Introduction to Pyro

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Goals for Today

- 1. Understanding the basic building blocks of Pyro
- 2. Building a simple Linear Regression Model in Pyro
- 3. Understanding the difference between an Autoencoder and Variational Autoencoder
- 4. Building a Variational Autoencoder in Pyro
- -> Keep the theory high-level -> Focus on practical coding exercises

Part o: Setting up the Workspace

Setting up the Workspace

Option 1: Local Jupyter Lab

- 1. Git clone the repo to your local machine
- 2. [Optional] create a new virtual environment with your favourite environment management tool
- 3. Install python requirements with pip3 install -r requirements.txt or poetry install if you use poetry
- 4. [Optional] Install graphviz, e.g. with sudo apt install graphviz on Ubuntu
- 5. Start a local Jupyter server and get ready to hack!

Option 2: Colab Environment

- 1. Go to Google Colab
- 2. Click on File -> Open Notebook -> GitHub
- 3. Enter github URL: https://github.com/pyladiesams/pyro-may2
 023
- 4. Find the part I and II notebooks and copy this code into the first cell of each of them.
- 5. Execute the first two cells.

Part I: Linear Regression in Pyro

Introduction: What is Pyro?

- Framework for probabilistic programing in Python
- Thin wrapper around PyTorch -> Comparable usage and syntax
- Flexible, lightweight framework
- Allows us to reason about uncertainty
 - Accepts prior assumptions (i.e. prior distributions) across parameters
 - Facilitates regularization of parameters
 - Can perform well in very high dimensional but sparse environments
 - Estimates posterior distributions of parameters and predictions

Building Blocks of Pyro

- PyroModule → Subclass or register torch modules as Pyro Modules (similar to torch.nn.Module)
- PyroSample → Specify distribution to draw samples from
- pyro.plate → Sample copies of a random variable
- SVI → Main inference algorithm of Pyro

PyroModule

- Used to subclass torch modules as Pyro modules
- Parameters of PyroModules are registered with Pyro's parameter store and can be regularized with PyroSample (see next slide)
- Initialized Pytorch modules can also be registered with pyro with pyro.module(name: str, object: nn.Module)

```
from torch import nn
from pyro.nn import PyroModule
assert issubclass(PyroModule[nn.Linear], nn.Linear)
assert issubclass(PyroModule[nn.Linear], PyroModule)
```

```
In [25]: pyro.get_param_store().get_all_param_names()
Out[25]: dict_keys([])
In [26]: _ = PyroModule[nn.Linear](3, 1)(X)
In [27]: pyro.get_param_store().get_all_param_names()
Out[27]: dict_keys(['weight', 'bias'])
```

PyroSample

- Initializes a tensor, that will draw a sample from a specified distribution whenever called!
- Regularized through a Pyro distribution
- Use expand and to_event to shape the output
- Use PyroParam for PyroModules, or pyro.sample for other variables

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a bA bR sigma obs data

a ~ Normal bA ~ Normal bR ~ Normal bAR ~ Normal sigma ~ Uniform obs ~ Normal

pyro.plate

- Technical implementation of plate notation in graphical models
- Context manager used to indicate repeated, independent sampling
- Usage: with pyro.plate(name: str, n_samples: int)

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SVI

- Stochastic Variational Inference as main inference algorithm of Pyro
- Finds approximation of intractable posterior by maximizing ELBO
- Facilitates flexible inference through guides
- Basic use cases make use of Pyro's Autoguides

```
model = MyModel()
svi = pyro.infer.SVI(
    model=model,
    guide=pyro.infer.autoguide.AutoDiagonalNormal(model),
    optim=pyro.optim.Adam(optim_args={"lr": le-3}),
    loss=pyro.infer.Trace_ELBO()
)

total_loss = 0
for epoch in range(EPOCHS):
    total_loss += svi.step(X, y)
```

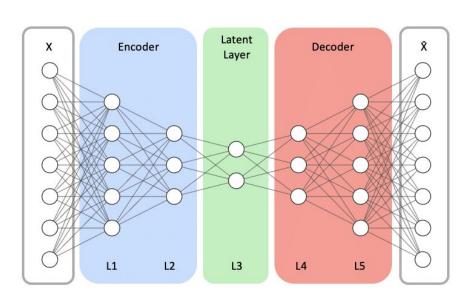
Time to get coding!

→ Find the first tasks in "workshop/Part 1 - Linear Modelling with Pyro - Empty Template.ipynb"

Let's take a break of ~15 minutes to ask questions, network, have a snack,

Part II: Variational Autoencoders in Pyro

Autoencoders



- Learns efficient data representations
- Compresses input into a lower-dimensional space
- Minimizes reconstruction error to learn meaningful features
- → E.g. used for dimensionality reduction
- → No regularization will lead to non-continuous latent space



Original Digit



Reconstructed Digit

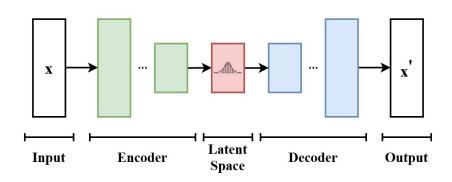






Latent Space samples

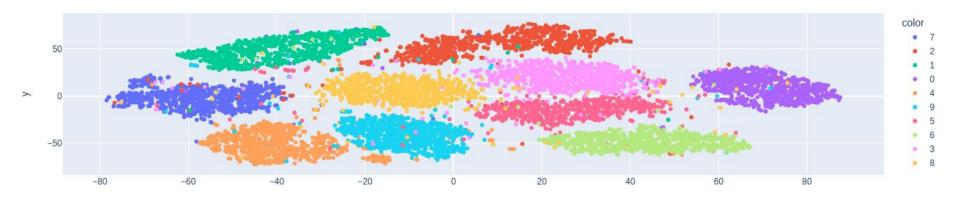
Variational Autoencoders



By EugenioTL - Own work, CC BY-SA 4.0, https://commons.wikimedia.org/w/index.php?curid=107231101

- Variational Autoencoders (VAEs) are architecturally similar to regular Autoencoders
- VAEs model a latent space as probability distribution
- Probability distribution serves as regularization of latent space

→ Facilitates finite, complete and continuous latent space for interpolation and sampling



T-SNE Embedding of Latent Space of Variational Autoencoder





Reconstructed Digits



Latent Space samples



Original Digit



Figure 4: Samples from generative model.

Time to get coding!

→ Find the second tasks in "workshop/Part 2 -Variational Autoencoder - Empty Template.ipynb"

Thank you for dropping by!