

Wildlife Species Classification in Camera Trap Images: Tai National Park

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Introduction

- ▶ The project is primarily motivated by the urgent need to enhance wildlife conservation and ecological research due to the imminent threats faced by Earth's biodiversity, including habitat loss, climate change, and human activities.
- ▶ Through the development of an image classification model, we aim to support wildlife preservation and environmental stewardship by enabling the efficient monitoring and categorization of wildlife species, facilitating more informed conservation decisions.



Background

- ▶ In the realm of wildlife conservation and ecological research, data collection is often a challenging and resource-intensive task.
- ▶ Traditional methods for monitoring and tracking wildlife populations involve field surveys, camera traps, and manual observations, which are not only time-consuming but also labor-intensive.
- ▶ However, with the advancements in machine learning and computer vision, it is now possible to leverage technology to automate this process to a large extent.
- ▶ Our project focuses on the problem of image classification to identify seven specific species: birds, civets, duikers, hogs, leopards, other monkeys, and rodents. We are also addressing the issue of images that contain no animals.
- ▶ The potential impact of this project extends to various areas, including the efficient management of protected areas, understanding species distribution and behavior, and aiding researchers in their studies.

Problem Statement

Our aim is to develop a model capable of classifying images into one of seven specified species categories or as containing no animals.



The Categories are :

Antelope
Duiker

Civet
Genet

Bird

Hog

Leopard

Monkey
Prosimian

Rodent

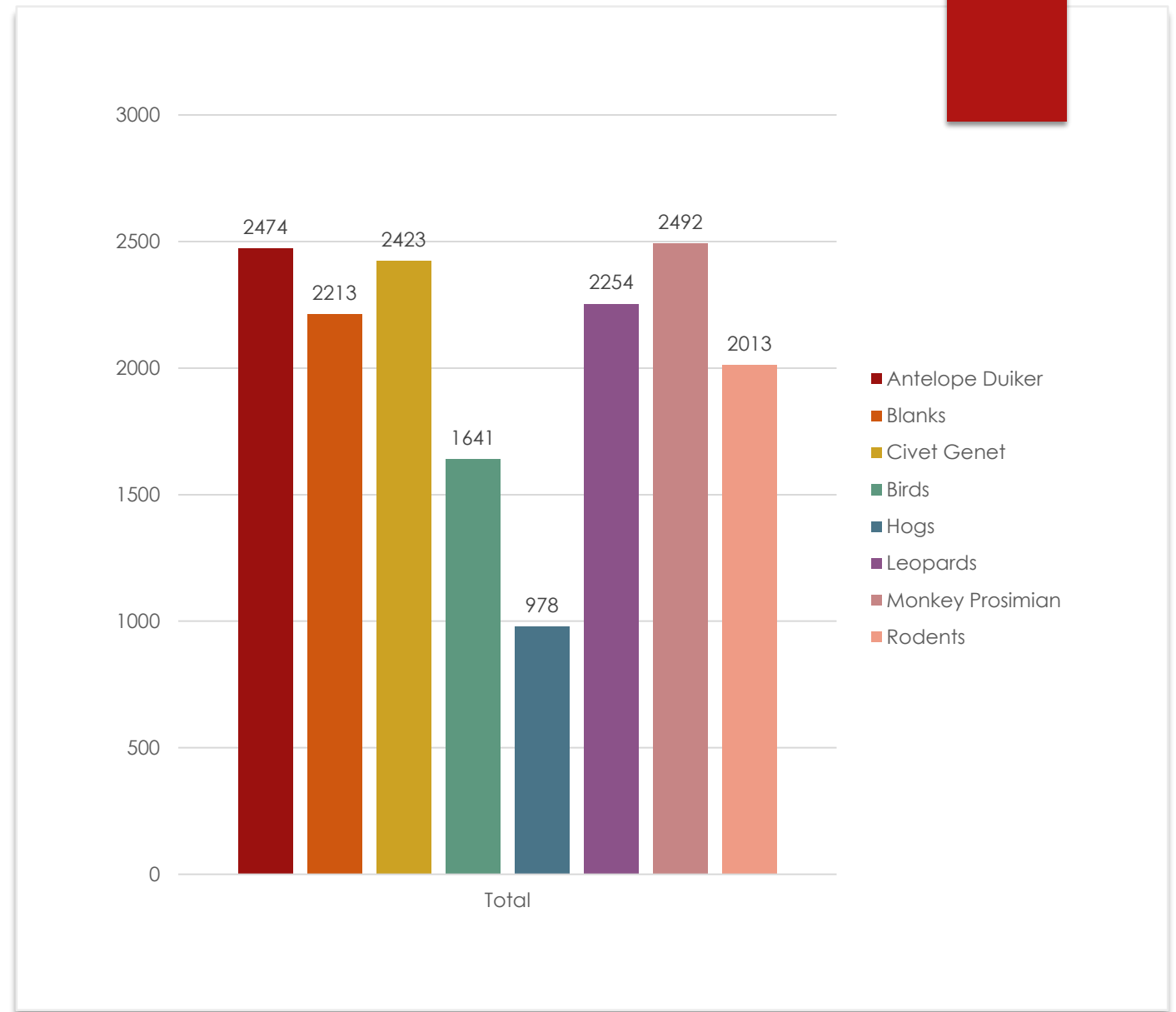
The Dataset

- ▶ The Dataset has been provided by drivendata.org.
- ▶ It has over 16000 training images and 4000 test images.
- ▶ Each image is .jpg file
- ▶ Each image has been assigned its site, filepath and its label for training set.
- ▶ The site is the location where the image was taken
- ▶ The resolution of the image varies and is not fixed.
- ▶ There is no overlap between sites in testing data and training data

