

Mining Data Streams

The Stream Model
Sliding Windows
Counting 1's

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Stream data

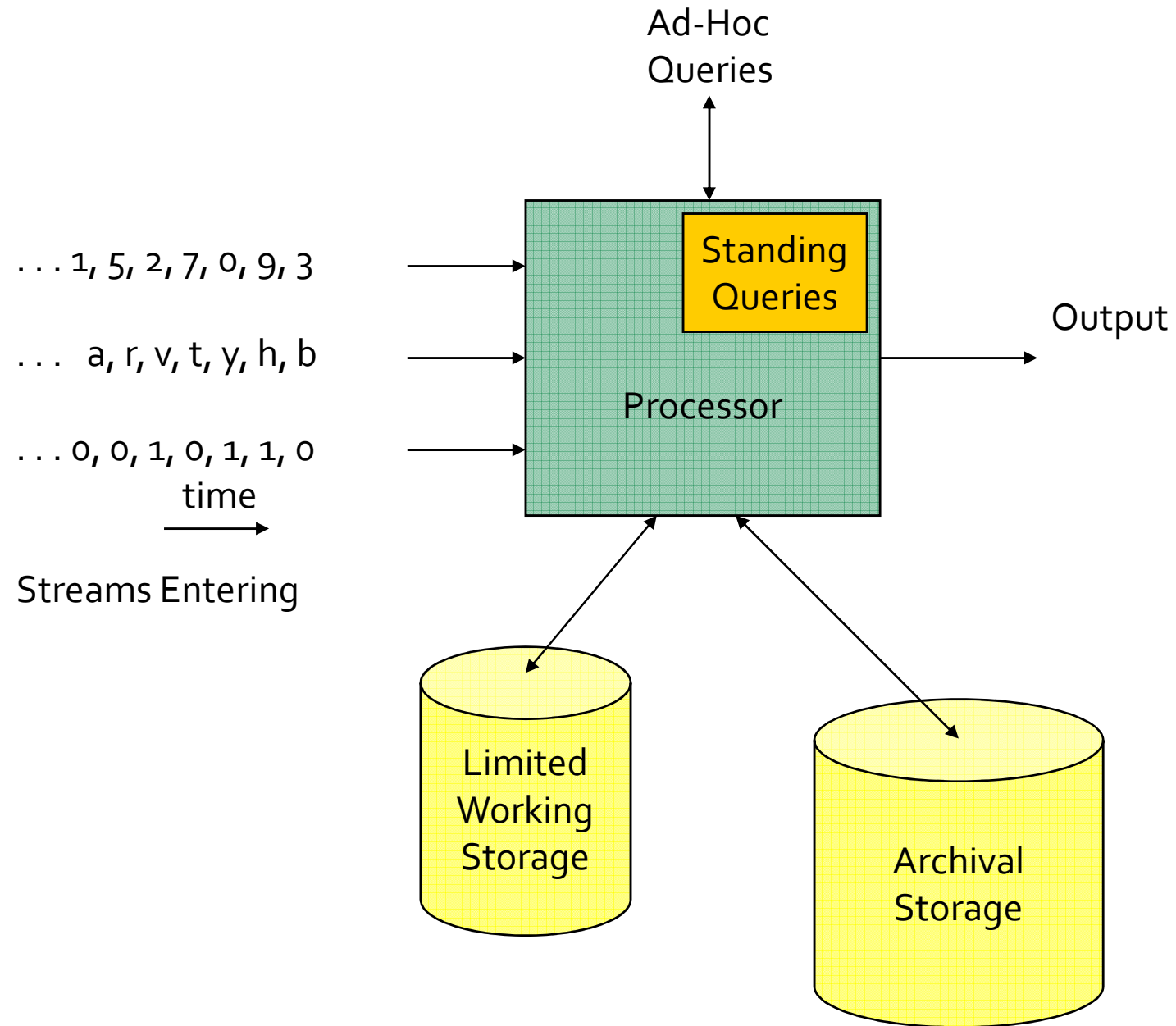
- Log files / Mobile and Web App
- E-Commerce purchase
- In game player activity
- Social Network
- Geospatial Services
- Telemetry
- Processing
 - Sequentially
 - Sliding window

Data Management Vs. Stream Management

- In a DBMS, input is under the control of the programming staff.
 - SQL INSERT commands or bulk loaders.
- Stream management is important when the input rate is controlled externally.
 - **Example:** Google search queries.

