

# Lines, Planes, and Hyperplanes.

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April 22, 2015

## Question

What defines a line?

## Answer

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1. two points,

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## Answer

1. two points,
2. point and direction/slope.

## Definition (Vector Equations of a Line)

Let  $\mathbf{r}_0$  (position) and  $\mathbf{v}$  (direction/slope) be vectors of  $\mathbb{R}^n$  and  $t \in \mathbb{R}$  a scalar. Then

$$\mathbf{r}(t) = \mathbf{r}_0 + t\mathbf{v}$$

is the **vector equation** of a line.

This is also called the **parametric form** of the line because the line's points are parameterized by  $t$ .

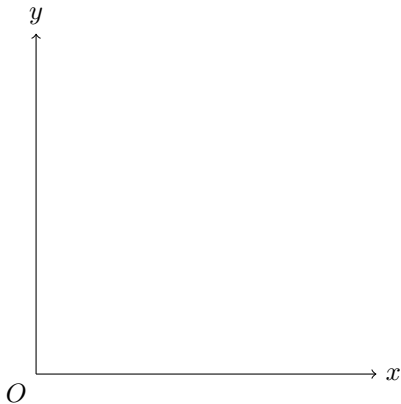
## Definition (Direction Numbers)

When  $\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$  the components of the line  $\mathbf{v}$  are called the **direction numbers** of  $L$ .

Note **any** vector parallel to  $\mathbf{v}$  could be used to define the same line.

## Example

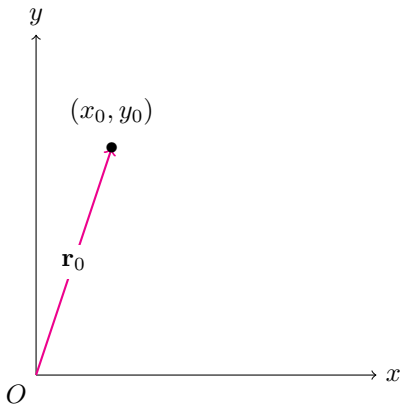
The line  $L$  as described by two vectors (i.e. a point  $\mathbf{r}_0$  and direction  $\mathbf{v}$ ).



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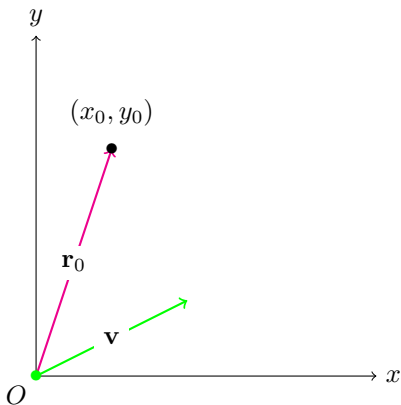


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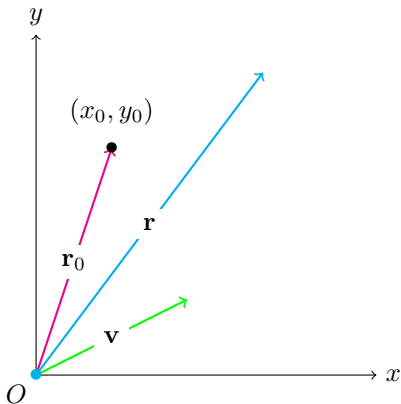
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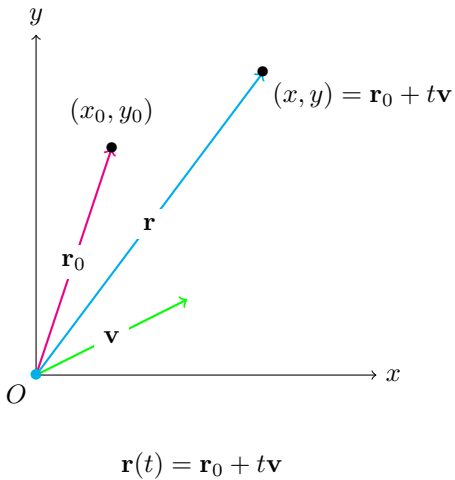
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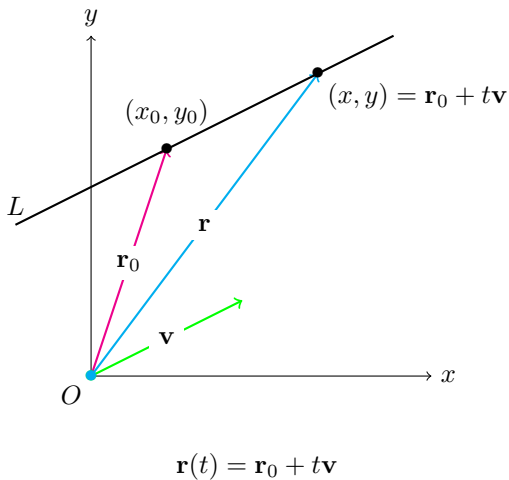
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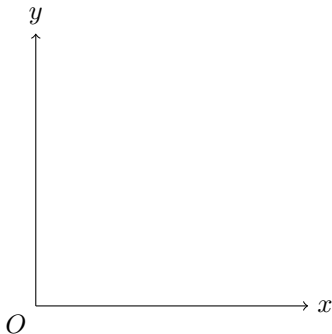
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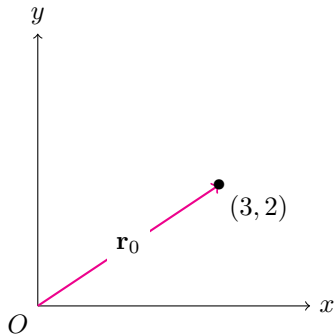


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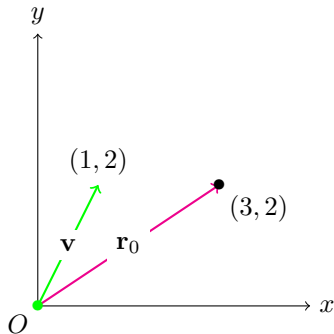


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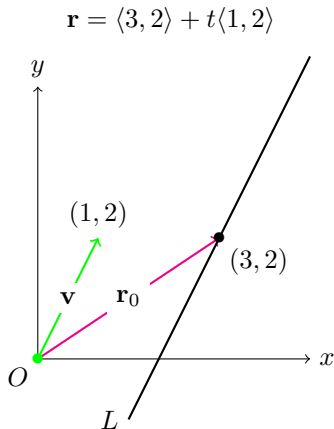




