### M-estimation

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# Acknowledgements

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<sup>&</sup>lt;sup>1</sup>Footnotes are reserved asides for possible discussion or questions

#### Overview

Introduce M-estimation

Computational M-estimation

Applications

Conclusion

## Introduction to M-estimation

# M-estimation: a short history

- M(aximum likelihood)-estimation
  - More general framework<sup>2</sup>
  - Defined as a zero of an estimating function
- Developed to study robust statistics<sup>3,4</sup>
  - Mean robust to outliers
- Operate under frequentist superpopulation model

<sup>&</sup>lt;sup>2</sup>Stefanski LA & Boos DD (2002) The American Statistician, 56(1), 29-38.

<sup>&</sup>lt;sup>3</sup>Huber PJ (1964) Annals of Mathematical Statistics, 35, 73–101.

<sup>&</sup>lt;sup>4</sup>Huber PJ (1973) Annals of Statistics, 1, 799–821.

### M-estimation: the basics

M-estimator: solution for  $\theta$  in

$$\sum_{i=1}^{n} \psi(O_i; \hat{\theta}) = 0$$

#### where

- $O_1, O_2, ..., O_n$  are independent observations
- $\bullet \ \theta = (\theta_1, ..., \theta_k)$
- $\psi(.)$  is a known  $k \times 1$  estimating function
  - ullet Does not depend on i
  - Proof of CAN follows from unbiased estimating functions<sup>5</sup>

<sup>&</sup>lt;sup>5</sup>See pages 327-329 of 'Essential Statistical Inference' by Boos & Stefanski

Task: estimate the mean  $(\mu)$  of  $\{1, 5, 3, 7, 24\}$ 

Using  $\hat{\mu} = n^{-1} \sum_{i=1}^{n} Y_i$ 

$$\hat{\mu} = \frac{1+5+3+7+24}{5} = \frac{40}{5} = 8$$

The equivalent estimating function is

$$\sum_{i=1}^{n} (Y_i - \hat{\mu}) = 0$$

To find  $\hat{\mu}$ , we use a root-finding algorithm<sup>6</sup>

- Select a grid of values
  - 0, 5, ..., 25
- Plug in guess for  $\hat{\mu}$  into  $\sum_{i=1}^{n} (Y_i \hat{\mu})$
- Select values that straddle zero
  - 5, 10
- Select new grid and repeat process
  - 5, 6, 7, 8, 9, 10
- ullet Terminate procedure when  $\hat{\mu}$  that returns zero is found

End up with  $\hat{\mu}=8$ 

<sup>&</sup>lt;sup>6</sup>This procedure is a simple example of the bisection algorithm.

### M-estimation: the basics

Asymptotic sandwich variance

$$V(\theta) = B(\theta)^{-1} F(\theta) \left( B(\theta)^{-1} \right)^{T}$$

Empirical sandwich variance estimator

$$V_n(O_i; \hat{\theta}) = B_n(O_i; \hat{\theta})^{-1} F_n(O_i; \hat{\theta}) \left( B_n(O_i; \hat{\theta})^{-1} \right)^T$$

where

$$B_n(O_i; \hat{\theta}) = n^{-1} \sum_{i=1}^n -\psi'(O_i; \hat{\theta})$$

$$F_n(O_i; \hat{\theta}) = n^{-1} \sum_{i=1}^n \psi(O_i; \hat{\theta}) \psi(O_i; \hat{\theta})^T$$

### Connections to maximum likelihood estimation

When the correct parametric family is assumed

$$B(\theta) = F(\theta) = I(\theta)$$

Therefore

$$V(\theta) = I(\theta)^{-1}$$

When the parametric family is incorrect

$$B(\theta) \neq F(\theta)$$

and the correct limiting variance is  $V(\boldsymbol{\theta})$ 

# Advantages of the sandwich estimator

#### Key advantages

- Robust to secondary assumptions
- Automation of the delta method
- Captures uncertainty of parameters that depend on other estimated parameters
- Less computationally intensive
  - Relative to bootstrap, Monte Carlo

