# Package 'gpsinterp'

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Type Package

Title Interpolation of Longitude, Latitude and Direction with JOSM
Version 0.1.0
<b>Depends</b> R (>= 3.3)
<b>Imports</b> dplyr (>= 0.7), purrr (>= 0.2), tibble (>= 1.4), tidyr (>= 0.7), xml2 (>= 1.1)
Suggests testthat
<b>Description</b> Finds coordinates and direction (angle) of a sequence of photos with no GPS exif tags. In JOSM (Java editor for OpenStreetMap), manually identify points that can be located exactly, then interpolate in-between points with R. Repeat the procedure until the approximation is good enough.
<pre>URL http://github.com/the-knife/gpsinterp</pre>
BugReports http://github.com/the-knife/gpsinterp/issues
License GPL-2
Encoding UTF-8
LazyData true
SystemRequirements JOSM (required), exiftool (optional)
RoxygenNote 6.0.1
NeedsCompilation no
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2 interp\_init

interp\_cleanup

Clean up after interpolation

# **Description**

Removes temporary environment (.exif) containing data that was used during interpolation.

# Usage

```
interp_cleanup()
```

#### **Details**

As closing R session will also delete that environment, this is not mandatory.

interp\_init

Initialize data before interpolation

# **Description**

List photos in input directory and creates an environment for storing data during interpolation iterative process. This is a mandatory prerequisite for interpolating positions.

# Usage

```
interp_init(path = ".")
```

# **Arguments**

path

(optional) path where input and output are located. This is not necessary if the working directory is already set to that location.

# **Details**

Search for image files in input/photo and stores them in a data.frame.

As the process is iterative (a succession of manual modifications in JOSM and interpolations in R), it is necessary to keep track of intermediate results. Therefore, a temporary environment (named .exif) is created.

Once interpolation is over, it is possible to delete that environment with interp\_cleanup.

# Value

Nothing. Only .exif\$base is created.

### **Examples**

```
interp_init()
```

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interp_josm	Interpolation and JOSM update	

# Description

Reads exact positions, linearly interpolates non-exact positions, updates osm file and displays it in JOSM.

# Usage

```
interp_josm(path = ".")
```

# **Arguments**

path

(optional) path where input and output are located. This is not necessary if the working directory is already set to that location.

#### **Details**

Reads approx.osm and detects exact locations (moved manually in JOSM). Then interpotales linearly other points. Updates approx.osm and opens it in JOSM (http://localhost:8111 is used to open the file in JOSM, which must be opened beforehand).

#### Value

Nothing. Only .exif\$base and approx.osm are updated.

#### **Examples**

```
# interp_josm()
```

write\_coord\_csv

Write coordinates and direction in a csv file.

## **Description**

Write computed longitudes, latitudes (and directions) in a csv file. Images are not modified.

# Usage

```
write_coord_csv(path = ".", file = "interp_gps.csv", direction = TRUE,
    ...)
```

# **Arguments**

path	(optional) path where input and output are located. This is not necessary if the working directory is already set to that location.
file	the name of the csv file (default : "interp_gps.csv")
direction	should direction to next photo be calculated and included in the file?
	other arguments passed to write.csv

4 write\_exiftool

|--|

# Description

Runs exiftool commands to write computed longitudes, latitudes (and directions) in image files.

# Usage

```
write_exiftool(path = ".", direction = TRUE)
```

# **Arguments**

path (optional) path where input and output are located. This is not necessary if the

working directory is already set to that location.

direction should direction to next photo be calculated and included in the file?

# **Details**

In order to write image files, **exiftool** must be installed.

Files are not overwritten: a copy of the images including new exif tags are written in the output directory.

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