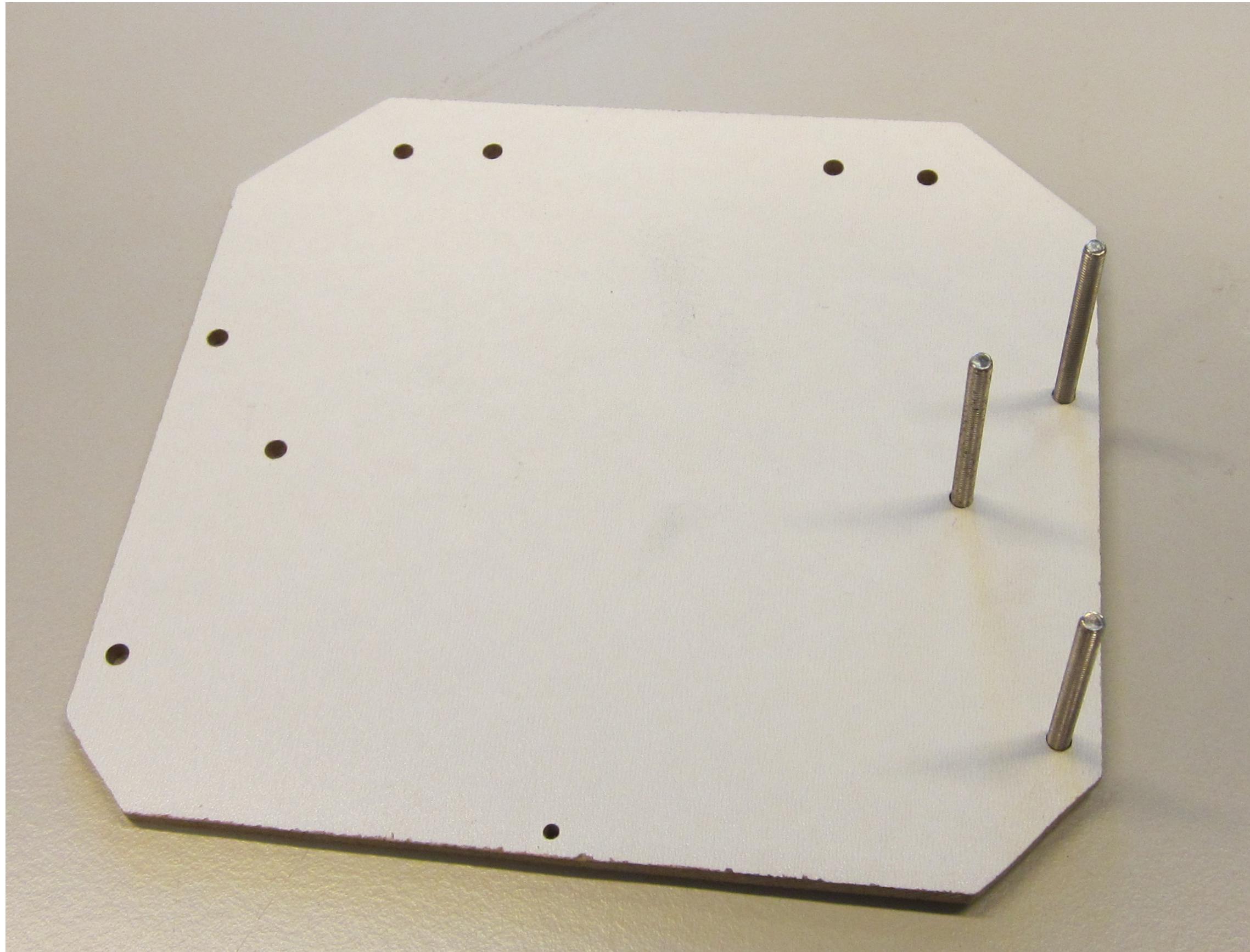


Systèmes embarqués

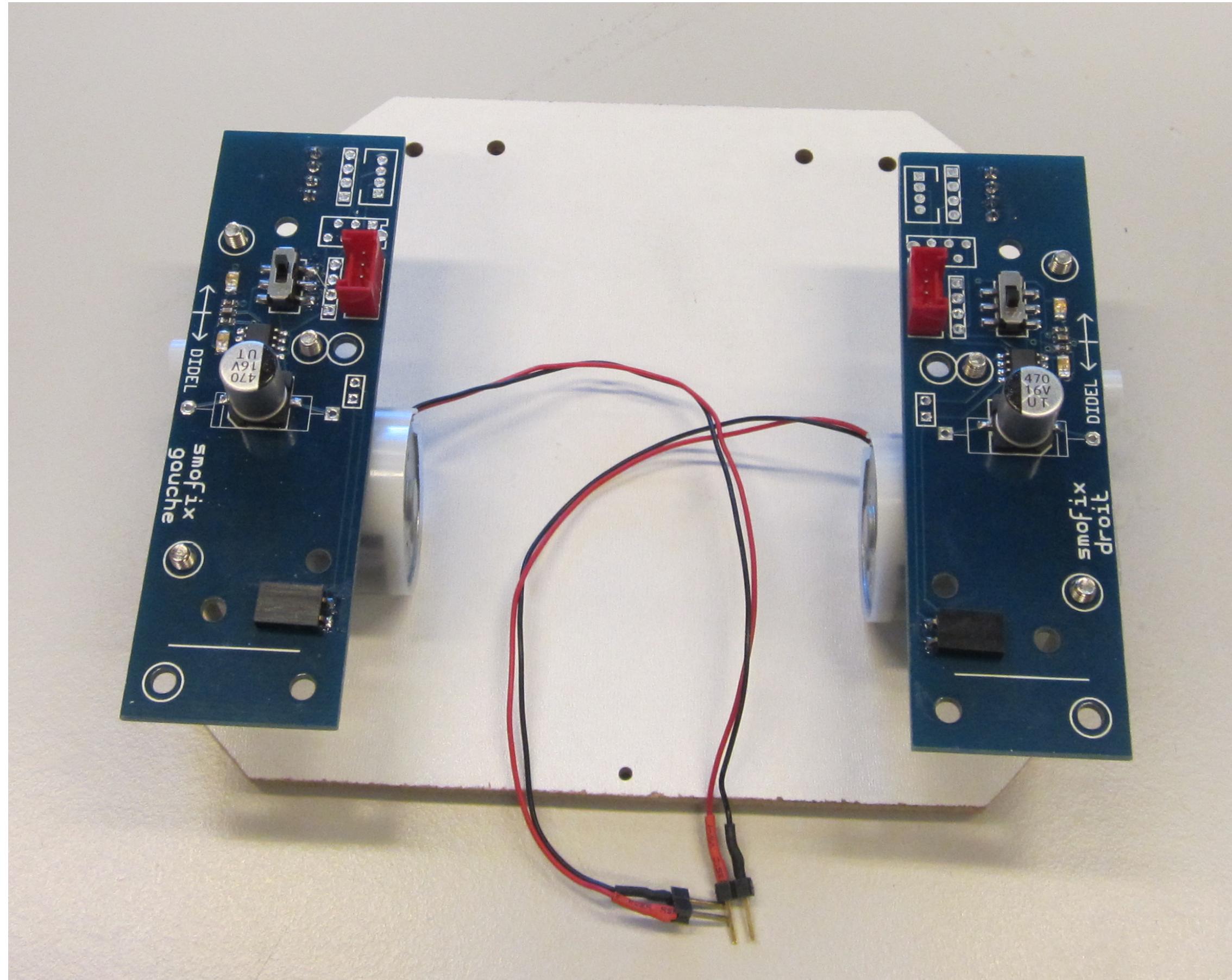