Bread matrix

$$B_n(Y_i; \hat{\mu}) = 5^{-1} \sum_{i=1}^{5} -\psi'(Y_i; \hat{\mu})$$

Here

$$\psi'(Y_i; \hat{\mu}) = \frac{d}{d\hat{\mu}} (Y_i - \hat{\mu}) = -1$$

Therefore

$$B_n(Y_i; \hat{\mu}) = 5^{-1} \sum_{i=1}^{5} -(-1) = \frac{5}{5} = 1$$

Filling matrix

$$F_n(Y_i; \hat{\mu}) = 5^{-1} \sum_{i=1}^{5} \psi(Y_i; \hat{\mu}) \psi(Y_i; \hat{\mu})^T$$

Here

$$\psi(Y_i; \hat{\mu})\psi(Y_i; \hat{\mu})^T = (Y_i - \hat{\mu})(Y_i - \hat{\mu}) = (Y_i - \hat{\mu})^2$$

Therefore

$$F_n(Y_i; \hat{\mu}) = 5^{-1} \sum_{i=1}^{5} (Y_i - 8)^2 = 68$$

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Sandwich matrix

$$V_n(O_i; \hat{\theta}) = B_n(O_i; \hat{\theta})^{-1} F_n(O_i; \hat{\theta}) \left( B_n(O_i; \hat{\theta})^{-1} \right)^T$$
$$V_n(O_i; \hat{\theta}) = 1^{-1} \times 68 \times 1^{-1} = 68$$

Scale by n for finite-sample variance estimate

$$n^{-1}V_n(O_i; \hat{\theta}) = 68/5 = 13.6$$

# Computational M-estimation

# Implementation of M-estimators

Solving 'by-hand' has issues

- More than one parameter
- May introduce math errors

However, can all be done by the computer

#### Procedure

- Root-finding procedure for  $\hat{\theta}$
- Numerically approximate derivatives in  $B_n(O_i; \hat{\theta})$
- Matrix algebra for sandwich

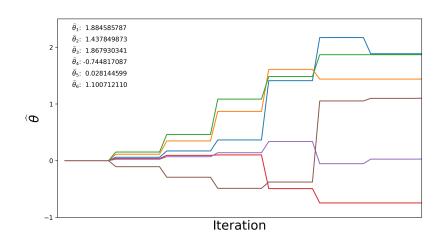
## Software<sup>7</sup>



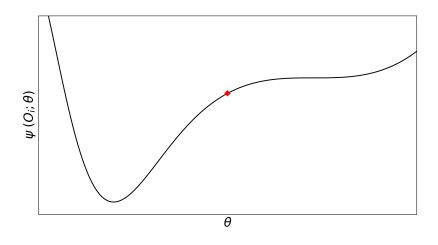
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 $<sup>^7 {\</sup>tt delicatessen:}$  Zivich et al. arXiv:2203.11300, geex: Saul & Hudgens (2020) J Stat Soft

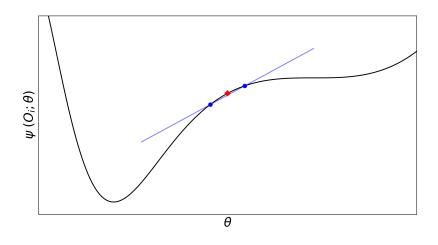
# Root-finding



# Numerical approximation of derivative



# Numerical approximation of derivative



# Application of M-estimators

### Outline

#### Robust mean

#### Regression

- Simple
- Robust

#### Causal estimation methods

- Inverse probability weighting
- G-computation

### Fusion designs

• Bridged treatment comparisons

# Robust Mean

### Problem with the mean

#### Sensitivity to outliers

- For  $\{1, 5, 3, 7, 24\}$
- ullet Observation of 24 has large impact on  $\hat{\mu}$
- Mean  $(\hat{\mu} = 8)$  is larger than the other 4 observations

