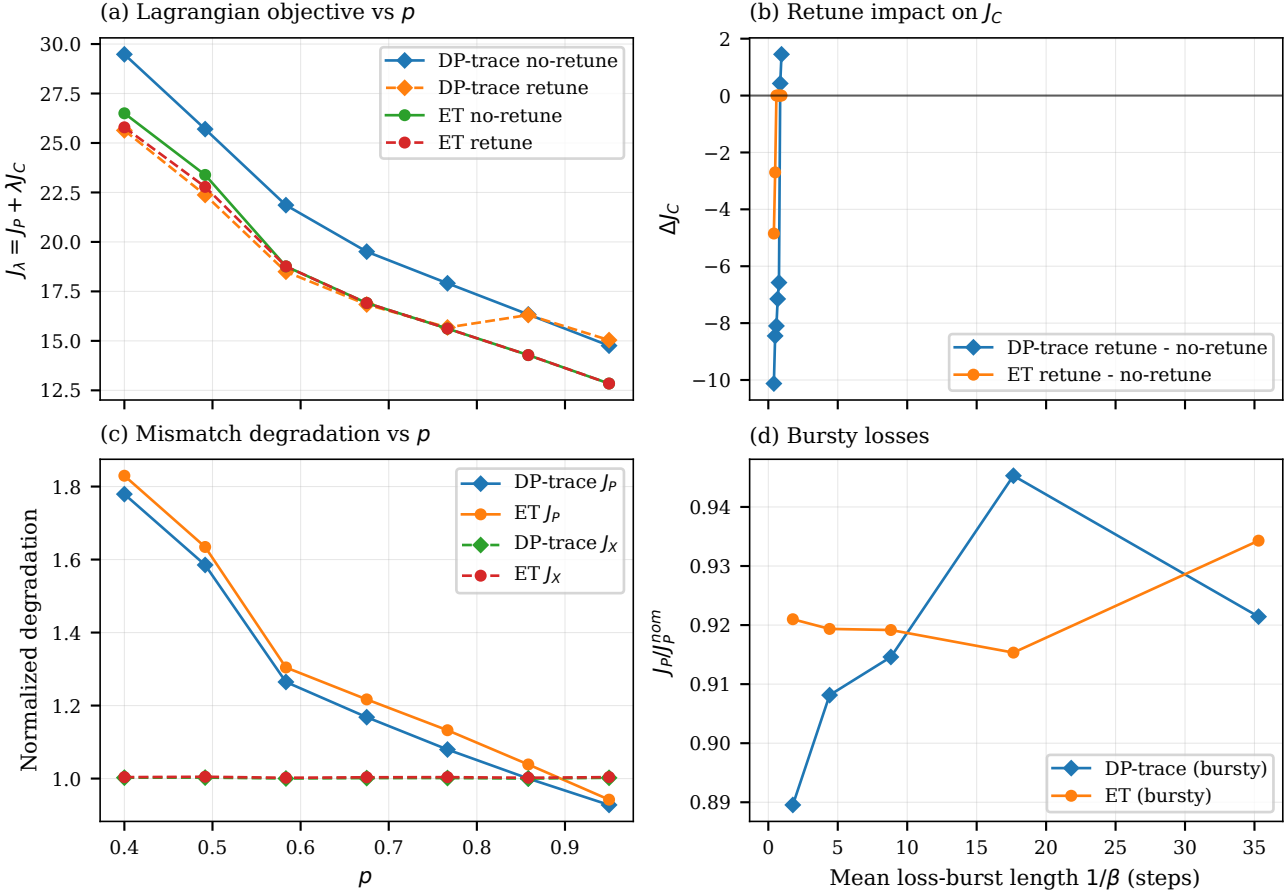
(a) Lagrangian objective vs p
$J_\lambda = J_P + \lambda J_C$
DP-trace no-retune
DP-trace retune
ET no-retune
ET retune
(b) Retune impact on J_C
ΔJ_C
DP-trace retune - no-retune
ET retune - no-retune
(c) Mismatch degradation vs p
Normalized degradation
DP-trace J_P
ET J_P
DP-trace J_X
ET J_X
p
(d) Bursty losses
J_P / J_P^{nom}
DP-trace (bursty)
ET (bursty)
Mean loss-burst length $1/\beta$ (steps)