CA Lab3 Report

Q, Queue
Mackerels!

Contents

I Clock Implementation

I. 1 Offline Mode

On Signal lose the clock can run in offline mode and increment internal clock variable.

```
void processEventsClock(CLOCKEVENT event)
{   if (event==NOCLOCKEVENT)
        return;

    if (++secs >= 60)
    {   secs = 0;
        if (++mins >= 60)
        {   mins = 0;
            if (++hrs >= 24)
            {   hrs = 0;
                if (++day > days_in_month(month, year))
                {   day = 1;
                    if (++month > 12)
                    {   month = 1;
                        year++;
                    }
                }
                if (++weekday > 7)
                { weekday = 1;
                }
            }
        }
     }
}
```

I. 2 Changing Clock timezone

Coordinated Universal Time UTC is used to specify clock timezones.

By pressing the `PTH3` button on the Dragon12 board the clock time zone will toggle `DE` UTC `+2` summer/winter `+1` timezone and `US` UTC `-4` summer/winter `-5` timezone. Depending on current timezone of the DCF77 signal

```
#define BUTTONS_POLLING_RATE   50         // once in n * 10ms
#ifdef SIMULATOR // inlined // hardware independent boolean value
  #define poll_buttons_state() (PTH)
#else
  #define poll_buttons_state() (~PTH)
#endif

#define PH3                     0x08U
#define TOGGLE_TIME_ZONE_BUTTON  PH3
static volatile void (*toggle_time_zone)(void) = toggle_de_time_zone;
void poll_buttons(void)
{
    static char counter = BUTTONS_POLLING_RATE;
    if (counter-- != 0) return;
    counter = BUTTONS_POLLING_RATE;
    if (poll_buttons_state() & TOGGLE_TIME_ZONE_BUTTON)
    {   // function pointer changes value on each call!
        toggle_time_zone(); displayTimeClock(); displayDateDcf77();
    }
}
```

I. 3 Synchronizing with External Clock

The clock keeps track of time and date separately from the DCF77 clock signal with its own time zone.

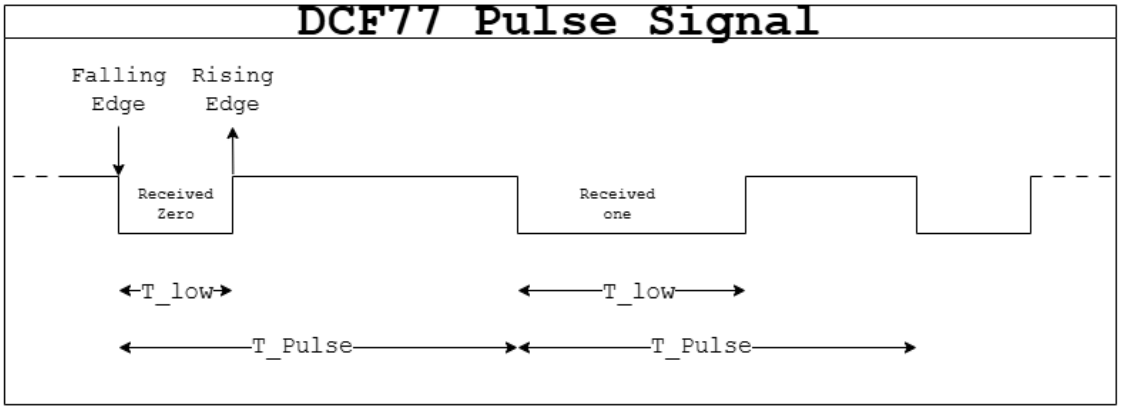
When the a valid DCF77 signal is received the `setClock` function is called overwrite the clock with the received clock values.

If the referenced external clock from the DCF77 signal changes the its timezone, which correspond to summer/winter time saving changes, all recorded timezone must follow that changes to.

Finally the timezone is adjusted back to the internal clock timezone.

```
void setClock(char hours, char minutes, char seconds, char _day, char _month, int
_year, char _weekday, char referenced_time_zone)
{
    char clock_time_zone, i;

    day   = _day;
    month = _month;
    year  = _year;

    hrs   = hours;
    mins  = minutes;
    secs  = seconds;

    weekday = _weekday;

    ticks = 0;

    if (referenced_time_zone != LAST_REFERENCED_CLOCK_TIME_ZONE)
    {
        // time zone change needs to stay relative to the reference
        // somer/winter time

        clock_time_zone += (referenced_time_zone - LAST_REFERENCED_CLOCK_TIME_ZONE);

        for (i = 0; i < KNOWN_TIME_ZONES_COUNT; i++)
            CURRENT_TIME_ZONES[i] +=
            (referenced_time_zone - LAST_REFERENCED_CLOCK_TIME_ZONE);

        LAST_REFERENCED_CLOCK_TIME_ZONE = referenced_time_zone;
        // not fully tested code!
    }

    clock_time_zone = CLOCK_TIME_ZONE;

    CLOCK_TIME_ZONE = referenced_time_zone;

    adjust_to_timezone(clock_time_zone);    // adjust back to current clock time zone
}
```

