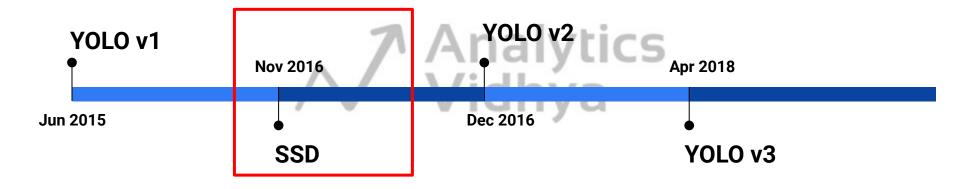


# Single Stage Learning





SSD performs localization and classification in a single pass



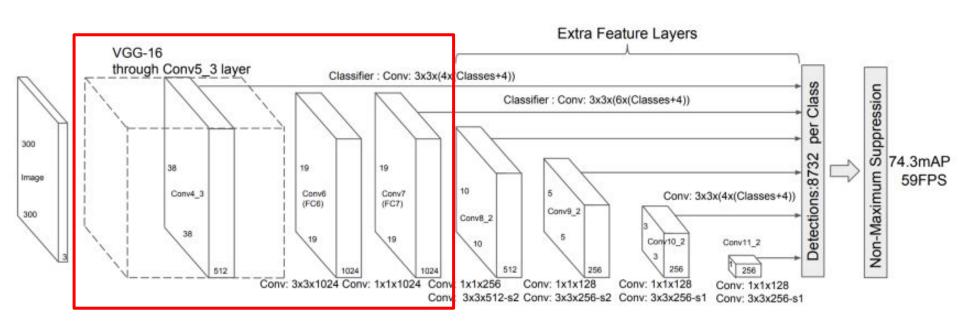


SSD performs localization and classification in a single pass

Vidhya

Uses VGG16 Architecture to generate feature map







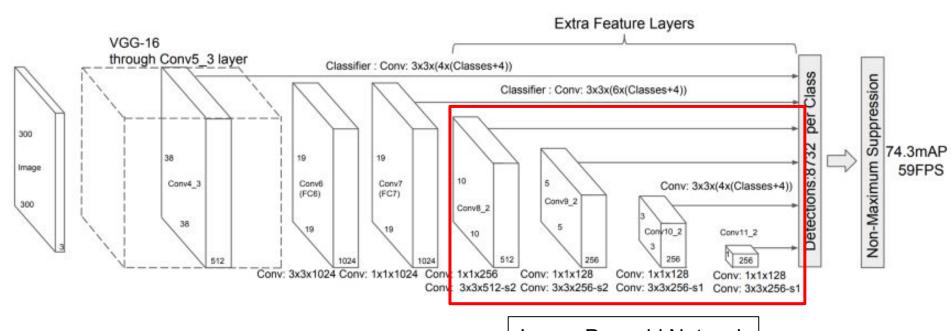


Image Pyramid Network

An

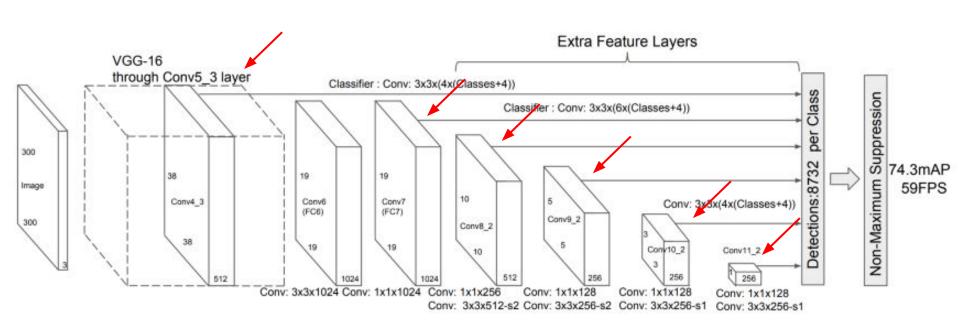


SSD performs localization and classification in a single pass

Uses VGG16 Architecture to generate feature map

Multi-scale feature maps for detection







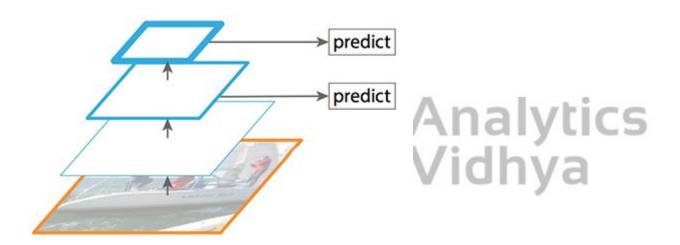


Image Pyramid Network



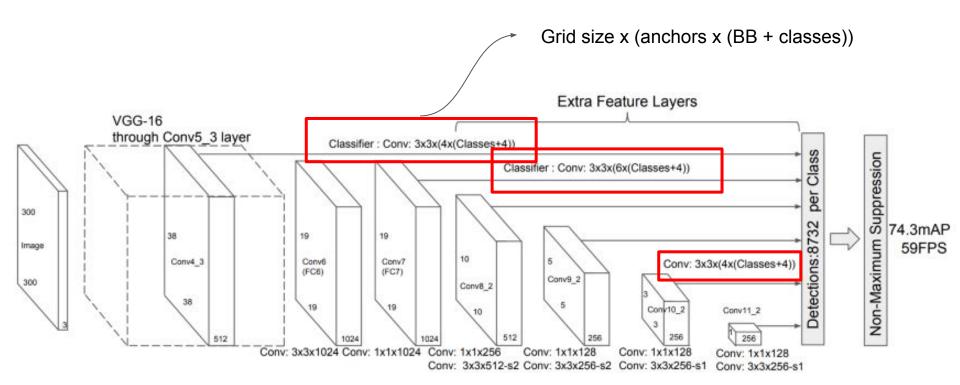
SSD performs localization and classification in a single pass

Uses VGG16 Architecture to generate feature map

Multi-scale feature maps for detection

Uses anchor boxes over feature maps







• SSD performs localization and classification in a single pass

Uses VGG16 Architecture to generate feature map

• Multi-scale feature maps for detection

Uses anchor boxes over feature maps

Applies Non-max suppression