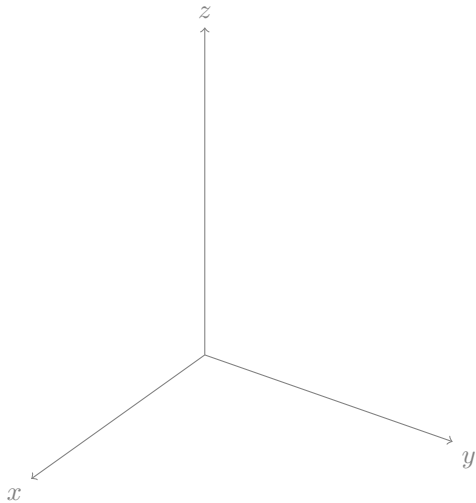
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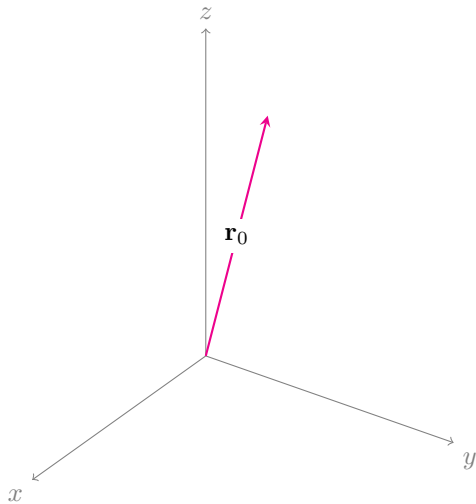


Extending to  $\mathbb{R}^3$



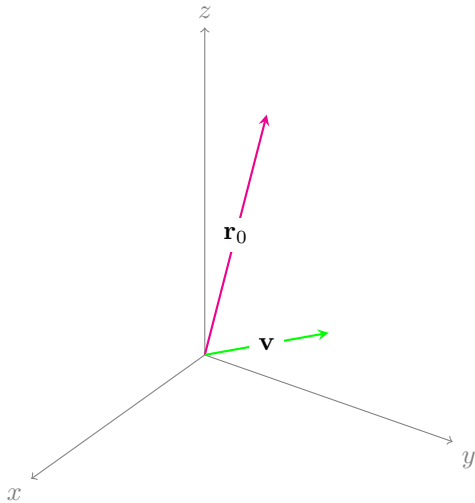
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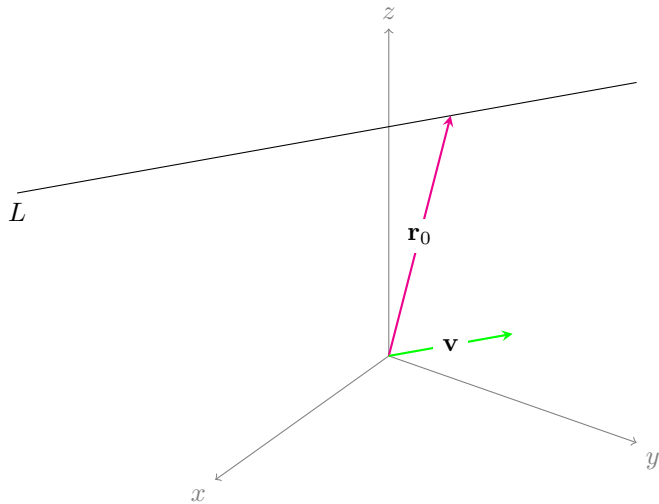
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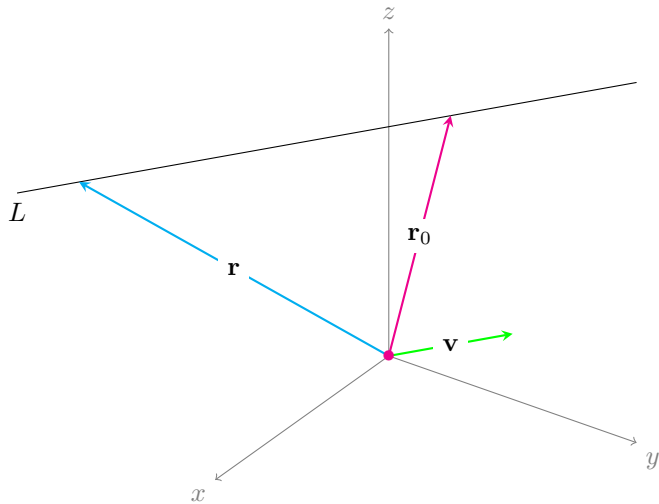
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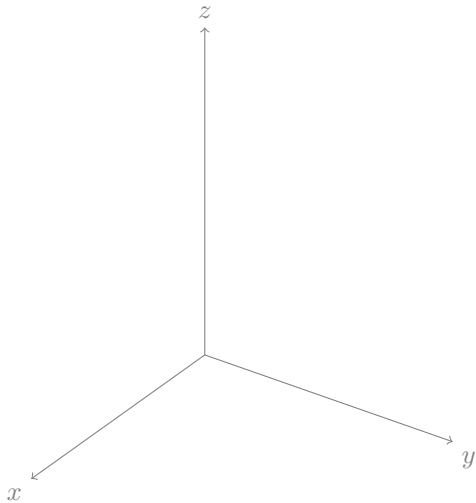
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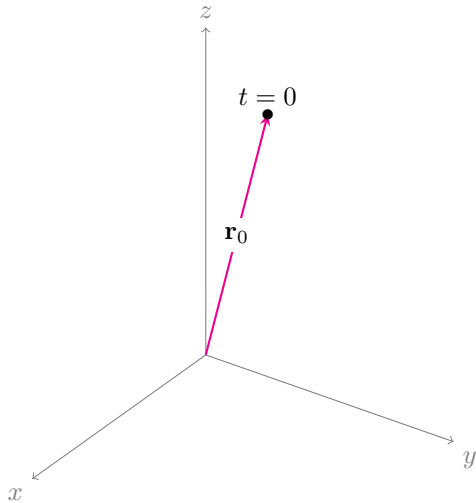
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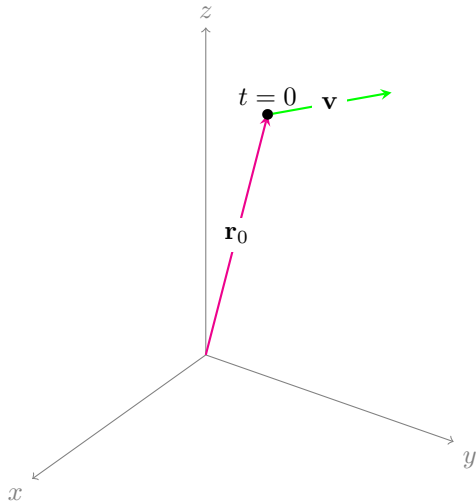
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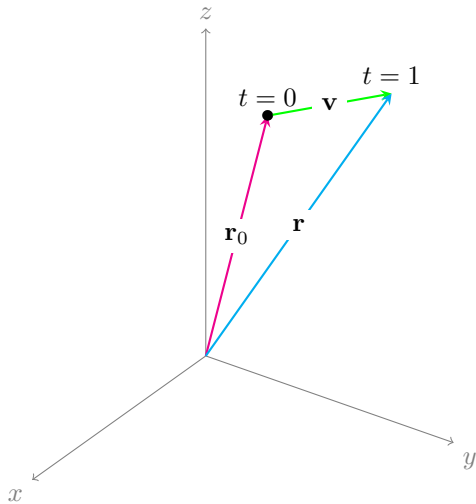