#### Robust mean<sup>8</sup>

$$\sum_{i=1}^{n} f_k(Y_i - \bar{\mu}) = 0$$

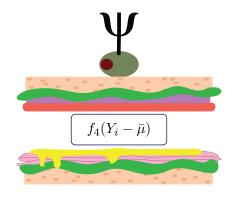
$$f_k(x) = \begin{cases} x, & \text{if } -k < x < k \\ k, & \text{if } x \ge k \\ -k, & \text{if } x \le -k \end{cases}$$

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<sup>&</sup>lt;sup>8</sup>Mean and median are special cases where  $k \to \infty$  and  $k \to 0$ , respectively

### Robust Mean

With k=4



$$\bar{\mu}=5$$
 and  $\bar{Var}(\bar{\mu})=3.3$ 

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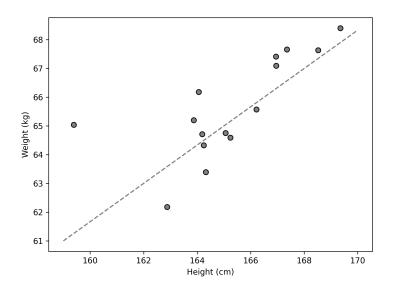
# Regression

#### **Notation**

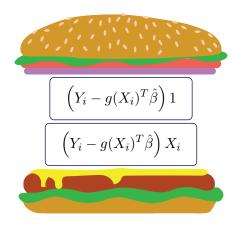
 $Y_i$ : independent variable  $X_i$ : dependent variable

$$g(X_i) = (1, X_i)$$
  
$$\beta = (\beta_0, \beta_1)$$

# Example



# Simple Linear Regression

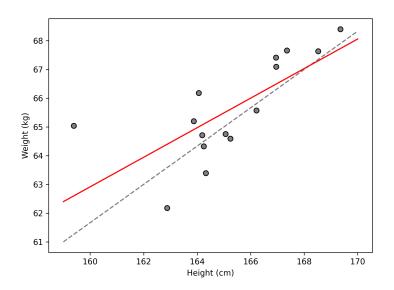


Notice: the estimating function is the score equation

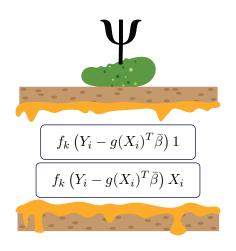
• Easy to develop as M-estimators

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# Simple Linear Regression



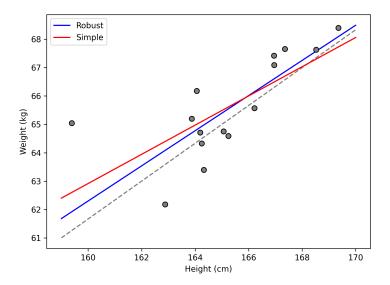
# Robust Linear Regression



Outliers can only impact up to k

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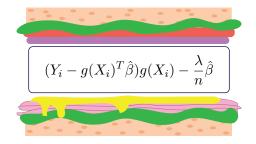
## Robust Linear Regression



# Other regression models

### Penalized regression<sup>9</sup>

ullet Ridge or  $L_2$  penalty

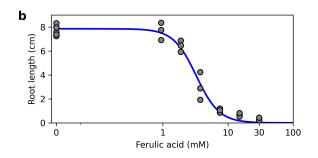


<sup>&</sup>lt;sup>9</sup>Fu WJ. (2003) *Biometrics*, 59, 126-132

# Other regression models

Dose-response regression<sup>10</sup>

• 3-parameter log-logistic models<sup>11</sup>



<sup>&</sup>lt;sup>10</sup>An H et al. (2019) *R Journal*, 11(2), 171.

