

## HW2

### 2.13

2.13

$$g(\bar{w}) = -\cos(2\pi \bar{w}^T \bar{w}) + 2\bar{w}^T \bar{w}$$

$$\nabla g(\bar{w}) = 4\pi \sin(2\pi \bar{w}^T \bar{w}) \bar{w} + 4\bar{w}$$

$\text{[in, out]} = \text{gradient\_descent}(\alpha, w_0)$

$\uparrow$  initial point.  
fixed step length

in =  $\{\bar{w}^k = \bar{w}^{k-1} - \alpha \nabla g(\bar{w}^{k-1})\}_{k=0}^K$   
out =  $\{g(\bar{w}^k)\}_{k=0}^K$        $K$  - total number of steps

code:

```
max_its = 50
while linalg.norm(grad) > 10**(-5) and iter <= max_its:
    # take gradient step
    grad = 2*w + 4*pi*sin(2*pi*dot(w.T,w))*w # 2.13
```

Whole program please see file two\_d\_grad\_wrapper\_hw.py

### 2.17

2.17

(a)  $\nabla g(\bar{w}) = \frac{1}{1+e^{\bar{w}^T \bar{w}}} \cdot 2e^{\bar{w}^T \bar{w}} \bar{w}$

(b)  $\frac{\partial}{\partial w_i} g(\bar{w}) = \frac{1}{1+e^{\sum_{j=1}^n w_j^2}} \cdot 2e^{\sum_{j=1}^n w_j^2} \cdot w_i$

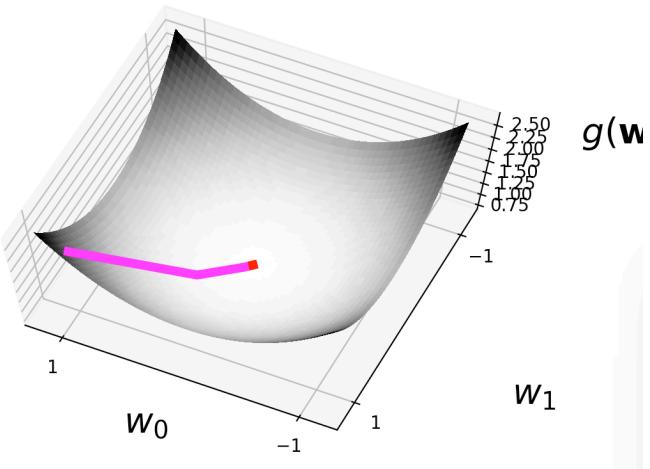
Let  $\nabla g(\bar{w}) = 0$ . So, the unique stationary point is  $\bar{w} = [0, 0]^T$

$\frac{\partial^2}{\partial w_i \partial w_j} g(\bar{w}) = \begin{cases} \frac{1}{(1+e^{\sum_{j=1}^n w_j^2})^2} 2e^{\sum_{j=1}^n w_j^2} \cdot w_i w_j + \frac{1}{(1+e^{\sum_{j=1}^n w_j^2})} e^{\sum_{j=1}^n w_j^2} \cdot 2 & i=j \\ \frac{1}{(1+e^{\sum_{j=1}^n w_j^2})^2} 4e^{\sum_{j=1}^n w_j^2} w_i w_j & \text{otherwise.} \end{cases}$

$\nabla^2 g(\bar{w}) = \frac{e^{\bar{w}^T \bar{w}}}{(1+e^{\bar{w}^T \bar{w}})^2} \cdot 4\bar{w}^T \bar{w} + 2 \cdot \frac{e^{\bar{w}^T \bar{w}}}{1+e^{\bar{w}^T \bar{w}}} \cdot \bar{I}_{N \times N}$

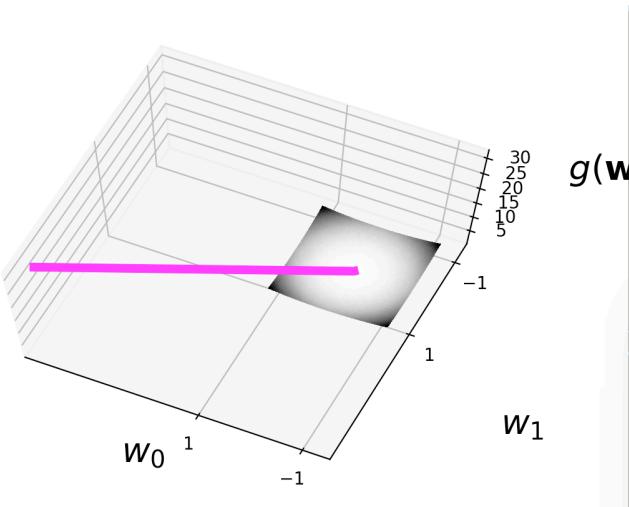
according to exercise 2.10,  $\bar{w}^T \bar{w}$  has all non-negative eigenvalues, so  $\nabla^2 g(\bar{w})$  is non-negative, which means  $g(\bar{w})$  is convex. the stationary point in a) is global minimum.