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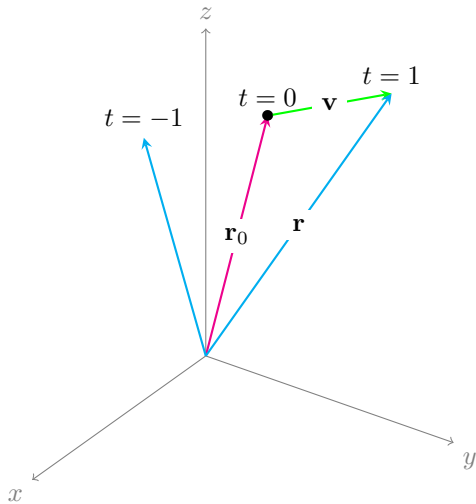
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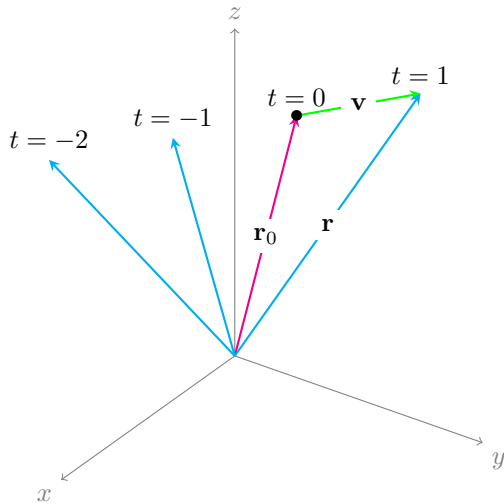
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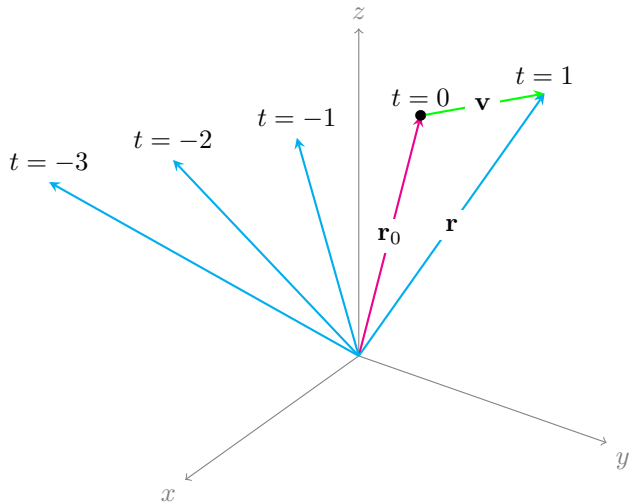
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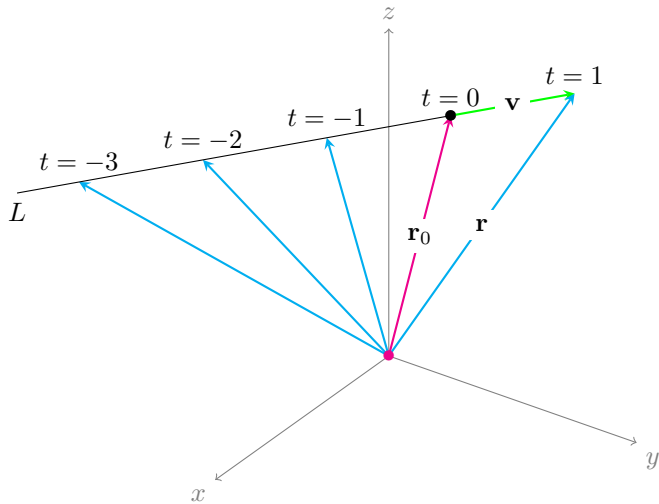
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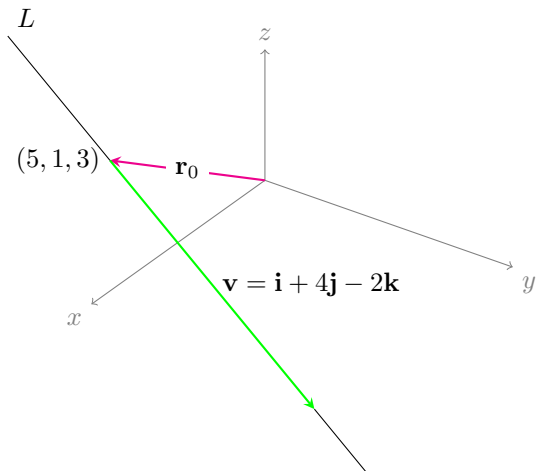
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## Question

Find a vector equation and parametric equations for the line that passes through the point  $(5, 1, 3)$  and is parallel to the vector  $\mathbf{i} + 4\mathbf{j} - 2\mathbf{k}$ .

Find two other points on the line.

## Example





## Answer

Here  $\mathbf{r}_0 = \langle 5, 1, 3 \rangle$  and  $\mathbf{v} = \mathbf{i} + 4\mathbf{j} - 2\mathbf{k} = \langle 1, 4, -2 \rangle$ .

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$$

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$$\begin{aligned}\mathbf{r} &= \mathbf{r}_0 + t\mathbf{v} \\ &= \langle 5, 1, 3 \rangle + t\langle 1, 4, -2 \rangle\end{aligned}$$

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$$\begin{aligned}\mathbf{r} &= \mathbf{r}_0 + t\mathbf{v} \\ &= \langle 5, 1, 3 \rangle + t\langle 1, 4, -2 \rangle\end{aligned}$$

Two other points are given by  $t = -1$  and  $t = 1$ :

$$\langle 4, -3, 5 \rangle \qquad \qquad \qquad \langle 6, 5, 1 \rangle.$$

## Symmetric Equation

Notice  $\mathbf{r} = \langle 5, 1, 3 \rangle + t\langle 1, 4, -2 \rangle$  is equivalent to

$$\langle x, y, z \rangle = \langle 5, 1, 3 \rangle + t\langle 1, 4, -2 \rangle$$

which means we have the set of equations

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Solving for  $t$  gives

$$t = \frac{x - 5}{2}$$

$$t = \frac{y - 1}{8}$$

$$t = \frac{z - 3}{-4}.$$

and therefore

$$\frac{x - 5}{2} = \frac{y - 1}{8} = \frac{z - 3}{-4}$$

is another description of the line.

In three space, when  $a, b, c \neq 0$ ,

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

defines a line through  $(x_0, y_0, z_0)$  with slope  $\langle a, b, c \rangle$ .

