System Design Day 11: Ride-Sharing system

🚗 Ride-Sharing System Design Summary

🔽 Core Functional Requirements

- Rider selects a pickup location via map.
- Sees ETA and price.
- Can pay for the ride.
- Gets matched to a driver.
- Receives real-time driver updates.

High-Level Architecture Components

- 1. Clients: Riders and drivers (mobile/web).
- 2. **APIs**: Rider & Driver APIs behind Load Balancers; support horizontal scaling.

3. Databases:

- User DB: Info about riders & drivers.
- Trips DB: Trip status, route, fare, etc.
- Use **sharding** on user_id and trip_id for scalability.
- Use **global indexes** (by driver_id/rider_id) for fast queries.

4. Event Bus (Kafka):

- Enables decoupling and async communication.
- Used for real-time data updates (e.g., driver location, ride requests).

5. Map Service (Mapbox/Google Maps):

- Serves map tiles, geocoding, directions.
- 6. Payment Integration (e.g., Stripe):

- Stripe processes payment and invokes a webhook.
- Webhook pushes event to Kafka for ride updates.

7. Pricing Service:

- Implements dynamic pricing (surge based on demand).
- Uses Spark Structured Streaming on Kafka events → Redis cache.

8. Matching Service:

- Matches riders with nearby drivers.
- Uses **Uber's H3 hexagonal geospatial index** for location clustering.

Real-Time Data Flow

- Use WebSockets (vs. polling) for location updates.
- Driver location pushed to rider in real time.
- Kafka event bus distributes updates across services.

Key Design Considerations

Scalability:

- Load-balanced APIs.
- Horizontally sharded DB.

Fault Tolerance:

Event-driven system allows for async retries.

• Performance:

- Redis cache for pricing and demand.
- H3 for fast location-based lookups.

· Extensibility:

Plug-and-play with external services like Stripe and Mapbox.

■ Example: Ride Lifecycle

- 1. Rider opens app → sees map via Mapbox.
- 2. App queries ETA via Ride Service.

- 3. Price fetched from Pricing API (uses Redis + Spark).
- 4. Rider books and pays via Stripe → webhook fires → event added to Kafka.
- 5. Matching Service finds nearby driver using H3 cells.
- Driver accepts → both parties notified → real-time location sent over WebSocket.

Optimization Topics (Not Fully Covered)

- Redundancy and failure recovery.
- ETA prediction algorithms.
- · Geo-shard placement strategies.
- Data analytics and BI pipelines.

This system showcases **event-driven microservices**, **real-time communication**, **distributed data processing**, and **3rd-party service integration** — making it scalable, modular, and robust for production.s