportrait, poincare, polysols, power\_equivalent, rational\_equivalent, ratsols, redode, reduceOrder, reduce\_order, regular\_parts, regularsp, remove\_RootOf, riccati\_system, riccatisol, rifread, rifsimp, rightdivision, rtaylor, separablesol, singularities, solve\_group, super\_reduce, symgen, symmetric\_power, symmetric\_product, symtest, transinv, translate, untranslate, varparam, zoom]*