The Stream Model

- Input tuples enter at a rapid rate, at one or more input ports.
- The system cannot store the entire stream accessibly.
- How do you make critical calculations about the stream using a limited amount of (primary or secondary) memory?



Two Forms of Query

1. *Ad-hoc queries*: Normal queries asked one time about streams.
 - *Example*: What is the maximum value seen so far in stream S ?
2. *Standing queries*: Queries that are, in principle, asked about the stream at all times.
 - *Example*: Report each new maximum value ever seen in stream S .

Applications

- Mining query streams.
 - Google wants to know what queries are more frequent today than yesterday.
- Mining click streams.
 - Yahoo! wants to know which of its pages are getting an unusual number of hits in the past hour.
 - Often caused by annoyed users clicking on a broken page.
- IP packets can be monitored at a switch.
 - Gather information for optimal routing.
 - Detect denial-of-service attacks.

Sliding Windows

- A useful model of stream processing is that queries are about a *window* of length N – the N most recent elements received.
 - **Alternative**: elements received within a time interval T .
- **Interesting case**: N is so large it cannot be stored in main memory.
 - Or, there are so many streams that windows for all do not fit in main memory.

qwertyuiopasdfghjklzxcvbnm

qwertyuiopasdfghjkl zxcvbnm

qwertyuiopasdfghjklzxcvbnm

qwertyuiopasdfghjklzxvcvbnm

← Past Future →

Example: Averages

- Stream of integers, window of size N .
- **Standing query**: what is the average of the integers in the window?
- For the first N inputs, sum and count to get the average.
- Afterward, when a new input i arrives, change the average by adding $(i - j)/N$, where j is the oldest integer in the window before i arrived.
- **Good**: $O(1)$ time per input.
- **Bad**: Requires the entire window in main memory.

Counting 1's

Approximating Counts
Exponentially Growing Blocks
DGIM Algorithm

Approximate Counting

- You can show that if you insist on an exact sum or count of the elements in a window, you cannot use less space than the window itself.
- But if you are willing to accept an approximation, you can use much less space.
- We'll consider the simple case of counting bits, which includes counting elements of a certain type as a special case.
- Sums are a fairly straightforward extension.

Counting Bits

- **Problem:** given a stream of 0's and 1's, be prepared to answer queries of the form “how many 1's in the most recent k bits?” where $k \leq N$.
- **Obvious solution:** store the most recent N bits.
- But answering the query will take $O(k)$ time.
 - Very possibly too much time.
- And the space requirements can be too great.
 - Especially if there are many streams to be managed in main memory at once, or N is huge.

Example: Bit Counting

- Count recent hits on URL's belonging to a site.
- Stream is a sequence of URL's.
- Window size $N = 1$ billion.
- Think of the data as many streams – one for each URL.
- Bit on the stream for URL x is 0 unless the actual stream has x .

DGIM Method

- Name refers to the inventors:
 - Datar, Gionis, Indyk, and Motwani.
- Store only $O(\log^2 N)$ bits per stream.
 - N = window size.
- Gives approximate answer, never off by more than 50%.
 - Error factor can be reduced to any $\varepsilon > 0$, with more complicated algorithm and proportionally more stored bits.

Timestamps

- Each bit in the stream has a *timestamp*, starting 0, 1, ...
- Record timestamps modulo N (the window size), so we can represent any *relevant* timestamp in $O(\log_2 N)$ bits.

