

TRAINING FREE, ONE SHOT DETECTION

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Take a look at this:

See it here?



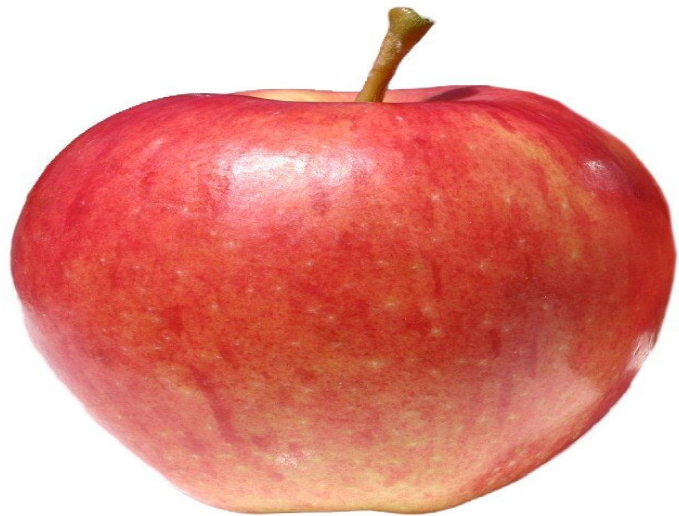
How about here?



Image credit: [istockphoto.com/ansonmiao](https://www.istockphoto.com/ansonmiao)

Single Example, No Training!

(Most) people can find the apple from one look.



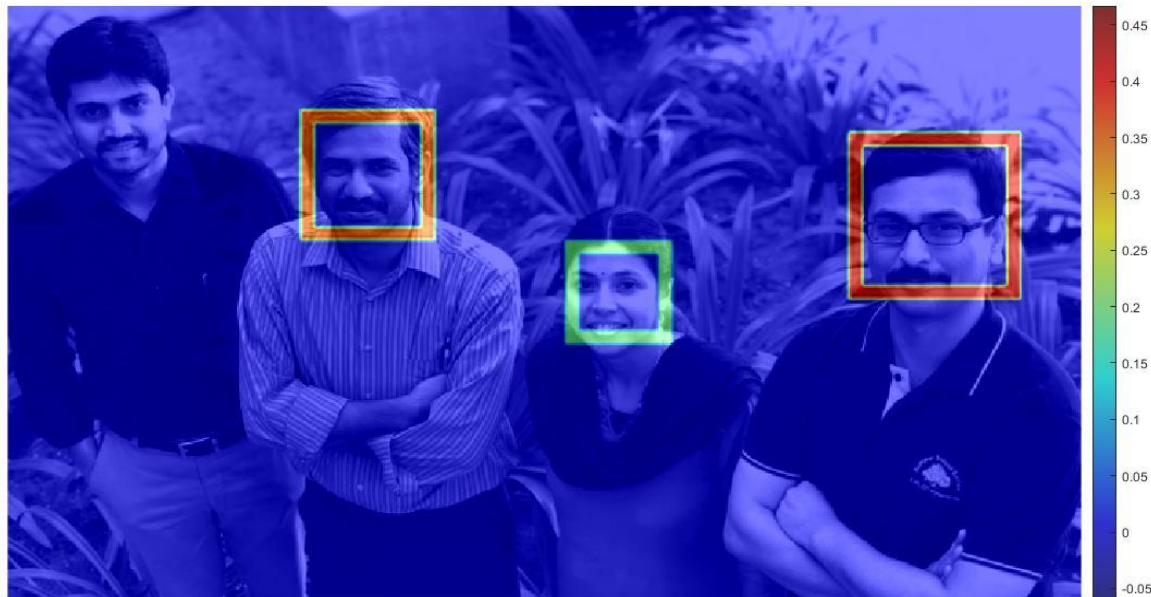
Even if they've never seen it before.

