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#include<reg51.h>
#define msec 100
#define lcd_data_str_pin P2
#include<stdio.h>

sbit gcA=P1^0;      // interrupt for A (green corridor)
sbit gcB=P1^1;      // interrupt for B (green corridor)
sbit gcC=P1^2;      // interrupt for C (green corridor)
sbit gcD=P1^3;      // interrupt for D (green corridor)

sbit SenA=P0^7;     // sensor in line A
sbit SenB=P0^2;     // sensor in line B
sbit SenC=P0^1;     // sensor in line C
sbit SenD=P0^5;     // sensor in line D

void normal();

void main (void)
{
    while(1)
    {
        normal();
    }
}

void delay(unsigned int m_sec) //Time delay function
{
    int i,j ;
    for(i=0;i<m_sec;i++)
    for(j=0;j<500;j++);
}

```

```
void normal()
{
    P2=0x28;P3=0x11;  // A Green
    delay(5000);
    if(SenA == 0)
    {delay(10000);}

    while(gcA==1)
    {
        P2=0x28;P3=0x11;  // A Green
        delay(5000);
    }

    P2=0x41;P3=0x11;  // A yellow
    delay(2000);
    P2=0x82;P3=0x11;  // B Green
    delay(5000);
    if(SenB == 0)
    {delay(10000);}

    while(gcB==1)
    {
        P2=0x82;P3=0x11;  // B Green
        delay(5000);
    }

    P2=0x81;P3=0x11;  // B yellow
    delay(2000);
}
```

```
P2=0x88;P3=0x14;    // C Green
delay(5000);
if(SenC == 0)
    {delay(10000);}

    while(gcC==1)
    {
        P2=0x88;P3=0x14;    // C Green
        delay(5000);
    }

P2=0x88;P3=0x12;    // C yellow
delay(2000);
P2=0x88;P3=0x41;    // D Green
delay(5000);
if(SenD == 0)
    {delay(10000);}

    while(gcD == 1)
    {
        P2=0x88;P3=0x41;    // D Green
        delay(5000);
    }

P2=0x88;P3=0x21;    // D yellow
delay(2000);
```

```
}
```