

ZRecognition
TPJ665
Final Capstone Project

Patrick Ziajski
Zarak Khattak

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SENECA COLLEGE OF APPLIED ARTS AND TECHNOLOGY
School of Electronics and Mechanical Engineering Technology
1750 Finch Ave East, Toronto, Ontario, M2J 2X5. Tel. 416-491-5050
www.senecacollege.ca

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1 Executive Summary

Z-Recognition is a License Plate Recognition system which provides clients with a new and intuitive way to implement and enforce parking systems. Our goal is to allow for the successful implementation of both hardware and software elements to allow for a working project. The hardware aspect of the project involves the implementation of a microcontroller which will hold all the pre-required software to run the system. A camera that will be used to capture images of License plates. A speaker and a Servo Motor. The software aspect of the project entails the creation of a python script which will bring together all the hardware elements and have them operate with each other. The script will use the capture an image which will be processed as a JavaScript Object Notation (JSON) using Microsoft Azure Cognitive Services to process the image as text. The captured data will then be cross referenced against a database for validity and the Servo Motor will operate in response to valid data being found, whereas, the speaker will operate if no matching data is found.

2 Introduction

Security is an important feature for a company providing a service to their customer. The company must ensure that its service can only be used by authorized personnel. This is where Z-Recognition comes into play. Z-Recognition is a license plate recognition system that ensures only authorized personnel have access to a designated area. Z-Recognition accomplishes this by taking an image of the approaching vehicle and processing it. If the vehicle is authorized, meaning the license plate is recognized, the vehicle is given access. Our group has decided on a license plate recognition system due to its uses in modern day society. Today, one can still find areas that are monitored by a single employee, or by a ticket-based entry system. These systems could be found inferior because of their reliance on periodic human interaction or supervision. Z-Recognition is designed to run autonomously with minimal costs, and a single requirement of an active internet. This license plate recognition system also implements a core feature in the future of computer technology, machine learning. With machine learning, an artificial intelligence (AI) can provide systems the ability to learn and improve without being explicitly programmed. This means that automated systems become more secure and reliable, without the need of constant supervision. Finally, this project will require both hardware and software implementation to be fully functional. It will require us to work with and learn both software

development and hardware assembly which we, as Computer Engineering and Technology students, would prefer.

3 Functional Features

- Image processing - Using Microsoft's Cloud based Computer Vision Service, called Azure, a captured image will be uploaded to Azure's Service. The service perform Optical Character Recognition (OCR) on the image, and it will return a JavaScript Object Notation (JSON) object with all the recognized characters.
- Motor Control - The Raspberry Pi 3 Model B, a MicroController Unit (MCU), will control a servo-motor to imitate a gate arm used to allow entrance into a secure area.
- Scheduled script execution - The main python script will be executed at specified time intervals
- Sound execution - The Raspberry Pi will emit a sound from a speaker in order to audibly notify the personnel using the system of whether they have been given or denied access.

4 System Specifications

Camera

- 720p/30fps
- Fixed focus
- Field of View - 60°

Raspberry Pi 3 Model B

- Quad Core 1.2GHz Broadcom BCM2837 64bit CPU
- 1GB RAM
- BCM43438 wireless LAN
- 40-pin extended GPIO
- 4 Pole stereo output
- Micro SD

Servo-motor

- Operating voltage - 3.0V - 7.2V

Microsoft Azure

- Active subscription
- Cognitive Services resource

5 Operating Instructions

Please follow the listed steps to ensure that the system is operating as intended:

- Ensure that the Raspberry Pi Microprocessor is powered on
 - Plug the power cord into the Pi and connect to a power source
 - Launch the python script
- Connect the Pi to an internet source
 - Connect using Wi-Fi or using an Ethernet Cable
- Ensure that the Camera is on
 - Connect the Camera to a powersource and aim in the direction towards which you want to capture the images

6 Product Design, Implementation, and Operation of the System

6.1 System Block-Diagram

6.2 UML Diagram

6.3 Software Flow-Chart

6.4 Component images and components description/Captures of the major GUI used

6.5 Theory of operation of the entire system

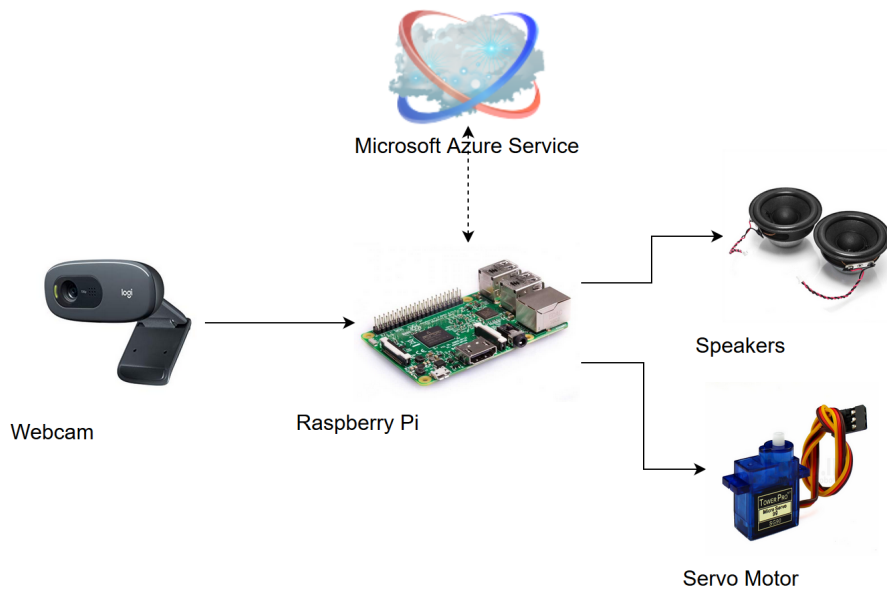


Figure 1: System Block-Diagram

7 Maintenance Requirements

Routine maintenance is a good way to avoid any unwanted interruptions for the services being provided. It is recommended that proactive maintenance be done on the system at a frequency of one week (7 days) or anytime that the system fails to operate.

- Reset the Pi Microprocessor
- Relaunch the Python script

Please ensure that you test the service after completing maintenance to ensure that all systems are up and running.

If you are unsure of how to complete any of these tasks, please get in touch with the contacts available in the contact(s) section of the report.

A Electrical Schematics

B Parts List

BILL OF MATERIALS		
Component Name	Quantity	Price (CAD)
Raspberry Pi 3 Model B	1	\$35.00
Logitech C270 HD Webcam	1	\$32.00
RioRand 5PCS x SG90 Micro 9d Servo	1	\$16.99
Gikfun 2" 8 Ohm 2W Audio Speaker	1	\$16.88
Total Cost w/ Tax		\$113.98

Table 1: Bill of Materials

NOTE All prices are in Canadian Dollars (CAD)

C List of all User Names and passwords used in software

Currently there are no log in credentials required for any aspect of the software system

D References

E Contact Information

Patrick Ziajski
Phone: (647) 339 2847
Email: pziajski@myseneca.ca

Zarak Khattak
Phone: (587) 226 3196
Email: zkhattak@myseneca.ca