Overview of One Shot Detection Scheme

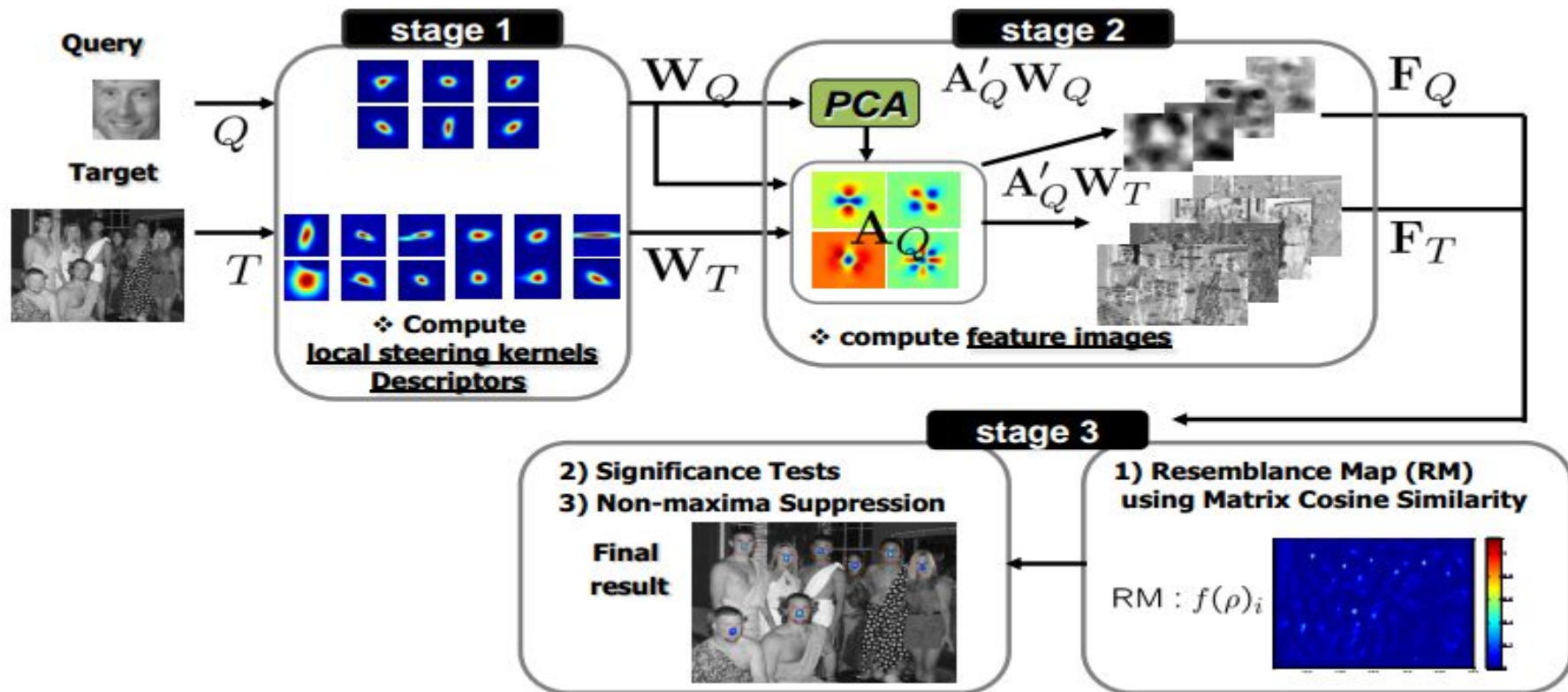
Query



Output



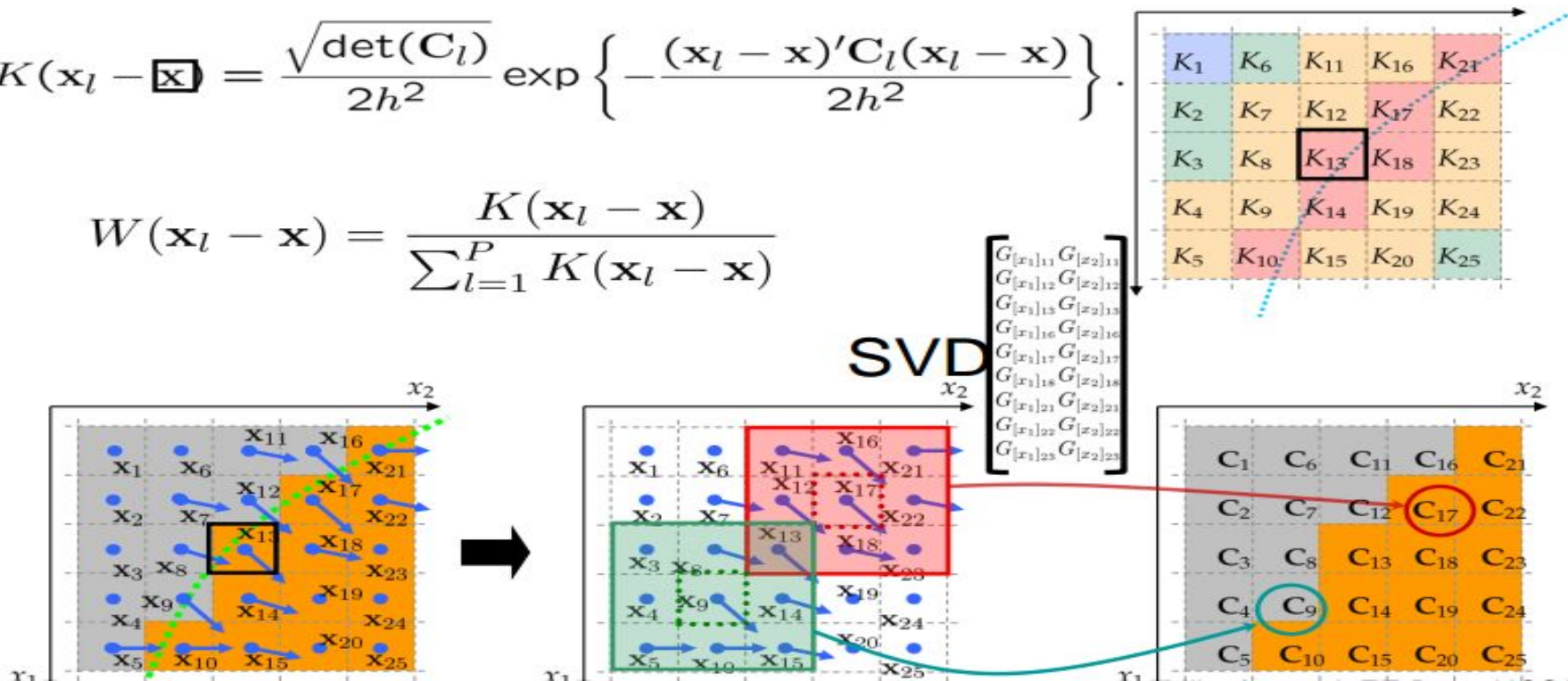
