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2.1

$$1) g(w) = \frac{1}{2} gw^2 + rw + d.$$

$$\text{First: } g'(w) = \frac{\partial g(w)}{\partial w} = gw + r$$

$$\text{second: } g''(w) = \frac{\partial^2 g(w)}{\partial w^2} = g$$

$$2) g(w) = -\cos(2\pi w^2) + w^2$$

$$\text{First: } g'(w) = [\sin(2\pi w^2)] \cdot 4\pi w + 2w$$

$$\begin{aligned} \text{second: } g''(w) &= [\cos(2\pi w^2)] (4\pi w)^2 + [\sin(2\pi w^2)] (4\pi) + 2 \\ &= 4\pi [4\pi w^2 \cos(2\pi w^2) + \sin(2\pi w^2)] + 2. \end{aligned}$$

$$3). g(w) = \sum_{p=1}^P \log(1 + e^{-\alpha_p w})$$

$$\text{First: } g'(w) = \sum_{p=1}^P \left( \frac{1}{1 + e^{-\alpha_p w}} e^{-\alpha_p w} \cdot (-\alpha_p) \right)$$

$$= \sum_{p=1}^P \left( \frac{-\alpha_p e^{-\alpha_p w}}{1 + e^{-\alpha_p w}} \right)$$

$$\begin{aligned} \text{second: } g''(w) &= \sum_{p=1}^P \frac{(\alpha_p^2 e^{-\alpha_p w})(1 + e^{-\alpha_p w}) - \alpha_p^2 e^{-2\alpha_p w}}{(1 + e^{-\alpha_p w})^2} \\ &= \sum_{p=1}^P \frac{\alpha_p^2 e^{-\alpha_p w}}{(1 + e^{-\alpha_p w})^2} \end{aligned}$$

$$2.2 \quad 1) g(\bar{w}) = \frac{1}{2} \bar{w}^T \bar{Q} \bar{w} + \bar{r}^T \bar{w} + d$$

$$\text{Gradient: } \nabla_{\bar{w}} g(\bar{w}) = \frac{1}{2} (\bar{Q}^T \bar{w} + \bar{Q} \bar{w}) + \bar{r} = \frac{1}{2} (\bar{Q} \bar{w} + \bar{Q} \bar{w}) + \bar{r} = \bar{Q} \bar{w} + \bar{r}$$

Hessian:

$$\nabla_{\bar{w}}^2 g(\bar{w}) = \frac{1}{2} (\bar{Q} + \bar{Q}^T) = \bar{Q}$$

$$2) g(\bar{w}) = -\cos(2\pi \bar{w}^T \bar{w}) + \bar{w}^T \bar{w}$$

$$\text{Gradient: } \nabla_{\bar{w}} g(\bar{w}) = [\sin(2\pi \bar{w}^T \bar{w})] (4\pi \bar{w}) + 2\bar{w}$$

$$\text{Hessian: } \nabla_{\bar{w}}^2 g(\bar{w}) = [\cos(2\pi \bar{w}^T \bar{w})] (4\pi \bar{w})^2 + [\sin(2\pi \bar{w}^T \bar{w})] 4\pi + 2.$$

$$3) g(\bar{w}) = \sum_{p=1}^P \log(1 + e^{-\bar{a}_p^T \bar{w}})$$

$$\text{Gradient: } \nabla_{\bar{w}} g(\bar{w}) = \sum_{p=1}^P \left( \frac{-\bar{a}_p e^{-\bar{a}_p^T \bar{w}}}{1 + e^{-\bar{a}_p^T \bar{w}}} \right)$$

$$\text{Hessian: } \nabla_{\bar{w}}^2 g(\bar{w}) = \sum_{p=1}^P \frac{\bar{a}_p^T \bar{a}_p}{(1 + e^{-\bar{a}_p^T \bar{w}})^2}$$

2.5

$$\text{for } h(\bar{w}) = g(\bar{v}) + \nabla g(\bar{v})^T (\bar{w} - \bar{v})$$

$$h(\bar{w}) - g(\bar{v}) - \nabla^T g(\bar{v}) \bar{w} + \nabla^T g(\bar{v}) \bar{v} = 0$$

$$[1 \quad -\nabla^T g(\bar{v})] \begin{bmatrix} h(\bar{w}) \\ \bar{w}_1 \\ \vdots \\ \bar{w}_N \end{bmatrix} + \nabla^T g(\bar{v}) \bar{v} - g(\bar{v}) = 0.$$

$$\underbrace{n^T}_{\bar{w}} \begin{bmatrix} h \\ \bar{w}_1 \\ \vdots \\ \bar{w}_N \end{bmatrix} + r = 0$$