II DCF77 Signal Sampling



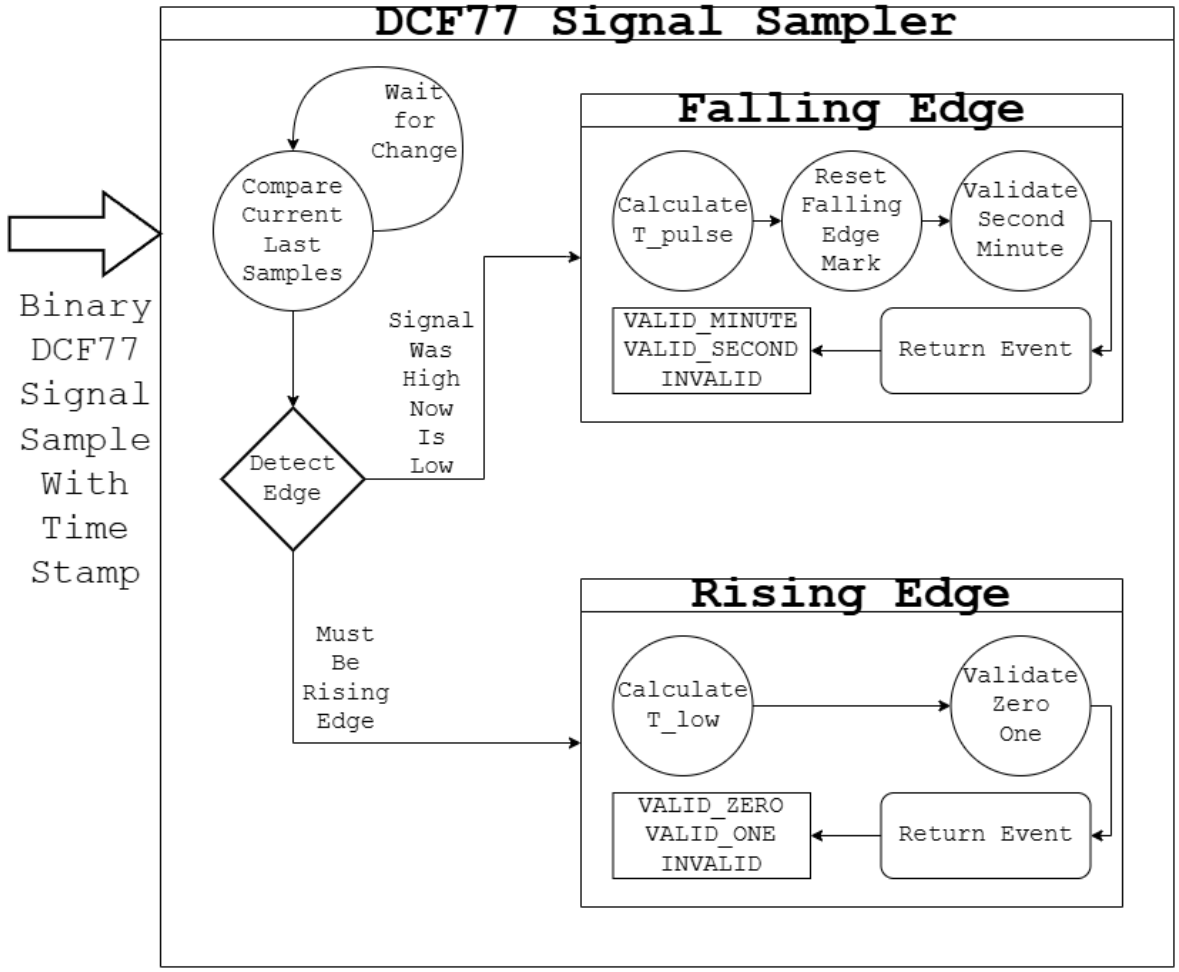


Figure 1: DCF77-Signal-Sampler

III DCF77 Signal Decoding

The signal decoding is implemented as a finite state machine using a function pointer `transition` the points to the current state of the machine.