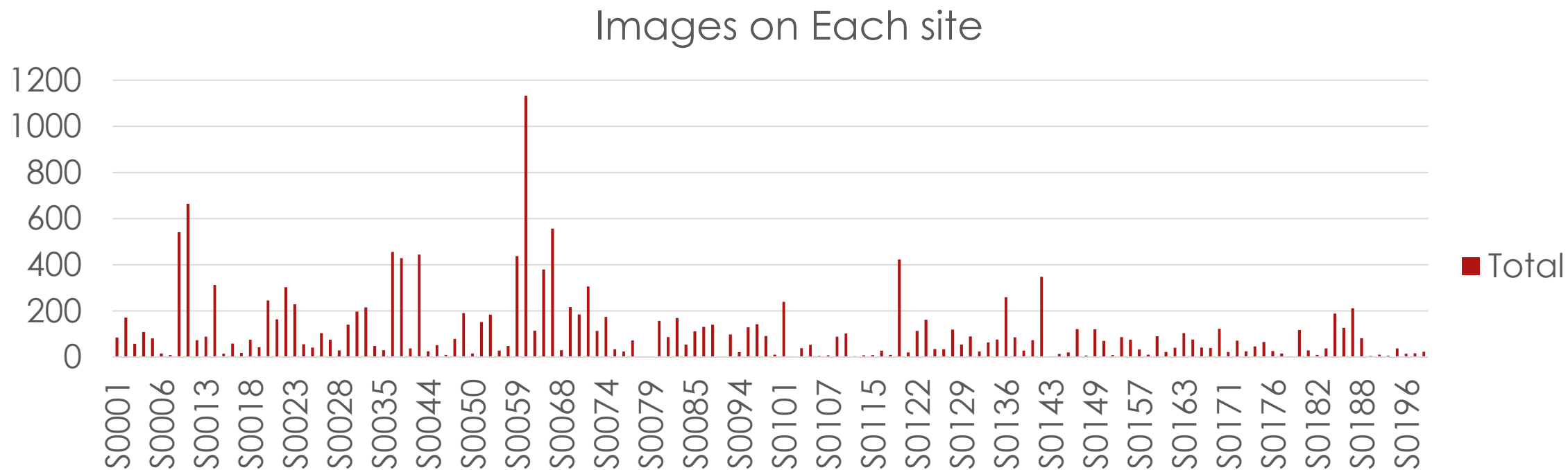


Data Exploration

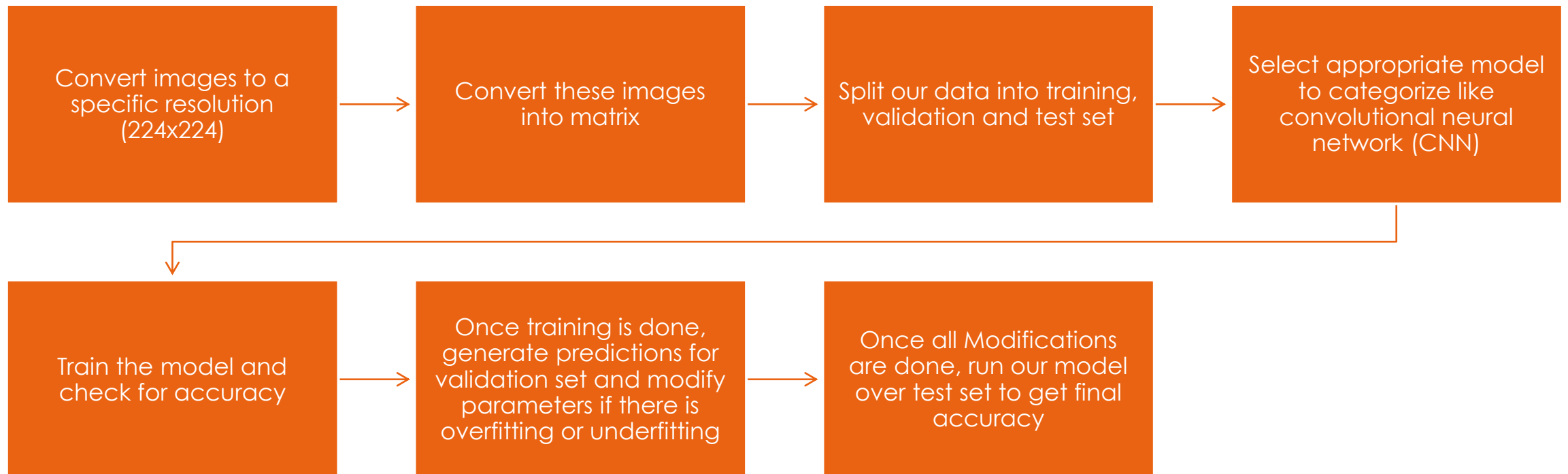
► Data Description



Data Exploration



Baseline Approach

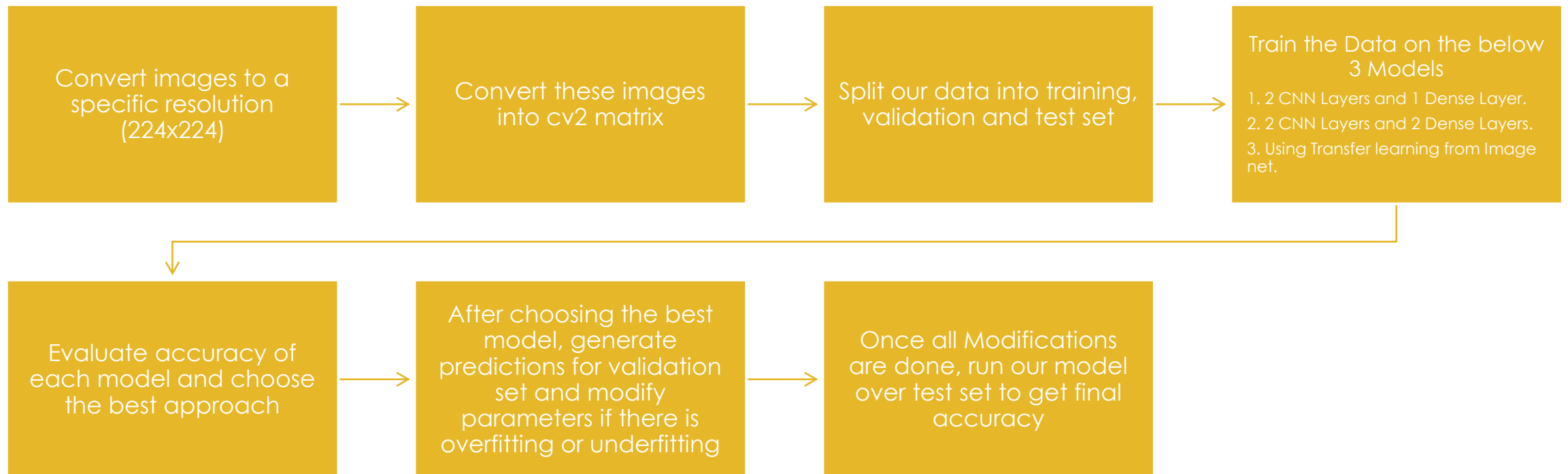


Preliminary Test Results

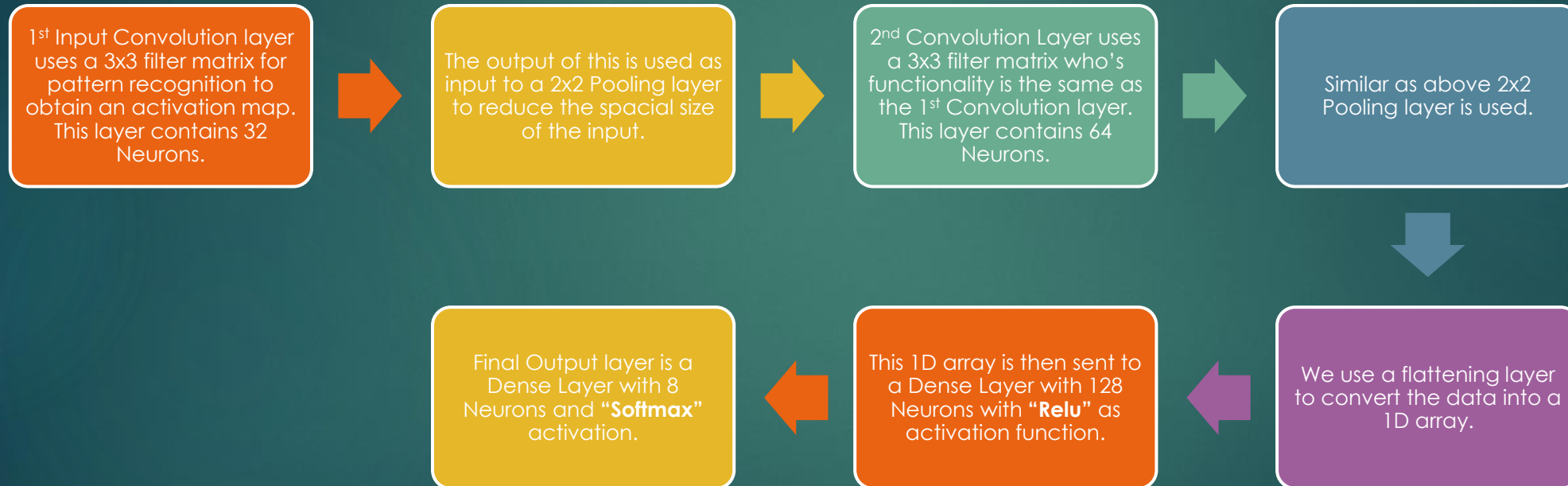
- ▶ Accuracy of 72% on validation set and 89.7% on Training set indicating variance over following Neural net configuration:
- ▶ 2 Convolution layer with 32 filter and 64 filters respectively
- ▶ 2 Max pooling layers each after a convolution layer
- ▶ 1 Flatten Layer
- ▶ 2 Dense layers with 128 neurons and 8 neurons respectively

```
Epoch 1/10
110/110 [=====] - 73s 641ms/step - loss: 2.0637 - accuracy: 0.3180
Epoch 2/10
110/110 [=====] - 67s 608ms/step - loss: 1.2347 - accuracy: 0.5751
Epoch 3/10
110/110 [=====] - 747s 7s/step - loss: 0.8978 - accuracy: 0.7071
Epoch 4/10
110/110 [=====] - 70s 637ms/step - loss: 0.6955 - accuracy: 0.7611
Epoch 5/10
110/110 [=====] - 69s 629ms/step - loss: 0.5788 - accuracy: 0.8111
Epoch 6/10
110/110 [=====] - 73s 660ms/step - loss: 0.5028 - accuracy: 0.8369
Epoch 7/10
110/110 [=====] - 74s 672ms/step - loss: 0.4342 - accuracy: 0.8586
Epoch 8/10
110/110 [=====] - 67s 608ms/step - loss: 0.3615 - accuracy: 0.8840
Epoch 9/10
110/110 [=====] - 78s 710ms/step - loss: 0.3213 - accuracy: 0.8923
Epoch 10/10
110/110 [=====] - 72s 656ms/step - loss: 0.3150 - accuracy: 0.8974
47/47 [=====] - 9s 179ms/step - loss: 1.2960 - accuracy: 0.7213
Test accuracy: 0.7213333249092102
```

