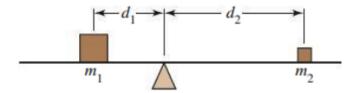
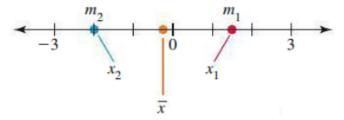
16.6: Integrals for Mass Calculations

Suppose we have two masses m_1 and m_2 on a beam (with no mass) that are distances d_1 and d_2 away from a pivot point. This beam will be balanced when $m_1d_1 = m_2d_2$.



This concept can be used to to find the balance point \bar{x} between 2 objects with masses m_1 and m_2 :



$$m_1(x_1 - \bar{x}) = m_2(\bar{x} - x_2) \implies m_1(x_1 - \bar{x}) + m_2(x_2 - \bar{x}) = 0.$$

$$\Rightarrow \bar{x} =$$

Next, we can generalize this to n objects with masses m_1, \ldots, m_n :

$$m_1(x_1 - \bar{x}) + m_2(x_2 - \bar{x}) + \dots + m_n(x_n - \bar{x}) = \sum_{k=1}^n m_k(x_k - \bar{x}) = 0.$$

$$\Rightarrow \bar{x} =$$

Definition. (Center of Mass in One Dimension)

Let ρ be an integrable density function on the interval [a, b] (which represents a thin rod or wire). The **center of mass** is located at the point $\bar{x} = \frac{M}{m}$, where the **total moment** M and mass m are

$$M = \int_a^b x \rho(x) dx$$
 and $m = \int_a^b \rho(x) dx$.

Example. Find the mass and center of mass of the thin rods with the following density functions:

$$\rho(x) = 2 + \cos(x)$$
, for $0 \le x \le \pi$

$$\rho(x) = \begin{cases} x^2 & \text{if } 0 \le x \le 1\\ x(2-x) & \text{if } 1 < x \le 2 \end{cases}$$

Definition. (Center of Mass in Two Dimensions)

Let ρ be an integrable area density function defined over a closed bounded region R in \mathbb{R}^2 . The coordinates of the center of mass of the object represented by R are

$$\bar{x} = \frac{M_y}{m} = \frac{1}{m} \iint_R x \rho(x, y) dA$$
 and $\bar{y} = \frac{M_x}{m} = \frac{1}{m} \iint_R y \rho(x, y) dA$,

where $m = \iint_R \rho(x, y) dA$ is the mass, and M_y and M_x are the moments with respect to the y-axis and x-axis, respectively. If ρ is constant, the center of mass is called the **centroid** and is independent of the density.

Example. Find the center of mass of the following plane regions with variable density:

$$R = \{(x,y) : 0 \le x \le 4, \ 0 \le y \le 2\}; \ \rho(x,y) = 1 + x/2.$$

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The quarter disk in the first quad	$\frac{1}{x}$ lrant bounded by x^2	$x^2 + y^2 = 4 \text{ with } \rho(x, y)$	$) = 1 + x^2 + y^2$

Definition. (Center of Mass in Three Dimensions)

Let ρ be an integrable area density function defined over a closed bounded region D in \mathbb{R}^3 . The coordinates of the center of mass of the region are

$$\bar{x} = \frac{M_{yz}}{m} = \frac{1}{m} \iiint_D x \rho(x, y, z) \, dV$$
$$\bar{y} = \frac{M_{xz}}{m} = \frac{1}{m} \iiint_D y \rho(x, y, z) \, dV$$
$$\bar{z} = \frac{M_{xy}}{m} = \frac{1}{m} \iiint_D z \rho(x, y, z) \, dV$$

where $m = \iiint_D \rho(x, y, z) dA$ is the mass, and M_{yz} , M_{xz} , and M_{xy} are the moments with respect to the coordinate planes.

17.1: Vector Fields

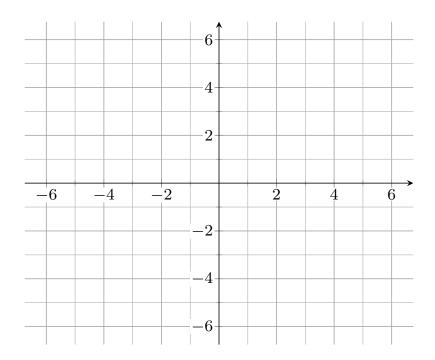
Definition. (Vector Fields in Two Dimensions)

Let f and g be defined on a region R of \mathbb{R}^2 . A **vector field** in \mathbb{R}^2 is a function \mathbf{F} that assigns to each point in R a vector $\langle f(x,y), g(x,y) \rangle$. The vector field is written as

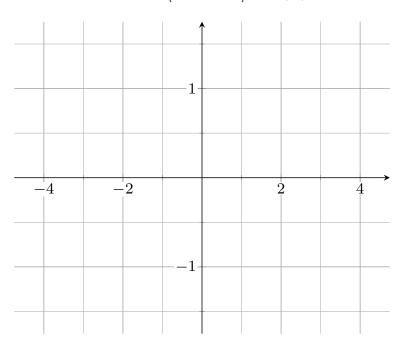
$$\mathbf{F}(x,y) = \langle f(x,y), g(x,y) \rangle$$
 or $\mathbf{F}(x,y) = f(x,y)\mathbf{i} + g(x,y)\mathbf{j}$.