The finite state machine has the `RESET` state defined as `waiting_for_minute_end` where if anything were to go wrong with the decoding the machine stay at that state until the `VALID_MINUTE` event comes around

```
#define RESET_FSM wait_for_minute_end

static volatile void (*transition)(DCF77EVENT event) = RESET_FSM;

void processEventsDCF77(DCF77EVENT event)
{
    switch (event)
    {
        case INVALID:
        case VALID_MINUTE:
            RESET_FSM(event);
            break;

        case VALID_ONE:
        case VALID_ZERO:
            transition(event);
            received_bit++;
            break;
    }
}
```

III. 1 Machine States

Each machine state is defined as separate function. Where the events are processed until machine transitions into next state by assigning the function pointer `transition` to the next state.

```
static void decode_minutes(DCF77EVENT event)
{
    char bit = (event == VALID_ONE) ? 1 : 0;

    if (received_bit == 28) // check parity
    {
        if (parity != bit) transition = RESET_FSM;   // invalid
        else {
            parity = 0;     // common used resource!
            transition = decode_hours;
        }
        return;
    }

    parity ^= bit;

    received_minutes += bit * TRANSMISSION_BIT_WEIGHT[received_bit - 21];
    // minutes bit weighted offset
}
```

III. 2 DCF77 Signal Decoder FSM

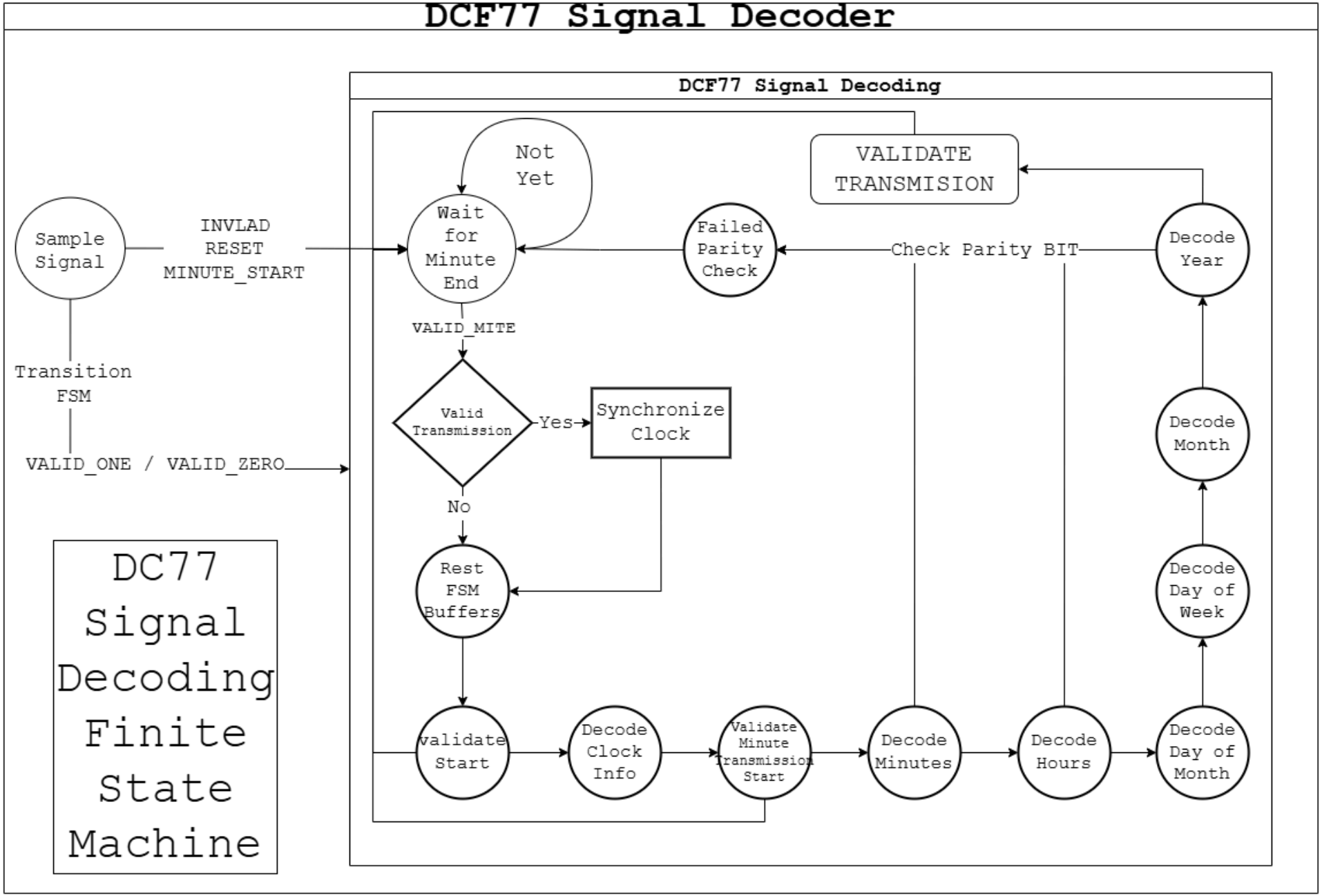


Figure 2: DCF77-Signal-Decoder-FSM