

Project - Lane Segmentation for Self-Driving Systems

Steps to Solve Lane Segmentation - U-Net with Best Practices

1. Data Loading and Preprocessing

1.1 Load the Data

1.2 Define custom dataset

1.3 Data Exploration

2. Lane Segmentation using U-Net with Best Practices

2.0 Define validation and test dataloader

2.1 Define model architecture

2.2 Train the model

2.3 Calculate IoU score

2.4 Inference on Test Dataset

Code Walkthrough of U-Net with Best Practices