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## Definition (Symmetric Form of a Line)

In  $\mathbb{R}^n$  when  $\mathbf{x} = \langle x_0, \dots, x_{n-1} \rangle$  is a vector-valued variable,

$\mathbf{p} = \langle p_0, \dots, p_{n-1} \rangle$  is a fixed, and  $\mathbf{a} = \langle a_0, \dots, a_{n-1} \rangle \in (\mathbb{R} - \{0\})^n$  then

$$\frac{x_0 - p_0}{a_0} = \dots = \frac{x_{n-1} - p_{n-1}}{a_{n-1}}$$

defines a line through  $\mathbf{p}$  with direction  $\mathbf{a}$ .



## Question

Find the **parametric** and **symmetric** equations of the line through  $(2, 4, -3)$  and  $(3, -1, 1)$ .

Where does this line intersect the  $xy$ -plane?

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## Answer

We are not explicitly given a direction vector but notice

$$\mathbf{v} = \langle 3, -1, 1 \rangle - \langle 2, 4, -3 \rangle = \langle 1, -5, 4 \rangle$$

is the direction of the line. We need only pick either  $(2, 4, -3)$  or  $(3, -1, 1)$  as  $\mathbf{r}_0$ .

## Answer (Continued)

Therefore the **parametric** equation of the line is given by

$$\langle x, y, z \rangle = \langle 2, 4, -5 \rangle + t \langle 1, -5, 4 \rangle$$

for  $t \in \mathbb{R}$  a parameter.

## Answer (Continued)

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The **symmetric** equation is

$$\frac{x - 2}{1} = \frac{y - 4}{-5} = \frac{z + 3}{4}.$$

and thus when in the  $xy$ -plane where  $z = 0$ ,  $x$  and  $y$  are given by

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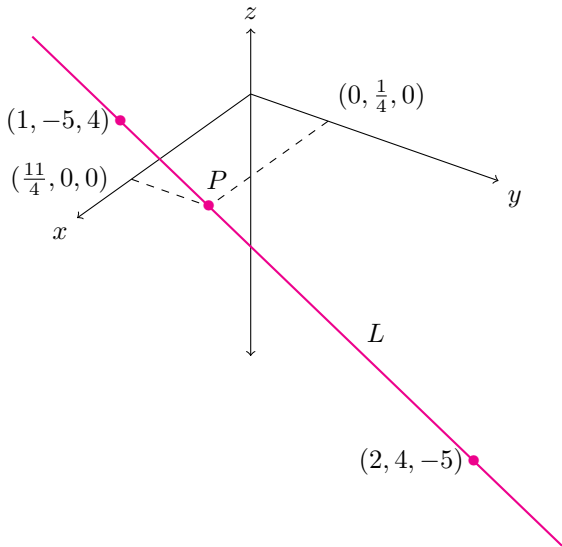
$$\frac{x-2}{1} = \frac{y-4}{-5} = \frac{3}{4}$$

which implies

$$x = \frac{11}{4} \qquad y = \frac{1}{4}.$$

## Answer (Continued)

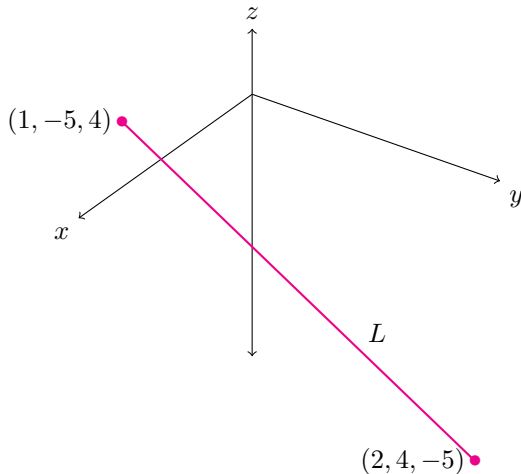
The line intersects the  $xy$  axis when  $z = 0$ .



# Line Segments

We can also use parameterized curves to describe **line segments**:

$$\mathbf{r}(t) = \langle 2 + t, 4 - 5t, -3 + 4t \rangle \quad t \in [0, 1]$$





# Line Segments

## Proposition

The line through the (tail of the) vectors  $\mathbf{r}_0$  and  $\mathbf{r}_1$  is given by

$$\mathbf{r}(t) = \mathbf{r}_0 + t(\mathbf{r}_1 - \mathbf{r}_0)$$

where the line segment given by  $\mathbf{r}_0$  and  $\mathbf{r}_1$  is in the interval  $t \in [0, 1]$ .

## Definition (Skew)

Two lines  $L_0$  and  $L_1$  are skew when they **do not intersect** and **are not parallel**.

## Example

Show that the lines  $L_0$  (parameterized by  $t$ ) and  $L_1$  (parameterized by  $s$ ) with the parametric equations

$$x = 1 + t$$

$$y = -2 + 3t$$

$$z = 4 - t$$

$$x = 2s$$

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The corresponding direction vectors for  $L_0$  and  $L_1$  are

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which are not scalar multiples of one another — thus the lines cannot be parallel.

It remains to show the lines do not intersect.

## Answer (Continued)

Towards a contradiction, suppose the lines **do** have a point of intersection given by

$$1 + t = 2s$$

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Notice substituting the second ( $s = -5 + 3t$ ) into the first gives

$$1 + t = -10 + 6t \implies$$

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$$1 + t = -10 + 6t \implies 5t = 11 \implies$$



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which means  $s =$

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which means  $s = \frac{1+t}{2} = \frac{8}{5}$ .

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This implies, by the third equation, that

$$4 - \frac{11}{5} = 2\frac{8}{5} \implies \frac{-39}{20} = 0 \quad \textcolor{red}{\text{⚡}}$$

## Question

What is defined by

1. **three** points, or
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## Answer

A plane.

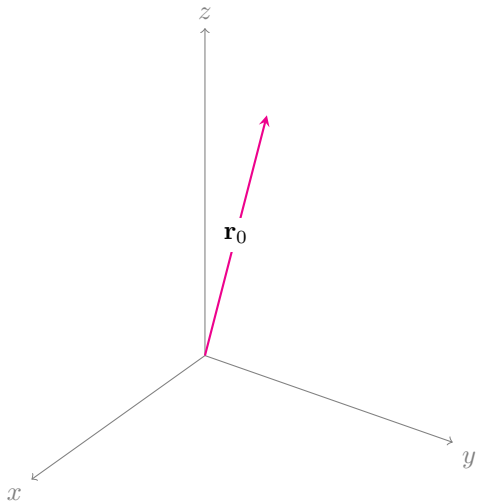
## Definition (Parametric Equation of Plane)

Let  $\mathbf{r}_0$  (position) and  $\mathbf{v}_0, \mathbf{v}$  (direction) be vectors of  $\mathbb{R}^n$  and  $s, t \in \mathbb{R}$  a scalar.  
Then

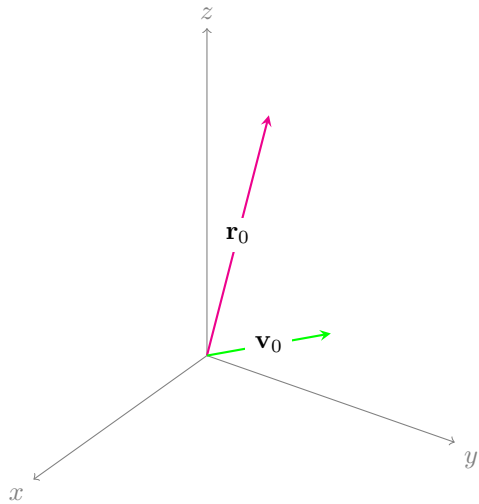
$$\mathbf{r}(s, t) = \mathbf{r}_0 + s\mathbf{v}_0 + t\mathbf{v}_1$$

defines a **plane** in  $\mathbb{R}^n$ .