Montage du robot

Pierre-Yves Rochat

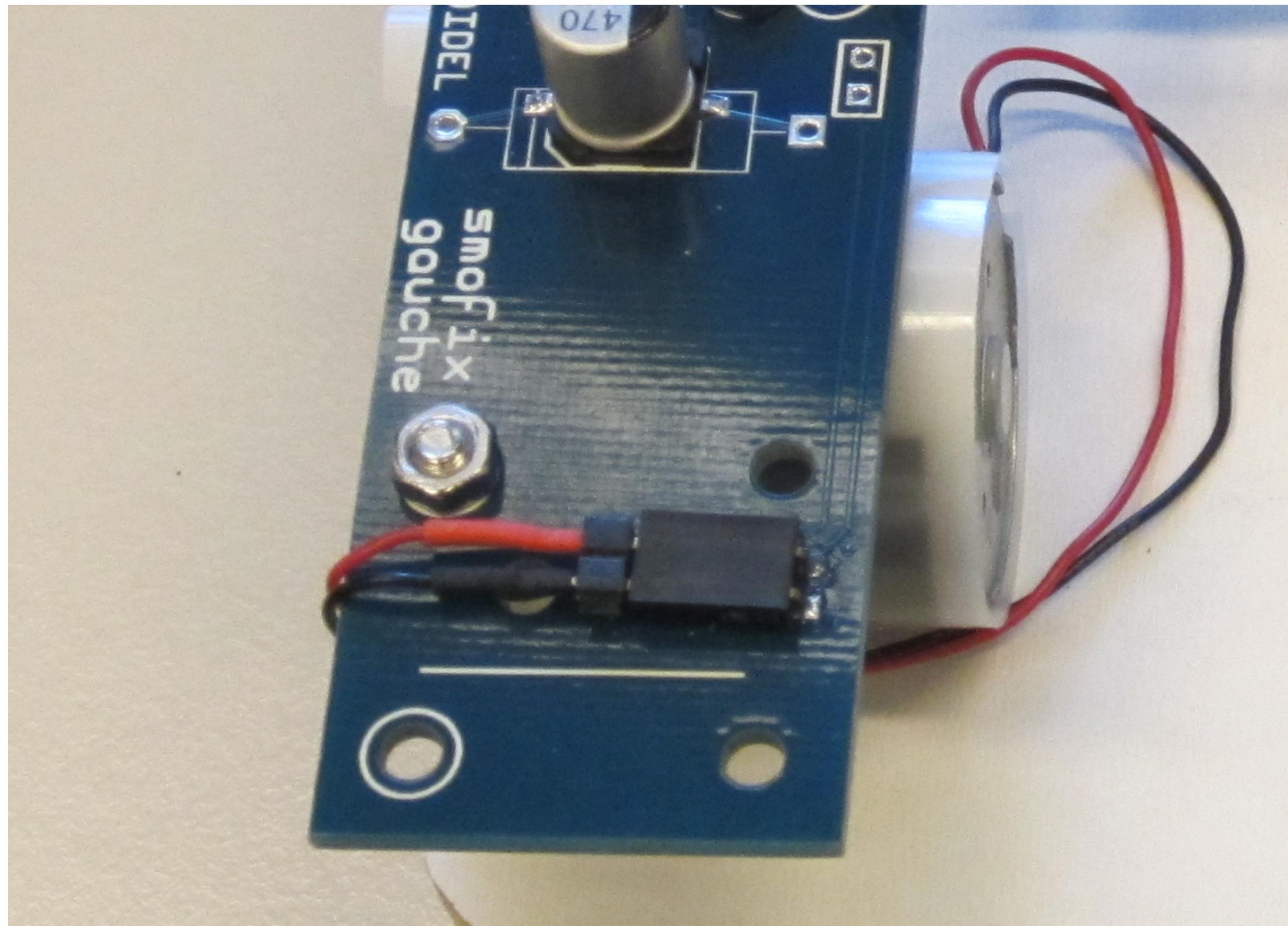
Base et vis de fixation des moteurs



