

AMR/UMR as a basis for Knowledge Grounding/Situated Grounding

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Outline

- Background on GL-VN: a synchronization of the Generative Lexicon and VerbNet
- GL-AMR – adding a layer of inference to AMR
- More on Quantification
- Decorating the tree – mapping AMR/UMR to Wikidata
- AMR/UMR applications

GL-VerbNet as a basis for Logical Inference

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Moving beyond shallow semantics

We need to move beyond shallow semantic parsing to deeper semantic analysis of text;

Understanding sentences requires more than identifying events and participants and giving them semantic role labels;

It is essential to recognize temporal sequencing within the event and any changes in state that might have occurred.

Our Goal: A Whole that Is Greater than the Sum of Its Parts



Bring resources and theories together to enable not just better extraction of events and participants from text, but deeper semantic analysis and clearer linking of events and participants across sentences and documents.

- VerbNet: comprehensive verb resource; generalizations across related verbs; predicate argument structure;
- Generative Lexicon: best known for semantic components (qualia) of nouns, but compelling theory of contextual meaning arising from the interaction of noun and verb meaning; more recently, event decomposition;

Outline

- Enrich VerbNet semantic representations (nuanced temporal and causal sequencing, arguments with selectional preferences, verb-specific features)
- Improve our ability to identify a verb's VerbNet class (state-of-art WSD)
- Improve VerbNet semantic role labeling (state-of-art SRL)
- Evaluate

VerbNet goals

Domain-independent verb lexicon

Verbs grouped into hierarchical classes

- Semantic similarities
- Shared syntactic alternations

Explicitly described class properties

- Thematic roles involved in the predicate-argument structure
- Selectional preferences for those roles
- Syntactic frames
- Semantic representations

Run-51.3.2

MEMBERS

AMBLE (FN 1; WN 1; G 1)	GOOSE_STEP (WN 1)
AMBULATE (WN 1; G 1)	HIKE (FN 1; WN 2; G 1)
BACKPACK (WN 1)	HITCHHIKE (WN 1)
BOLT (FN 1, 2, 3, 4; WN 4; G 1)	HOPSCOTCH
BOUND (FN 1; WN 1; G 1)	JOUNCE
BREEZE	LIMP (FN 1; WN 1, 2)
BUSTLE (WN 1)	LOLLOP (WN 1)

ROLES

- AGENT [+ANIMATE]
- THEME [+ANIMATE | +MACHINE]
- LOCATION [+CONCRETE]

FRAMES

NP V

EXAMPLE	"The horse jumped."
SYNTAX	<u>THEME</u> V
SEMANTICS	MOTION(DURING(E), THEME)

NP V PP.LOCATION

EXAMPLE	"The horse jumped over the fence."
SYNTAX	<u>THEME</u> V {{+SPATIAL}} <u>LOCATION</u>
SEMANTICS	MOTION(DURING(E), THEME) PREP (E, THEME, LOCATION)

VerbNet widely used

Linking lexical resources to ontologies (Indig, et. al. 2016, Brown et al., 2017)

Semantic role labeling tasks (Shi and Mihalcea, 2005, Gung & Palmer, 2021)

Word sense disambiguation for verbs (Abend et al., 2008; Brown et al., 2011; Kawahara and Palmer, 2014; Palmer et al., 2018)

Inference-enabling tasks (Giuglea and Moschitti, 2006; Loper et al., 2007; Zaenen et al., 2008; Kawahara and Palmer, 2014)

Story generation (Martin et al., AAIL-2018; Tambwekar, P, et. al, IJCAI 2019; Ammanabrolu, P., et. al., AAIL-2020)

VerbNet – 2023: Generative Lexicon/VerbNet

Synchronizes semantics w/ GL dynamic event structure

- *Brown, S., Bonn, J., Kazeminejad, G., Zaenen, A., Pustejovsky, J., Palmer, M., Semantic Representations for NLP using VerbNet and the Generative Lexicon.*
- *Kazeminejad, G., Palmer, M., Brown, S., & Pustejovsky, J., Componential analysis of English verbs. [*Front Artif Intell.* 2022](#)*
- *Stowe, K., et. al., SemLink 2.0, IWCS, 2021*
- *Gung & Palmer, VerbNet Semantic Parsing, IWCS, 2021*



VerbNet semantic representations

Class-based semantic representations

Representations make use of semantic predicates:

- **motion**
- **perceive**
- **cause**

Reference semantic role participants and an event variable E .