<sup>&</sup>lt;sup>11</sup>Example provided in Zivich et al. arXiv:2203.11300

### Causal Effect Estimation

### **Notation**

 $Y_i$ : outcome of interest

 $A_i$ : action of interest

 $Y_i^a$ : potential outcome under action a

 $W_i$ : vector of covariates

$$g(W_i) = (1, W_i)$$
  
 $g(A_i, W_i) = (1, A_i, W_i)$ 

#### Aside: Identification vs Estimation

Following all relies on identification assumptions: causal consistency, exchangeability, positivity<sup>12</sup>

- Identification: writing interest parameter in terms of observable data
- Estimation: how the parameter in terms of observable data is estimated

<sup>&</sup>lt;sup>12</sup>Identification should always precede estimation (see Maclaren OJ & Nicholson R (2019) *arXiv:1904.02826*, Aronow PM et al. (2021) *arXiv:2108.11342* for why)

#### Aside: Nuisance Parameters

Causal inference (and related) problems can be set up as

$$\theta = (\mu, \eta)$$

 $\mu$  is the *interest* parameter  $\eta$  is the *nuisance* parameter

- To estimate  $\mu$ , need to estimate  $\eta$
- But  $\eta$  is not of any immediate interest
- Example: causal mean and propensity scores

### Motivating Example

#### Example from Morris et al. $(2022)^{13}$

- Comparison of covariate adjustment methods
  - Gain power in randomized trials
  - Account for systematic error in observational studies
- Data from the GetTested trial<sup>14</sup>
  - Efficacy of e-STI testing on STI testing uptake
  - ullet  $W_i$ : gender, age, number of sexual partners, sexual orientation, ethnicity
  - Will ignore missing data here<sup>15</sup>

<sup>&</sup>lt;sup>13</sup>Morris TP et al. (2022) *Trials* 23(1), 1-17.

<sup>&</sup>lt;sup>14</sup>Wilson E et al. (2017) *PLOS Medicine* 14(12), e1002479

<sup>&</sup>lt;sup>15</sup>Don't do this. Will be a later slide on extending the M-estimators

### Inverse Probability Weighting

The IPW estimator is

$$\frac{1}{n} \sum_{i=1}^{n} \frac{Y_i A_i}{\Pr(A=1|W_i; \hat{\alpha})} - \frac{1}{n} \sum_{i=1}^{n} \frac{Y_i (1-A_i)}{\Pr(A=0|W_i; \hat{\alpha})}$$

Estimate  $\hat{\alpha}$  using a logistic model,  $\eta = \alpha$ 

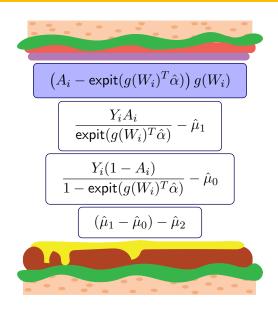
Estimating the variance for the RD

- Bootstrap
  - Computationally expensive
  - The "GEE trick"
    - ullet Treats  $\hat{lpha}$  as known
    - Conservative estimate of the variance<sup>16</sup>
  - Sandwich

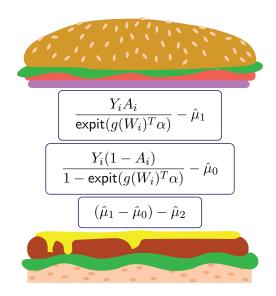
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<sup>&</sup>lt;sup>16</sup>Only true for some parameters, see Reifeis & Hudgens (2022) *Am J Epidemiol* for an exception

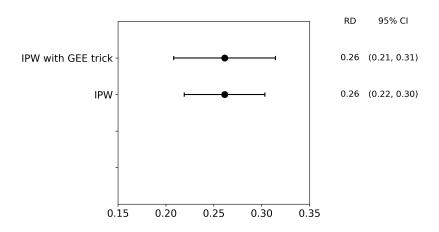
## Inverse Probability Weighting



### Inverse Probability Weighting



#### Results



### **G**-computation

G-computation<sup>17</sup>

$$\frac{1}{n} \sum_{i=1}^{n} \left( E[Y_i | A_i = 1, W_i; \hat{\beta}] - E[Y_i | A_i = 0, W_i; \hat{\beta}] \right)$$