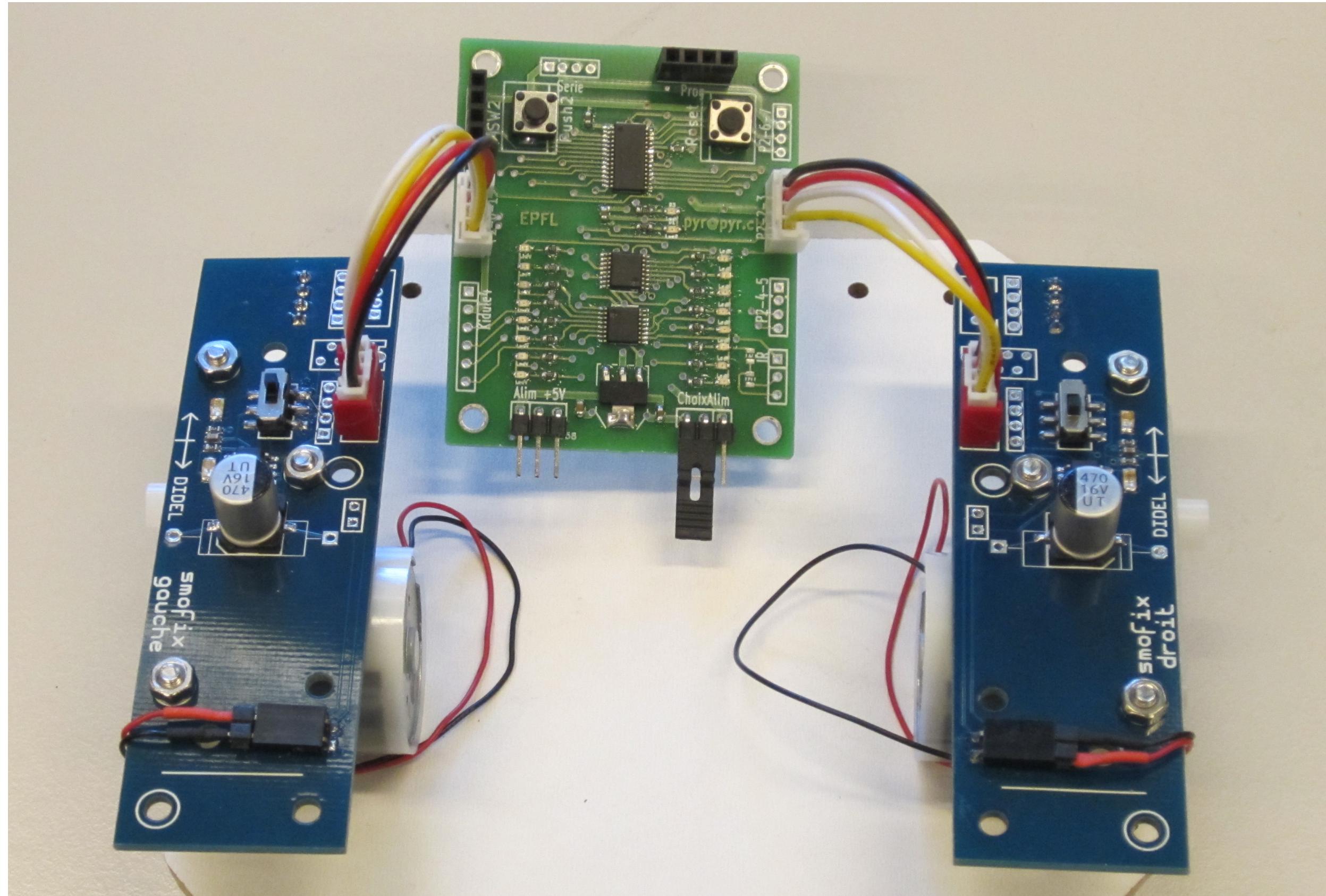
Fixation des moteurs



Fils des moteurs : noir (-) rouge (+)