A vector field $\mathbf{F} = \langle f, g \rangle$ is continuous or differentiable on a region R of \mathbb{R}^2 if f and g are continuous or differentiable on R, respectively.

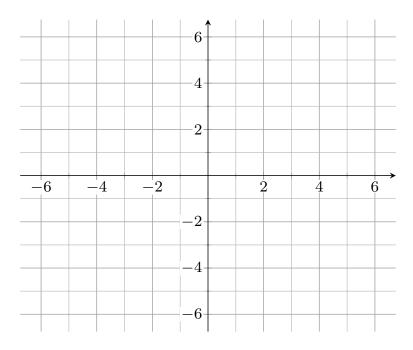
Example. Sketch the vector field $\mathbf{F} = \langle 0, x \rangle$.



Example. Sketch the vector field $\mathbf{F} = \langle 1 - y^2, 0 \rangle$ for $|y| \leq 1$.



Example. Sketch the vector field $\mathbf{F} = \langle -y, x \rangle$.



Definition. (Radial Vector Fields in \mathbb{R}^2)

Let $\mathbf{r} = \langle x, y \rangle$. A vector field of the form $\mathbf{F} = f(x, y)\mathbf{r}$, where f is a scalar valued function, is a **radial vector field**. Of specific interest are the radial vector fields

$$\mathbf{F}(x,y) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y \rangle}{|\mathbf{r}|^p} = \frac{\mathbf{r}}{|\mathbf{r}|} \frac{1}{|\mathbf{r}|^{p-1}},$$

where p is a real number. At every point (expect the origin), the vectors of this field are directed outward from the origin with a magnitude of $|\mathbf{F}| = \frac{1}{|\mathbf{r}|^{p-1}}$.

Example. Let C be the circle $x^2 + y^2 = a^2$, where a > 0.

a) Show that at each point of C, the radial vector field $\mathbf{F}(x,y) = \frac{\mathbf{r}}{|\mathbf{r}|} = \frac{\langle x,y \rangle}{\sqrt{x^2 + y^2}}$ is orthogonal to the line tangent to C at that point.

b) Show that at each point of C, the rotation vector field $\mathbf{G}(x,y) = \frac{\langle -y,x\rangle}{\sqrt{x^2+y^2}}$ is parallel to the line tangent to C at that point.

Definition. (Vector Fields and Radial Vector Fields in \mathbb{R}^3)

Let f, g, and h be defined on a region D of \mathbb{R}^3 . A **vector field** in \mathbb{R}^3 is a function \mathbf{F} that assigns to each point in D a vector $\langle f(x,y,z), g(x,y,z), h(x,y,z) \rangle$. The vector field is written as

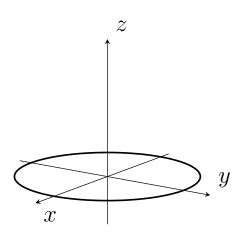
$$\mathbf{F}(x,y,z) = \langle f(x,y,z), g(x,y,z), h(x,y,z) \rangle \quad \text{or} \quad \mathbf{F}(x,y,z) = f(x,y,z)\mathbf{i} + g(x,y,z)\mathbf{j} + h(x,y,z)\mathbf{k}.$$

A vector field $\mathbf{F} = \langle f, g, h \rangle$ is continuous or differentiable on a region D of \mathbb{R}^3 if f, g, and h are continuous or differentiable on D, respectively. Of particular importance are the **radial vector fields**

$$\mathbf{F}(x, y, z) = \frac{\mathbf{r}}{|\mathbf{r}|^p} = \frac{\langle x, y, z \rangle}{|\mathbf{r}|^p},$$

where p is a real number.

Example. Sketch the vector field $\mathbf{F}(x,y,z) = \langle 0,0,1-x^2-y^2 \rangle$, for $x^2+y^2 \leq 1$.



Definition. (Gradient Fields and Potential Functions)

Let φ be differentiable on a region of \mathbb{R}^2 or \mathbb{R}^3 . The vector field $=\nabla \varphi$ is a **gradient** field and the function φ is a **potential function** for **F**.

Example. Sketch and interpret the gradient field associated with the temperature function $T = 200 - x^2 - y^2$ on the circular plane $R = \{(x, y) : x^2 + y^2 \le 25\}$.

Example. Sketch and interpret the gradient field associated with the velocity potential $\varphi = \tan^{-1}(xy)$.