## **Experiment1.2**

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#### Aim:

Write a program to access various feature matching algorithms for object recognition.

**Software Required:** Google colab notebook

Feature matching using: Brute-force algorithm -

import numpy as np

import cv2 as cv

import matplotlib.pyplot as plt

img1 = cv.imread('/content/IMG\_5160.png',cv.IMREAD\_GRAYSCALE)

img2 = cv.imread('/content/fotor\_2023-5-

26\_21\_26\_26.png',cv.IMREAD\_GRAYSCALE)

orb = cv.ORB\_create()

kp1, des1 = orb.detectAndCompute(img1,None)

kp2, des2 = orb.detectAndCompute(img2,None)

bf = cv.BFMatcher(cv.NORM\_HAMMING, crossCheck=True)

matches = bf.match(des1,des2)

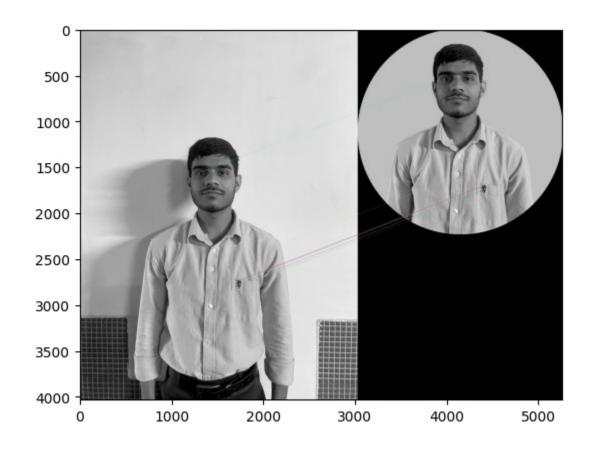
matches = sorted(matches, key = lambda x:x.distance)

img3=cv.drawMatches(img1,kp1,img2,kp2,matches[:10],None,flags=cv.Dra

wMatchesFlags\_NOT\_DRAW\_SINGLE\_POINTS)

plt.imshow(img3),plt.show()

# **Output:**



### Feature matching using: FLANN algorithm -

import cv2 import matplotlib.pyplot as plt %matplotlib inline img1 = cv2.imread('/content/IMG 5160.png') img2 = cv2.imread('/content/fotor\_2023-5-26\_21\_26\_26.png') img1 = cv2.cvtColor(img1, cv2.COLOR\_BGR2GRAY) img2 = cv2.cvtColor(img2, cv2.COLOR\_BGR2GRAY) sift = cv2.xfeatures2d.SIFT create() keypoints\_1, descriptors 1 = sift.detectAndCompute(img1.None) keypoints 2, descriptors 2 = sift.detectAndCompute(img2,None) bf = cv2.BFMatcher(cv2.NORM L1, crossCheck=True) matches = bf.match(descriptors 1,descriptors 2) matches = sorted(matches, key = lambda x:x.distance) img3 = cv2.drawMatches(img1, keypoints 1, img2, keypoints 2, matches[:50], img2, flags=2) plt.imshow(img3),plt.show()

## **Output:**