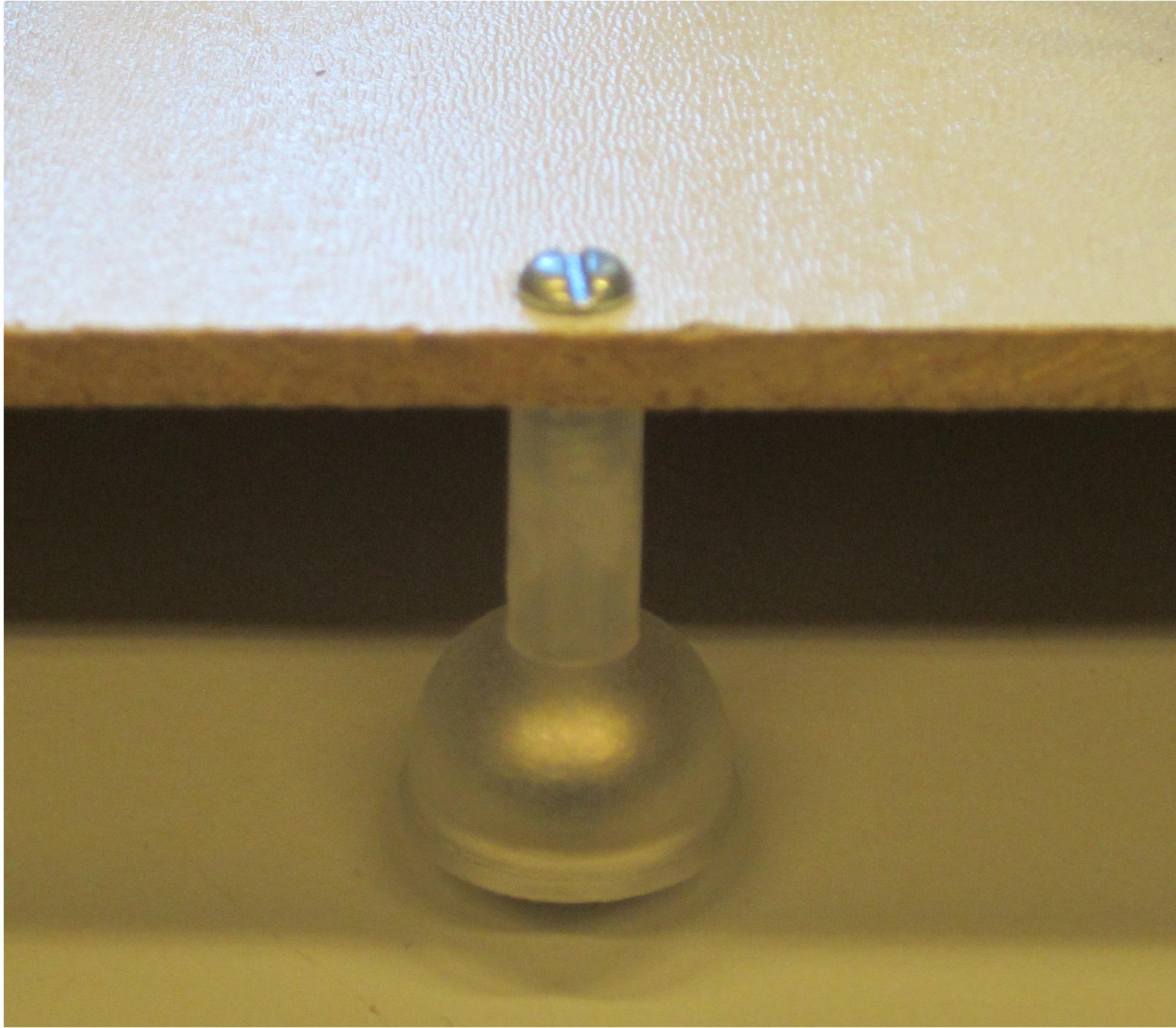


Carte microcontrôleur MSP430G2553

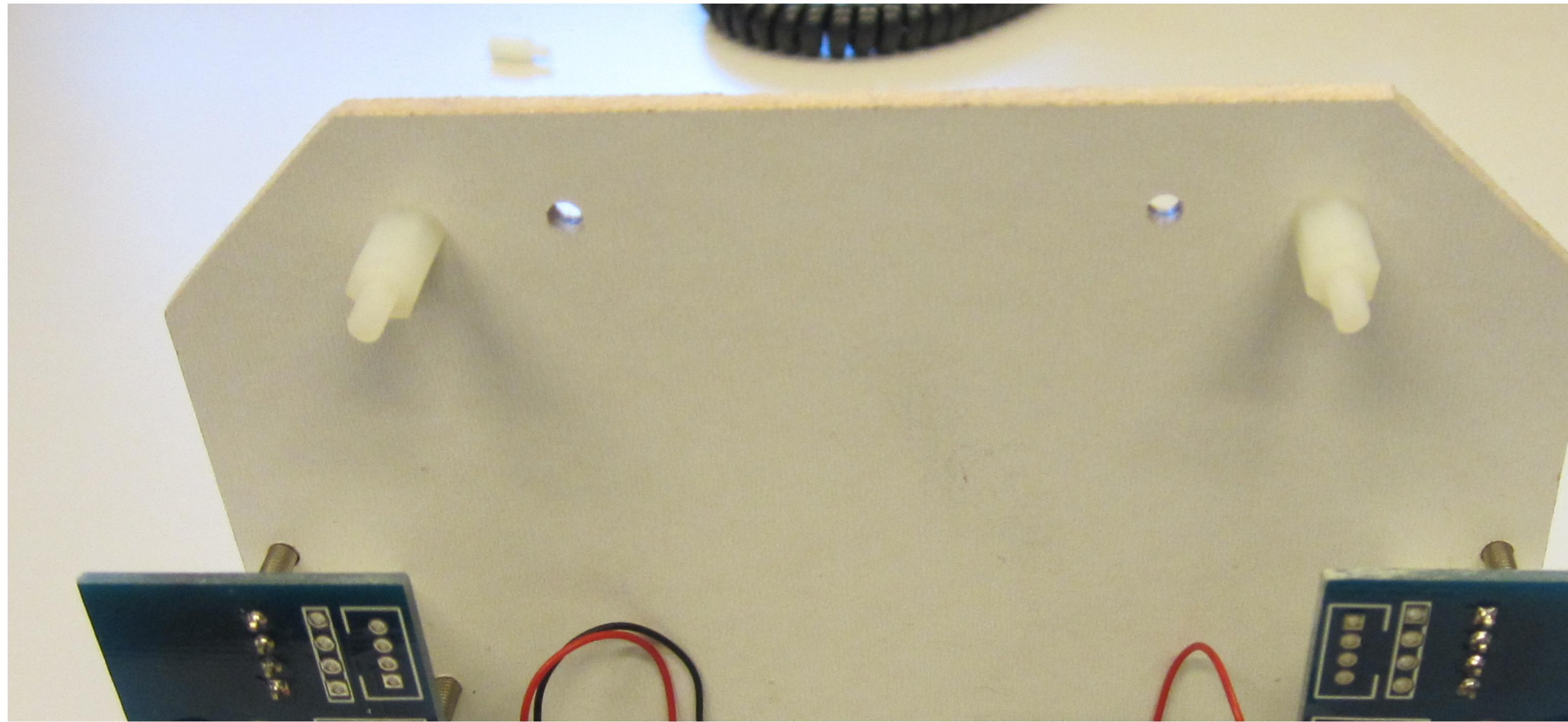


(SMD = monté en surface)

