

# CSDS 440: Machine Learning

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Office hours T, Th 11:15-11:45 or by appointment

[Zoom link](#)

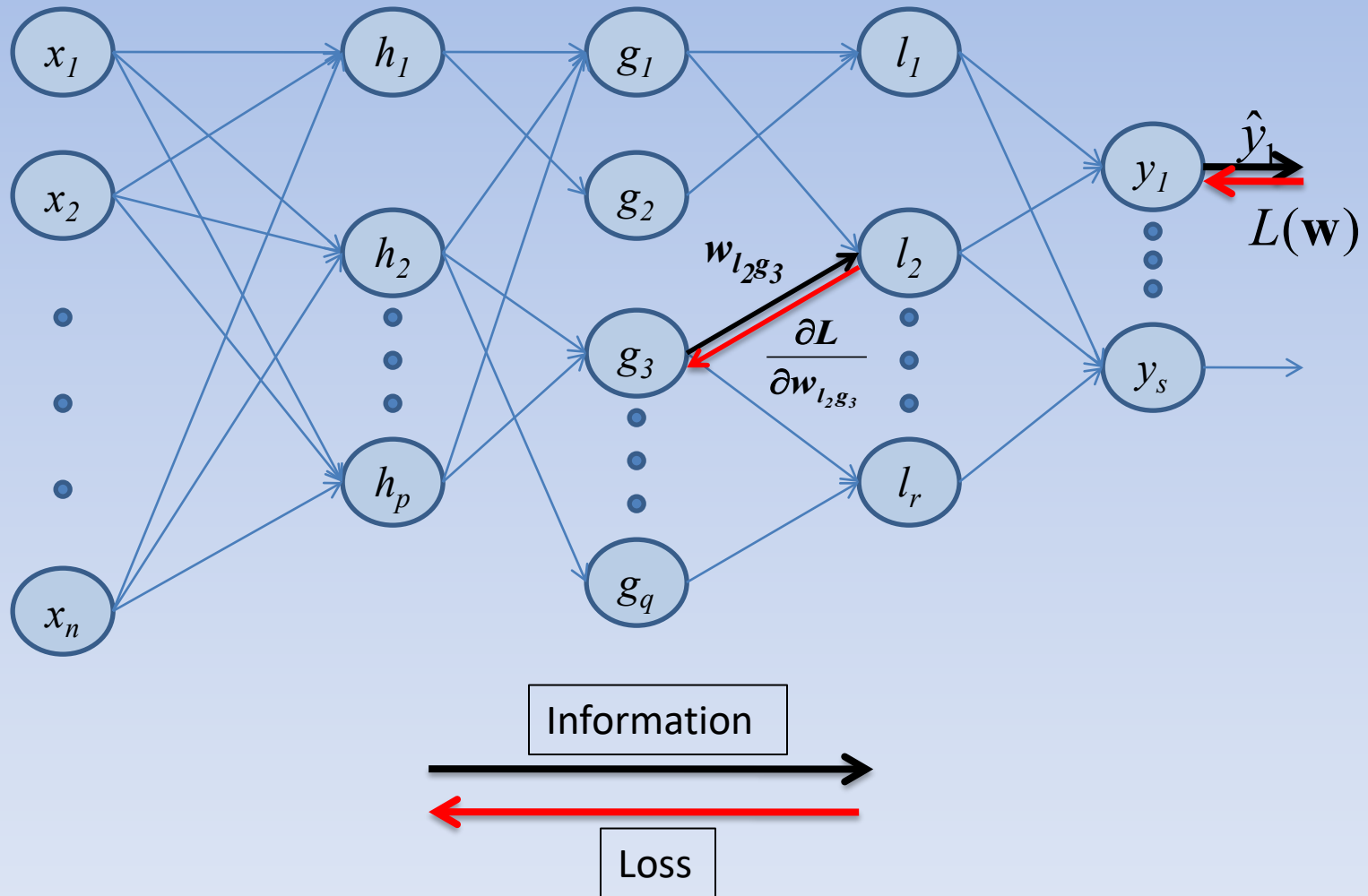
# Recap

- To estimate perceptron parameters we define a  $l$  function that measures the distance between our  $e$  labels and the  $t$  labels.
- The gradient descent procedure will converge to a global minimum because  $\frac{d}{dt} l(w) < 0$ .
- We can also use stochastic gradient descent. This is different from regular GD because  $\frac{d}{dt} l(w) > 0$ .
- SGD is useful if the function has multiple local minima. It can also be used during online learning.
- The XOR function cannot be learned with a perceptron.
- In a general neural network, there are layers of hidden units between input and output.
- Every Boolean function can be represented by a network with one hidden layer.
- Every continuous function can be represented by a network with one hidden layer.
- However, the tradeoffs are (1) (2) (3).
- The activation functions in an ANN must be non-linear for learning.
- The sigmoid function outputs  $h(u) = 1/(1 + \exp(-u))$ .
- Backpropagation performs local gradient descent. First, information flows forward through the network to compute the output. Then, the error flows backward to compute the gradients.

