

# Particle-in-Cell Simulation Using a Fast Poisson Solver with Truncated Green's Functions

Chong Shik Park, Ph.D.

Department of Accelerator Science

Korea University, Sejong



## **Space Charge Solvers**

Wave Equations or Helmholtz Equations:

$$\left[ \vec{\nabla}^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right] \left\{ \begin{matrix} \phi \\ \vec{A} \end{matrix} \right\} = - \left\{ \begin{matrix} \rho / \varepsilon_0 \\ \mu_0 \vec{J} \end{matrix} \right\}$$

Poisson Equation:

$$\vec{\nabla}^2 \phi = -\frac{\rho}{\varepsilon_0}$$

• General Solution of the Poisson Equation with Green's function

$$\phi(\vec{r}) = \frac{1}{\varepsilon_0} \int G(\vec{r}, \vec{r}') \rho(\vec{r}') d^3 \vec{r}' = \frac{1}{4\pi\varepsilon_0} \int \frac{1}{|\vec{r} - \vec{r}'|} \rho(\vec{r}') d^3 \vec{r}'$$

- Inclusion of boundary conditions makes the problem more complicated.
  - Open boundary condition is preferred.
  - This is true if the pipe radius in an accelerator is much larger than the beam bunch transverse size



## **Hockney-Eastwood Algorithm**

#### **Poisson Solver**

- One of most popular algorithms in beam physics codes is Hockney-Eastwood(HE) in which Fast Fourier Transform(FFT) with zero-padding is used thanks to the convolution theorem
- The potential at a mesh point (p,q) can always be written as the sum of contributions from all other source points (p',q')

$$\phi(p,q) = \frac{h_x h_y h_z}{4\pi\varepsilon_0} \sum G(p,q;p',q') \rho(p',q')$$

• The potential as the convolution of the source distribution  $\rho$  with the Green's function of the interaction potential G.

$$\mathcal{F}\{\hat{\phi}\}_{k,l} = \mathcal{F}\{\hat{G}\}_{k,l} \, \mathcal{F}\{\hat{\rho}\}_{k,l}$$

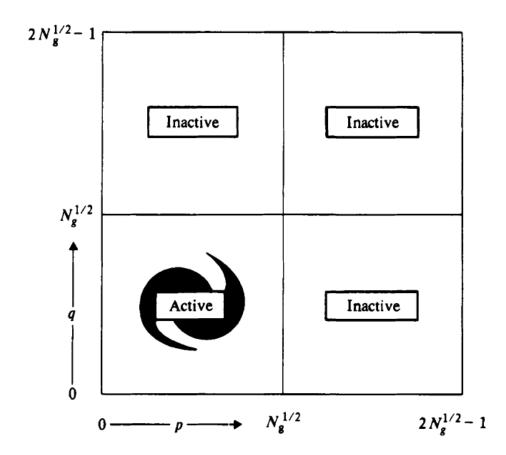
$$\phi(\vec{r}) = \frac{h_x h_y h_z}{4\pi\varepsilon_0} \mathcal{F}^{-1} \left\{ \sum_{z} \mathcal{F}\{\hat{G}\} \mathcal{F}\{\hat{\rho}\} \right\}$$

- The convolution method will solve a periodic system of sources with an arbitrary form of interaction.
- No conductors or boundaries are permitted in the system.
  - This is true if the pipe radius in an accelerator is much larger than the beam bunch transverse size.



## **Integrated Green's Function**

- For a beam with a large aspect ratio, the direct use of the FFT-based method will be inefficient since a large number of grid points are needed to resolve the variation of the Green function inside a grid cell.
- This convolution can be replaced by a cyclic convolution in a double-gridded computational domain.
- This makes use of the symmetry of the Green function
- The potential outside the original domain is incorrect but is irrelevant to the physical domain.