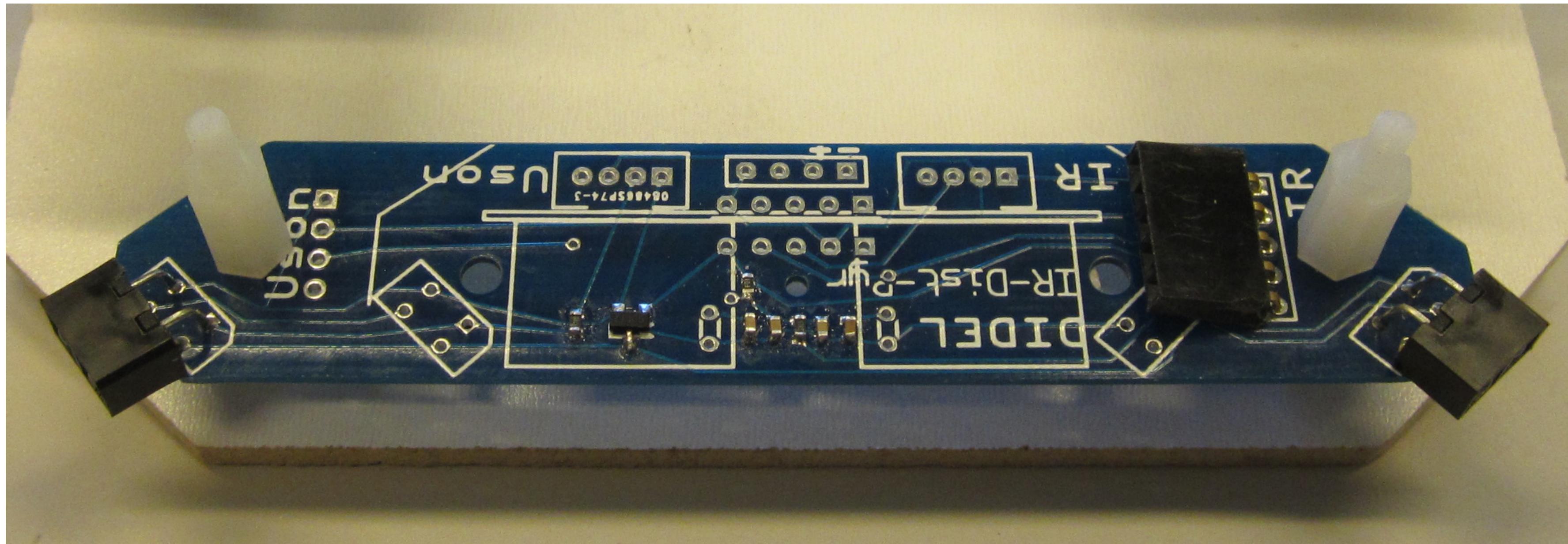
Balcaster



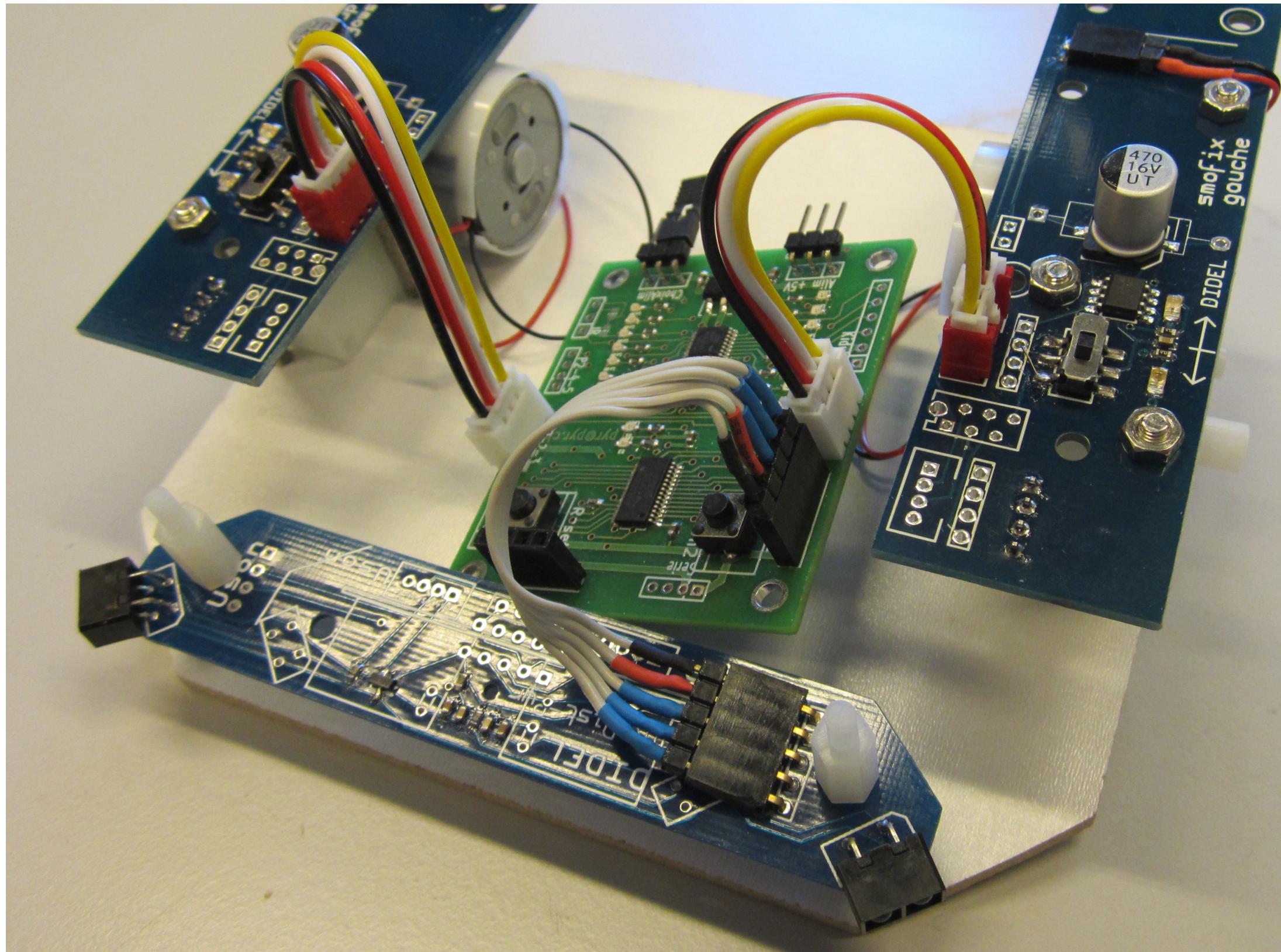
Entretoises