One Shot Detection System Pipeline



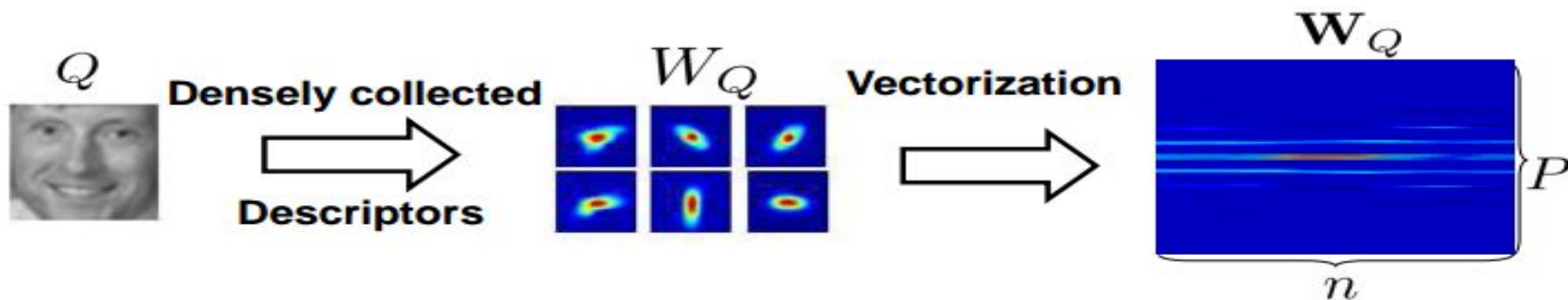
Stage 1: Calculation of Local Descriptors