#### **More Green's Function Techniques**

#### 2.5 D Hockney-Eastwood Solver

- Can be implemented to the beam with a large transverse-to-longitudinal aspect ratio
- The beam is squeezed to a single slice
- Space charge fields are calculated only in the transverse dimensions.
- Then, the fields are scaled with the longitudinal line density to be applied in the all 3-dimensional directions.

#### **Shifted Green's Function**

- In order include beam-beam effects or image charge effects, the computational domain need to contain both the particle domain and the field domain, i.e., both beams.
- This results in a poor spatial resolution of the beams because of a large empty space b/w two beams.
- This is also computationally inefficient because the electric fields in the empty space between two beams are not used.
- Using the shifted Green function, the center of the field domain is shifted to the center of the particle domain.
- Then, the FFT can be used to calculate the cyclic convolution using the new Green function.



#### **Vico-Greengard-Ferrando Methods**

- In the Hockney-Eastwood FFT-based method, the Green's function is defined in long range and has singular at  $\vec{r}=\vec{r}'$
- Recently, Vico et al introduced a truncated spectral kernel for Green's function by replacing as follows:

$$G(\vec{r}) \Longrightarrow G^L(\vec{r}) = G(\vec{r}) \operatorname{rect}\left(\frac{r}{2L}\right),$$

where  $L > \sqrt{d}$ , and the indicator function  $\operatorname{rect}(x)$  is defined as

$$rect(x) = \begin{cases} 1, & x < 1/2 \\ 0, & x > 1/2 \end{cases}$$

• In the Vico-Greengard-Ferrando (VGF) Poisson Solver, the Fourier transform of **the Green's function can be solved analytically** and computed in the truncated dimensions:

$$\mathcal{F}\{G^L\} = \frac{2}{\varepsilon_0} \left[ \frac{\sin\left(\frac{L|\vec{k}|}{2}\right)}{|\vec{k}|} \right]^2$$

• Then, the potential becomes:

$$\phi(\vec{r}) = \frac{2}{(2\pi)^3 \varepsilon_0} \int e^{i\vec{k}\cdot\vec{r}'} \left[ \frac{\sin\left(\frac{L|\vec{k}|}{2}\right)}{|\vec{k}|} \right]^2 \rho(\vec{r}') d^3\vec{k}$$



# Implementation of Algorithms and Comparison

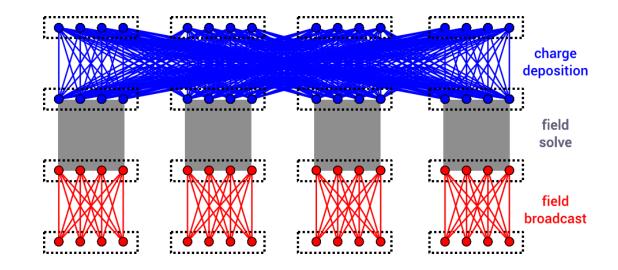
#### **Charge Distribution and Exact Solution**

Using a 3-D Gaussian charge distribution

$$\rho(\vec{r}) = \frac{Q}{\sigma^3 (2\pi)^{3/2}} e^{\left(-\frac{r^2}{2\sigma^2}\right)},$$

- Generate and deposit macro-particles on grids
  - $N_x \times N_v \times N_z$  grid domain
  - For simplifying the problem, assume that  $N_x = N_y = N_z$
- The exact solution of the Poisson equation is

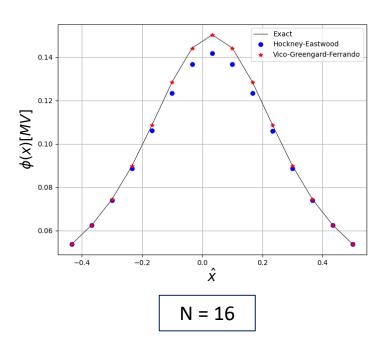
$$\phi(\vec{r}) = \frac{Q}{4\pi\varepsilon_0} \frac{1}{r} \operatorname{erf}\left(\frac{r}{\sqrt{2}\sigma}\right)$$