Describe participants during various stages of the event evoked by the syntactic frame.

Class-based Assumptions

The arguments as semantic roles;

Explicit AND implicit arguments included

OLD - Temporal sequencing is indicated with the second-order predicates start, during, and end;

NEW – Temporal sequencing uses event variable E and subevent variables $e_1, e_2 \dots e_n$

Semantically coherent classes

Class-based semantic representations

For some classes (e.g., Battle-36.4), verbs are semantically coherent (e.g., *battle*, *skirmish*, *war*);

Sparta warred with Athens.

NP V PP

Agent V with Co-Agent

social interaction(during(E), Agent, Co-Agent)

conflict(during(E), Agent, Co-Agent)

possible contact(during(E), Agent, Co-Agent)

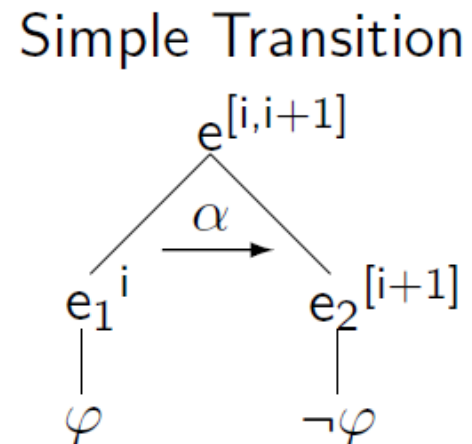
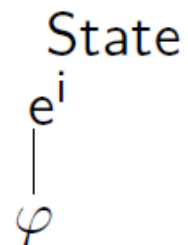
manner(Hostile, Agent)

Impetus for change (cont.)

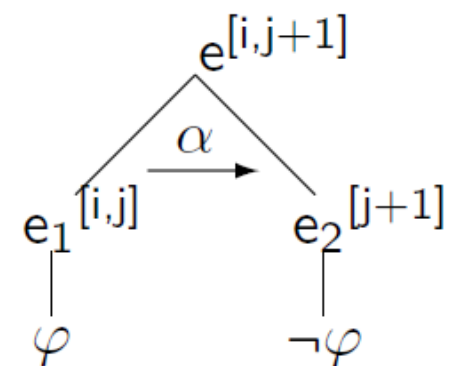
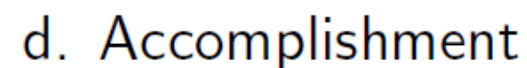
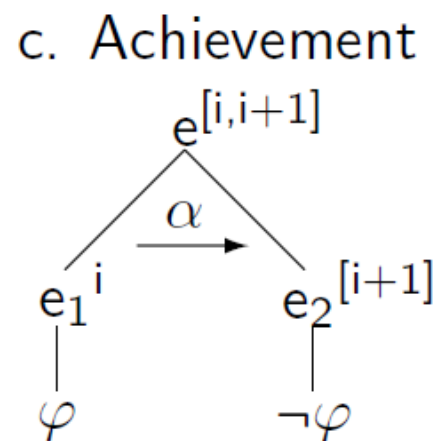
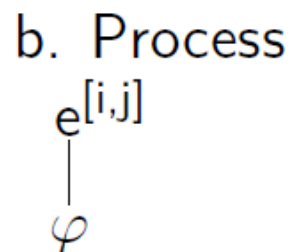
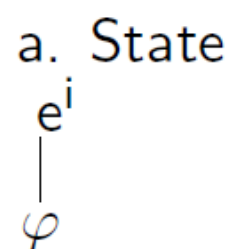
Attempts to use VerbNet in robotics showed the need for:

- a 1st-order representation;
- more specific event causal relation, instead of `cause(Agent,E)`;
- more explicit temporal relations, over reified events rather than functional expressions over the matrix event, E.