# Today

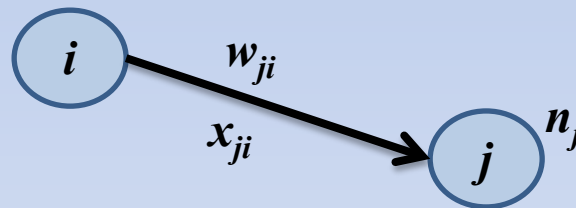
- Artificial Neural Networks (Ch 4, Mitchell)

# Backpropagation



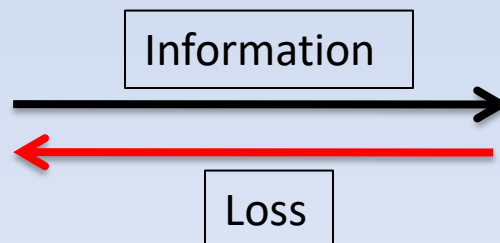
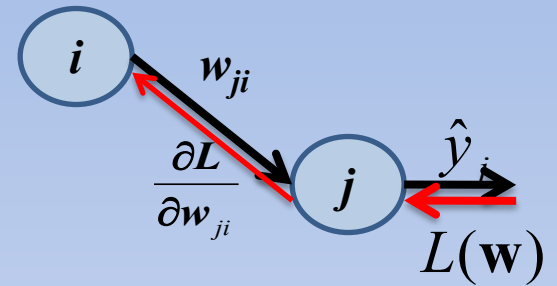
# Backpropagation (SGD)

- Let  $x_{ji}$  be the  $i^{\text{th}}$  input to unit  $j$
- Let  $w_{ji}$  be the parameter associated with  $x_{ji}$
- Let  $n_j = \sum_i w_{ji} x_{ji}$  be the “net input” to unit  $j$



- Observe that 
$$\frac{\partial L}{\partial w_{ji}} = \frac{\partial L}{\partial n_j} \frac{\partial n_j}{\partial w_{ji}} = \frac{\partial L}{\partial n_j} x_{ji}$$

# Output Layer



# Derivation (output layer)

$$h(u) = \frac{1}{(1 + e^{-u})}; 1 - h(u) = \frac{e^{-u}}{(1 + e^{-u})} \quad \text{(Sigmoid)}$$

$$\frac{dh}{du} = \frac{e^{-u}}{(1 + e^{-u})^2} = h(u)(1 - h(u)) \quad \text{(Derivative of Sigmoid)}$$

$$L(w_{ji}) = \frac{1}{2} (y_j - h(n_j))^2 \quad \text{(Squared Loss)}$$

$$\frac{\partial L}{\partial n_j} = (h(n_j) - y_j) \frac{\partial h(n_j)}{\partial n_j}$$

$$\frac{\partial h(n_j)}{\partial n_j} = h(n_j)(1 - h(n_j)) \quad \text{(Using Derivative of Sigmoid)}$$