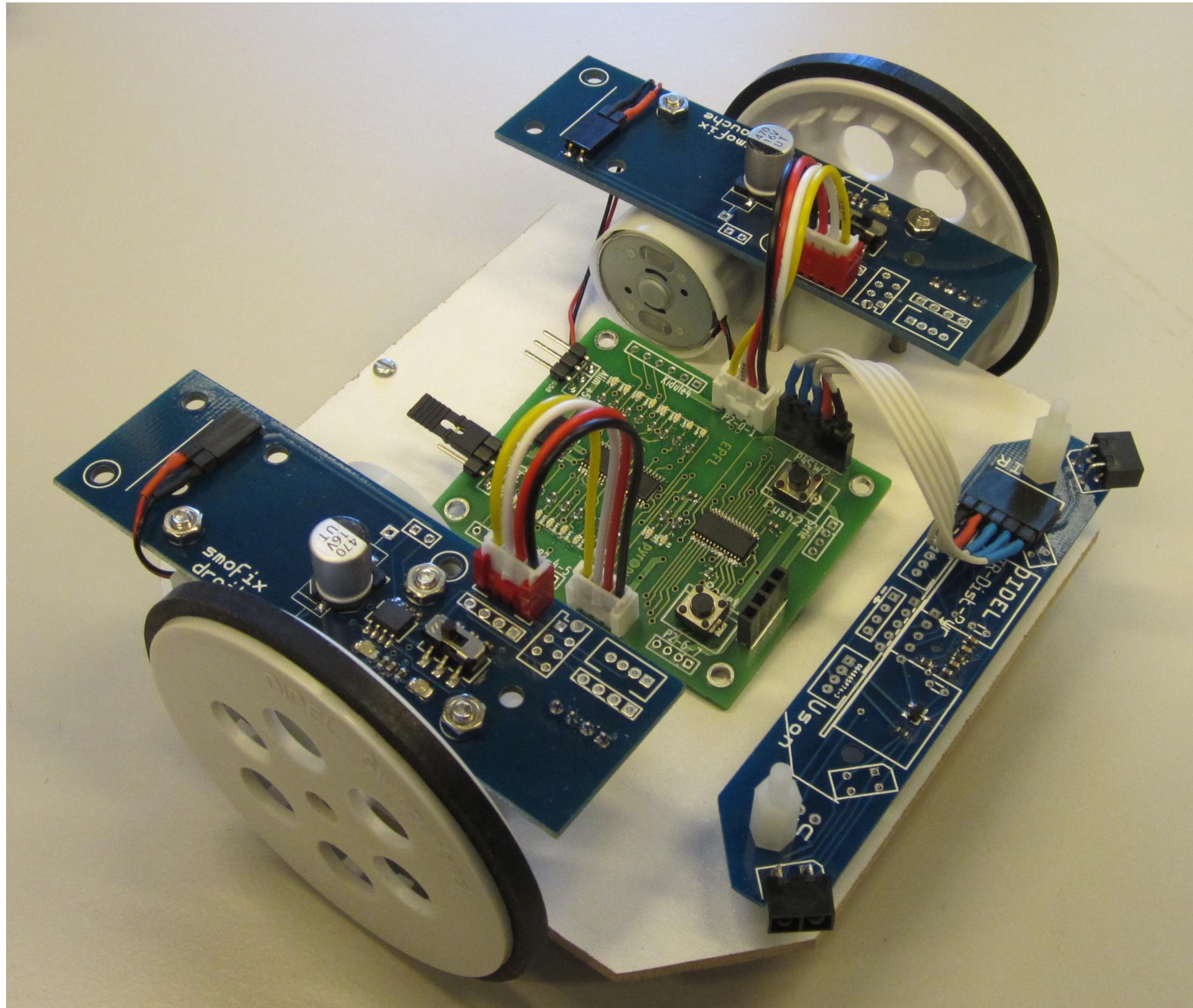
Capteurs de distance IR



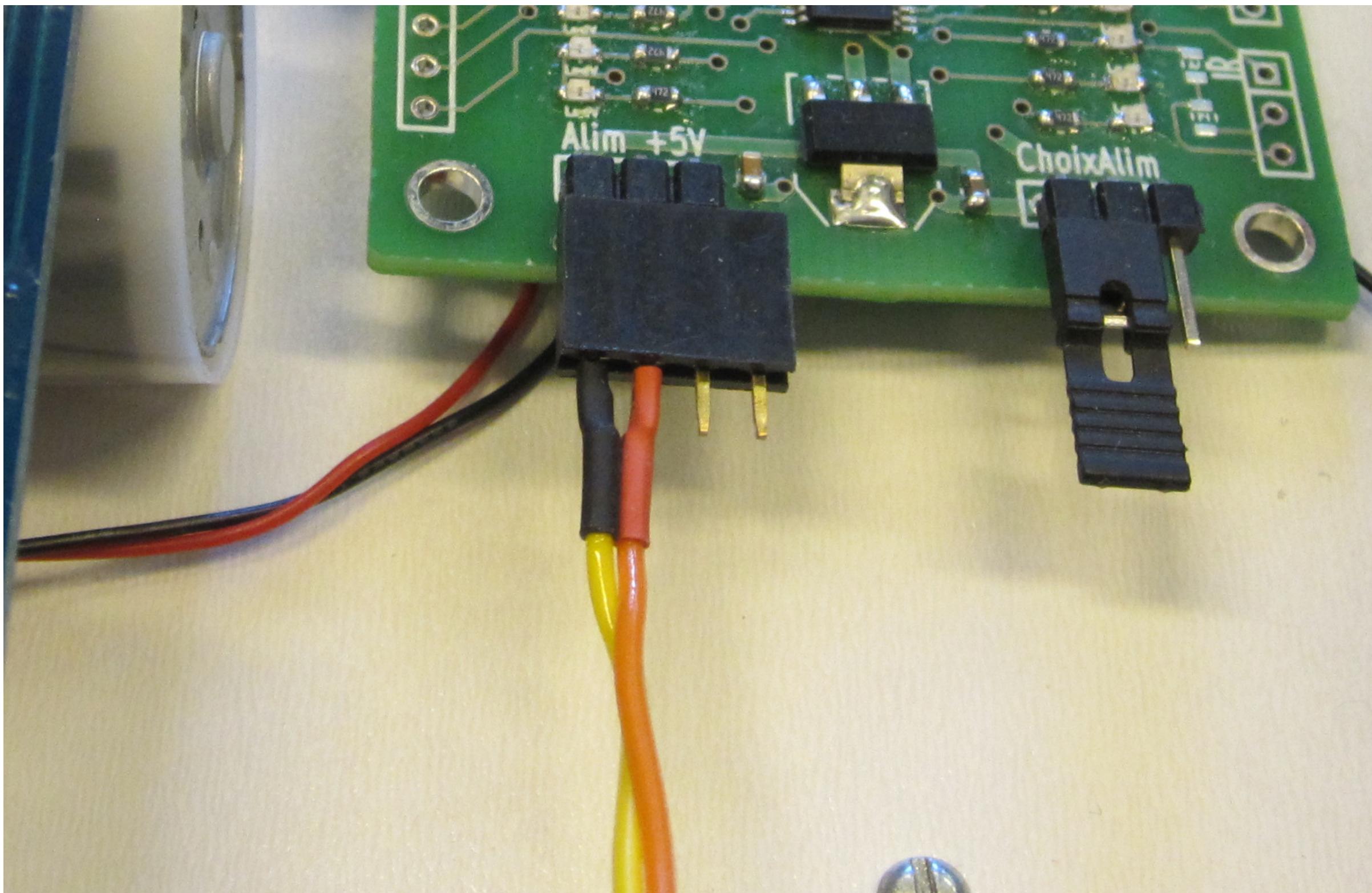