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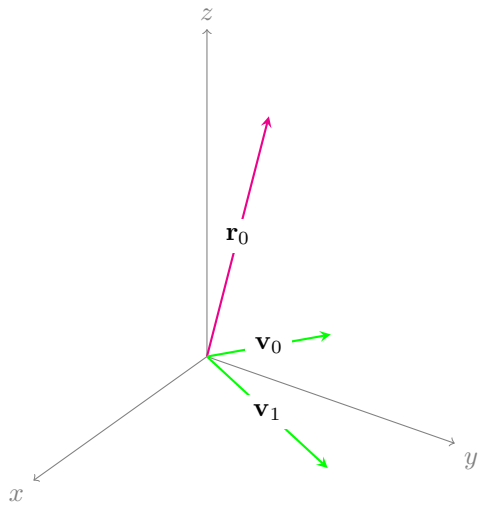


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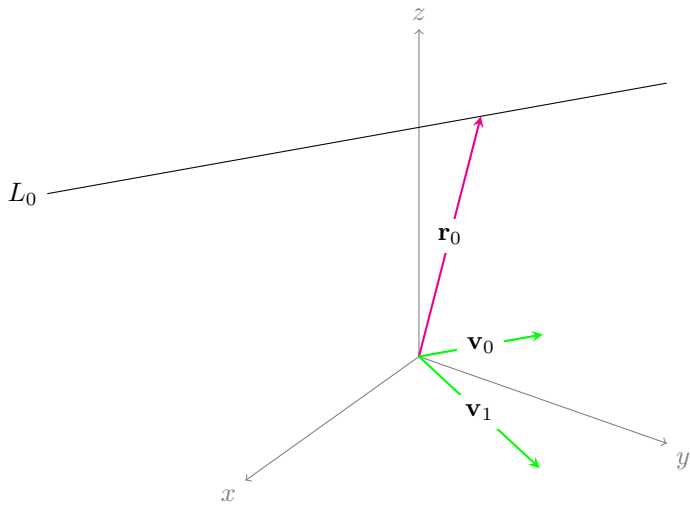




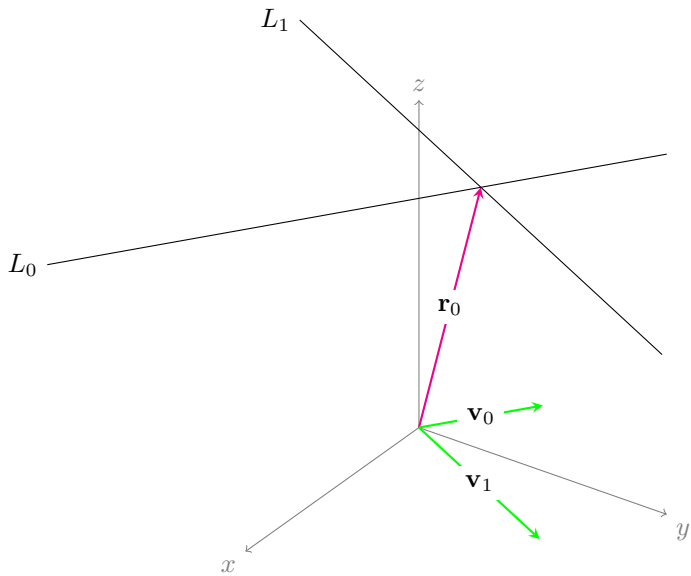
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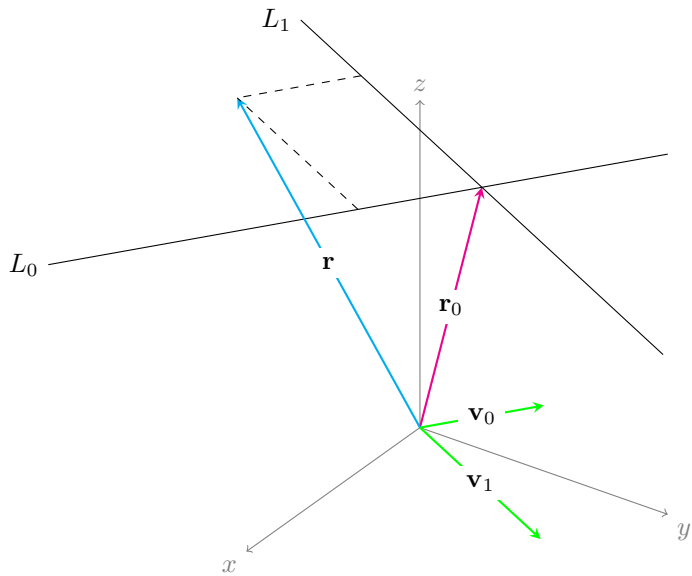
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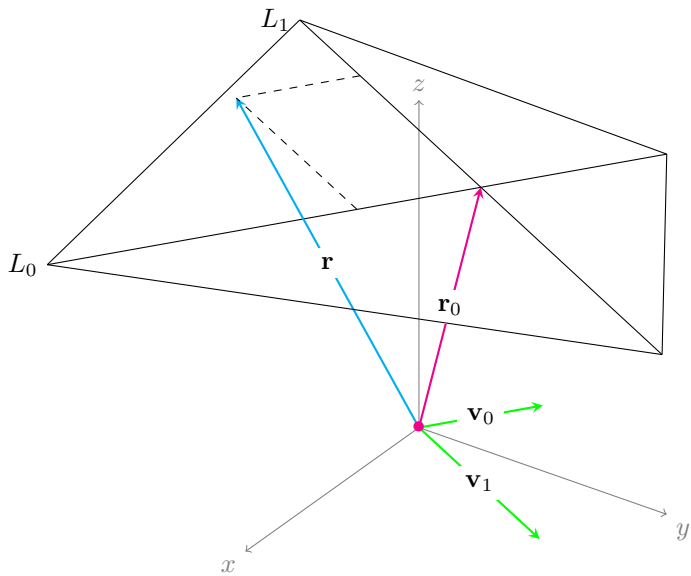
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Notice however, that the two vectors  $\mathbf{v}_0$  and  $\mathbf{v}_1$  uniquely (up to scalar multiple) define a cross product and that this cross product can instead be used to define the vector.