Estimate  $\hat{\beta}$  using a logistic model for binary  $Y_i$ ,  $\eta=\beta$ 

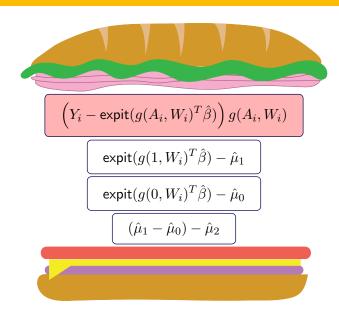
Estimating the variance for the RD

- Bootstrap
- Sandwich

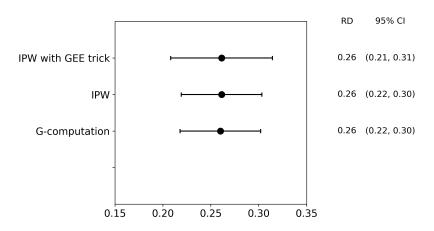
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<sup>&</sup>lt;sup>17</sup>See Snowden et al. (2011) Am J Epidemiol for details on this 'trick'

### **G**-computation



#### Results



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## Missing Data

Do not ignore

- If MCAR, may lose efficiency
- If MAR, may be biased

M-estimation makes extending the estimators simple

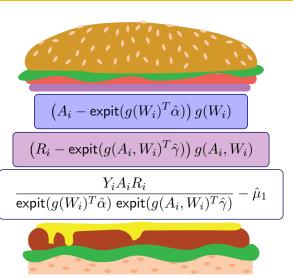
$$R_i$$
: observed  $Y_i$  ( $R_i = 1$ ) or missing  $Y_i$  ( $R_i = 0$ )

$$\frac{1}{n} \sum_{i=1}^{n} \frac{Y_i R_i I(A_i = a)}{\Pr(A_i = a | W_i; \hat{\alpha}) \Pr(R_i = 1 | A_i, W_i; \hat{\gamma})}$$

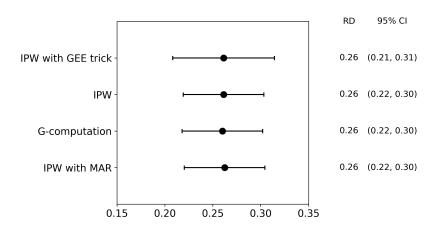
$$\eta = (\alpha, \gamma)$$

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### Inverse Probability Weighting with Missing Y



#### Results



# Fusion Designs

### What is a fusion design?

Combine data across sources in a principled way to address a question none of the constituent data sets could address as well alone 18

#### Examples

- Transporting the average causal effect
- Measurement error corrections
- Two-stage studies
- Bridged treatment comparisons

<sup>&</sup>lt;sup>18</sup>See Cole et al. (2022) Am J Epidemiol for examples

#### **Notation**

```
T_i: time of event C_i: time of censoring T_i^* = \min(T_i, C_i) \Delta_i = I(T_i = T_i^*) F(t): risk at time t
```

 $A_i$ : action of interest,  $\{1, 2, 3\}$ 

 $W_i$ : vector of covariates

#### Bridged treatment comparisons<sup>19</sup>

Parameter of Interest 
$$(\Pr(Y^3|S=1) - \Pr(Y^2|S=1)) + (\Pr(Y^2|S=1) - \Pr(Y^1|S=1))$$
 Bridge

- Target population  $(S_i = 1)$ : 3 vs 2
- Secondary population  $(S_i = 0)$ : 2 vs 1

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<sup>&</sup>lt;sup>19</sup>See Breskin et al. (2021) *Stats in Med* and Zivich et al. (2022) *arXiv:2206.04445* for details on identification

### Motivating Example

What is the one-year risk difference function comparing triple versus mono antiretroviral therapy (ART) on a composite outcome for the ACTG 320 trial?