Final Approach

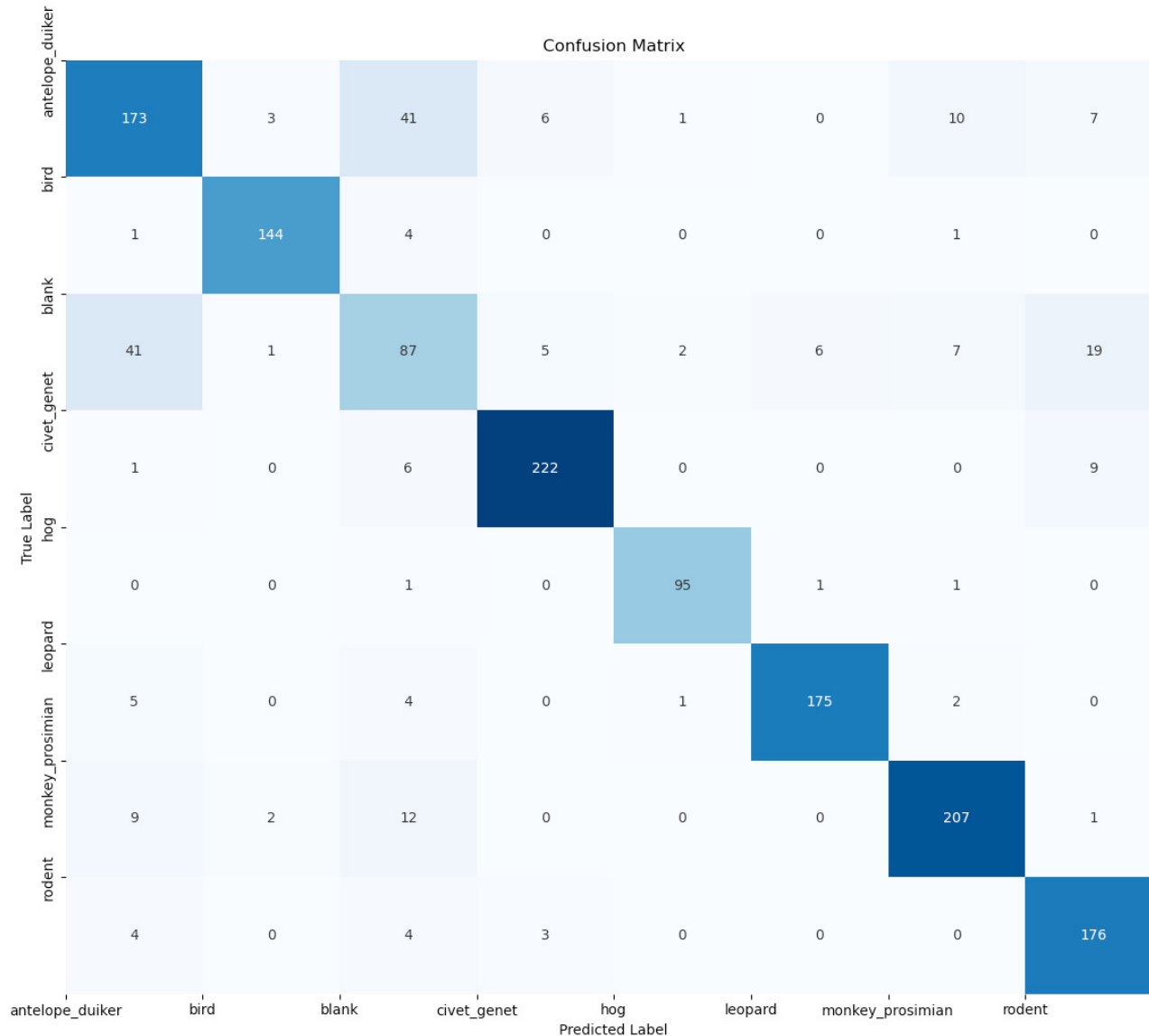


Model 1



Model 1 Training Performance

Epoch	loss	Train Accuracy	val_loss	val_accuracy
1/10	1.6485	0.4776	1.0136	0.6533
2/10	0.8253	0.7172	0.7521	0.7533
3/10	0.5804	0.8067	0.7077	0.7659
4/10	0.4464	0.8516	0.5932	0.8148
5/10	0.3589	0.879	0.5986	0.8278
6/10	0.2985	0.9022	0.67	0.8226
7/10	0.2571	0.9136	0.5778	0.8481
8/10	0.2184	0.93	0.6611	0.8433
9/10	0.2042	0.9331	0.5969	0.8478
10/10	0.1775	0.9462	0.5841	0.8552



Model 1 Confusion Matrix (Holdout Set)

Model 1 Evaluation (Holdout Set)