This cross product is called the **normal** of the plane given by  $\mathbf{v}_0$  and  $\mathbf{v}_1$ . We denote by

$$\mathbf{n} = \mathbf{v}_0 \times \mathbf{v}_1.$$

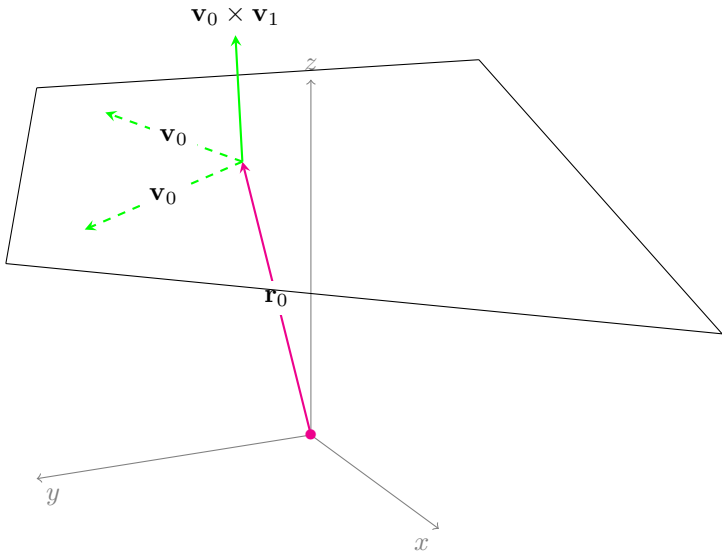
Notice however, that the two vectors  $\mathbf{v}_0$  and  $\mathbf{v}_1$  uniquely (up to scalar multiple) define a cross product and that this cross product can instead be used to define the vector.

This cross product is called the **normal** of the plane given by  $\mathbf{v}_0$  and  $\mathbf{v}_1$ . We denote by

$$\mathbf{n} = \mathbf{v}_0 \times \mathbf{v}_1.$$

Note **every** vector in the plane is orthogonal to this normal vector.

## Example





## Definition (Vector Equation of the Plane)

Let  $\mathbf{n}$  be a vector and  $\mathbf{r}_0$  be a fixed position vector. The plane through  $\mathbf{r}_0$  with normal  $\mathbf{n}$  is given by

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

for vector-valued variable  $\mathbf{r}$ .

Equivalently we may also write

$$\mathbf{n} \cdot \mathbf{r} = \mathbf{n} \cdot \mathbf{r}_0$$

for the plane.

## Scalar Equation of the Plane

To obtain a scalar equation for the plane write

$$\mathbf{n} = \langle a, b, c \rangle \qquad \mathbf{r} = \langle x, y, z \rangle \qquad \mathbf{r}_0 = \langle x_0, y_0, z_0 \rangle$$

and recall the vector equation of the plane is given by  $\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0)$  or

$$\langle a, b, c \rangle \cdot \mathbf{r} = \langle x - x_0, y - y_0, z - z_0 \rangle.$$

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$$\langle a, b, c \rangle \cdot \mathbf{r} = \langle a, b, c \rangle \cdot \mathbf{r}_0.$$

Expanding yields

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

as the equation of the plane in  $\mathbb{R}^3$  — a kind of “point-normal” analogue of the point-slope equation for the line.

## Definition (Scalar Equation of the Plane)

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## Definition (Linear Equation of the Plane)

Let  $a, b, c, d$  be reals and  $x, y, z$  real valued variables. Then

$$ax + by + cz + d = 0$$

defines the plane in three-space.

## Question

Consider the plane given by

$$2(x - 1) - 3(y - 2) + 7(z) = 0.$$

1. What is this planes normal?

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$$2(x - 1) - 3(y - 2) + 7(z) = 0.$$

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2. Give a point where this plane passes through.  $(1, 2, 0)$ .

## Question

Find an equation of the plane through the point  $(2, 4, -1)$  with normal  $\mathbf{n} = \langle 2, 3, 4 \rangle$ . Find where this plane intersects the  $x$ ,  $y$ , and  $z$  axis and sketch the plane.

## Question

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## Answer

Trivially, the plane is given by  $\mathbf{n} \cdot \langle x - 2, y - 4, z + 1 \rangle$  or equivalently

$$2(x - 2) + 3(y - 4) + 4(z - 1) = 0$$

$$\implies 2x + 3y + 4z = 12.$$

## Answer (Continued)

The  $x$ -intercept is found by setting  $y = z = 0$  (and so on). Doing so yields

$$x = 6$$

$$y = 4$$

$$z = 3.$$

So we have the plane passes through

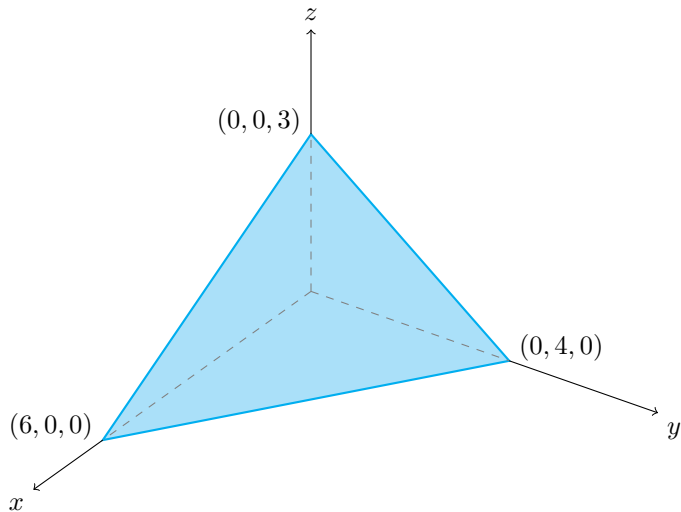
$$(6, 0, 0)$$

$$(0, 4, 0)$$

$$(0, 0, 3)$$

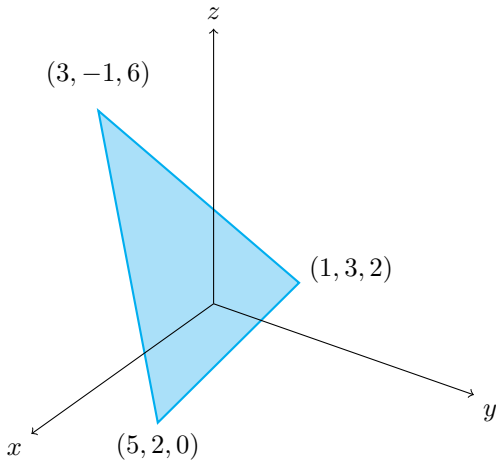
which we can sketch.

Answer (Continued)



## Question

Find an equation of the plane that passes through the points  $(1, 3, 2)$ ,  $(3, -1, 6)$ , and  $(5, 2, 0)$ .



