Uncertainty

Introduction

- The world is not a well-defined place.
- There is uncertainty in the facts we know:
 - What's the temperature? Imprecise measures
 - Is Bush a good president? Imprecise definitions
 - Where is the pit? Imprecise knowledge
- There is uncertainty in our inferences
 - If I have a blistery, itchy rash and was gardening all weekend I probably have poison ivy
- People make successful decisions all the time anyhow.

Sources of Uncertainty

- Uncertain data
 - missing data, unreliable, ambiguous, imprecise representation, inconsistent, subjective, derived from defaults, noisy...
- Uncertain knowledge
 - Multiple causes lead to multiple effects
 - Incomplete knowledge of causality in the domain
 - Probabilistic/stochastic effects
- Uncertain knowledge representation
 - restricted model of the real system
 - limited expressiveness of the representation mechanism
- inference process
 - Derived result is formally correct, but wrong in the real world
 - New conclusions are not well-founded (eg, inductive reasoning)
 - Incomplete, default reasoning methods

Reasoning Under Uncertainty

- So how do we do reasoning under uncertainty and with inexact knowledge?
 - heuristics
 - ways to mimic heuristic knowledge processing methods used by experts
 - empirical associations
 - experiential reasoning
 - based on limited observations
 - probabilities
 - objective (frequency counting)
 - subjective (human experience)

Decision making with uncertainty

Rational behavior:

- For each possible action, identify the possible outcomes
- Compute the probability of each outcome
- Compute the utility of each outcome
- Compute the probability-weighted (expected)
 utility over possible outcomes for each action
- Select the action with the highest expected utility (principle of Maximum Expected Utility)

Some Relevant Factors

- expressiveness
 - can concepts used by humans be represented adequately?
 - can the confidence of experts in their decisions be expressed?
- comprehensibility
 - representation of uncertainty
 - utilization in reasoning methods
- correctness
 - probabilities
 - relevance ranking
 - long inference chains
- computational complexity
 - feasibility of calculations for practical purposes
- reproducibility
 - will observations deliver the same results when repeated?

Basics of Probability Theory

- mathematical approach for processing uncertain information
 - sample space set $X = \{x1, x2, ..., xn\}$
 - collection of all possible events
 - can be discrete or continuous
 - probability number P(xi): likelihood of an event xi to occur
 - non-negative value in [0,1]
 - total probability of the sample space is 1
 - for mutually exclusive events, the probability for at least one of them is the sum of their individual probabilities
 - experimental probability
 - based on the frequency of events
 - subjective probability
 - based on expert assessment

Compound Probabilities

- describes independent events
 - do not affect each other in any way
- joint probability of two independent events A and B

$$P(A \cap B) = P(A) * P(B)$$

union probability of two independent events A and B

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

= $P(A) + P(B) - P(A) * P(B)$

Probability theory

- Random variables
 - Domain
- Atomic event: complete specification of state
- Prior probability: degree of belief without any other evidence
- Joint probability: matrix of combined probabilities of a set of variables

- Alarm, Burglary, Earthquake
 - Boolean (like these), discrete, continuous
- Alarm=True ∧ Burglary=True ∧
 Earthquake=False
 alarm ∧ burglary ∧ earthquake
- P(Burglary) = .1
- P(Alarm, Burglary) =

	alarm	¬alarm
burglary	.09	.01
¬burglary	.1	.8

Probability theory (cont.)

- Conditional probability: probability of effect given causes
- Computing conditional probs:

$$- P(a \mid b) = P(a \land b) / P(b)$$

- P(b): normalizing constant
- Product rule:

$$- P(a \wedge b) = P(a \mid b) P(b)$$

• Marginalizing:

-
$$P(B) = \Sigma_a P(B, a)$$

-
$$P(B) = \Sigma_a P(B \mid a) P(a)$$

(conditioning)

- P(burglary | alarm) = .47P(alarm | burglary) = .9
- P(burglary | alarm) =
 P(burglary ∧ alarm) / P(alarm)
 = .09 / .19 = .47
- P(burglary ∧ alarm) =
 P(burglary | alarm) P(alarm) =
 .47 * .19 = .09
- P(alarm) =
 P(alarm ∧ burglary) +
 P(alarm ∧ ¬burglary) =
 .09+.1 = .19