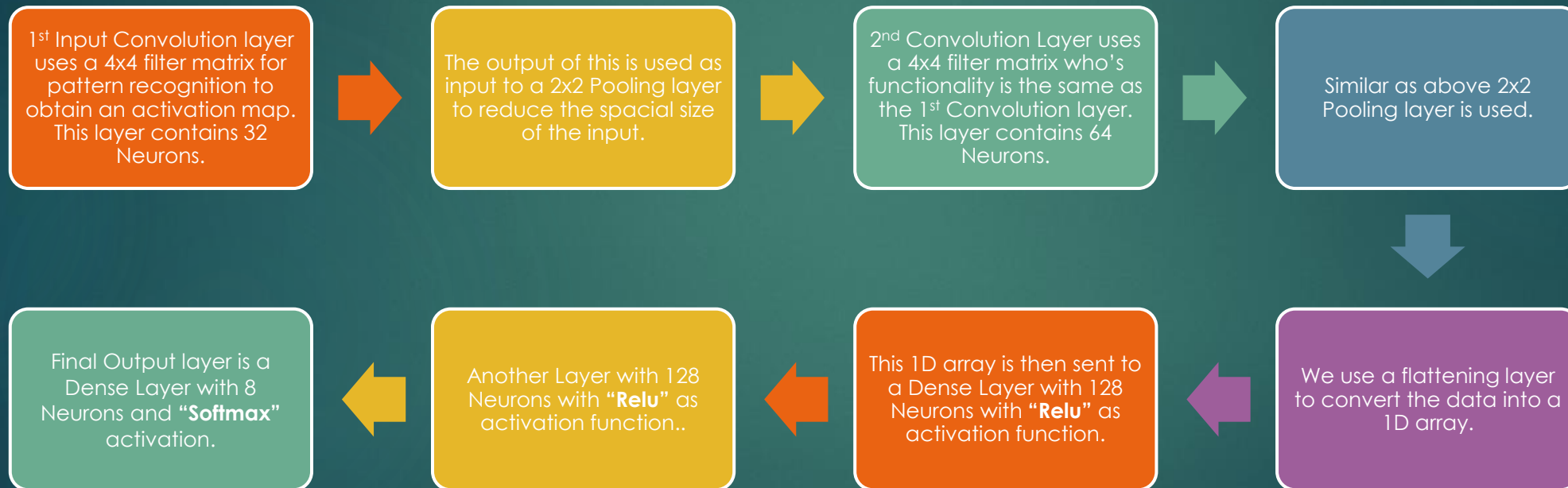
	precision	recall	f1-score	support
antelope_duiker	0.74	0.72	0.73	241
bird	0.96	0.96	0.96	150
blank	0.55	0.52	0.53	168
civet_genet	0.94	0.93	0.94	238
hog	0.96	0.97	0.96	98
leopard	0.96	0.94	0.95	187
monkey_prosimian	0.91	0.9	0.9	231
rodent	0.83	0.94	0.88	187
accuracy			0.85	1500
macro avg	0.86	0.86	0.86	1500
weighted avg	0.85	0.85	0.85	1500