## Answer

We can get two (arbitrary) direction vectors from these three points. (The vectors should be given from the same tail.)

$$\mathbf{v}_0 = \langle 3, -1, 6 \rangle - \langle 1, 3, 2 \rangle = \langle 2, -4, 4 \rangle$$

$$\mathbf{v}_1 = \langle 5, 2, 0 \rangle - \langle 1, 3, 2 \rangle = \langle 4, -1, -2 \rangle$$

## Answer (Continued)

The normal to the plane is then  $\langle 2, -4, 4 \rangle \times \langle 4, -1, -2 \rangle$  which we compute by

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & -4 & 4 \\ 4 & -1 & -2 \end{vmatrix} = \begin{vmatrix} -4 & 4 \\ -1 & -2 \end{vmatrix} \mathbf{i} - \begin{vmatrix} 2 & 4 \\ 4 & -2 \end{vmatrix} \mathbf{j} + \begin{vmatrix} 2 & -4 \\ 4 & -1 \end{vmatrix} \mathbf{k} \\ = \langle 12, 20, 14 \rangle.$$



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$$12(x - 1) + 20(y - 3) + 12(z - 2) = 0$$

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$$12(x - 1) + 20(y - 3) + 12(z - 2) = 0$$

which simplifies to the linear equation

$$6x + 10y + 7z = 50.$$

## Question

Find the point at which the line

$$x = 2 + 3t$$

$$y = -4t$$

$$z = 5 + t$$

intersects the plane  $4x + 5y - 2z = 18$ .

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## Note

What are the types of intersections we can get here?

## Answer

The point or line of intersection must be those points  $(x, y, z)$  satisfying both equations simultaneously. Thus we substitute the points of the line into the equation of the plane

$$4(2 + 3t) + 5(-4t) - 2(5 + t) = 18$$

and solve for  $t$

$$t = -2.$$

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Thus the **point** of intersection is

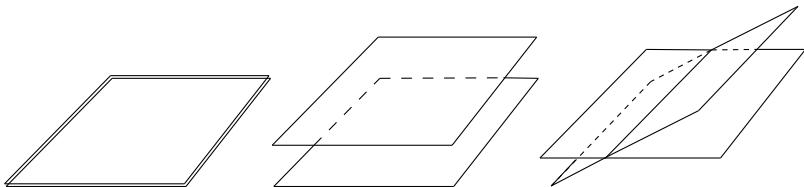
$$(2 + 3(-2), -4(-2), 5 + (-2)) = (-4, 8, 3).$$



## Definition

Two **planes** are **parallel** if their normal vectors are parallel. (Note this does not preclude that the planes are identical.)

In fact, the only types of intersection the plane can have are:



## Question

Are the two planes given by

$$x + 2y - 3z = 4$$

$$2x + 4y - 6z = 3$$

parallel?

## Question

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$$x + 2y - 3z = 4$$

$$2x + 4y - 6z = 3$$

parallel?

## Answer

Yes.

## Question

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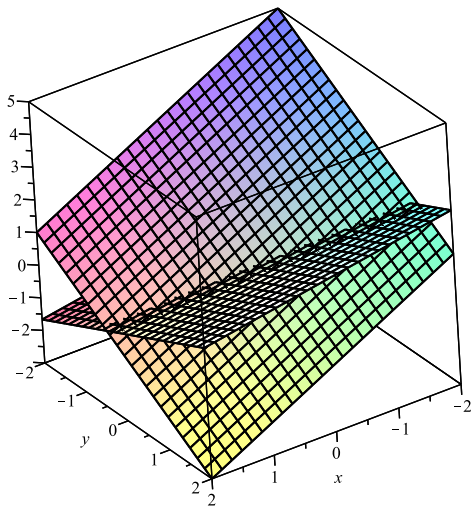
parallel?

## Answer

Yes. The normals are  $\langle 1, 2, -3 \rangle$  and  $\langle 2, 4, -6 \rangle$  respectively — which are clearly parallel because they only differ by the scalar multiple 2.

## Question

Find the angle between the planes  $x + y + z = 1$  and  $x - 2y + 3z = 1$  and then give the line of intersection as a symmetric equation.



(Recall:  $x + y + z = 1$  and  $x - 2y + 3z = 1$  )

## Answer

The normal vector of these planes are

$$\mathbf{n}_0 = \langle 1, 1, 1 \rangle \qquad \mathbf{n}_1 = \langle 1, -2, 3 \rangle$$

Notice the angle between the planes is the same as the angle between the normals which is given by

$$\begin{aligned} \cos \theta &= \frac{\mathbf{n}_0 \cdot \mathbf{n}_1}{|\mathbf{n}_0||\mathbf{n}_1|} \\ &= \frac{1(1) + 1(-2) + 1(3)}{\sqrt{1+1+1}\sqrt{1+4+9}} \\ &= \frac{2}{\sqrt{42}} \implies \theta \approx 72^\circ. \end{aligned}$$

## Answer (Continued)

Now for the line of intersection.

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Remember, every line of a plane is perpendicular to the plane's normal.

Thus a line in **two** planes must be perpendicular to **both** normals.



## Answer (Continued)

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Remember, every line of a plane is perpendicular to the plane's normal.

Thus a line in **two** planes must be perpendicular to **both** normals.

However, there is a unique (up to scalar multiple) vector  $\mathbf{v}$  perpendicular to  $\mathbf{n}_0$  and  $\mathbf{n}_1$  and that is

$$\mathbf{v} = \mathbf{n}_0 \times \mathbf{n}_1 = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 1 & 1 \\ 1 & -2 & 3 \end{vmatrix} = \langle 5, -2, -3 \rangle.$$

That is, this is the **direction vector** for the line! All we need now is a point.

(Recall:  $x + y + z = 1$  and  $x - 2y + 3z = 1$  )

### Answer (Continued)

As any point on both planes will do let us solve for when  $z = 0$  in both equations (i.e. a solution in the  $xy$ -plane). That is, we want a solution of

$$x + y - 1 = 0$$

$$x - 2y - 1 = 0$$

(Recall:  $x + y + z = 1$  and  $x - 2y + 3z = 1$  )

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$$3y = 0$$

and thus

$$(1, 0, 0)$$

is a point on both planes. (Check.)

## Answer (Continued)

The line of intersection is given by

$$\langle x, y, z \rangle = \langle 1, 0, 0 \rangle + t\langle 5, -2, -3 \rangle$$

which corresponds to the symmetric equation

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$$\langle x, y, z \rangle = \langle 1, 0, 0 \rangle + t \langle 5, -2, -3 \rangle$$

which corresponds to the symmetric equation

$$\frac{x-1}{5} = \frac{y-0}{-2} = \frac{z-0}{-3}.$$

## Alternate Definition of a Line

It stands to reason that we can define lines in three-space by the intersection of two planes.

### Proposition

In general, the equation of a line given by

$$\frac{x - a_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

can be regarded to be the line of intersection of the two planes

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} \qquad \frac{y - y_0}{b} = \frac{z - z_0}{c}.$$

## Question

Find a formula for the distance  $D$  from point  $P = (x_1, y_1, z_1)$  to the plane  $ax + by + cz + d = 0$ .



