

# Error propagation for TIMS Pb/Pb geochronology

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The Pb-budget of meteorites consists of extraterrestrial and terrestrial components. To separate the two components, we spike the sample with a solution that contains synthetic  $^{202}\text{Pb}$  and  $^{205}\text{Pb}$ . The spike serves two purposes. First, the  $^{205}\text{Pb}$  in it is used as a tracer to compare the sample (which is a mixture of extraterrestrial and terrestrial Pb) with a blank solution (which contains only terrestrial Pb). Second, if the true  $^{205}\text{Pb}/^{202}\text{Pb}$ -ratio of the spike is known, then this can be used to correct for mass-dependent fractionation. The extraterrestrial  $^{204}\text{Pb}/^{206}\text{Pb}$  and  $^{207}\text{Pb}/^{206}\text{Pb}$ -ratios of the sample can then be estimated as

$$\begin{cases} [4/6]_e = \frac{4_s - 4_b}{6_s - 6_b} \\ [7/6]_e = \frac{7_s - 7_b}{6_s - 6_b} \end{cases} \quad (1)$$

respectively, where  $x_s$  represents the amount (in pmol) of fractionation-corrected  $^{20x}\text{Pb}$  in the spike-sample-blank mixture, and  $x_b$  is the corresponding amount in the spike-blank mixture:

$$x_* = M_* [x/5]_* F_*^{\beta(x)} \quad (2)$$

where  $M_*$  is the amount (in pmol) of  $^{205}\text{Pb}$  added to the spike-sample-blank mixture (if  $* = s$ ) or spike-blank mixture (if  $* = b$ );  $[x/5]_*$  is the corresponding  $^{20x}\text{Pb}/^{205}\text{Pb}$ -ratio; and  $F_*^{\beta(x)}$  is the kinetic fractionation factor of Young et al. (2002), with

$$F_* = \frac{[2/5]_t}{[2/5]_*} \quad \text{and} \quad (3)$$

$$\beta(x) = \frac{\ln(205) - \ln(m_x)}{\ln(205) - \ln(202)} \quad (4)$$

in which  $m_x = 20x$  is the molar masses of  $x$ , and  $[2/5]_t$  is the true atomic  $^{202}\text{Pb}/^{205}\text{Pb}$ -ratio of the spike.

Because isotopic ratios are strictly positive quantities whose uncertainties are best expressed in relative terms, it is useful to cast Equation 1 into a logarithmic form:

$$\begin{cases} l_{46} \equiv \ln[4/6]_e = l_4 - l_6 \\ l_{76} \equiv \ln[7/6]_e = l_7 - l_6 \end{cases} \quad (5)$$

where

$$l_4 = \ln(\exp[l_4(s)] - \exp[l_4(b)]) \quad (6)$$

$$l_6 = \ln(\exp[l_6(s)] - \exp[l_6(b)]) \quad (7)$$

$$l_7 = \ln(\exp[l_7(s)] - \exp[l_7(b)]) \quad (8)$$

with

$$l_x(*) = \ln M_* + \ln[x/5]_* + \beta(x) (\ln[2/5]_t - \ln[2/5]_*) \quad (9)$$

In order to solve Equation 5, we must first solve Equation 9 (for  $x \in \{4, 6, 7\}$  and  $* \in \{b, s\}$ ), and propagate its uncertainties. Let  $\Sigma$  be the covariance matrix of the blank-corrected  $l_*(x)$ -measurements:

$$\Sigma = \begin{bmatrix} s[l_b(4)]^2 & s[l_b(4), l_s(4)] & s[l_b(4), l_b(6)] & s[l_b(4), l_s(6)] & s[l_b(4), l_b(7)] & s[l_b(4), l_s(7)] \\ s[l_s(4), l_b(4)]^2 & s[l_s(4)]^2 & s[l_b(4), l_b(6)] & s[l_b(4), l_s(6)] & s[l_b(4), l_b(7)] & s[l_b(4), l_s(7)] \\ s[l_b(6), l_b(4)]^2 & s[l_b(6), l_s(4)] & s[l_b(6)]^2 & s[l_b(6), l_s(6)] & s[l_b(6), l_b(7)] & s[l_b(6), l_s(7)] \\ s[l_s(6), l_b(4)]^2 & s[l_s(6), l_s(4)] & s[l_s(6), l_b(6)] & s[l_s(6)]^2 & s[l_s(6), l_b(7)] & s[l_s(6), l_s(7)] \\ s[l_b(7), l_b(4)]^2 & s[l_b(7), l_s(4)] & s[l_b(7), l_b(6)] & s[l_b(7), l_s(6)] & s[l_b(7)]^2 & s[l_b(7), l_s(7)] \\ s[l_s(7), l_b(4)]^2 & s[l_s(7), l_s(4)] & s[l_s(7), l_b(6)] & s[l_s(7), l_s(6)] & s[l_s(7), l_b(7)] & s[l_s(7)]^2 \end{bmatrix} \quad (10)$$