$$K(\mathbf{x}_l - \mathbf{x}) = \frac{\sqrt{\det(\mathbf{C}_l)}}{2h^2} \exp \left\{ -\frac{(\mathbf{x}_l - \mathbf{x})' \mathbf{C}_l (\mathbf{x}_l - \mathbf{x})}{2h^2} \right\}$$

$$W(\mathbf{x}_l - \mathbf{x}) = \frac{K(\mathbf{x}_l - \mathbf{x})}{\sum_{l=1}^P K(\mathbf{x}_l - \mathbf{x})}$$



Stage 2: Feature Extraction from Descriptors

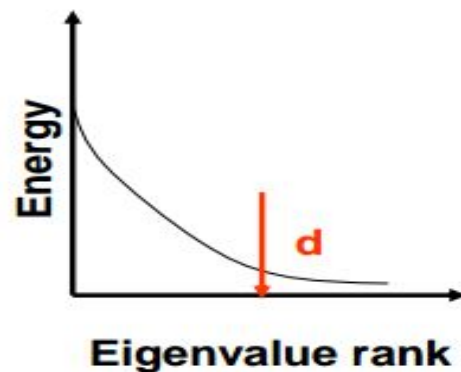


 **Apply PCA to W_Q for dimensionality reduction**

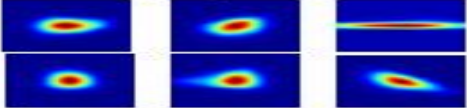


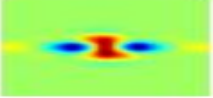


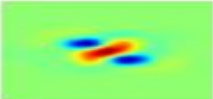


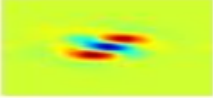


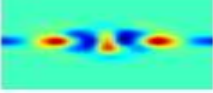


- Retain the d largest principal components $A_Q \in \mathbb{R}^{P \times d}$
- Project W_Q and W_T onto A_Q

$$\mathbf{F}_Q = [\underline{\mathbf{f}}_Q^1, \dots, \underline{\mathbf{f}}_Q^n] = \mathbf{A}_Q' \mathbf{W}_Q$$

$$\mathbf{F}_T = [\underline{\mathbf{f}}_T^1, \dots, \underline{\mathbf{f}}_T^{n_T}] = \mathbf{A}_Q' \mathbf{W}_T$$



Stage 2: Salient features after PCA

Object: Car		
LSK $W_Q(x_l - x; 2)$	Query Q	Target T
		
 1st eigenvector $A_Q(1)$	 $F_Q(1)$	 $F_T(1)$
 2nd eigenvector $A_Q(2)$	 $F_Q(2)$	 $F_T(2)$
 3rd eigenvector $A_Q(3)$	 $F_Q(3)$	 $F_T(3)$
 4th eigenvector $A_Q(4)$	 $F_Q(4)$	 $F_T(4)$
Eigenvectors	Query features	Target features