Two Primitive Event Types

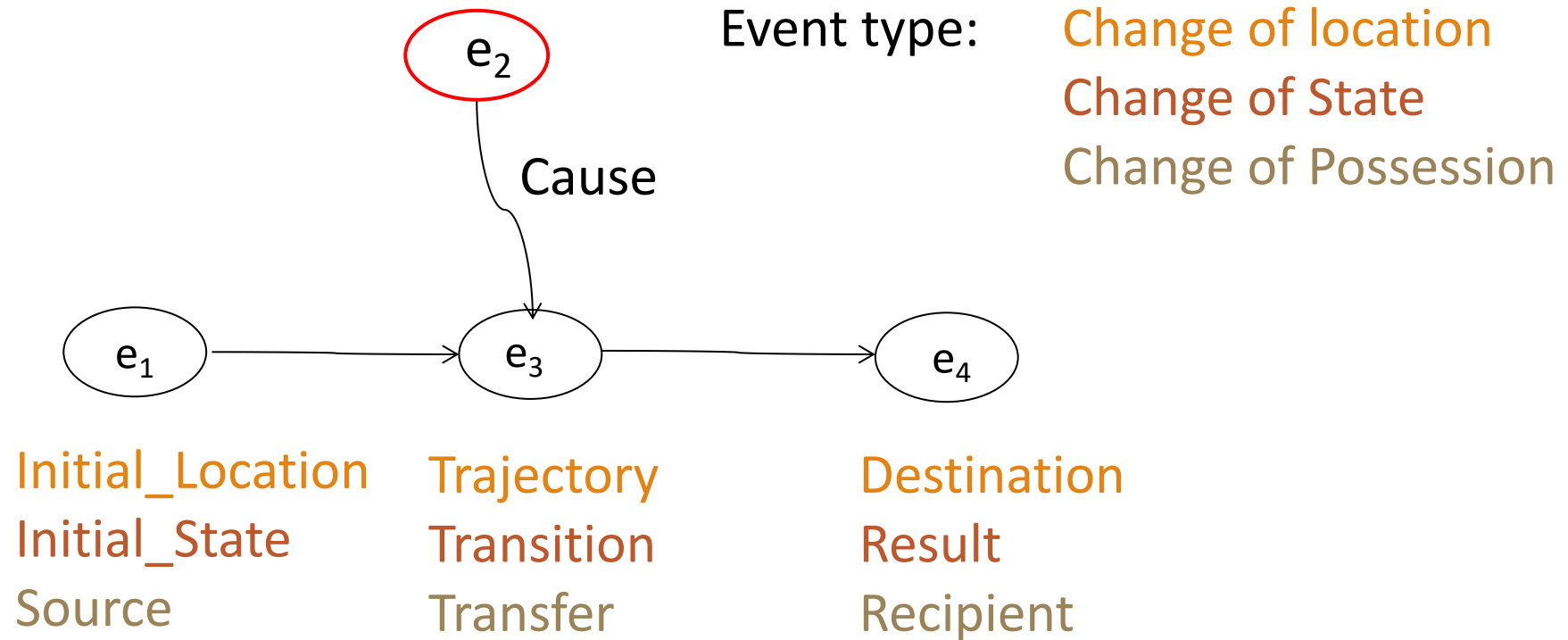


Derived Vendler Event Types



Generative
Lexicon
dynamic
event
structure

GL-VN: “Change” event structure



VerbNet with GL event structure

Elimination of tripartite division of temporal span of the event, i.e., Start, During, End;

Subevents introduced as 1st-order quantified individuals, $e_1; e_2; \dots$;

Temporal (Allen-like) relations can be employed for verb-class specific semantics:

`before($e_2; e_3$)`

`meets($e_2; e_3$)`

`while($e_2; e_3$)`

Causation is an event-relation: `cause($e_1; e_2$)`

VerbNet class:
run-51.3.2-2-1

Theme

Destination

Trajectory

Many fighters have rushed to the south through Syrian army lines.