(c)



```
##### ML Algorithm functions #####
def gradient_descent(w0):
    w = w0
    g_path = []
    w_path = []
    w_path.append(w)
    #g_path.append(-cos(2*pi*dot(w.T,w)) + 2*dot(w.T,w))      # 2.13
    g_path.append(np.log(1 + np.e ** dot(w.T,w)))           # 2.14
    # start gradient descent loop
    grad_1 = 1
    grad_2 = 1
    iter = 1
    max_its = 10
    while iter <= max_its:
        # take gradient step
        #grad = 2*w + 4*pi*sin(2*pi*dot(w.T,w))*w      # 2.15
        I = np.eye(2)
        grad_1 = (1 / (1 + np.e ** dot(w.T,w))) * 2 * (np.e ** (dot(w.T,w))) * w
        grad_2 = 4*(np.e**dot(w.T,w))*dot(w,w.T) / (1 + np.e**dot(w.T,w))**2 + (2 * np.e**dot(w.T,w)) / (1 + np.e**dot(w.T,w)) * I
        w = w - dot(linalg.inv(grad_2),grad_1)
        print w
        # update path containers
        w_path.append(w)
        #g_path.append(-cos(2*pi*dot(w.T,w)) + 2*dot(w.T,w))      # 2.13
        g_path.append(np.log(1 + np.e ** dot(w.T,w)))           # 2.14
        iter+= 1
    g_path = asarray(g_path)
    g_path.shape = (iter,1)
    w_path = asarray(w_path)
    w_path.shape = (iter,2)
```

(d)



$$(d). \quad g(\bar{w}) = \log(1 + e^{\bar{w}^\top \bar{w}}) \quad \bar{w} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} \quad \Rightarrow \quad g(\bar{w}) \approx \bar{w}^\top \bar{w}$$

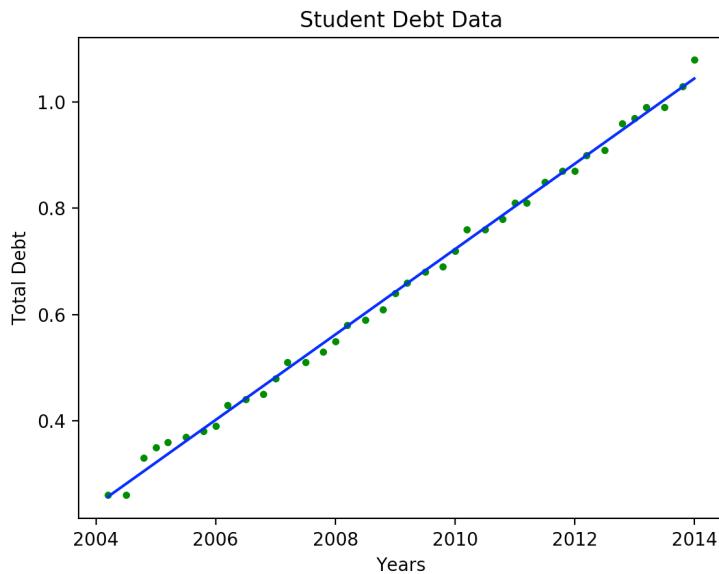
$$\begin{aligned} h(\bar{w}) &= g(\bar{w}^0) + \nabla g(\bar{w}^0)^\top (\bar{w} - \bar{w}^0) + \frac{1}{2} (\bar{w} - \bar{w}^0)^\top \nabla^2 g(\bar{w}^0) (\bar{w} - \bar{w}^0) \\ &= \bar{w}^0 \bar{w}^0 + 2 \bar{w}^0 \bar{w} + \frac{1}{2} (\bar{w} - \bar{w}^0)^\top \cdot 2 (\bar{w} - \bar{w}^0) \\ &= \cancel{\bar{w}^0 \bar{w}^0} + 2 \bar{w}^0 \bar{w} - \cancel{2 \bar{w}^0 \bar{w}^0} + \bar{w}^\top \bar{w} - \cancel{2 \bar{w}^0 \bar{w}} + \cancel{\bar{w}^0 \bar{w}^0} \\ &= \bar{w}^\top \bar{w} \end{aligned}$$

Let  $\nabla h(\bar{w}) = 2\bar{w} = 0 \quad \boxed{\bar{w} = [0 \ 0]}$  which is stationary point.