Independence

- When two sets of propositions do not affect each others' probabilities, we call them independent, and can easily compute their joint and conditional probability:
 - Independent (A, B) if $P(A \wedge B) = P(A) P(B)$, $P(A \mid B) = P(A)$
- For example, {moon-phase, light-level} might be independent of {burglary, alarm, earthquake}
 - Then again, it might not: Burglars might be more likely to burglarize houses when there's a new moon (and hence little light)
 - But if we know the light level, the moon phase doesn't affect whether we are burglarized
 - Once we're burglarized, light level doesn't affect whether the alarm goes off
- We need a more complex notion of independence, and methods for reasoning about these kinds of relationships

Exercise: Independence

p(smart ∧	smart		⊣smart	
study ∧ prep)	study	¬study	study	⊣study
prepared	.432	.16	.084	.008
¬prepared	.048	.16	.036	.072

□ Queries:

- Is smart independent of study?
- Is *prepared* independent of *study*?

Conditional independence

- Absolute independence:
 - A and B are **independent** if $P(A \wedge B) = P(A) P(B)$; equivalently, $P(A) = P(A \mid B)$ and $P(B) = P(B \mid A)$
- A and B are conditionally independent given C if
 - $-P(A \wedge B \mid C) = P(A \mid C) P(B \mid C)$
- This lets us decompose the joint distribution:
 - $P(A \land B \land C) = P(A \mid C) P(B \mid C) P(C)$
- Moon-Phase and Burglary are conditionally independent given Light-Level
- Conditional independence is weaker than absolute independence, but still useful in decomposing the full joint probability distribution

Exercise: Conditional independence

ro / o ros o ret	smart		⊸smart	
p(smart ∧ study ∧ prep)	study	⊸study	study	⊸study
prepared	.432	.16	.084	.008
¬prepared	.048	.16	.036	.072

□ Queries:

- Is smart conditionally independent of prepared, given study?
- Is study conditionally independent of prepared, given smart?

Conditional Probabilities

- describes dependent events
 - affect each other in some way
- conditional probability of event a given that event B has already occurred
 P(A|B) = P(A ∩ B) / P(B)

Bayesian Approaches

- derive the probability of an event given another event
- Often useful for diagnosis:
 - If X are (observed) effects and Y are (hidden) causes,
 - We may have a model for how causes lead to effects (P(X | Y))
 - We may also have prior beliefs (based on experience) about the frequency of occurrence of effects (P(Y))
 - Which allows us to reason abductively from effects to causes (P(Y | X)).
- has gained importance recently due to advances in efficiency
 - more computational power available
 - better methods

Bayes' Rule for Single Event

- single hypothesis H, single event E
 P(H|E) = (P(E|H) * P(H)) / P(E)
 or
- P(H|E) = (P(E|H) * P(H) / (P(E|H) * P(H) + P(E|¬H) * P(¬H))

Bayes Example: Diagnosing Meningitis

- Suppose we know that
 - Stiff neck is a symptom in 50% of meningitis cases
 - Meningitis (m) occurs in 1/50,000 patients
 - Stiff neck (s) occurs in 1/20 patients
- Then
 - -P(s|m) = 0.5, P(m) = 1/50000, P(s) = 1/20
 - -P(m|s) = (P(s|m) P(m))/P(s) $= (0.5 \times 1/50000) / 1/20 = .0002$
- So we expect that one in 5000 patients with a stiff neck to have meningitis.

Advantages and Problems Of Bayesian Reasoning

- advantages
 - sound theoretical foundation
 - well-defined semantics for decision making
- problems
 - requires large amounts of probability data
 - sufficient sample sizes
 - subjective evidence may not be reliable
 - independence of evidences assumption often not valid
 - relationship between hypothesis and evidence is reduced to a number
 - explanations for the user difficult
 - high computational overhead

Some Issues with Probabilities

- Often don't have the data
 - Just don't have enough observations
 - Data can't readily be reduced to numbers or frequencies.
- Human estimates of probabilities are notoriously inaccurate.
 In particular, often add up to >1.
- Doesn't always match human reasoning well.
 - P(x) = 1 P(-x). Having a stiff neck is strong (.9998!) evidence that you don't have meningitis. True, but counterintuitive.
- Several other approaches for uncertainty address some of these problems.

