

Numerical Analysis

Lecture 6: Approximating Eigenvalues

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Outline

- 1 Linear Algebra and Eigenvalues
- 2 The Power Method
- 3 The Inverse Power Method

Eigenvalues and Eigenvectors

Eigenvalues and Eigenvectors

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$$

Eigenvalues and Eigenvectors

We have

$$(\mathbf{A} - \lambda\mathbf{I})\mathbf{x} = \mathbf{0}$$

Definition (Characteristic Polynomial)

If \mathbf{A} is a square matrix, the **characteristic polynomial** of \mathbf{A} is defined by

$$p(\lambda) = \det(\mathbf{A} - \lambda\mathbf{I})$$

Eigenvalues and Eigenvectors

Definition (Characteristic Polynomial)

If \mathbf{A} is a square matrix, the **characteristic polynomial** of \mathbf{A} is defined by

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Comments

- p is an n th-degree polynomial and, consequently, has at most n distinct zeros, some of which might be complex.
- If λ is a zero of p , then, since $\det(\mathbf{A} - \lambda\mathbf{I}) = 0$, we can prove that the linear system defined by

$$(\mathbf{A} - \lambda\mathbf{I})\mathbf{x} = \mathbf{0}$$

has a solution with $\mathbf{x} \neq \mathbf{0}$.

Eigenvalues and Eigenvectors

Finding the Eigenvalues & Eigenvectors

- To determine the eigenvalues of a matrix, we can use the fact that λ is an eigenvalue of A if and only if

$$\det(\mathbf{A} - \lambda\mathbf{I}) = 0$$

- Once an eigenvalue λ has been found, a corresponding eigenvector $\mathbf{x} \neq \mathbf{0}$ is determined by solving the system

$$(\mathbf{A} - \lambda\mathbf{I})\mathbf{x} = \mathbf{0}$$

Eigenvalues and Eigenvectors

Difficulties

- Finding the determinant of an $n \times n$ matrix is computationally expensive.
- Finding good approximations to the roots of $\rho(\lambda)$ is also difficult.
- The computational complexity of solving a linear system is high.

Linear Algebra

Linearly Independent

Let $\{\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(k)}\}$ be a set of vectors. The set is linearly independent if whenever

$$\mathbf{0} = \alpha_1 \mathbf{v}^{(1)} + \alpha_2 \mathbf{v}^{(2)} + \dots + \alpha_k \mathbf{v}^{(k)},$$

then $\alpha_i = 0, \forall i$. Otherwise the set of vectors is linearly dependent.

Linearly Combination and Basis

Suppose that $\{\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(k)}\}$ is a set of k linearly independent vectors. Then, for any vector \mathbf{x} , a unique collection of constants $\beta_1, \beta_2, \dots, \beta_k$ exists with

$$\mathbf{x} = \beta_1 \mathbf{v}^{(1)} + \beta_2 \mathbf{v}^{(2)} + \dots + \beta_k \mathbf{v}^{(k)}.$$

Linear Algebra

Linearly Independent Eigenvectors

If A is a matrix and $\lambda_1, \lambda_2, \dots, \lambda_k$ are distinct eigenvalues of A with associated eigenvectors $\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \dots, \mathbf{x}^{(k)}$, then $\{\mathbf{x}^{(1)}, \mathbf{x}^{(2)}, \dots, \mathbf{x}^{(k)}\}$ is a linearly independent set.

Orthogonal Vectors

A set of vectors $\{v^{(1)}, v^{(2)}, \dots, v^{(n)}\}$ is called orthogonal if $(v^{(i)})^t v^{(j)} = 0$, for all $i \neq j$. If, in addition, $(v^{(i)})^t v^{(i)} = 1$, for all $i = 1, 2, \dots, n$, then the set is called orthonormal.

Orthogonal Matrices

Definition

A matrix Q is said to be orthogonal if its columns $\{\mathbf{q}_1^t, \mathbf{q}_2^t, \dots, \mathbf{q}_n^t\}$ form an orthonormal set in \mathbb{R}^n .

Properties

Suppose that Q is an orthogonal $n \times n$ matrix. Then

- Q is invertible with $Q^{-1} = Q^t$;
- For any \mathbf{x} and \mathbf{y} in \mathbb{R}^n , $(Q\mathbf{x})^t Q\mathbf{y} = \mathbf{x}^t \mathbf{y}$;
- For any \mathbf{x} in \mathbb{R}^n , $\|Q\mathbf{x}\|_2 = \|\mathbf{x}\|_2$.

Similar Matrices

Definition

Two matrices A and B are said to be similar if a nonsingular matrix S exists with $A = S^{-1}BS$.

Properties

Suppose A and B are similar matrices with $A = S^{-1}BS$ and λ is an eigenvalue of A with associated eigenvector \mathbf{x} . Then λ is an eigenvalue of B with associated eigenvector $S\mathbf{x}$.