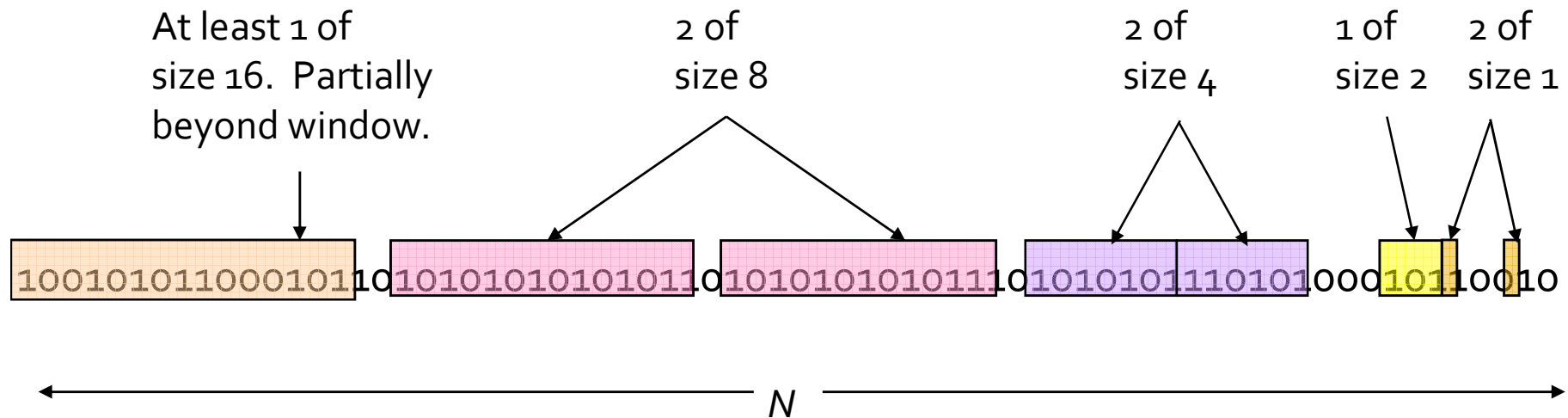
Buckets

- A *bucket* is a segment of the window; it is represented by a record consisting of:
 1. The timestamp of its end [$O(\log N)$ bits].
 2. The number of 1's between its beginning and end.
 - Number of 1's = *size* of the bucket.
- **Constraint on bucket sizes:** number of 1's must be a power of 2.
 - Thus, only $O(\log \log N)$ bits are required for this count.

Representing a Stream by Buckets

- Either one or two buckets with the same power-of-2 number of 1's.
- Buckets do not overlap.
- Buckets are sorted by size.
 - Older buckets are not smaller than newer buckets.
- Buckets disappear when their end-time is $> N$ time units in the past.

Example: Bucketized Stream



Updating Buckets

- When a new bit comes in, drop the last (oldest) bucket if its end-time is prior to N time units before the current time.
- If the current bit is 0, no other changes are needed.

Updating Buckets: Input = 1

- If the current bit is 1:
 1. Create a new bucket of size 1, for just this bit.
 - End timestamp = current time.
 2. If there are now three buckets of size 1, combine the oldest two into a bucket of size 2.
 3. If there are now three buckets of size 2, combine the oldest two into a bucket of size 4.
 4. And so on ...

Example: Managing Buckets

Initial

100101011000101101010101010101101010101010110101010111010100010110010

1 arrives; makes third block of size 1.

0010101100010110101010101010110101010101011010101110101000101100101

Combine oldest two 1's into a 2.

0010101100010110101010101010110101010101011010101110101000101100101

Later, 1, 0, 1 arrive. Now we have 3 1's again.

0101100010110101010101010110101010101011010101110101000101100101101

Combine two 1's into a 2.

0101100010110101010101010110101010101011010101110101000101100101101

The effect ripples all the way to a 16.

0101100010110101010101010110101010101011010101110101000101100101101

Querying

- To estimate the number of 1's in the most recent $k \leq N$ bits:
 1. Restrict your attention to only those buckets whose end time stamp is at most k bits in the past.
 2. Sum the sizes of all these buckets but the oldest.
 3. Add half the size of the oldest bucket.
- **Remember:** we don't know how many 1's of the last bucket are still within the window.