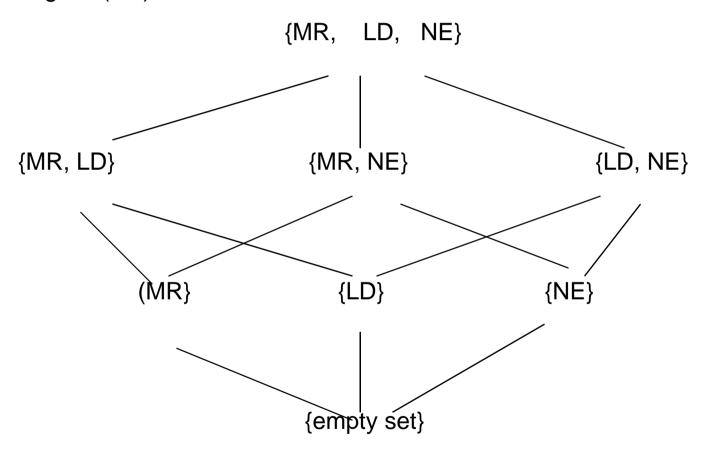
Dempster-Shafer Theory

- mathematical theory of evidence
- Notations
 - Environment T: set of objects that are of interest
 - frame of discernment FD
 - power set of the set of possible elements
 - mass probability function m
 - assigns a value from [0,1] to every item in the frame of discernment
 - mass probability m(A)
 - portion of the total mass probability that is assigned to an element A of FD

D-S Underlying concept

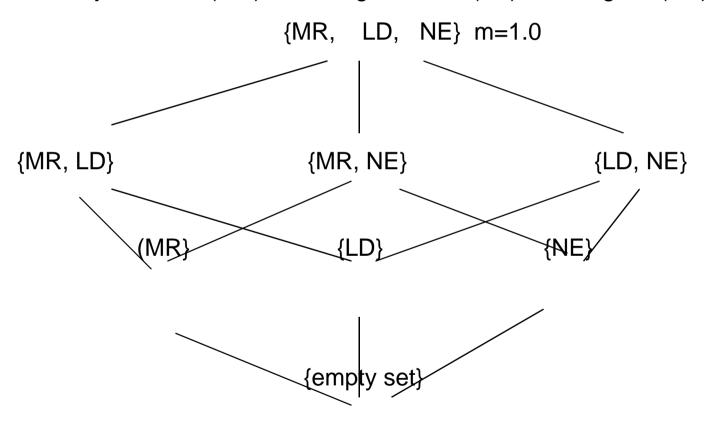
- The most basic problem with uncertainty is often with the axiom that P(X) + P(not X) = 1
 - If the probability that you have poison ivy when you have a rash is .3, this means that a rash is strongly suggestive (.7) that you don't have poison ivy.
 - True, in a sense, but neither intuitive nor helpful.
- What you really mean is that the probability is .3 that you have poison ivy and .7 that we don't know yet what you have.
- So we initially assign all of the probability to the total set of things you *might* have: the frame of discernment.

Example: Frame of Discernment



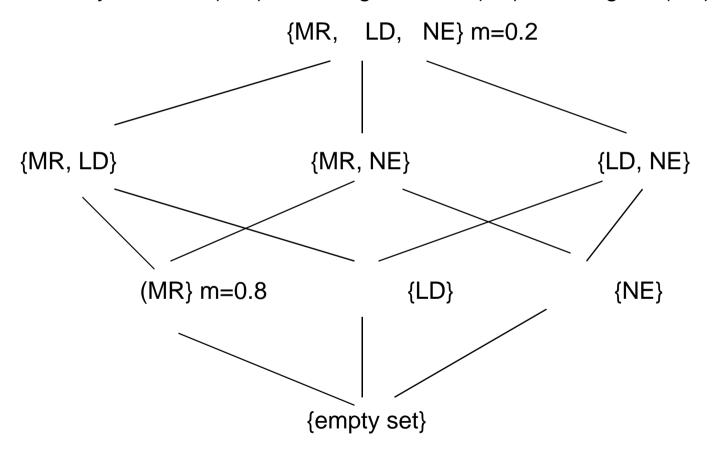
Example: We don't know anything

Frame of Discernment:



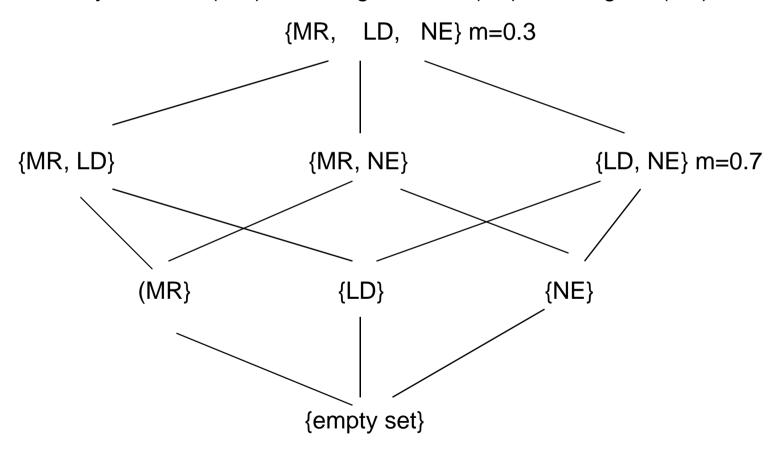
Example: We believe MR at 0.8

Frame of Discernment:



Example: We believe NOT MR at 0.7

Frame of Discernment:

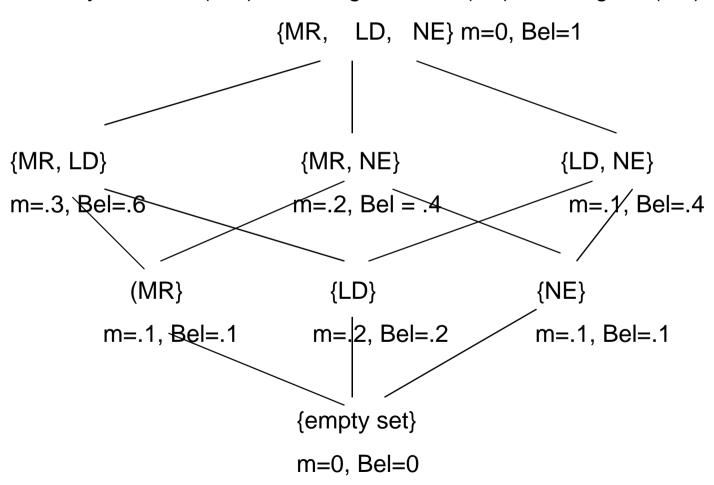


Belief and Certainty

- belief Bel(A) in a subset A
 - sum of the mass probabilities of all the proper subsets of A
 - likelihood that one of its members is the conclusion
- plausibility Pls(A)
 - maximum belief of A, upper bound
 - -1 Bel(not A)
- certainty Cer(A)
 - interval [Bel(A), Pls(A)]
 - expresses the range of belief

Example: Bel, Pls

Frame of Discernment:



Interpretation: Some Evidential Intervals

- Completely true: [1,1]
- Completely false: [0,0]
- Completely ignorant: [0,1]
- Doubt -- disbelief in X: Dbt = Bel(not X)
- Ignorance -- range of uncertainty: Igr =Pls-Bel
- Tends to support: [Bel, 1] (0<Bel<1)
- Tends to refute: [0, Pls] (0>Pls<1)
- Tends to both support and refute: [Bel, Pls] (0<Bel<Pls<1)

Advantages and Problems of Dempster-Shafer

advantages

- clear, rigorous foundation
- ability to express confidence through intervals
 - certainty about certainty

problems

- non-intuitive determination of mass probability
- very high computational overhead
- may produce counterintuitive results due to normalization when probabilities are combined
- Still hard to get numbers

Certainty Factors

- shares some foundations with Dempster-Shafer theory, but more practical
- denotes the belief in a hypothesis H given that some pieces of evidence are observed
- no statements about the belief is no evidence is present
 - in contrast to Bayes' method