Diagonally Similar Matrices

Definition

An $n \times n$ matrix A is similar to a diagonal matrix D if and only if A has n linearly independent eigenvectors. In this case, $D = S^{-1}AS$, where the columns of S consist of the eigenvectors, and the i th diagonal element of D is the eigenvalue of A that corresponds to the i th column of S .

Properties

An $n \times n$ matrix A that has n distinct eigenvalues is similar to a diagonal matrix.

Symmetric Matrices

Definition

An $n \times n$ matrix A is symmetric if and only if there exists a diagonal matrix D and an orthogonal matrix Q with $A = QDQ^t$.

Properties

- Suppose that A is a symmetric $n \times n$ matrix. There exist n eigenvectors of A that form an orthonormal set, and the eigenvalues of A are real numbers.
- A symmetric matrix A is positive definite if and only if all the eigenvalues of A are positive.

Geršgorin Circle

Let A be an $n \times n$ matrix and R_i denote the circle in the complex plane with center a_{ii} and radius $\sum_{j=1, j \neq i}^n |a_{ij}|$; that is,

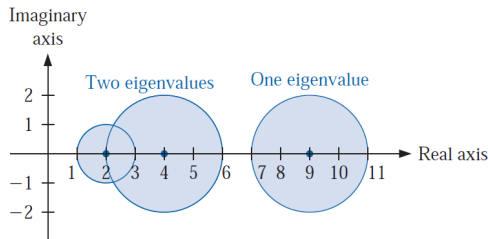
$$R_i = \left\{ z \in \mathcal{C} : |z - a_{ii}| \leq \sum_{j=1, j \neq i}^n |a_{ij}| \right\}$$

where \mathcal{C} denotes the complex plane. The eigenvalues of A are contained within the union of these circles, $R = \bigcup_{i=1}^n R_i$. Moreover, the union of any k of the circles that do not intersect the remaining $(n - k)$ contains precisely k (counting multiplicities) of the eigenvalues.

Geršgorin Circle: Examples

Determine the Geršgorin circle for the matrix and use these to find bounds for the spectral radius of A .

$$A = \begin{bmatrix} 4 & 1 & 1 \\ 0 & 2 & 1 \\ -2 & 0 & 9 \end{bmatrix}$$



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The Power Method

Overview

- The Power method is an iterative technique used to determine the dominant eigenvalue of a matrix, that is, the eigenvalue with the largest magnitude.
- One useful feature of the Power method is that it produces not only an eigenvalue, but also an associated eigenvector.
- The Power method is often applied to find an eigenvector for an eigenvalue that is determined by some other means.

The Power Method

Overview

Assume an $n \times n$ matrix A has precisely one eigenvalue, λ_1 , that is largest in magnitude, that is

$$|\lambda_1| > |\lambda_2| \geq |\lambda_3| \geq \cdots \geq |\lambda_n| \geq 0.$$

The Power Method

Observation 1/2

If \mathbf{x} is any vector in \mathbb{R}^n , the fact that $\{\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(n)}\}$ is linearly independent implies that constants $\beta_1, \beta_2, \dots, \beta_n$ exist with

$$\mathbf{x} = \beta_1 \mathbf{v}^{(1)} + \beta_2 \mathbf{v}^{(2)} + \dots + \beta_n \mathbf{v}^{(n)}.$$

Multiplying both sides of this equation by $A, A^2, \dots, A^k, \dots$ gives

$$A\mathbf{x} = \sum_{j=1}^n \beta_j A\mathbf{v}^{(j)} = \sum_{j=1}^n \beta_j \lambda_j \mathbf{v}^{(j)}$$

$$A^k \mathbf{x} = \sum_{j=1}^n \beta_j A^k \mathbf{v}^{(j)} = \sum_{j=1}^n \beta_j \lambda_j^k \mathbf{v}^{(j)}$$

The Power Method

Observation 2/2

We further have

$$A^k x = \lambda_1^k \sum_{j=1}^n \beta_j \left(\frac{\lambda_j}{\lambda_1} \right)^k v^{(j)},$$

and

$$\lim_{k \rightarrow \infty} A^k x = \lim_{k \rightarrow \infty} \lambda_1^k \beta_1 v^{(1)}.$$

The Power Method

The Iterative Procedure

Let $X_0 = [1, 1, \dots, 1]^t$, $Y_k = AX_k$, and $X_{k+1} = \frac{1}{c_{k+1}} Y_k$ where $c_{k+1} = \|Y_k\|_\infty$. Then, we have

$$\lim_{k \rightarrow \infty} X_k = v^{(1)}, \lim_{k \rightarrow \infty} c_k = \lambda_1.$$

