

# MATRIX WORKSHOP LEARNING SHEET

**Goal:** Understand and practice matrix operations, inverses, transposes, multiplications, change of basis, and numerical derivatives.

## I. Concept Refresher — Without Computing

### 1. Matrix Inverse & Identity

If  $A$  is invertible:

$A * A^{-1} = A^{-1} * A = I$  (identity matrix).

### 2. Matrix Multiplication Basics

If  $A$  is  $n \times m$  and  $B$  is  $m \times k$ , then  $A * B$  is  $n \times k$ .

Matrix multiplication is not commutative ( $A * B \neq B * A$ ).

### 3. Simplifying Matrix Expressions

Use  $A * A^{-1} = I$  and  $B * B^{-1} = I$  repeatedly to simplify long products.

## II. Working with NumPy

Useful functions:

- Transpose: `np.transpose(X)` or `X.T`
- Multiply: `np.dot(X, Y)` or `X.dot(Y)`
- Inverse: `np.linalg.inv(X)`
- Addition/Subtraction: `+`, `-`

## III. Change of Basis Verification

Formula:  $T_{\text{new}} = P^{-1} * T_{\text{std}} * P$

Check that  $T_{\text{new}} * P^{-1} * v_{\text{std}} = P^{-1} * T_{\text{std}} * v_{\text{std}}$ .

If `np.allclose(left, right)` returns `True`, the formula is verified.

General rotation matrix:

$T_{\text{std}}(\theta) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$

## IV. Numerical Derivative

Approximation formula:

$f'(x_i) \approx (f(x_{i+1}) - f(x_{i-1})) / (x_{i+1} - x_{i-1})$

Use central difference for better accuracy.

## V. Self-Learning: Properties of Square Matrices

**Determinant:**

- For 2x2:  $ad - bc$
- $\det(AB) = \det(A) * \det(B)$
- $\det(A^T) = \det(A)$
- $\det(A^{-1}) = 1 / \det(A)$
- $\det(A) = 0 \rightarrow$  matrix not invertible.

**Eigenvalues & Eigenvectors:**

$A * v = \lambda * v$ ; solve  $|A - \lambda * I| = 0$  for  $\lambda$ .

Each  $\lambda$  has one or more eigenvectors.

**Diagonalization:**

$A = P * D * P^{-1}$ , where  $D$  is diagonal (eigenvalues) and columns of  $P$  are eigenvectors.

Possible only if  $A$  has enough independent eigenvectors.

**Summary Checklist:**

- Simplify  $A * A^{-1} = I$
- Predict output matrix sizes
- Compute transpose, inverse, and product
- Verify change-of-basis formula
- Implement central-difference derivative
- Understand determinant, eigenvalues, diagonalization