has_location(e1, Theme, ?Initial_Location)
¬has_location(e3, Theme, Destination)
motion(e2, Theme, Trajectory)
¬has_location(e3, Theme, ?Initial_Location)
has_location(e3, Theme, Destination)

VerbNet class:
run-51.3.2-2-1

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¬has_location(e1, Theme, Destination)

motion(e2, Theme, Trajectory)

¬has_location(e3, Theme, ?Initial_Location)

has_location(e3, Theme, Destination)

VerbNet class:
run-51.3.2-2-1

Theme

Destination

Trajectory

Many fighters have *rushed* *to the south* *through Syrian army lines*.

has_location(e1, *Many fighters*, ?Initial_Location)

¬has_location(e1, Theme, *to the south*)

motion(ē2, *Many fighters*, *through Syrian...*)

¬has_location(e3, Theme, ?Initial_Location)

has_location(e3, *Many fighters*, *to the south*)

implicit
argument



Agent VerbNet class: Destination
 Concealment-16

Some have hidden near Damascus.

visible(e1, Agent)
do(e2, Agent)
¬visible(e3, Agent)
location(e3, Agent, Destination)
cause(e2, e3)

VerbNet class:
Concealment-16

Agent Destination

Some have hidden near Damascus.

visible(e1, Some fighters)
do(e2, Some fighters)
¬visible(e3, Some fighters)
location(e3, Some fighters, near Damascus)
cause(e2, e3)

VerbNet class:
Concealment-16

Agent Destination

Some have hidden near Damascus.

visible(e1, Some fighters)
do(e2, Some fighters)
¬visible(e3, Some fighters)
location(e3, Some fighters, near Damascus)
cause(e2, e3)

Sentence 1: Destination = Sentence2: Destination

Revision complete — Susan Brown, Julia Bonn

Stage 1 - Major theoretical revisions

Generic representations for all basic VerbNet frame types created.

- change of location
- change of state
- change of possession
- states
- processes

Changes made automatically to 130 classes and manually checked.

Stage 2 - Semantics for verbs of creation, perception, experience, etc. completed. (additional 122 classes)

Status of completed revisions, 6746 verbs



Change of location	48 classes
Change of state	61 classes
Change of possession	16 classes
Transfer information	22 classes
States	39 classes
Business/organization	7 classes
Substance emission	5 classes

Total gold-standard classes. 198 classes, + 124 classes = 322 out of 329

~4,500 verb senses

Automatically processed 130 classes
~2,200 verb senses

Verb-specific features

GHAZALEH KAZEMINEJAD

*Kazeminejad, et. al., Frontiers in Artificial
Intelligence: Language and Computation, in press*

Adding verb-specific features

VerbNet classes can be quite heterogenous

However, classes can often be subdivided based on additional semantic features of the verbs

- selectional restrictions on a thematic role
- directionality of motion
- manner of an action
- change of value on a scale
- affect of a participant

Calibratable-change-of-state

Increase (e.g., *build, soar, grow, jump*)

Decrease (e.g., *fall, drop, plunge*)

Fluctuate (e.g., *swing, seesaw, fluctuate*)

The price of oil soared to \$50 a barrel.

has_val(e1, Patient, Initial_State)

change_value(e2, **direction**, ?Extent, Attribute, Patient)

has_val(e3, Patient, Result)

Verb Specific Features



drive-11.5

Verb Features:
+medium_water

WordNet:
row%2:38:00

Groupings:
None

ROW

sight-30.2

Verb Features:
+seeing

WordNet:
spot%2:39:00
spot%2:30:00

Groupings:
spot.01

FrameNet:
Becoming_aware

BSO:
See Activity

PERCEIVE

SPOT

ROLES:
Experience
Stimulus

remedy-45.7

Verb Features:
+positive_change
+physical_change

WordNet:
None

Groupings:
sterilize.01
sterilize.02

REMEDY

STERILIZE

ZE

SHORT

other_cos-45.4

Verb Features:
+increase
+change_intensity

WordNet:
None

Groupings:
None

EMULSIFY

ESCALATE

terminus-47.9

Verb Features:
+end

WordNet:
terminate%2:42:

Groupings:
terminate.01

FrameNet:

TERMINATE

calibratable_cos-45.6.1

Verb Features:
+decrease

WordNet:
drop%2:30:00

Groupings:
drop.02

FrameNet:

DROP

Universal Verb Index

AKHILESH APPALA

(ALSO LEO KIM, KEVIN STOWE, PRAJNYA SATISH, PIYUSH MISHRA & LAN SANG)

UVI – Universal Verb Index

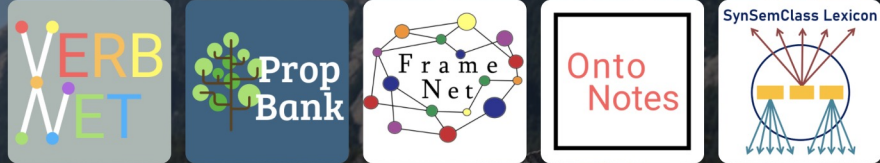


Unified Verb Index – Web Interface to VerbNet, FrameNet, WordNet, Event Force Dynamics

A tutorial video on the NLP Applications page

Welcome to the Unified Verb Index
hosted at the University of Colorado Boulder

The Unified Verb Index is a system which merges links and web pages from five different natural language processing projects:



Please click on the following button to go to the UVI Tutorial Video:

[UVI Tutorial Video](#)

Force Dynamics

SemLink

Thematic Role
Hierarchy

Preposition Class
Hierarchy

Unified Verb Index



VerbNet FrameNet

PropBank [OntoNotes](#)

2 result(s) matching query

run-n

run-v

RUN-51.3.2



Click to copy link

Full Class View

run-51.3.2
run-51.3.2-1
run-51.3.2-2
run-51.3.2-2-1

Member Verb Lemmas:

AMBLE

AMBULATE

BACKPACK

BOLT

BOUND

BREEZE

BUSTLE

CAPER

CAROM

CAVORT

CHARGE

CHUNTER

CLAMBER

CLIMB

CLUMP

CRAWL

CREEP

DODDER

FALTER

FLIT

FLOUNCE

FROLIC

GALLIVANT

GAMBOL

GHOST

GLOBETROT

GOOSE_STEP

HIKE

HITCHHIKE

HOPSCOTCH

JOUNCE

LIMP

LOLLOP

LUMBER

LURCH

MEANDER

MINCE

MOSEY

NIP

PACE

POOTLE

POUNCE

PUSSYFOOT

ROAR

ROMP

Fire-10.10

Unified Verb Index

Menu

Home

Search

VerbNet

FrameNet

PropBank

OntoNotes

2 result(s) matching query (click to view):

fire-10.10

throw-17.1-1

1 result(s) by Class ID:

fire-10.10

Full Class View

fire-10.10

NP V NP

NP V NP PP.source

NP V NP PP.attribute

Member Verb Lemmas:

FIRE

DISMISS

SACK

DROP

UNSEAT

OUST

EXPEL

REMOVE

CAN

SEND_AWAY

SUSPEND

FORCE_OUT

TERMINATE

GIVE_THE_BOOT

LAY_OFF

LET_GO

SHITCAN

ROLES:

Agent [+animate | +organization]

Theme [+animate | +organization]

Source [+organization]

Attribute

EXAMPLE:

I fired two secretaries.