2.7:

$$1) g(w) = w^2 \quad g''(w) = 2 > 0 \quad \therefore \text{convex}$$

$$2) g(w) = e^{w^2} \quad g'(w) = 2e^{w^2}w, \quad g''(w) = 2e^{w^2} + 4w^2e^{w^2} > 0 \quad \therefore \text{convex}$$

$$3) g(w) = \log(1+e^w) \quad g''(w) = \frac{2e^{w^2}(2w^2+e^{w^2}+1)}{(1+e^{w^2})^2} > 0 \quad \therefore \text{convex}$$

$$4) g(w) = -\log(w) \quad g'(w) = \frac{1}{w \ln 2} \quad g''(w) = \frac{1}{w^2 \ln 2} > 0 \quad \therefore \text{convex}$$

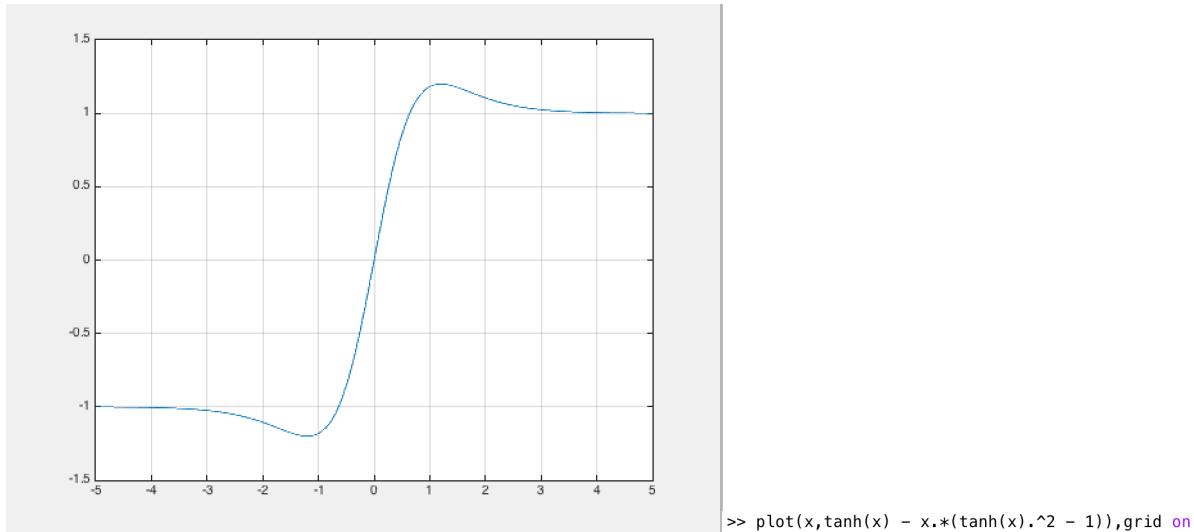
## 2.8

$$(1) g(w) = w \cdot \tanh(w)$$

$$\frac{dg(w)}{dw} = \tanh(w) - w \cdot ((\tanh(w))^2 - 1)$$

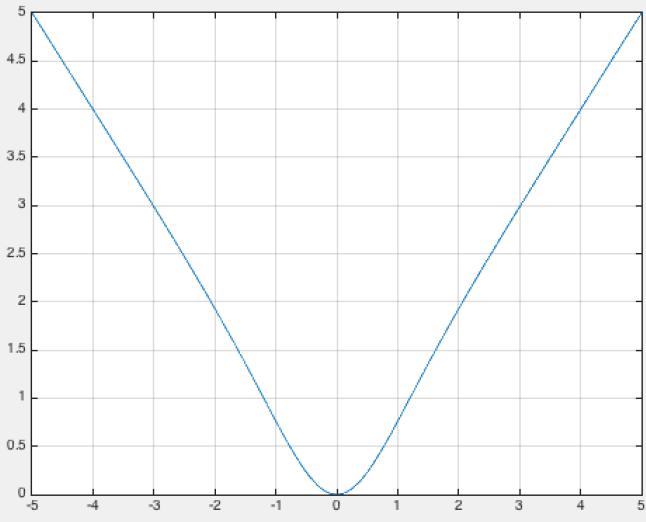
After we that the first order equal to 0, then we can obtain that  $w = 0$ .

This figure show the  $\frac{dg(w)}{dw}$ , and we can find that  $w = 0$  is the stationary point.



To check the answer, we plot the  $g(w)$ , that shows the stationary point is the global minimal point.

```
x = -5:0.01:5;
plot(x,x.*tanh(x)),grid on
```



(2)

After plot the second order of the  $g(w)$ ,  $g''(w) < 0$  at some point, so it is non-convex

```
>> f = x.*tanh(x);
>> g = diff(f)
```

```
g =
```

$$\tanh(x) - x * (\tanh(x)^2 - 1)$$

```
>> k = diff(g)
```

```
k =
```

$$2*x*tanh(x)*(tanh(x)^2 - 1) - 2*tanh(x)^2 + 2$$

```
>> plot(x,2.*x.*tanh(x).*(tanh(x).^2 - 1) - 2.*tanh(x).^2 + 2)
```