Belief and Disbelief

- measure of belief
 - degree to which hypothesis H is supported by evidence E
 - -MB(H,E) = 1 IF P(H) = 1(P(H|E) - P(H)) / (1-P(H)) otherwise
- measure of disbelief
 - degree to which doubt in hypothesis H is supported by evidence E
 - -MB(H,E) = 1 IF P(H) = 0(P(H) - P(H|E)) / P(H)) otherwise

Certainty Factor

- certainty factor CF
 - ranges between -1 (denial of the hypothesis H) and 1 (confirmation of H)
- CF = (MB MD) / (1 min (MD, MB))
- combining antecedent evidence
 - use of premises with less than absolute confidence
 - E1 ∧ E2 = min(CF(H, E1), CF(H, E2))
 - E1 \vee E2 = max(CF(H, E1), CF(H, E2))
 - $\neg E = \neg CF(H, E)$

Combining Certainty Factors

- certainty factors that support the same conclusion
- several rules can lead to the same conclusion
- applied incrementally as new evidence becomes available
- Cfrev(CFold, CFnew) =
 - CFold + CFnew(1 CFold) if both > 0
 - CFold + CFnew(1 + CFold) if both < 0</p>
 - CFold + CFnew / (1 min(|CFold|, |CFnew|)) if one < 0</p>

Advantages of Certainty Factors

- Advantages
 - simple implementation
 - reasonable modeling of human experts' belief
 - expression of belief and disbelief
 - successful applications for certain problem classes
 - evidence relatively easy to gather
 - no statistical base required

Problems of Certainty Factors

Problems

- partially ad hoc approach
 - theoretical foundation through Dempster-Shafer theory was developed later
- combination of non-independent evidence unsatisfactory
- new knowledge may require changes in the certainty factors of existing knowledge
- certainty factors can become the opposite of conditional probabilities for certain cases
- not suitable for long inference chains

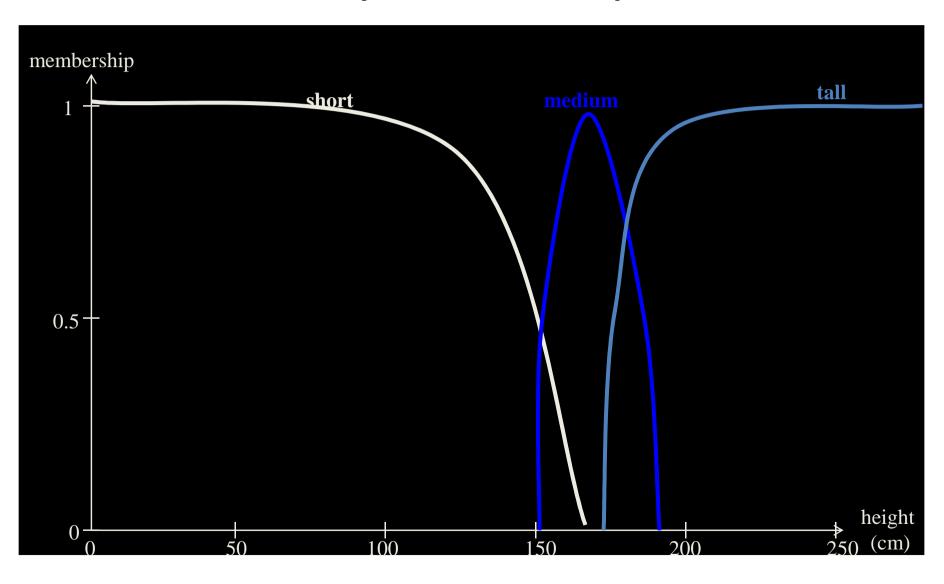
Fuzzy Logic

- approach to a formal treatment of uncertainty
- relies on quantifying and reasoning through natural (or at least non-mathematical) language
- Rejects the underlying concept of an excluded middle: things have a degree of membership in a concept or set
 - Are you tall?
 - Are you rich?
- As long as we have a way to formally describe degree of membership and a way to combine degrees of memberships, we can reason.