SHOW DEPENDENCY PARSE TREE

SYNTAX:

Agent VERB Theme

SEMANTICS:

AUTHORITY_RELATIONSHIP(e1 , Agent , Theme)

HAS_ORGANIZATION_ROLE(e1 , Theme , ?Attribute , Source)

DO(e2 , Agent)

¬ AUTHORITY_RELATIONSHIP(e3 , Agent , Theme)

¬ HAS_ORGANIZATION_ROLE(e3 , Theme , ?Attribute , Source)

CAUSE(e2 , e3)

Verb Sense Disambiguation & Semantic Role Labeling

JAMES GUNG & MARTHA PALMER

Class members are verb senses

Example: *draw*



VerbNet Class	Example	Ontonotes Sense	Wordnet Senses
Carry-11.4	<i>She drew the cart into the barn.</i>	1	1, 20, 27
Lure-59.3	<i>They drew him into the conspiracy.</i>	2	16, 24, 26
Remove-10.1	<i>The nurse drew blood.</i>	3	5, 7, 9, 13, 14, 17
Split-23.2	<i>She drew away from the crowd.</i>	4	12
Scribble-25.2	<i>He drew the symbols over the door.</i>	6	3, 6, 19
Create-26.4	<i>She drew him a picture.</i>	6	6, 8, 19

VSD results - Multi-task Learning (SRL + VSD)



System	WSJ	Brown
ClearWSD	97.0 \pm 0	89.3 \pm 0
Baseline	97.3 \pm 0.1	90.7 \pm 0
SRL + VSD	97.7^{**} \pm 0.1	91.3 \pm 0.4
SRL VSD	97.6 ^{**} \pm 0.1	91.3 \pm 0

Table 4: VerbNet classification (sense disambiguation)
accuracy on SemLink.

Gung & Palmer, IWCS 2021

VerbNet Parser

Identifies correct VerbNet class for a verb in a textual context

Identifies main participants in a sentence

Labels them w/ appropriate thematic roles

Inserts participants into semantic representation

Demo at <http://verbnet-semantic-parser.appspot.com/>

SRL Results

Same system (Bert-based)



System	PropBank	Brown	VerbNet	Brown
	WSJ		WSJ	
Zapirain et al. (2008)	78.9 \pm 0.9	–	77.0 \pm 0.9	62.9 \pm 1.0
Baseline	88.5 \pm 0.1	82.4 \pm 0.5	87.4 \pm 0.2	80.1 \pm 0.4
SRL + VSD	88.2 \pm 0.2	82.8* \pm 0.6	87.3 \pm 0.1	80.0 \pm 0.7
SRL VSD	88.3 \pm 0.2	82.2 \pm 0.4	87.4 \pm 0.2	80.6** \pm 0.4
PREDICTED CLASS	88.3 \pm 0.1	81.2 \pm 0.6	87.6** \pm 0.1	80.9** \pm 0.6
ALL CLASSES	88.6* \pm 0.3	82.3 \pm 0.5	87.6** \pm 0.2	81.1** \pm 0.6
GOLD CLASS	88.7** \pm 0.0	82.8* \pm 0.2	88.2** \pm 0.2	83.0** \pm 0.9

VerbNet Semantic Role Labeling

Find the participants & identify roles they play; essential building block for deeper representations of meaning

VerbNet class:
run-51.3.2-2-1

Theme

Destination

Trajectory

Many fighters have *rushed* *to the south* *through Syrian army lines*.

has_location(e1, Theme, ?Initial_Location)

¬ **has_location**(e3, Theme, ?Destination)

motion(e2, Theme, Trajectory)

¬ **has_location**(e3, Theme, ?Initial_Location)

has_location(e3, Theme, ?Destination)

VerbNet Parser Output

Many fighters have **rushed** 51.3.2-2-1 to the south through Syrian army lines .

[run-51.3.2-2-1](#)

Many fighters

Theme

A1 entity in motion

rushed

run-51.3.2-2-1

to the south

Destination

A2 path or secondary action of arg1

through Syrian army lines

AM-DIR direction

[e1](#)

e2

e3

HAS_LOCATION(*Many fighters* Theme ,

Ⓢ Initial_Location)

► View options

e1 **e2** e3

MOTION(*Many fighters* Theme , **?**
Trajectory)

¬HAS_LOCATION(*Many fighters* Theme ,
? Initial_Location)

e1 e2 **e3**

HAS_LOCATION(*Many fighters* Theme , *to
the south* Destination)

VerbNet Parser
Output