$\therefore$  Because initialization is further away,  $g(\bar{w}) = \log(1 + e^{\bar{w}^\top \bar{w}}) = \bar{w}^\top \bar{w}$ , the second Taylor g(w) is the minimum of  $g(\bar{w})$  itself.

For (c) and (d), please see the file NewTon\_Method\_2\_17.py in zip.

### 3.1



$$3.1. \quad g(\tilde{w}) = \sum_{p=1}^P (\tilde{x}_p^\top \tilde{w} - y_p)^2$$

$$\nabla g(\tilde{w}) = 2 \sum_{p=1}^P \tilde{x}_p (\tilde{x}_p^\top \tilde{w} - y_p) = 2 \left( \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^\top \right) \tilde{w} - 2 \sum_{p=1}^P \tilde{x}_p y_p$$

Let  $\nabla g(\tilde{w}) = 0$

$$\left( \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^\top \right) \tilde{w} = \sum_{p=1}^P \tilde{x}_p y_p$$

$$\boxed{\tilde{w}^* = \left( \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^\top \right)^{-1} \sum_{p=1}^P \tilde{x}_p y_p}$$

Through programming, we can predict that the total student debt will be  $3.9360119666$  in 2050

```

def read_data(filename):
    f = open(filename)
    csv_f = csv.reader(f)
    x = []
    y = []
    for row in csv_f:
        temp = array([1, float(row[0])])
        temp.shape = (2, 1)
        x.append(temp)
        y.append(float(row[1]))
    return x, y

def basic_linear_regression(x,y):
    A = array([0., 0., 0., 0.])
    A.shape = (2,2)
    for i in x:
        A += dot(i,i.T)
    A_inv = pinv(A)

    b = array([0., 0.])
    b.shape = (2,1)
    for i in range(len(x)):
        b += y[i] * x[i]
    w = dot(A_inv,b)
    return w

def main():
    x, y = read_data('student_debt.csv') # plot objective function
    w = basic_linear_regression(x,y)
    _x = []
    _y = []
    _b = w[0][0]
    _w = w[1][0]
    for i in range(len(x)):
        _x.append(x[i][1])
        temp = x[i][1] * _w + _b
        _y.append(temp)
    print(w)
    predict = _b + _w * 2050
    print(predict)

    plt.plot(_x,_y,'g.')
    plt.plot(_x,_y,'b')
    plt.title('Student Debt Data')
    plt.xlabel('Years')
    plt.ylabel('Total Debt')
    show()
main()

```

For 3.1, please see the file exercise\_regression\_line\_3\_1.py in zip.

### 3.3

3.3.

$$a). g(\tilde{w}) = \sum_{p=1}^P (\tilde{x}_p^T \tilde{w} - y_p)^2$$

$$= \sum_{p=1}^P [(\tilde{x}_p^T \tilde{w})^T (\tilde{x}_p^T \tilde{w}) - 2y_p (\tilde{x}_p^T \tilde{w}) + y_p^2]$$

$$= \sum_{p=1}^P [\frac{1}{2} \tilde{w}^T (2\tilde{x}_p \tilde{x}_p^T) \tilde{w} - 2y_p (\tilde{x}_p^T \tilde{w}) + y_p^2]$$

point in  $w_0$  is global minimum

$$\boxed{\bar{Q} = 2 \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^T}, \quad \boxed{\bar{r} = -2 \sum_{p=1}^P y_p \tilde{x}_p^T}, \quad \boxed{d = \sum_{p=1}^P y_p^2}$$

$$c) \nabla g(\tilde{w}) = \frac{1}{2} (\bar{Q} + \bar{Q}^T) \tilde{w} + \bar{r}$$

$$\nabla^2 g(\tilde{w}) = \bar{Q}$$

Because  $\bar{Q}$  has <sup>all</sup> non-negative eigenvalues (from (b)), so  $g(\tilde{w})$  convex.

$$d). g(\tilde{w}) = \sum_{p=1}^P (\tilde{x}_p^T \tilde{w} - y_p)^2$$

$$\nabla g(\tilde{w}) = -\bar{Q} \tilde{w} + \bar{r}, \quad \nabla^2 g(\tilde{w}) = \bar{Q}$$

$$h(\tilde{w}) = g(\tilde{w}_0) + \nabla g(\tilde{w}_0)^T (\tilde{w} - \tilde{w}_0) + \frac{1}{2} (\tilde{w} - \tilde{w}_0)^T \nabla^2 g(\tilde{w}_0) (\tilde{w} - \tilde{w}_0)$$

$$\text{Let } \nabla h(\tilde{w}) = \nabla g(\tilde{w}_0) + \nabla^2 g(\tilde{w}_0) (\tilde{w} - \tilde{w}_0) = 0$$

$$\bar{r} + \bar{Q}^T \tilde{w}_0 + \bar{Q}^T (\tilde{w} - \tilde{w}_0) = 0$$

$$\bar{r} + \bar{Q} \tilde{w} = 0 \quad \Rightarrow \quad -\sum_{p=1}^P \tilde{x}_p^T y_p + \left( \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^T \right) \tilde{w} = 0 \quad \Rightarrow \quad \boxed{\left( \sum_{p=1}^P \tilde{x}_p \tilde{x}_p^T \right) \tilde{w} = \sum_{p=1}^P \tilde{x}_p y_p}$$

which is first order system of linear equations

### 3.10

3.10.