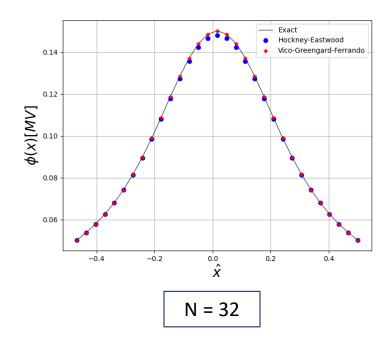


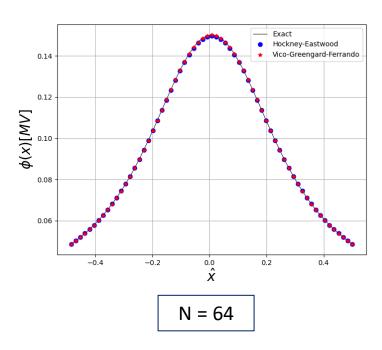


## **Space Charge Potentials along the Beam Axis**

#### For a different number of grids



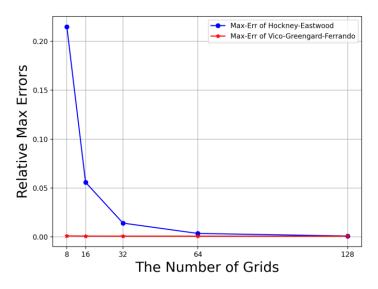


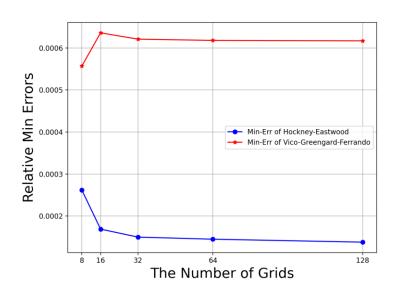


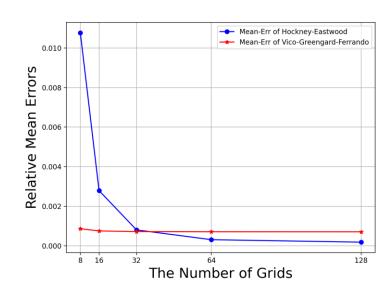
- The electric potentials along the longitudinal beam axis for each algorithm with the different number of grids.
- With small N, the potential with the HE algorithm has large deviation at the center of the beam.
- As *N* is increased, this deviation is decreased.



#### **Numerical Errors**



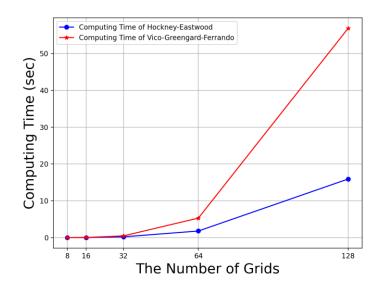


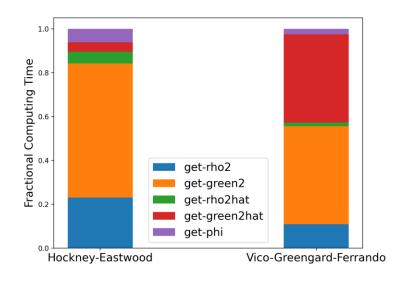


- The relative errors to the exact solutions in both algorithms are compared.
- The VGF algorithm has smaller maximum and mean errors for small grid sizes, but larger minimum errors for all grid sizes.
- The maximum relative error for VGF occurs at the edge of the grid, but at the center for HE.
- In the case of minimum relative error, the opposite is true.
- Moreover, unlike HE, the accuracy of the VGF algorithm does not depend significantly on the number of grid sizes.



## **Computing Time**





- With the VGF algorithm, the computation time increases significantly as the number of grids increases.
- However, it can easily compensate for computation time by showing fast convergence with a smaller number of grids.
- This can also be overcome by recent advances in **vectorization techniques** for processing large matrices.