Connection capteurs de distance IR



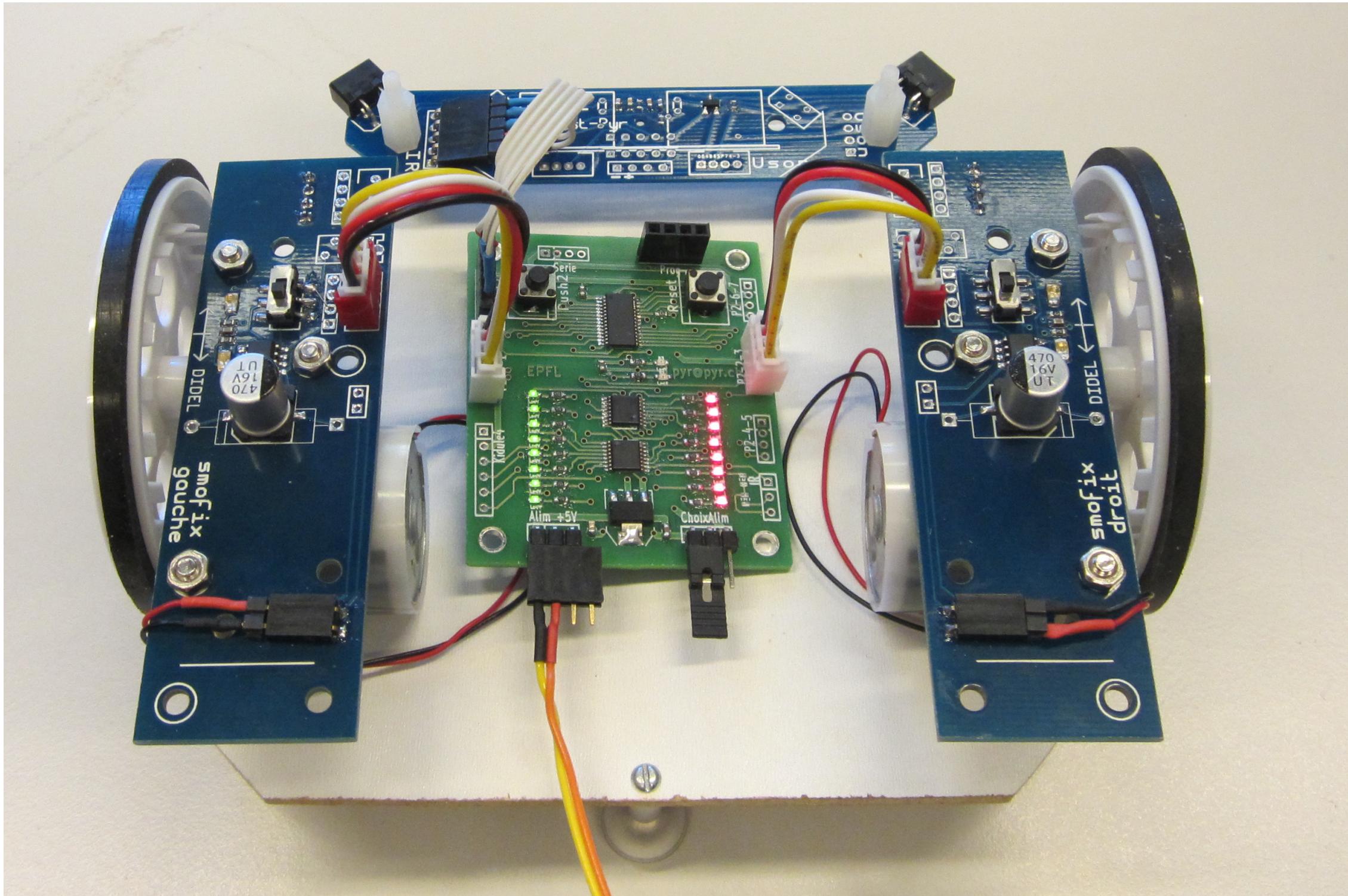
Roues



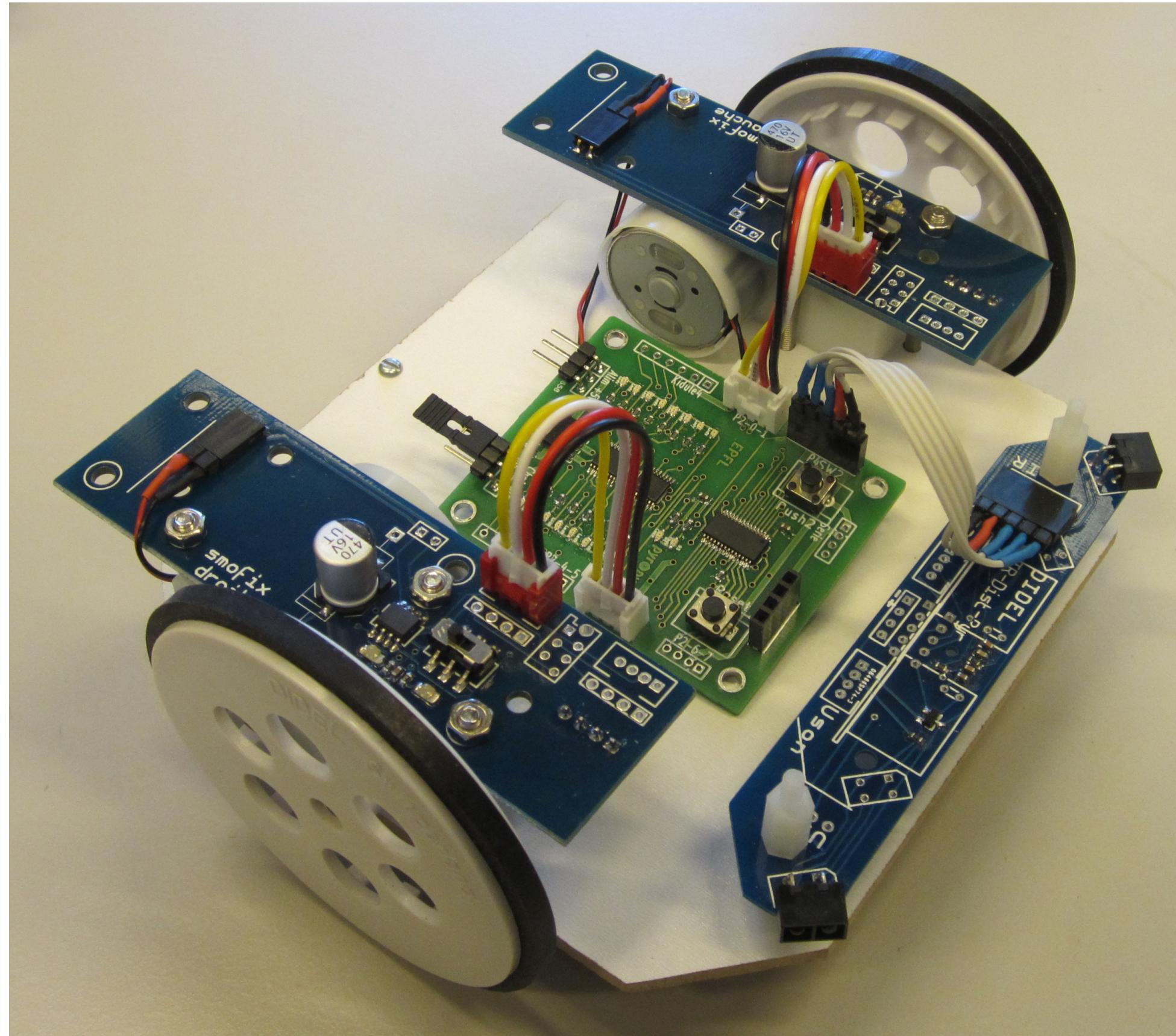
Alimentation de la carte (Gnd, +5V)



Robot complet



Robot complet



Programmation par le Launchpad