$$(a) \text{ logistic sigmoid: } \sigma(t) = \frac{1}{1+e^{-t}}$$

$$\sigma^{-1}(t) = \log\left(\frac{t}{1-t}\right) \Rightarrow \sigma^{-1}(\sigma(t)) = \log\left(\frac{\frac{1}{1+e^{-t}}}{1-\frac{1}{1+e^{-t}}}\right) = \log(e^t) = t.$$

Therefore, that indeed  $\sigma^{-1}(\sigma(t)) = t$  for all such values of  $t$ .

(b).

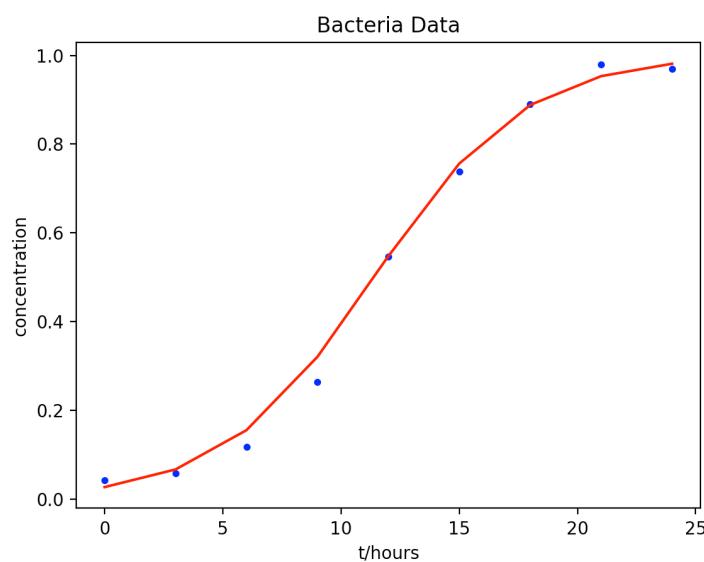
$$\text{for 3.24 } \sigma(b+x_p w) \approx y_p, \quad p=1, \dots, P.$$

then, we could obtain

$$\sigma^{-1}(\sigma(b+x_p w)) = \log\left(\frac{\frac{1}{1+e^{-(b+x_p w)}}}{1-\frac{1}{1+e^{-(b+x_p w)}}}\right) = \log(e^{b+x_p w}) = b+x_p w$$

$$b+x_p w = \log\left(\frac{y_p}{1-y_p}\right), \quad p=1, \dots, P$$

(c)



```

▼ def read_data(filename):
    f = open(filename)
    csv_f = csv.reader(f)
    x = []
    y = []
    ▼ for row in csv_f:
        temp = array([1, float(row[0])])
        temp.shape = (2, 1)
        x.append(temp)
        y.append(float(row[1]))
    print(y)
    return x, y

▼ def basic_linear_regression(x,y):
    A = array([0.,0.,0.,0.])
    A.shape = (2,2)
    for i in x:
        A += dot(i,i.T)
    A_inv = pinv(A)

    b = array([0.,0.])
    b.shape = (2,1)
    for i in range(len(x)):
        b += y[i] * x[i]
    w = dot(A_inv,b)
    return w

▼ def main():
    x, y = read_data('bacteria_data.csv') # plot objective function
    y_p = []
    ▼ for i in y:
        temp = np.log((i) / (1 - i))
        y_p.append(temp)
    w = basic_linear_regression(x,y_p)
    _x = []
    _y = []
    _b = w[0][0]
    _w = w[1][0]
    print(w)
    ▼ for i in range(len(x)):
        _x.append(x[i][1])
        temp = np.e**(_b + x[i][1] * _w) / (1 + np.e**(_b + x[i][1] * _w))
        _y.append(temp)
    # print(w)
    # predict = _b + _w * 2050
    # print(predict)

    plt.plot(_x,_y,'b.')
    plt.plot(_x,_y,'r')
    plt.title('Bacteria Data')
    plt.xlabel('t/hours')
    plt.ylabel('concentration')
    show()
main()

```

Please see file Logistic\_regression\_3\_10.py in zip