- Outcome: AIDS, death, or a large decline in CD4 (>50%)
- ACTG 320
  - ullet Randomized to triple ART (a=3) versus dual ART (a=2)
- ACTG 175
  - ullet Randomized to dual ART (a=2) versus mono ART (a=1)

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#### Estimator

$$\hat{\mu}_t = \left(\hat{F}_{320}^3(t) - \hat{F}_{320}^2(t)\right) + \left(\hat{F}_{175}^2(t) - \hat{F}_{175}^1(t)\right)$$

#### Tasks

- Incorporate treatment assignment
- Account for informative loss to follow-up
- Transport ACTG 175 results to ACTG 320 population<sup>20</sup>

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<sup>&</sup>lt;sup>20</sup>Westreich et al. (2017) Am J Epidemiol, 186(8), 1010-1014

Estimator for ACTG 320 pieces:

$$\hat{F}_{320}^{a}(t) = n_{320}^{-1} \sum_{i=1}^{n} \frac{I(A_i = a)I(S_i = 1)I(T_i^* \le t)\Delta_i}{\pi_A(S_i; \hat{\eta})\pi_C(W_i, A_i, S_i; \hat{\eta})}$$

where  $a \in \{2, 3\}$ ,

$$n_{320} = \sum_{i=1}^{n} I(S_i = 1)$$

$$\pi_A(S_i) = \Pr(A_i = a | S_i; \hat{\eta})$$

$$\pi_C(W_i, A_i, S_i; \hat{\eta}) = \Pr(C_i > t | W_i, A_i, S_i; \hat{\eta})$$

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Estimator for ACTG 175 pieces:

$$\hat{F}_{175}^{a}(t) = \hat{n}_{175}^{-1} \sum_{i=1}^{n} \frac{I(A_i = a)I(S_i = 1)I(T_i^* \le t)\Delta_i}{\pi_A(S_i; \hat{\eta})\pi_C(W_i, A_i, S_i; \hat{\eta})} \times \frac{1 - \pi_S(W_i; \hat{\eta})}{\pi_S(W_i; \hat{\eta})}$$

where  $a \in \{1, 2\}$ 

$$\hat{n}_{175} = \sum_{i=1}^{n} I(S_i = 0) \frac{1 - \pi_S(W_i; \hat{\eta})}{\pi_S(W_i; \hat{\eta})}$$

$$\pi_S(V_i; \hat{\eta}) = \Pr(S_i = 1 | W_i; \hat{\eta})$$

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## Bridged Treatment Comparisons: Diagnostic

Notice that<sup>21</sup>

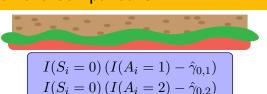
$$E\left[\hat{F}_{320}^{2}(t) - \hat{F}_{175}^{2}(t)\right] = 0$$

Offers a testable implication

- Compare difference in data
- ullet Difference from zero indicates  $\geq 1$  assumption is violated

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<sup>&</sup>lt;sup>21</sup>Zivich et al. (2022) *arXiv:2206.04445* proposed this diagnostic and a permutation test for the whole risk difference curve