where  $s[x]^2$ ,  $s[y]^2$  and  $s[x, y]$  are the (co) variances of  $x$  and  $y$ ; then conventional error propagation by first order Taylor approximation dictates that:

$$\Sigma = \begin{bmatrix} I_3 & 0_{3,5} & J_t \\ 0_{5,3} & J_s & J_t \end{bmatrix} \begin{bmatrix} \Sigma_b & 0_{5,3} & 0_{5,1} \\ 0_{3,5} & \Sigma_s & 0_{4,1} \\ 0_{1,5} & 0_{1,4} & s[5/2]_t^2 \end{bmatrix} \begin{bmatrix} I_3 & 0_{3,5} \\ 0_{5,3} & J_s^T \\ J_t^T & J_t^T \end{bmatrix} \quad (11)$$

where  $I_n$  is the  $n \times n$  identity matrix;  $0_{n,m}$  is an  $n \times m$  matrix of zeros;  $J_s$  and  $J_t$  are Jacobian matrices (with  $J_s^T$  and  $J_t^T$  their transpose):

$$J_s = \begin{bmatrix} \frac{1}{M_s} & \frac{-\beta(4)}{[2/5]_s} & \frac{1}{[4/5]_s} & 0 & 0 \\ \frac{1}{M_s} & \frac{-\beta(6)}{[2/5]_s} & 0 & \frac{1}{[6/5]_s} & 0 \\ \frac{1}{M_s} & \frac{-\beta(7)}{[2/5]_s} & 0 & 0 & \frac{1}{[7/5]_s} \end{bmatrix}; \quad J_t = \begin{bmatrix} \frac{\beta(4)}{[2/5]_t} \\ \frac{\beta(6)}{[2/5]_t} \\ \frac{\beta(7)}{[2/5]_t} \end{bmatrix} \quad (12)$$

and  $\Sigma_s$  and  $\Sigma_b$  are the covariance matrices of the sample and average blank, respectively.  $\Sigma_b$  is estimated from repeat measurements of

$$l'_b(x) = \ln M_b + \ln[x/5]_b - \beta(x) \ln[2/5]_b \quad (13)$$

(for  $x \in \{4, 6, 7\}$ ) whereas  $\Sigma_s$  contains the analytical uncertainties of the raw measurements for the sample:

$$\Sigma_s = \begin{bmatrix} s[M_s]^2 & 0 & 0 & 0 \\ 0 & s[2/5]_s^2 & s([2/5]_s, [4/5]_s) & s([2/5]_s, [6/5]_s) & s([2/5]_s, [7/5]_s) \\ 0 & s([4/5]_s, [2/5]_s) & s[4/5]_s^2 & s([4/5]_s, [6/5]_s) & s([4/5]_s, [7/5]_s) \\ 0 & s([6/5]_s, [2/5]_s) & s([6/5]_s, [4/5]_s) & s[6/5]_s^2 & s([6/5]_s, [7/5]_s) \\ 0 & s([7/5]_s, [2/5]_s) & s([7/5]_s, [4/5]_s) & s([7/5]_s, [6/5]_s) & s[7/5]_s^2 \end{bmatrix} \quad (14)$$

Although it is possible to solve Equation 5 by plugging the  $l_x(*)$  values from Equation 9 into Equations 6–7, this approach breaks down when the blank exceeds the signal. To rule out this possibility, it is better to estimate  $l_{46}$  and  $l_{76}$  using the method of maximum likelihood. Let  $\Delta$  be a column vector (and  $\Delta^T$  a row vector) of misfits:

$$\Delta = \begin{bmatrix} l_4(b) - c_{4b} \\ l_6(b) - c_{6b} \\ l_7(b) - c_{7b} \\ l_4(s) - \ln(\exp[c_{46} + c_6] + \exp[c_{4b}]) \\ l_6(s) - \ln(\exp[c_6] + \exp[c_{6b}]) \\ l_7(s) - \ln(\exp[c_{76} + c_6] + \exp[c_{7b}]) \end{bmatrix} \quad (15)$$

where  $c_{4b}$ ,  $c_{6b}$ ,  $c_{7b}$ ,  $c_6$ ,  $c_{46}$ ,  $c_{76}$  are the true (but unknown) values of  $l_4(b)$ ,  $l_6(b)$ ,  $l_7(b)$ ,  $l_6$ ,  $l_{46}$  and  $l_{76}(b)$ , respectively. These parameters can be estimated by maximising the likelihood function ( $\mathcal{L}$ ):

$$\mathcal{L} = \Delta^T \Sigma^{-1} \Delta \quad (16)$$

The uncertainties of  $c_{4b}$ ,  $c_{6b}$ ,  $c_{7b}$ ,  $c_6$ ,  $c_{46}$ ,  $c_{76}$  can be obtained by inverting the Hessian matrix of  $\mathcal{L}$  with respect to the parameters.

## References

Young, E. D., Galy, A., and Nagahara, H. Kinetic and equilibrium mass-dependent isotope fractionation laws in nature and their geochemical and cosmochemical significance. *Geochimica et Cosmochimica Acta*, 66(6):1095–1104, 2002.