Proof 1/3

We can easily prove that

$$X_k = \frac{\lambda_1^k}{c_1 c_2 \cdots c_k} \sum_{j=1}^n \beta_j \left(\frac{\lambda_j}{\lambda_1} \right)^k v^{(j)},$$

The Power Method

Proof 2/3

This means that

$$\lim_{k \rightarrow \infty} X_k = \lim_{k \rightarrow \infty} \frac{\beta_1 \lambda_1^k}{c_1 c_2 \cdots c_k} v^{(1)}.$$

Because both $\|X_k\|_\infty = \|v^{(1)}\|_\infty = 1$, we have

$$\lim_{k \rightarrow \infty} \frac{\beta_1 \lambda_1^k}{c_1 c_2 \cdots c_k} = 1, \text{ and } \lim_{k \rightarrow \infty} X_k = v^{(1)}.$$

The Power Method

Proof 3/3

Furthermore, from

$$\frac{\beta_1 \lambda_1^k}{c_1 c_2 \cdots c_k} \approx 1,$$

and

$$\frac{\beta_1 \lambda_1^{k-1}}{c_1 c_2 \cdots c_{k-1}} \approx 1,$$

we have $\lambda_1 \approx c_k$.

The Power Method

The matrix

$$A = \begin{bmatrix} -2 & -3 \\ 6 & 7 \end{bmatrix}$$

Has eigenvalues $\lambda_1 = 4$ and $\lambda_2 = 1$ with corresponding eigenvectors $\mathbf{v}_1 = (1, -2)^t$ and $\mathbf{v}_2 = (1, -1)^t$. If we start with the arbitrary vector $\mathbf{x}_0 = (1, 1)^t$ and multiply by the matrix A we obtain

$$\begin{aligned} \mathbf{x}_1 &= A\mathbf{x}_0 = \begin{bmatrix} -5 \\ 13 \end{bmatrix}, & \mathbf{x}_2 &= A\mathbf{x}_1 = \begin{bmatrix} -29 \\ 61 \end{bmatrix}, & \mathbf{x}_3 &= A\mathbf{x}_2 = \begin{bmatrix} -125 \\ 253 \end{bmatrix}, \\ \mathbf{x}_4 &= A\mathbf{x}_3 = \begin{bmatrix} -509 \\ 1021 \end{bmatrix}, & \mathbf{x}_5 &= A\mathbf{x}_4 = \begin{bmatrix} -2045 \\ 4093 \end{bmatrix}, & \mathbf{x}_6 &= A\mathbf{x}_5 = \begin{bmatrix} -8189 \\ 16381 \end{bmatrix}. \end{aligned}$$

As a consequence, approximations to the dominant eigenvalue $\lambda_1 = 4$ are

$$\begin{aligned} \lambda_1^{(1)} &= \frac{61}{13} = 4.6923, & \lambda_1^{(2)} &= \frac{253}{61} = 4.14754, & \lambda_1^{(3)} &= \frac{1021}{253} = 4.03557, \\ \lambda_1^{(4)} &= \frac{4093}{1021} = 4.00881, & \lambda_1^{(5)} &= \frac{16381}{4093} = 4.00200. \end{aligned}$$

An approximate eigenvector corresponding to $\lambda_1^{(5)} = \frac{16381}{4093} = 4.00200$ is

$$\mathbf{x}_6 = \begin{bmatrix} -8189 \\ 16381 \end{bmatrix}, \quad \text{which, divided by } 16381, \text{ normalizes to } \begin{bmatrix} -0.49908 \\ 1 \end{bmatrix} \approx \mathbf{v}_1.$$

The Power Method

Discussions

- The method fails if there is not a single dominant eigenvalues.
- The method fails if the initial vector, X_0 contains a zero contribution from the eigenvector associated with the dominant eigenvalue, i.e., $\beta_1 = 0$.
- How to find the other eigenvalues?

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The Inverse Power Method

Motivation

The Inverse Power method is a modification of the Power method that gives faster convergence. It is used to determine the eigenvalue of A that is closest to a specified number q .

The Inverse Eigenvalues

Suppose the matrix A has eigenvalues $\lambda_1, \dots, \lambda_n$ with linearly independent eigenvectors $\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(n)}$. Then, the eigenvalues of $(A - qI)^{-1}$, where $q \neq \lambda_i, \forall i$, are

$$\frac{1}{\lambda_1 - q}, \frac{1}{\lambda_2 - q}, \dots, \frac{1}{\lambda_n - q},$$

with these same eigenvectors $\mathbf{v}^{(1)}, \mathbf{v}^{(2)}, \dots, \mathbf{v}^{(n)}$.

Assignment

- Reading Assignment: Chap 9.1, 9.2, 9.3.
- Assignment (optional): Exercise 9.3.1 on Page 590.