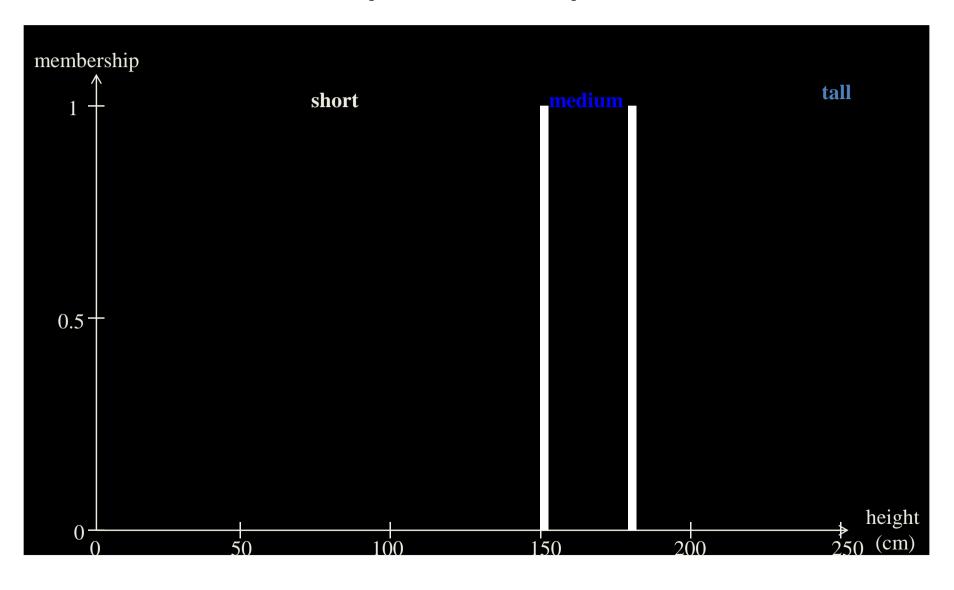
Fuzzy Set

- categorization of elements xi into a set S
 - described through a membership function m(s)
 - associates each element xi with a degree of membership in S
- possibility measure Poss{x∈S}
 - degree to which an individual element x is a potential member in the fuzzy set S
 - combination of multiple premises
 - $Poss(A \wedge B) = min(Poss(A), Poss(B))$
 - $Poss(A \lor B) = max(Poss(A), Poss(B))$

Fuzzy Set Example



Fuzzy vs. Crisp Set



Fuzzy Reasoning

- In order to implement a fuzzy reasoning system you need
 - For each variable, a defined set of values for membership
 - Can be numeric (1 to 10)
 - Can be linguistic
 - really no, no, maybe, yes, really yes
 - tiny, small, medium, large, gigantic
 - good, okay, bad
 - And you need a set of rules for combining them
 - Good and bad = okay.

Fuzzy Inference Methods

- Lots of ways to combine evidence across rules
 - $-\operatorname{Poss}(B|A) = \min(1, (1 \operatorname{Poss}(A) + \operatorname{Poss}(B)))$
 - implication according to Max-Min inference
 - also Max-Product inference and other rules
 - formal foundation through Lukasiewicz logic
 - extension of binary logic to infinite-valued logic
- Can be enumerated or calculated.

Some Additional Fuzzy Concepts

- Support set: all elements with membership > 0
- Alpha-cut set: all elements with membership greater than alpha
- Height: maximum grade of membership
- Normalized: height = 1

Some typical domains

- Control (subways, camera focus)
- Pattern Recognition (OCR, video stabilization)
- Inference (diagnosis, planning, NLP)

Advantages and Problems of Fuzzy Logic

advantages

- general theory of uncertainty
- wide applicability, many practical applications
- natural use of vague and imprecise concepts
 - helpful for commonsense reasoning, explanation

problems

- membership functions can be difficult to find
- multiple ways for combining evidence
- problems with long inference chains

Uncertainty: Conclusions

- In AI we must often represent and reason about uncertain information
- This is no different from what people do all the time!
- There are multiple approaches to handling uncertainty.
- Probabilistic methods are most rigorous but often hard to apply;
 Bayesian reasoning and Dempster-Shafer extend it to handle problems of independence and ignorance of data
- Fuzzy logic provides an alternate approach which better supports ill-defined or non-numeric domains.
- Empirically, it is often the case that the main need is some way of expressing "maybe". Any system which provides for at least a three-valued logic tends to yield the same decisions.