# Derivation (output layer)

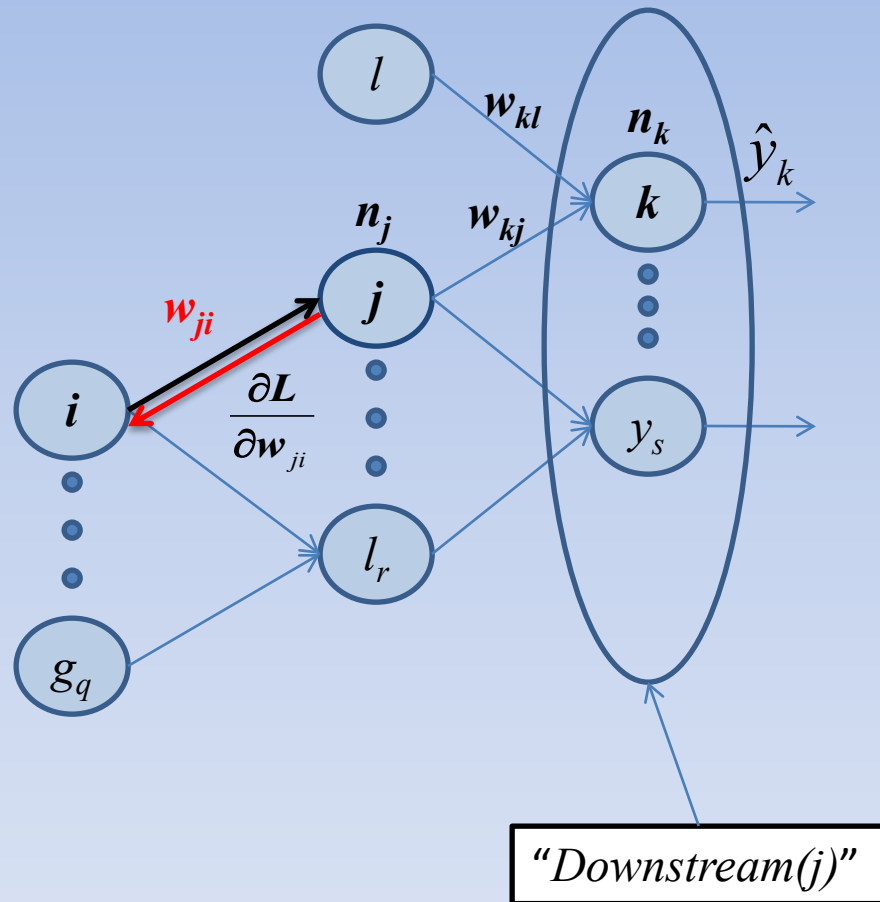
$$\frac{\partial L}{\partial n_j} = (h(n_j) - y_j) \frac{\partial h(n_j)}{\partial n_j}$$

$$\frac{\partial h(n_j)}{\partial n_j} = h(n_j)(1 - h(n_j))$$

$$\frac{\partial L}{\partial w_{ji}} = (h(n_j) - y_j) h(n_j)(1 - h(n_j)) x_{ji}$$



# Hidden Layer



# Derivation (Hidden Layer)

- Since  $j$  affects the output only through  $Downstream(j)$ ,

$$\frac{\partial L}{\partial n_j} = \sum_{k \in Downstream(j)} \frac{\partial L}{\partial n_k} \frac{\partial n_k}{\partial n_j}$$

Already calculated,  
next layer

$$n_k = \sum_l w_{kl} h(n_l); \frac{\partial n_k}{\partial n_j} = \frac{\partial (w_{kj} h(n_j))}{\partial n_j}$$

$$= w_{kj} \frac{\partial h(n_j)}{\partial n_j} = w_{kj} h(n_j)(1 - h(n_j))$$

$$\frac{\partial L}{\partial n_j} = h(n_j)(1 - h(n_j)) \sum_{k \in Downstream(j)} \frac{\partial L}{\partial n_k} w_{kj}$$

# Derivation (Hidden Layer)

$$\frac{\partial L}{\partial w_{ji}} = \frac{\partial L}{\partial n_j} x_{ji}$$

$$= h(n_j)(1 - h(n_j))x_{ji} \sum_{k \in \text{Downstream}(j)} \frac{\partial L}{\partial n_k} w_{kj}$$

$$= h(n_j)(1 - h(n_j))x_{ji} \sum_{k \in \text{Downstream}(j)} \frac{\partial L}{\partial w_{kj}} \frac{w_{kj}}{x_{kj}}$$

# Review

- Consider a neural network with 2 input units, 2 hidden units and 1 output unit and all weights initialized to 1, with the bias set to zero. Using squared loss, show the weights after the first backprop update with these examples.

$x_1$	$x_2$	$f$
0	0	0
0	1	1

# Updates

$$\frac{\partial L}{\partial w_{oh}} = h(n_o)(1 - h(n_o))x_{oh}(h(n_o) - y_o)$$

$$\frac{\partial L}{\partial w_{hi}} = h(n_h)(1 - h(n_h))x_{hi} \sum_{k \in \text{Downstream}(h)} \frac{\partial L}{\partial w_{kh}} \frac{w_{kh}}{x_{kh}}$$

# Example notes

- Zeros as inputs
- SGD effects
- Vanishing gradients