$$loss = -\frac{1}{N} \cdot \sum_{i=1}^N \sum_{j=1}^M y_{ij} \log p_{ij}$$

Model 1
Evaluation
Metric
(Holdout set)
As per
Competition

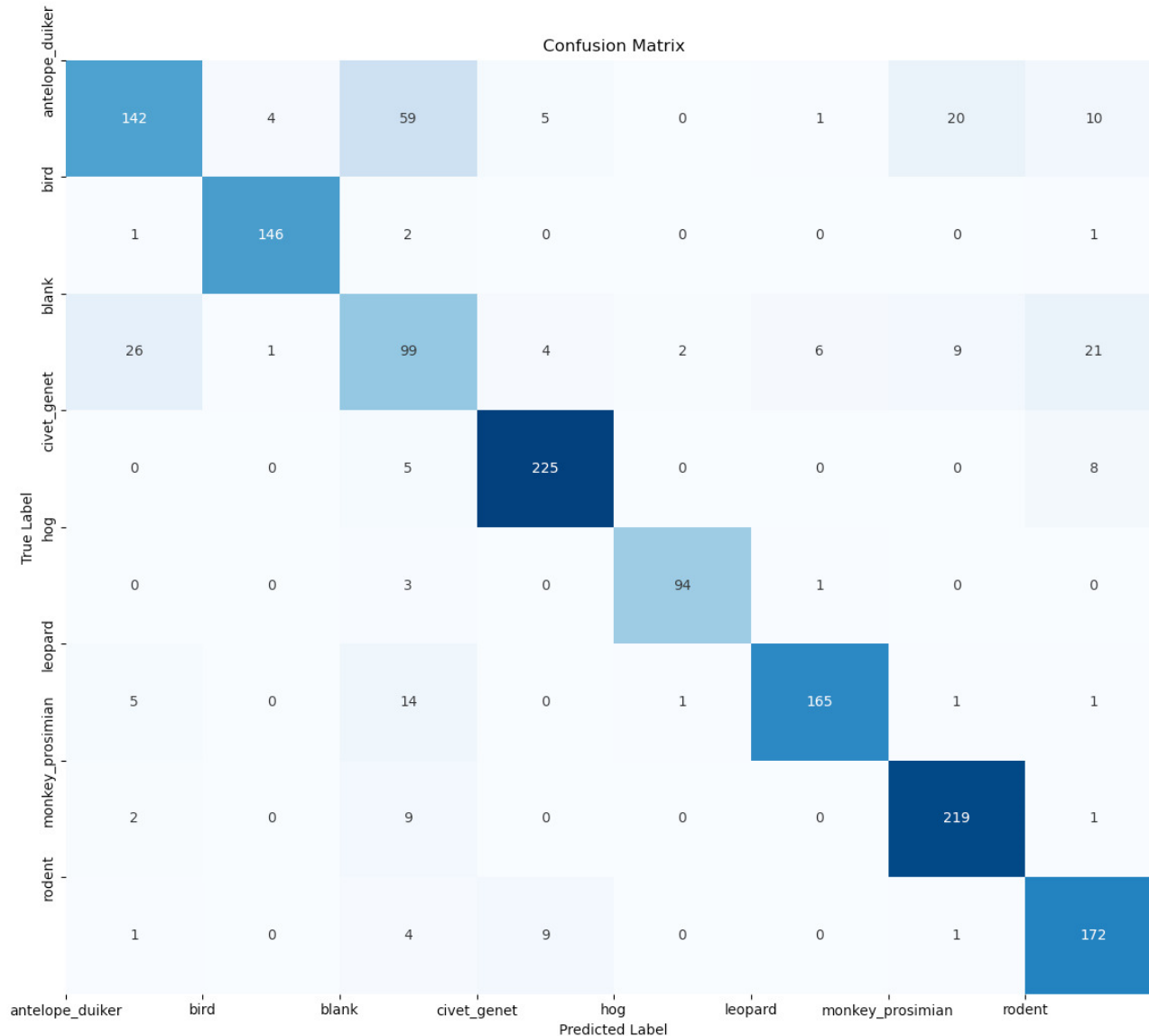
LOG LOSS:
5.310431599329929

Model 2



Model 2 Training Performance

Epoch	loss	Train Accuracy	val_loss	val_accuracy
1/10	1.4448	0.467	1.0601	0.6341
2/10	0.8382	0.7059	0.7758	0.7478
3/10	0.5618	0.8055	0.6781	0.7696
4/10	0.4719	0.8381	0.6456	0.7937
5/10	0.3534	0.8797	0.6427	0.8211
6/10	0.2934	0.8994	0.634	0.8304
7/10	0.251	0.9138	0.6247	0.8422
8/10	0.2173	0.9242	0.6263	0.8522
9/10	0.2059	0.9299	0.6492	0.8404
10/10	0.171	0.9426	0.6462	0.8463



Model 2 Confusion Matrix (Holdout Set)

Model 2 Evaluation (Holdout Set)

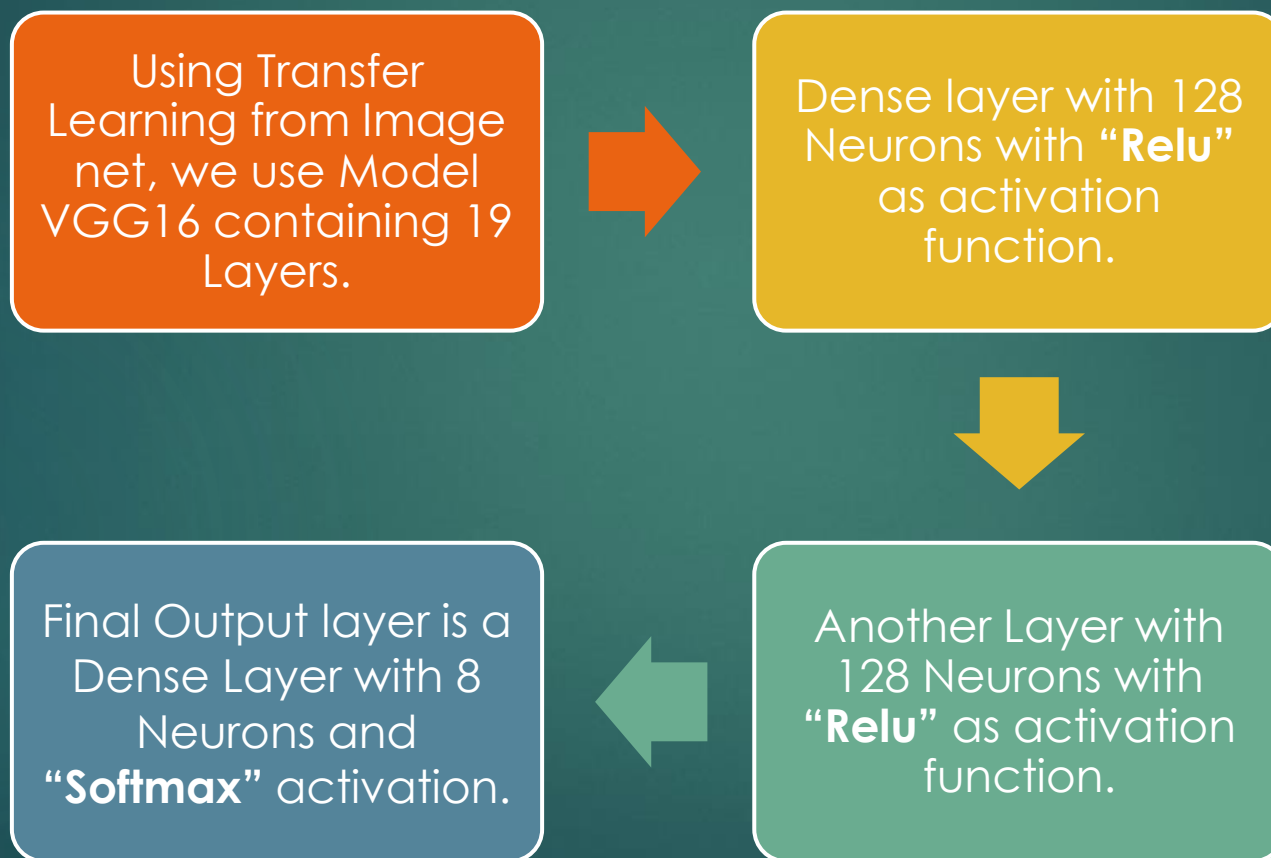
	precision	recall	f1-score	support
antelope_duiker	0.8	0.59	0.68	241
bird	0.97	0.97	0.97	150
blank	0.51	0.59	0.55	168
civet_genet	0.93	0.95	0.94	238
hog	0.97	0.96	0.96	98
leopard	0.95	0.88	0.92	187
monkey_prosimian	0.88	0.95	0.91	231
rodent	0.8	0.92	0.86	187
accuracy			0.84	1500
macro avg	0.85	0.85	0.85	1500
weighted avg	0.85	0.84	0.84	1500