Stage 3: Finding similarity between features

Target **image** is divided into a set of overlapping **patches**

$$F_Q \longleftrightarrow F_{T_i}$$

Query T_0



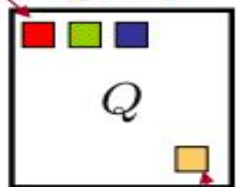
Target



T_{M-1}

f_Q^1

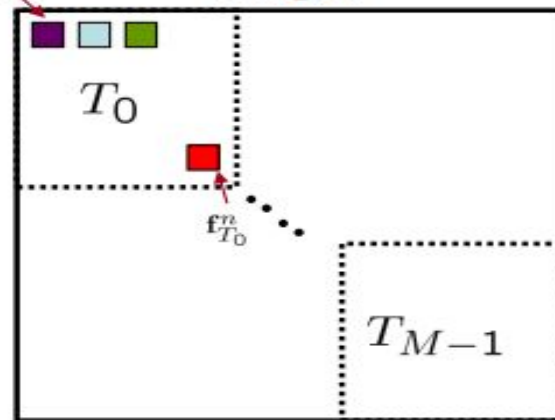
Query



f_Q^n

$f_{T_0}^1$

Target



Stage 3: Matrix Cosine Similarity

What about a set of vectors? **Matrix Cosine Similarity**

→ **Frobenius Inner product between normalized matrices**

Query

Target patch

$$\begin{aligned}\rho(\mathbf{F}_Q, \mathbf{F}_{T_i}) &= \langle \bar{\mathbf{F}}_Q, \bar{\mathbf{F}}_{T_i} \rangle_F = \text{trace}\left(\frac{\mathbf{F}'_Q \mathbf{F}_{T_i}}{\|\mathbf{F}_Q\|_F \|\mathbf{F}_{T_i}\|_F}\right) \in [-1, 1], \\ &= \sum_{\ell=1}^n \frac{\mathbf{f}_Q^{\ell'} \mathbf{f}_{T_i}^{\ell}}{\|\mathbf{F}_Q\|_F \|\mathbf{F}_{T_i}\|_F}, \\ &= \sum_{\ell=1}^n \rho(\mathbf{f}_Q^{\ell}, \mathbf{f}_{T_i}^{\ell}) \frac{\|\mathbf{f}_Q^{\ell}\| \|\mathbf{f}_{T_i}^{\ell}\|}{\|\mathbf{F}_Q\|_F \|\mathbf{F}_{T_i}\|_F}.\end{aligned}$$

A **weighted** sum of the column-wise vector **cosine similarities**

$$= \rho(\text{colstack}(\mathbf{F}_Q), \text{colstack}(\mathbf{F}_{T_i}))$$

Stage 3: Generate Resemblance Map

Resemblance Map (RM)

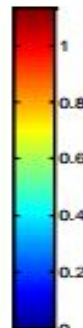
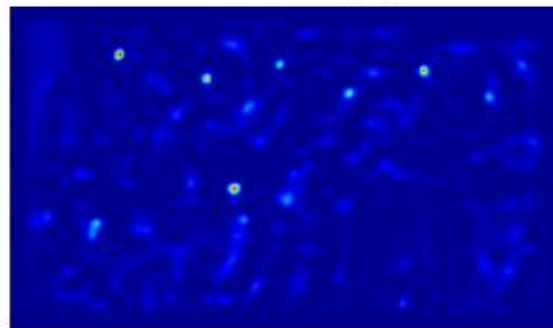
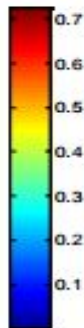
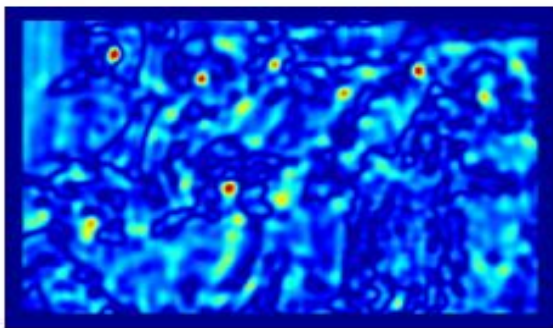
Describes the proportion of variance in common between two features