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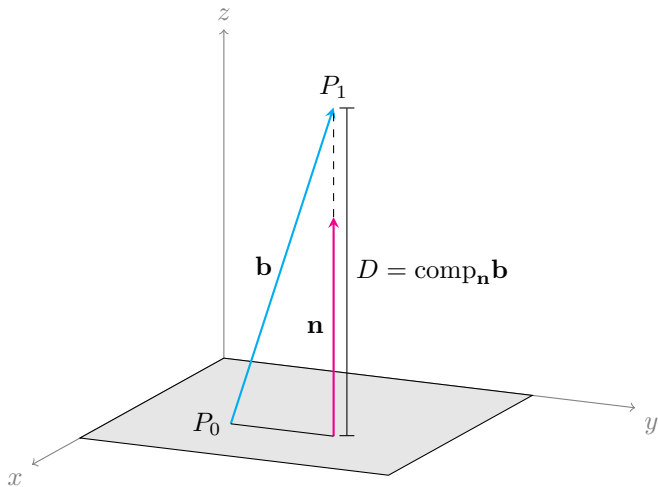
## Answer

Let  $(x_0, y_0, z_0)$  be a point from the plane and let

$$\mathbf{b} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle$$

The shortest distance to the plane is given by the projection of the vector  $\mathbf{b}$  into the normal  $\mathbf{n} = \langle a, b, c \rangle$  of the plane.

## Answer (Continued)



## Answer (Continued.)

So, we need only calculate the **component** (i.e. the length of the projection) of  $\mathbf{b} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle$  onto  $\mathbf{n} = \langle a, b, c \rangle$ :

$$\begin{aligned} D &= |\text{comp}_{\mathbf{n}} \mathbf{b}| \\ &= \frac{|\mathbf{n} \cdot \mathbf{b}|}{|\mathbf{n}|} \\ &= \frac{|a(x_1 - x_0) + b(y_1 - y_0) + c(z_1 - z_0)|}{\sqrt{a^2 + b^2 + c^2}} \\ &= \frac{|(ax_1 + by_1 + cz_1) - (ax_0 + by_0 + cz_0)|}{\sqrt{a^2 + b^2 + c^2}}. \end{aligned}$$

By definition.

## Answer (Continued)

We have calculated the distance from  $P_1$  to **any** point  $P_0$  on the plane with normal  $\langle a, b, c \rangle$  is

$$D = \frac{|(ax_1 + by_1 + cz_1) - (ax_0 + by_0 + cz_0)|}{\sqrt{a^2 + b^2 + c^2}}.$$

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However, as we know  $(x_0, y_0, z_0)$  is on the plane we must have

$$ax_0 + by_0 + cz_0 + d = 0$$

and thereby  **$ax_0 + by_0 + cz_0 = -d$** . (Notice that the point  $(x_0, y_0, z_0)$  has been eliminated from the equation!)

## Answer (Continued)

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Thus, this is the “distance to the plane” is

$$D = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}}.$$

## Again with algebra

Let us repeat this answer using the algebra rules instead of using explicit points. That is, we calculate the distance from arbitrary point  $\mathbf{x}_1$  to the plane given by  $ax + by + cz + d = 0$  with normal  $\mathbf{n} = \langle a, b, c \rangle$

Let  $\mathbf{x}_0$  lie on the plane (thus  $\mathbf{n} \cdot \mathbf{x}_0 = -d$ ) and let  $\mathbf{b} = \mathbf{x}_0 - \mathbf{x}_1$

$$\begin{aligned} D = |\text{comp}_{\mathbf{n}} \mathbf{b}| &= \frac{|\mathbf{n} \cdot \mathbf{b}|}{|\mathbf{n}|} \\ &= \frac{\mathbf{n} \mathbf{x}_0 - \mathbf{n} \mathbf{x}_1}{|\mathbf{n}|} && \text{distribution} \\ &= \frac{|-d - \mathbf{n} \mathbf{x}_1|}{|\mathbf{n}|} \\ &= \frac{|\mathbf{n} \mathbf{x}_1 + d|}{|\mathbf{n}|}. \end{aligned}$$

## Question

Find the distance between the two **parallel** planes  $10x + 2y - 2z = 5$  and  $5x + y - z = 1$ . (If they were not parallel the distance would be



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First notice the normals are  $\langle 10, 2, -2 \rangle$  and  $\langle 5, 1, -1 \rangle$  which indeed correspond to parallel planes.

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We **just** devised a formula for this.

## Answer (Continued.)

So, let us pick an arbitrary point on

$$10x + 2y - 2z = 5,$$

say  $(\frac{1}{2}, 0, 0)$ , and find its distance to the plane

$$5x + 1y - 1z = 1.$$

## Answer (Continued.)

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$$5x + 1y - 1z = 1.$$

$$D = \frac{|(5)(\frac{1}{2}) + (1)(0) + (-1)(0) + (-1)|}{|\langle 5, 1, -1 \rangle|} = \frac{3/2}{3\sqrt{3}} = \frac{\sqrt{3}}{6}.$$

## Question

We previously showed the lines

$$L_0 : \quad x = 1 + t \quad y = -2 + 3t \quad z = 4 - t$$

$$L_1 : \quad x = 2s \quad y = 3 + s \quad z = -3 + 4s$$

were skew. What then, is the distance between them?

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## Answer

If the lines  $L_0$  and  $L_1$  are skew then they be viewed as laying on two separate parallel planes  $P_0$  and  $P_1$ . The distance between the lines is the same as the distance between the planes.



## Answer (Continued.)

The normal of these planes, for them to be parallel, should be the cross-product of the line's direction vectors:

$$\langle 1, 3, -1 \rangle \times \langle 2, 1, 4 \rangle = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 2 & -1 \\ 2 & 1 & 4 \end{vmatrix} = \langle 13, -6, -5 \rangle.$$

We're now free to choose a point from one line and calculate the distance to the plane given by the other line.

## Answer (Continued.)

Recall the two lines are

$$L_0 : \quad x = 1 + t \quad y = -2 + 3t \quad z = 4 - t$$

$$L_1 : \quad x = 2s \quad y = 3 + s \quad z = -3 + 4s$$

Setting  $s = t = 0$  we see the point  $(1, -2, 4)$  lies on  $L_0$  and  $(0, 3, -3)$  on  $L_1$ .

## Answer (Continued.)

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The plane defined by  $L_1$  is given by

$$\begin{aligned} 13(x - 0) - 6(y - 3) - 5(z + 3) &= 0 \\ \implies 13x - 6y - 5z + 3 &= 0 \end{aligned}$$

### Answer (Continued.)

By our equation, the distance from the point  $(1, -2, 4)$  to the plane  $13x - 6y - 5z + 3 = 0$  is

$$D = \frac{|13(1) - 6(-2) - 5(4) + 3|}{|\langle 13, -6, -5 \rangle|} = \frac{8}{\sqrt{230}}$$

Next week.

Next week

- ▶ Midterm examination.

Week after next

- ▶ Matrices.
- ▶ Linear system solving.