$$loss = -\frac{1}{N} \cdot \sum_{i=1}^N \sum_{j=1}^M y_{ij} \log p_{ij}$$

Model 2
Evaluation
Metric
(Holdout set)
As per
Competition

LOG LOSS:
5.718926337739923

Model 3

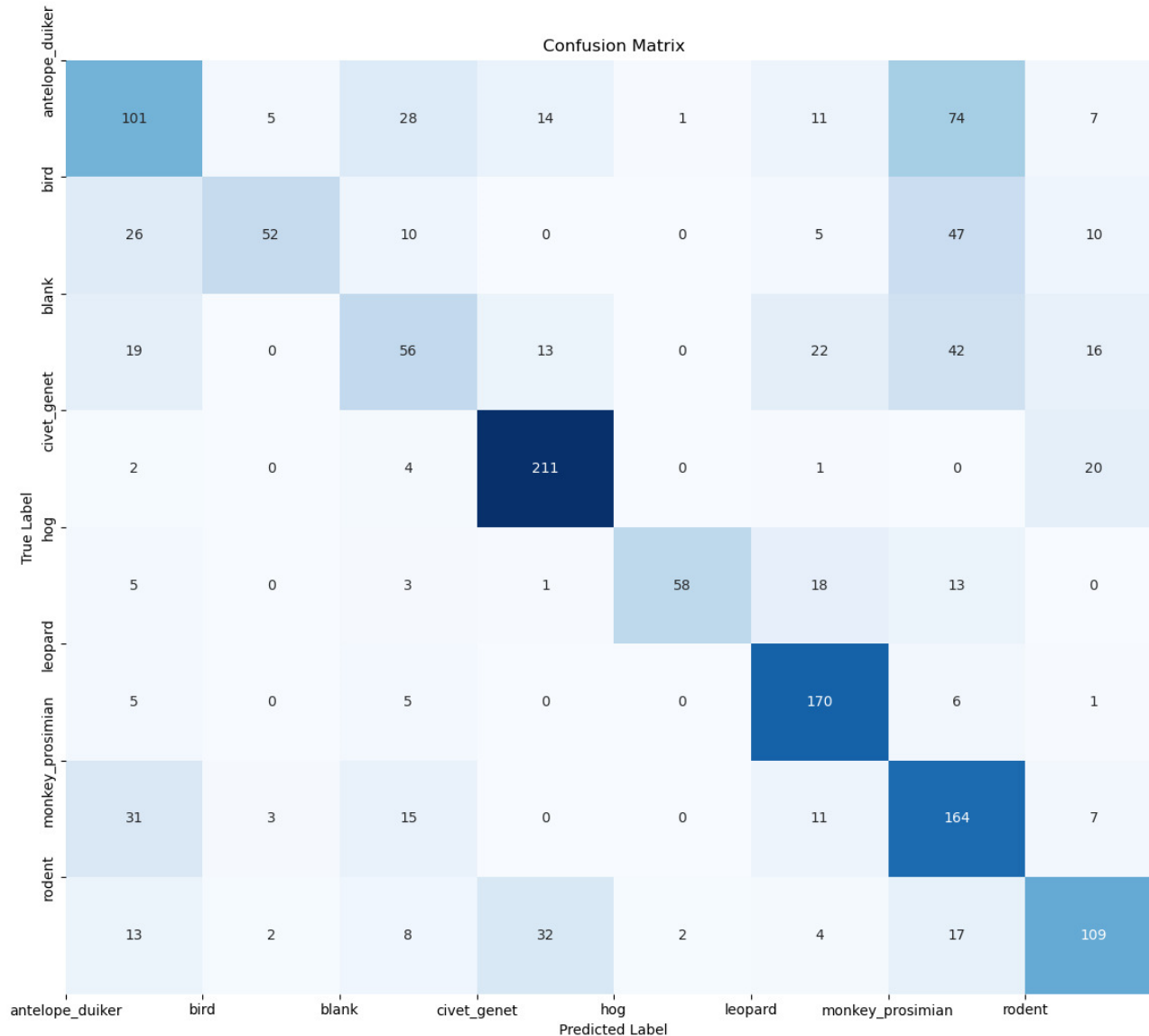


Layer (type)	Output Shape	Param #
=====		
input_4 (InputLayer)	[(None, None, None, 3)]	0
block1_conv1 (Conv2D)	(None, None, None, 64)	1792
block1_conv2 (Conv2D)	(None, None, None, 64)	36928
block1_pool (MaxPooling2D)	(None, None, None, 64)	0
block2_conv1 (Conv2D)	(None, None, None, 128)	73856
block2_conv2 (Conv2D)	(None, None, None, 128)	147584
block2_pool (MaxPooling2D)	(None, None, None, 128)	0
block3_conv1 (Conv2D)	(None, None, None, 256)	295168
block3_conv2 (Conv2D)	(None, None, None, 256)	590080
block3_conv3 (Conv2D)	(None, None, None, 256)	590080
block3_pool (MaxPooling2D)	(None, None, None, 256)	0
block4_conv1 (Conv2D)	(None, None, None, 512)	1180160
block4_conv2 (Conv2D)	(None, None, None, 512)	2359808
block4_conv3 (Conv2D)	(None, None, None, 512)	2359808
block4_pool (MaxPooling2D)	(None, None, None, 512)	0
block5_conv1 (Conv2D)	(None, None, None, 512)	2359808
block5_conv2 (Conv2D)	(None, None, None, 512)	2359808
block5_conv3 (Conv2D)	(None, None, None, 512)	2359808
block5_pool (MaxPooling2D)	(None, None, None, 512)	0
global_average_pooling2d_3 (GlobalAveragePooling2D)	(None, 512)	0
dense_26 (Dense)	(None, 128)	65664
dense_27 (Dense)	(None, 128)	16512
dense_28 (Dense)	(None, 8)	1032
=====		

VGG16

Model 3 Training Performance

Epoch	loss	Train Accuracy	val_loss	val_accuracy