Error Bound

- Suppose the oldest bucket within range has size 2^i .
- Then by assuming 2^{i-1} of its 1's are still within the window, we make an error of at most 2^{i-1} .
- Since there is at least one bucket of each of the sizes less than 2^i , and at least 1 from the oldest bucket, the true sum is no less than 2^i .
- Thus, error at most 50%.

Space Requirements

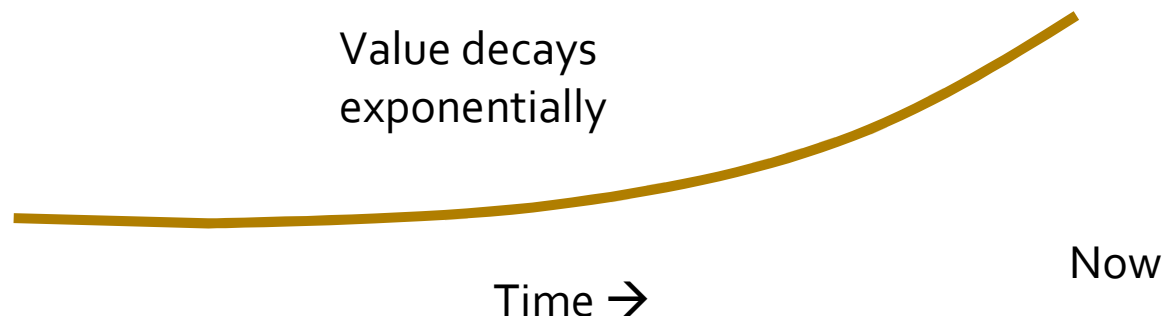
- We can represent one bucket in $O(\log N)$ bits.
 - It's just a timestamp needing $\log N$ bits and a size, needing $\log \log N$ bits.
- No bucket can be of size greater than N .
- There are at most two buckets of each size $1, 2, 4, 8, \dots$
- That's at most $\log N$ different sizes, and at most 2 of each size, so at most $2\log N$ buckets.

Exponentially Decaying Windows

Efficient Maintenance of E.D.W.'s
Application to Frequent Itemsets

Exponentially Decaying Windows

- **Viewpoint:** what is important in a stream is not just a finite window of most recent elements.
 - But all elements are not equally important; “old” elements less important than recent ones.
- Pick a constant $c \ll 1$ and let the “value” of the i -th most recent element to arrive be proportional to $(1-c)^i$.



Numerical Streams

- **Common case:** elements are numerical, with a_i arriving at time i .
- The stream has a value at time t : $\sum_{i \leq t} a_i (1-c)^{t-i}$.
- **Example:** are we in a rainy period?
 - $a_i = 1$ if it rained on day i ; 0 if not.
 - $c = 0.1$.
- If it rains every day, the value of the sum is $1 + .9 + (.9)^2 + \dots = 1/c = 10$.
- Value will be higher if the recent days have been rainy than if it rained long ago.

Maintaining the Stream Value

- Exponentially decaying windows make it easy to maintain this sum.
- When a new element x arrives:
 1. Multiply the previous value by $1-c$.
 2. Add x .

Maintaining Frequent Itemsets

- Imagine many streams, each Boolean, each representing the occurrence of one element.
- **Example:** sales of items.
 - One stream for each item.
 - Stream has a 1 when an instance of that item is sold.
- Want the most “frequent” sets of items.
 - Frequency can be represented by the “value” of the stream in the decaying-window sense.
- But there are too many itemsets to maintain the value for every stream.

A-Priori-Like Approach

- Take the support threshold s to be $1/2$.
 - I.e., count a set only when the value of its stream is at least $1/2$.
 - **Aside:** s cannot be greater than 1, because then we could never start counting any set.
- Start by counting only the singleton items that are above threshold.
- Then, start counting a set when it occurs at time t , **provided** all of its immediate subsets were already being counted (before time t).

Processing at Time t

1. Suppose set of items S are all the items sold at time t .
2. Multiply the value for each itemset being counted by $(1-c)$.
3. Add 1 to the values for every set $T \subseteq S$, such that either:
 - T is a singleton, or
 - Every immediate subset of T was being counted at time $t-1$.
4. Drop any values $< 1/2$.