

M-estimation for fusion designs

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¹Footnotes are reserved asides for possible later discussion or questions

M-estimation

M-estimators are the solution to

$$\frac{1}{n} \sum_{i=1}^n \psi(O_i; \hat{\theta}) = 0$$

Estimating function for the mean

$$\frac{1}{n} \sum_{i=1}^n Y_i = \mu \quad \rightarrow \quad \frac{1}{n} \sum_{i=1}^n (Y_i - \mu) = 0$$

²For a general introduction see either Chapter 7 of *Essential Statistical Inference* or Stefanski & Boos (2002) *Am Stat*

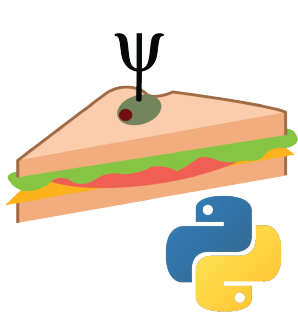
Example: inverse probability of missingness weighted mean

- MNAR conditional on W

$$\psi(O_i, \theta) = \begin{bmatrix} (R_i - \text{expit}(W_i^T \beta)) W_i \\ Y_i R_i \frac{1}{\text{expit}(W_i^T \beta)} - \mu \end{bmatrix}$$

Variance of μ can be estimated via sandwich variance

- Uncertainty of μ depends uncertainty of β



PROC IML;



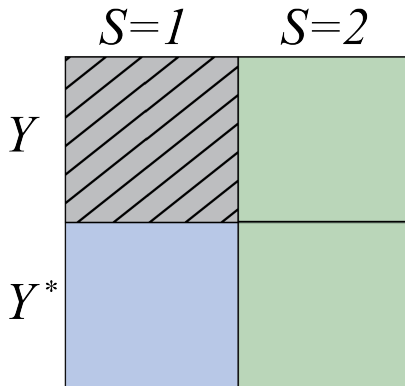
³delicatessen: Zivich et al. (2022) *arXiv*

⁴geex: Saul & Hudgens (2020) *J Stat Softw*

Fusion applications

A1: measurement error⁵

Estimate mean of variable Y for population $S = 1$



⁵Example based on Cole et al. *Am J Epidemiol* in-press

A1: measurement error

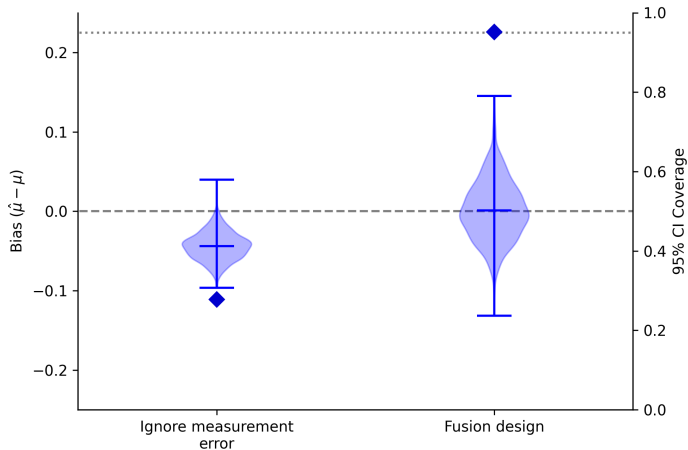
Estimating functions⁶

$$\psi(O_i; \theta) = \begin{bmatrix} I(S_i = 2)Y_i(Y_i^* - \alpha_1) \\ I(S_i = 2)(1 - Y_i)((1 - Y_i^*) - \alpha_0) \\ I(S_i = 1)(Y_i^* - \omega) \\ \mu(\alpha_1 + \alpha_0 - 1) - (\omega + \alpha_0 - 1) \end{bmatrix}$$