1/20	0.9799	0.636	1.0168	0.6263
2/20	0.952	0.6466	0.9589	0.6515
3/20	0.922	0.6615	1.0022	0.6448
4/20	0.8968	0.6724	0.9483	0.6574
5/20	0.8803	0.6806	0.9231	0.6696
6/20	0.8553	0.6868	0.9054	0.6793
7/20	0.8372	0.6917	0.9324	0.6626
8/20	0.8184	0.7031	0.8867	0.6759
9/20	0.8091	0.7017	0.927	0.6619
10/20	0.7805	0.7138	0.8801	0.6833
11/20	0.7694	0.7175	0.8674	0.6856
12/20	0.7583	0.7226	0.8499	0.7011
13/20	0.7558	0.7194	0.8393	0.7044
14/20	0.7308	0.7336	0.8546	0.6944
15/20	0.7178	0.7374	0.8113	0.7107
16/20	0.7018	0.7426	0.8036	0.717
17/20	0.6918	0.7468	0.7951	0.7152
18/20	0.6743	0.7537	0.8207	0.7163
19/20	0.67	0.7533	0.8125	0.7237
20/20	0.6631	0.7594	0.7688	0.72



Model 3 Confusion Matrix (Holdout Set)

Model 3 Evaluation (Holdout Set)

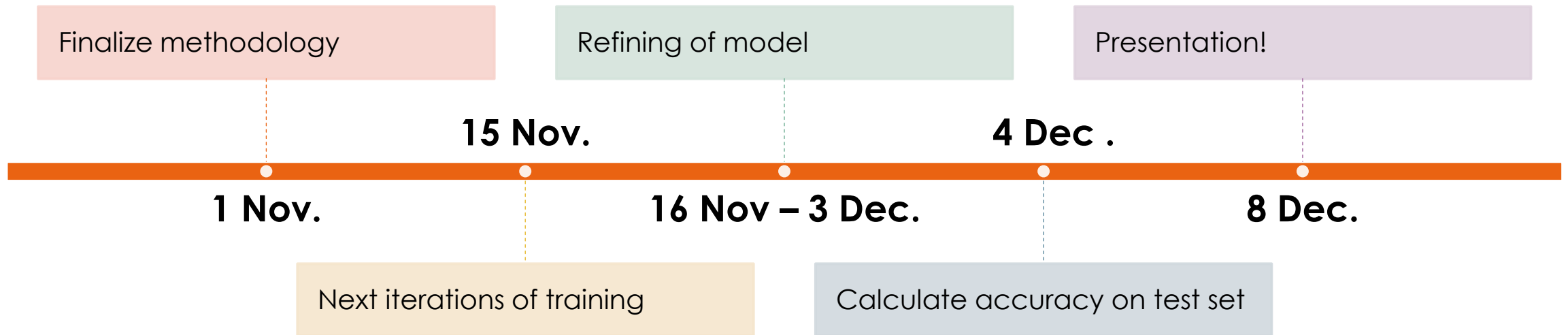
	precision	recall	f1-score	support
antelope_duiker	0.5	0.42	0.46	241
bird	0.84	0.35	0.49	150
blank	0.43	0.33	0.38	168
civet_genet	0.78	0.89	0.83	238
hog	0.95	0.59	0.73	98
leopard	0.7	0.91	0.79	187
monkey_prosimian	0.45	0.71	0.55	231
rodent	0.64	0.58	0.61	187
accuracy			0.61	1500
macro avg	0.66	0.6	0.6	1500
weighted avg	0.64	0.61	0.6	1500

$$loss = -\frac{1}{N} \cdot \sum_{i=1}^N \sum_{j=1}^M y_{ij} \log p_{ij}$$

Model 3
Evaluation
Metric
(Holdout set)
As per
Competition

LOG LOSS:
13.912850208199224

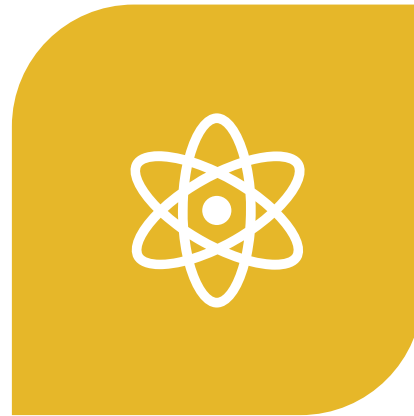
Project Timeline



Team Roles



ASEEM MISHRA – MODEL
DESIGN AND TRAINING



MARTIN EMMANUEL – TESTING
AND REFINING MODEL



SAGAR SHETH – DATA PRE
PROCESSING

Thank you