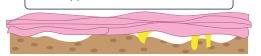
$$I(S_i = 1) (I(A_i = 2) - \hat{\gamma}_{1,2})$$

$$I(S_i = 1) (I(A_i = 3) - \hat{\gamma}_{1,3})$$

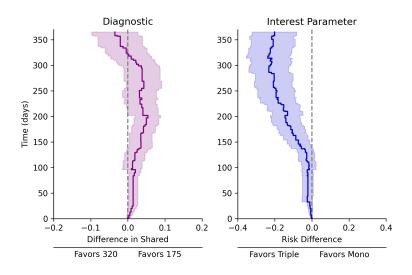
$$\left(I(S_i = 1) - \mathsf{expit}(W_i^T \hat{\delta})\right) W_i$$

$$\psi_{AFT}(O_i; \hat{\lambda}, \hat{\beta}, \hat{\alpha})$$

$$\psi_{RD(t)}(O_i; \hat{\mu}_t, \hat{\gamma}_{a,s}, \hat{\delta}, \hat{\lambda}, \hat{\beta}, \hat{\alpha})$$



# Bridged Treatment Comparisons<sup>22</sup>



<sup>&</sup>lt;sup>22</sup>Results presented using twister plots (Zivich et al. (2021) Am J Epidemiol)

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## Conclusions

### Key Advantages

#### Stacking estimating functions together

- Natural way to build an estimator
- Connects to interest versus nuisance parameters
- Sandwich variance
  - Percolates uncertainty of nuisance parameters
  - · Automation of the delta-method
  - Computationally efficient

#### Existing estimators

- Many can be expressed as M-estimators
- Score function

Flexible software to implement M-estimators

#### Limitations

#### Valid estimating functions

- $\psi(O_i; \theta)$  must not depend on i
  - Excludes models like Cox PH model
- Non-smooth estimating functions
  - Bread estimator may not be valid

#### Finite dimensional nuisance model

- Nuisance parameters assumed to be finite dimension
- Unclear how (and if) data-adaptive algorithms could be used

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### Further Reading

#### Introductory papers

- Stefanski LA & Boos DD. (2002). The calculus of M-estimation. The American Statistician, 56(1), 29-38.
- Cole SR, Edwards JK, Breskin A, et al. (2022). Illustration of Two Fusion Designs and Estimators. American Journal of Epidemiology.
- Jesus J & Chandler RE. (2011). Estimating functions and the generalized method of moments. *Interface Focus*, 1(6), 871-885.

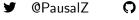
#### Software

- deli.readthedocs.io
- bsaul.github.io/geex/

#### **Thanks**

Slides & code available at: github.com/pzivich/Presentations

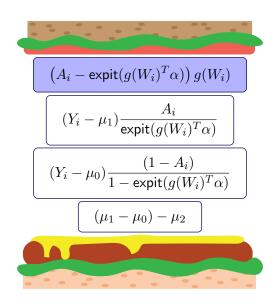






# **Appendix**

## Hajek IPW Estimator



### Augmented Inverse Probability Weighting

The AIPW estimator is

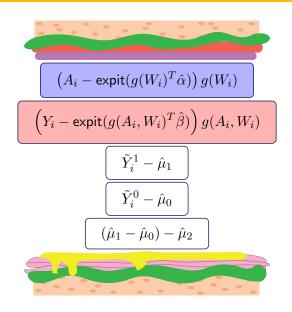
$$\frac{1}{n}\sum_{i=1}^{n}\tilde{Y}_{i}^{1}-\tilde{Y}_{i}^{0}$$

$$\tilde{Y}_{i}^{a} = \frac{Y_{i}I(A_{i} = a)}{\Pr(A_{i} = a|W_{i}; \hat{\alpha})} + \frac{E[Y_{i}|A_{i} = a, W_{i}; \hat{\beta}](...)}{\Pr(A_{i} = a|W_{i}; \hat{\alpha})}$$

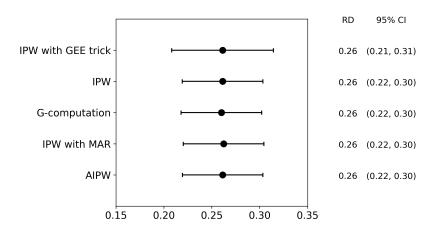
Estimating the variance for the RD

- Bootstrap
- Outer product of influence functions
- Sandwich

## Augmented Inverse Probability Weighting



#### Results



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