

# Complex Systems - Vinton Pat - Assignment 4

(2) (A) let  $T, S \in \mathbb{R}^{n \times n}$  be stochastic and let  $x \in \mathbb{R}_+^n$  be a distribution;  
 $\|x\|_1 = \sum x_i = 1$ , let  $\alpha \in [0, 1] \Rightarrow \|Tx\|_1 = \|Sx\|_1 = 1$

then:  $\|(\alpha T + (1-\alpha)S)x\|_1 = \alpha \|Tx\|_1 + (1-\alpha)\|Sx\|_1 = \alpha + (1-\alpha) = 1$

because  $\alpha, x, T, S \geq 0$   
 (1.4)

(B)  $Q \triangleq \frac{1}{n} \mathbf{1} \mathbf{1}^T$

$$P_{n+1} = [\alpha Q + (1-\alpha)T] P_n = \dots = [\alpha Q + (1-\alpha)T]^n P_0 \quad q \triangleq Q P_0 = \frac{1}{n} \mathbf{1} \triangleq P_0$$

given that the limit exists:  $\lim_{n \rightarrow \infty} P_n = P = \lim_{n \rightarrow \infty} [\alpha Q + (1-\alpha)T] P_n = [\alpha Q + (1-\alpha)T] P$

it must follow that  $P = I P = [\alpha Q + (1-\alpha)T] P = \alpha Q P + (1-\alpha) T P = \alpha q + (1-\alpha) T P$

$$\Leftrightarrow \text{(1.5)} \quad \alpha q = (I - (1-\alpha)T) P$$

$$\Leftrightarrow P = \alpha [I - (1-\alpha)T]^{-1} q$$

Remark for any  $v \in \mathbb{R}_+^n$  s.t.  $\|v\|_1 = 1$  we have  $Qv = q = (\frac{1}{n}, \frac{1}{n}, \dots, \frac{1}{n})$

So  $P_0$  doesn't matter as long as we pick a distribution.