where $O_i = (S_i, Y_i, Y_i^*)$ and $\theta = (\alpha_1, \alpha_0, \omega, \mu)$

⁶Measurement correction from Rogan & Gladen (1978) *Am J Epidemiol*

A1: measurement error^{7,8}



⁷Details and code available at github.com/pzivich/Presentations

⁸Based on 2000 repetitions with $n_1 = 750$, $n_2 = 200$, and $\mu = 0.37$

A2: transport and measurement error

Estimate mean of variable Y for population $S = 3$

	$S=1$	$S=2$	$S=3$
W			
Y			
Y^*			

A2: transport and measurement error

Estimating functions^{9,10}

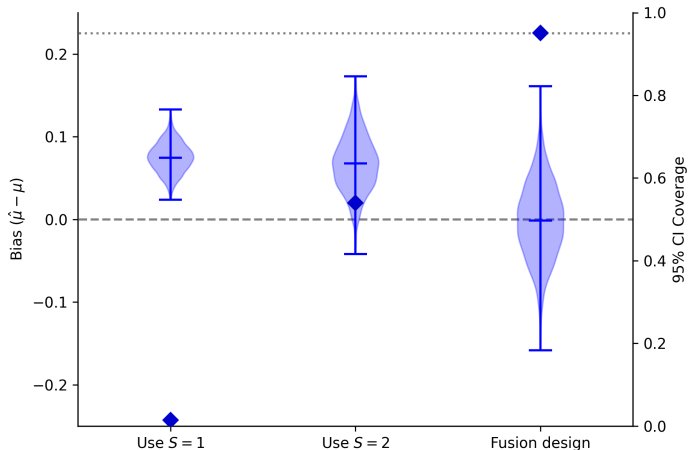
$$\psi(O_i; \theta) = \begin{bmatrix} I(S_i = 2)Y_i(Y_i^* - \alpha_1) \\ I(S_i = 2)(1 - Y_i)((1 - Y_i^*) - \alpha_0) \\ I(S_i \neq 2) (I(S_i = 3) - \text{expit}(W_i^T \beta)) W_i \\ I(S_i = 1) \frac{1 - \text{expit}(W_i^T \beta)}{\text{expit}(W_i^T \beta)} (Y_i^* - \omega) \\ \mu(\alpha_1 + \alpha_0 - 1) - (\omega + \alpha_0 - 1) \end{bmatrix}$$

where $O_i = (S_i, W_i, Y_i, Y_i^*)$ and $\theta = (\alpha_1, \alpha_0, \beta, \omega, \mu)$

⁹Measurement correction from Rogan & Gladen (1978) *Am J Epidemiol*

¹⁰Inverse odds weights from Westreich et al. (2017) *Am J Epidemiol*

A2: transport and measurement error^{11,12}



¹¹Details and code available at github.com/pzivich/Presentations

¹²Based on 2000 repetitions with $n_1 = 750$, $n_2 = 200$, $n_3 = 2000$, and $\mu = 0.42$

A3: bridged study design

Compared triple therapy to mono therapy through dual therapy¹³

- Using ACTG 320 and ACTG 175
- Restricting by CD4 between 50-300 cells/mm³

$$(F_3(t) - F_2(t)) + (F_2(t) - F_1(t))$$

¹³Breskin et al. (2021) *Stats in Med*

A3: bridged study design

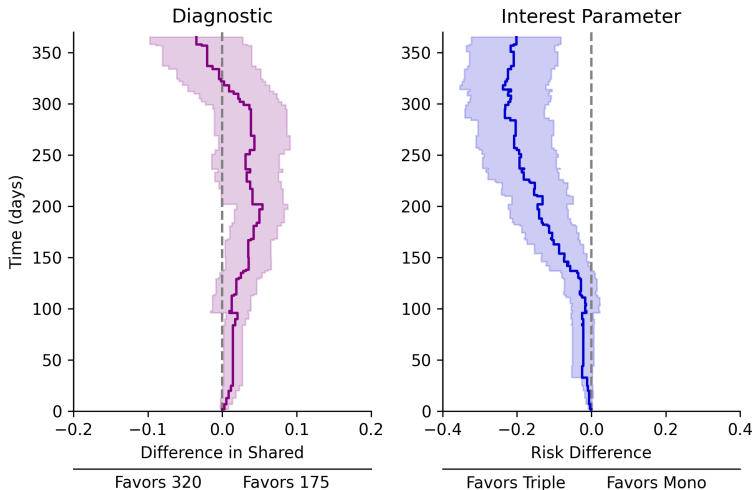
Estimating functions¹⁴

$$\psi(O_i; \theta) = \begin{bmatrix} (I(S_i = 320) - \text{expit}(W_i^T)) W_i \\ I(S_i = 175) (I(A_i = 1) - \gamma_{0,1}) \\ I(S_i = 175) (I(A_i = 2) - \gamma_{0,2}) \\ I(S_i = 320) (I(A_i = 2) - \gamma_{1,2}) \\ I(S_i = 320) (I(A_i = 3) - \gamma_{1,3}) \\ \psi_{AFT}(O_i; \lambda, \alpha) \\ \psi_{RD}(t, a; \mu_t, \beta, \gamma_{a,s}, \lambda, \alpha) \end{bmatrix}$$

where $O_i = (S_i, T_i^*, \delta_i, A_i, W_i)$ and $\theta = (\beta, \gamma_{a,s}, \lambda, \alpha, \mu_t)$

¹⁴Here, I am using a Weibull AFT model

A3: bridged study design



M-estimation provide an adaptable way to develop fusion estimators

- Stack estimating functions together
- Sandwich variance estimator

Limitations of M-estimators

- Reliance on parametric models
- Estimating functions can't depend on i

Supplement

Sandwich variance estimator

$$V_n(O_i; \hat{\theta}) = B_n(O_i; \hat{\theta})^{-1} F_n(O_i; \hat{\theta}) \left(B_n(O_i; \hat{\theta})^{-1} \right)^T$$

where the bread is

$$B_n(O_i; \hat{\theta}) = \frac{1}{n} \sum_{i=1}^n -\psi'(O_i; \hat{\theta})$$

and the filling is

$$F_n(O_i; \hat{\theta}) = \frac{1}{n} \sum_{i=1}^n \psi(O_i; \hat{\theta}) \psi(O_i; \hat{\theta})^T$$