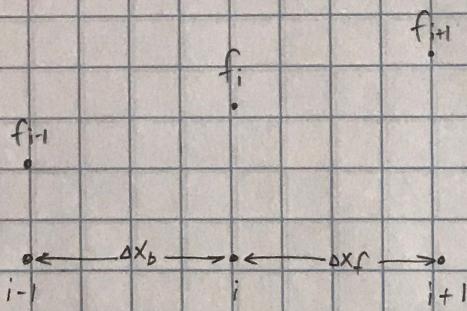


1)

$$\begin{aligned}x_{i+1} &= x_i - \Delta x_b \\x_{i-1} &= x_i + \Delta x_f \quad \Delta x_b \neq \Delta x_f\end{aligned}$$

$$\begin{aligned}f_{i-1} &= f(x_i - \Delta x_b) \\f_{i+1} &= f(x_i + \Delta x_f)\end{aligned}$$



Taylor Series definition : $\sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n$

for $a = x_i$ and $x = x_{i+1}, x_{i-1}$, the Taylor series for f_{i+1} & f_{i-1} become, respectively:

$$f_{i+1} = f_i + f'_i \underbrace{(x_i + \Delta x_f - x_i)}_{\Delta x_f} + \frac{1}{2} f''_i (\Delta x_f)^2 + \dots$$

$$f_{i-1} = f_i + f'_i \underbrace{(x_i - \Delta x_b - x_i)}_{-\Delta x_b} + \frac{1}{2} f''_i (-\Delta x_b)^2 + \dots = f_i - f'_i \Delta x_b + \frac{1}{2} f''_i \Delta x_b^2 + \dots$$

A centered-difference approximation for the first derivative can be found by $(f_{i+1} - f_{i-1})$, truncating the higher order terms, and solving for f'_i :

$$f_{i+1} - f_{i-1} = f_i - f_i + f'_i \Delta x_f + f'_i \Delta x_b + \frac{1}{2} f''_i (\Delta x_f)^2 - \frac{1}{2} f''_i (\Delta x_b)^2 + \dots$$

$$f_{i+1} - f_{i-1} = f'_i (\Delta x_f + \Delta x_b) + \frac{1}{2} f''_i [(\Delta x_f)^2 - (\Delta x_b)^2]$$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{\Delta x_f + \Delta x_b} - \frac{1}{2} f''_i \frac{[(\Delta x_f)^2 - (\Delta x_b)^2]}{(\Delta x_f + \Delta x_b)}$$

a.
$$f'_i = \frac{f_{i+1} - f_{i-1}}{\Delta x_f + \Delta x_b}$$

b. by inspection of the truncated 2nd-order term, the order of the error is : CONT. →

1) cont.

PAUL YUSKA

$$\frac{\Delta x_f^2 - \Delta x_b^2}{\Delta x_f + \Delta x_b} = \frac{\Delta x_f^2}{\Delta x_f + \Delta x_b} - \frac{\Delta x_b^2}{\Delta x_f + \Delta x_b} \approx \boxed{\Delta x_f - \Delta x_b}$$

Hand-wavey, I know.
I'm still missing something here. APPROX.

c. define $\left[\frac{df}{dx} \right]_{i+1/2} = f'_{i+\frac{1}{2}}$ as $\frac{f'_i + f'_{i+1}}{2} \leftarrow$ halfway between grid pts., regardless of spacing

where f'_{i+1} is found by solving the Taylor series about f_{i+1} in a similar manner as above.

for $a = x_{i+1}$ and $x = x_i, x_{i+2}$, and $x_{i+2} = x_{i+1} + \Delta x_{f_2}$

$$f'_{i+1} = \frac{f_{i+2} - f_i}{\Delta x_f + \Delta x_{f_2}}, \quad f'_i = \frac{f_{i+1} - f_{i-1}}{\Delta x_f + \Delta x_b}$$

define $\left[\frac{df}{dx} \right]_{i-\frac{1}{2}}$ similarly, finding f'_{i-1} in the same manner as f'_{i+1} :

$$f'_{i-1} = \frac{f_i - f_{i-2}}{\Delta x_b + \Delta x_{b_2}}, \quad f'_i = \uparrow$$

