

PROJECT STATUS REPORT 3

NOISE AND ECHO CANCELLATION IN A TELECONFERENCE

DATE: 29TH APRIL 2015

PROJECT STATUS SUMMARY

Our goal in this project is to appropriately apply noise cancellation in such a way which enables the system to extract only the voice signal removing as much noise as possible for a great teleconference experience.

To complete the project successfully, our project group and tasks are divided into 3 parts: Android group, Theory group and Management group.

The project schedule is perfectly in line with the schedule and we are confident to complete the project within due date. If required, the members are also planning to accelerate the progress by working weekends and extended hours in the next few weeks.

WORK PLANNED TILL 29TH APRIL, 2015

Android Part: As stated in the previous report, we have already completed all the android tasks before our own set deadline, and thus we didn't plan to work much on this part, rather refining our works.

Theory Part: The main goal was be to make research on below points:

- Non-linear algorithms: make a non-linear model and test them in MATLAB
- Wiener Filtering with the new model
- Test LMS in different scenarios being the main goal the avoidance of residual voice in the noise recordings
 - Record the noise from another room
 - Record from a louder noise source using an amplifier.

Management Part: Following up the progress of the group was set as the core responsibility of the management group.

WORK COMPLETED TILL 29TH APRIL, 2015

Android Part: As all the tasks were successfully completed on last week, we worked to refine our outcome on this part. We also started to implement a real time version of the LMS and NMLS algorithm first using only two phones and then three phones.

Theory Part: There have been different areas where to work:

- RLS: there will not be any more research on RLS
- LMS frequency domain: some more tests done, no progress.
- Non-Linear Algorithms: No results yet. It is planned to have some results in 1 week on this.
- Wiener Filtering: implementation and test done in theory (MATLAB). No improvement yet, but will continue working on it.

Management Part: Every members work progress was monitored and followed-up as required to finish everything within the set timeline and integrated to the progress report.

WORK PLANNED FOR NEXT WEEK

The main goal will be to make research on next points:

- Non-linear algorithms: make a non-linear model and test them in MATLAB
- Wiener Filtering: improve results
- Test LMS in different scenarios being the main goal the avoidance of residual voice in the noise recordings
 - Record the noise from another room
 - Record from a louder noise source using an amplifier.
- Combine LMS and Wiener filtering

OPEN ISSUES

No new open issues.

RISK ANALYSIS

The update of the risk analysis remains as the one in the project plan (see the table below).

Nr	Risk	P	C	R	Action
1	Do not find a good theoretical model	1	4	4	Read more literature
2	Do not pass the mid-term evaluation	1	4	4	Re-schedule the TRP
3	Problems with real time	2	4	8	Help and re-schedule TRP

As per the above table, the risk number 1 & 2 are less likely to affect our project outcome because we have good theoretical model with good performance and we have already completed all the 7 android tasks assigned for the mid-term evaluation.

Currently our main concern is the third risk factor, which might take a lot of time, but we are working hard to eliminate this risk factor as much as we can.

KEY PERFORMANCE INDICATORS (KPI'S)

To have a better understanding of the progress of the project the Gantt chart and the working hours of every individual compared to resource allocation table is attached as annexures below:

EQ2400

Week 5
4 - 20 - 15

Week 6
4 - 27 - 15

M T W T F S S M T W T F S S

[illegible]

Annex 2	Cost/hour (SEK)	Day	23/4	24/4	25/4	26/4	27/4	28/4	29/4
Animesh Das	400	Outcome (h)	6	6			6	6	7
		Plan (h)	6	6			6	6	6
Jonas Sedin	400	Outcome (h)	3	3			7	6	7
		Plan (h)	6	6			5	5	5
Mohammad Abdulla	400	Outcome (h)	5	4		2	5	5.5	5
		Plan (h)	5	2		5	5	5	5
Thomas Gaudy	400	Outcome (h)	4	7	5	2	8	2	6
		Plan (h)		6			6	6	6
Xavier Bush	400	Outcome (h)	3	4		2	7	6	5
		Plan (h)	6	6			4	4	4
		Outcome (h)							
		Plan (h)							