$$\text{RM} : f(\rho_i) = \frac{\rho_i^2}{1 - \rho_i^2}$$

Lawley-Hotelling Trace statistic

$$\text{RM} : |\rho_i|$$

$$\text{RM} : \frac{\rho_i^2}{1 - \rho_i^2}$$



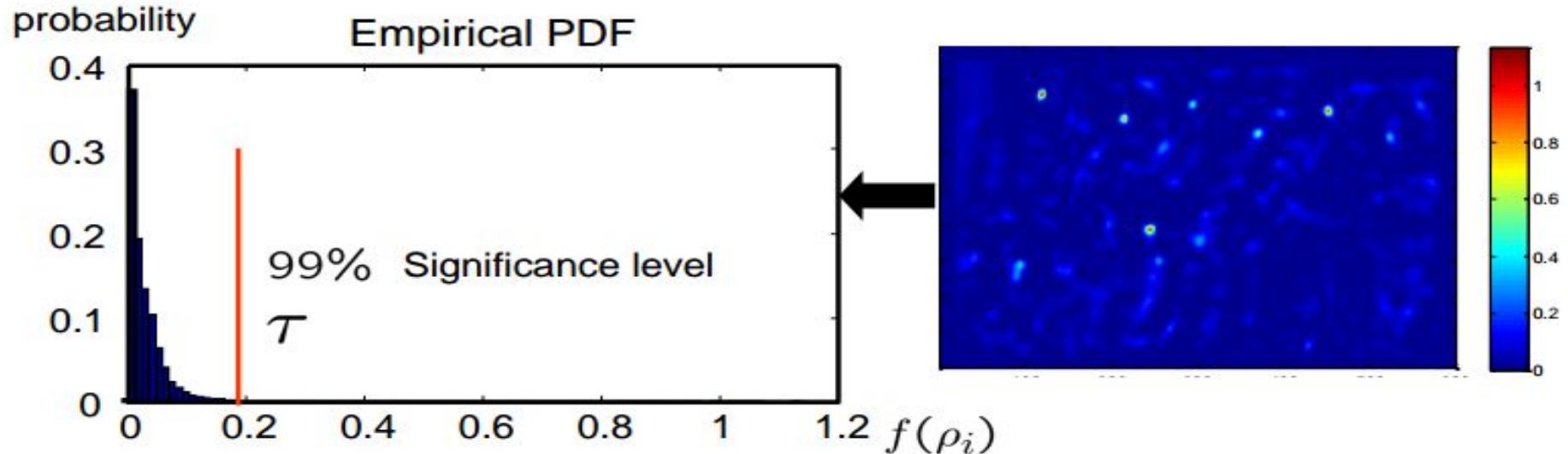
Stage 3: Significance Tests & Non Maxima Suppression

1. Is **any** sufficiently similar object present?

$$\max f(\rho_i) > \tau_0$$

i.e., $\tau_0 = 0.96$ so that $\sim 50\%$ of variance in common

2. **How many objects** of interest are present?



Experimental Results

query



target



output



Experimental Results

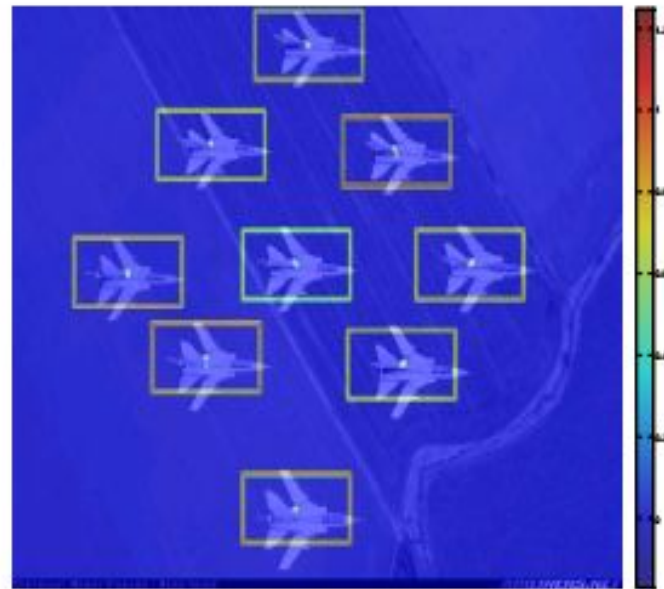
query



target



output



Limitations & Future Work

- 1. Make algorithm scalable for image and (video) retrieval**
- 2. Increase accuracy by incorporating “context”**
- 3. Detect /recognize objects of interest in general degraded data without explicit restoration**
- 4. Extension to large-scale data set requires a significant improvement of the computational complexity of the proposed method.**

THANK YOU!