define $x_{i\pm\frac{1}{2}}$ as $\frac{x_i + x_{i\pm 1}}{2} = \frac{x_i + (x_i + \Delta x_f)}{2} = x_i + \frac{1}{2} \Delta x_f$ and

$$\frac{x_{i-1} + x_i}{2} = \rightarrow = x_i - \frac{1}{2} \Delta x_b$$

then, f''_i can be approximated as:

$$f''_i \approx \left[\frac{f'_{i+1} + f'_i}{2} - \frac{f'_i + f'_{i-1}}{2} \right] \frac{1}{\frac{1}{2}(\Delta x_f + \Delta x_b)}$$

$$f''_i \approx \frac{\left(\frac{f_{i+2} - f_i}{\Delta x_f + \Delta x_{f_2}} + \frac{f_{i+1} - f_{i-1}}{\Delta x_f + \Delta x_b} \right) - \left(\frac{f_{i+1} - f_{i-1}}{\Delta x_f + \Delta x_b} + \frac{f_i - f_{i-2}}{\Delta x_b + \Delta x_{b_2}} \right)}{\Delta x_f + \Delta x_b}$$

2) a. Start w/ $\underline{\underline{A}}\underline{x} = \underline{b}$

Perturb the system: $\underline{\underline{A}} \rightarrow \underline{\underline{A}} + \underline{\underline{\delta A}}$, $\underline{b} \rightarrow \underline{b} + \underline{\delta b}$

$$(\underline{\underline{A}} + \underline{\underline{\delta A}})\underline{x} = \underline{b} + \underline{\delta b}$$

$\underline{\underline{A}}\underline{x} + \underline{\underline{\delta A}}\underline{x} = \underline{b} + \underline{\delta b}$ subtract unperturbed system to get

$$\underline{\underline{\delta A}}\underline{x} = \underline{\delta b} \rightarrow \underbrace{\underline{\underline{A}}\underline{\underline{A}}^{-1}\underline{\underline{\delta A}}}_{\underline{\underline{I}}} \underline{x} = \underline{\delta b}$$

$$\|\underline{\underline{A}}\| \|\underline{\underline{A}}^{-1}\| \geq \|\underline{\underline{I}}\| = \|\underline{\underline{A}}\underline{\underline{A}}^{-1}\|$$

$$\underbrace{\|\underline{\underline{A}}\| \|\underline{\underline{A}}^{-1}\| \|\underline{\underline{\delta A}}\| \|\underline{x}\|}_{C(A)} \geq \|\underline{\delta b}\| \rightarrow C(A) \|\underline{\underline{\delta A}}\| \|\underline{x}\| \geq \|\underline{\delta b}\|$$

$$C(A) \frac{\|\underline{\underline{\delta A}}\| \|\underline{x}\|}{\|\underline{\underline{A}}\| \|\underline{x}\|} \stackrel{n^2}{\rightarrow} \frac{\|\underline{\delta b}\|}{\|\underline{b}\|}$$

b. The condition # is a measure of sensitivity of changes in the solution of a system to perturbation of the input. High condition numbers ($C \gg 1$) are bad. C on the order of 1 is desirable.

PAUL YUSKA

$$4) \quad y(x) = ax^2 + bx^5$$

$$S(a, b) = \sum_{i=1}^N (y_i - ax^2 - bx^5)^2$$

$$\frac{\partial S}{\partial a} = \sum_{i=1}^N 2(y_i - ax^2 - bx^5)(2x) = \sum_{i=1}^N 4(y_i x - ax^3 - bx^6) = 0$$

$$\frac{\partial S}{\partial b} = \sum_{i=1}^N 2(y_i - ax^2 - bx^5)(5x^4) = \sum_{i=1}^N 10(y_i x^4 - ax^6 - bx^9) = 0$$

$$\begin{bmatrix} \sum_{i=1}^N x^3 & \sum_{i=1}^N x^6 \\ \sum_{i=1}^N x^6 & \sum_{i=1}^N x^9 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^N y_i x \\ \sum_{i=1}^N y_i x^4 \end{bmatrix}$$