

# Optimal parallelization strategy on MiniMax search tree based on Kalah game

基於kalah之最大最小搜尋樹優化平行策略

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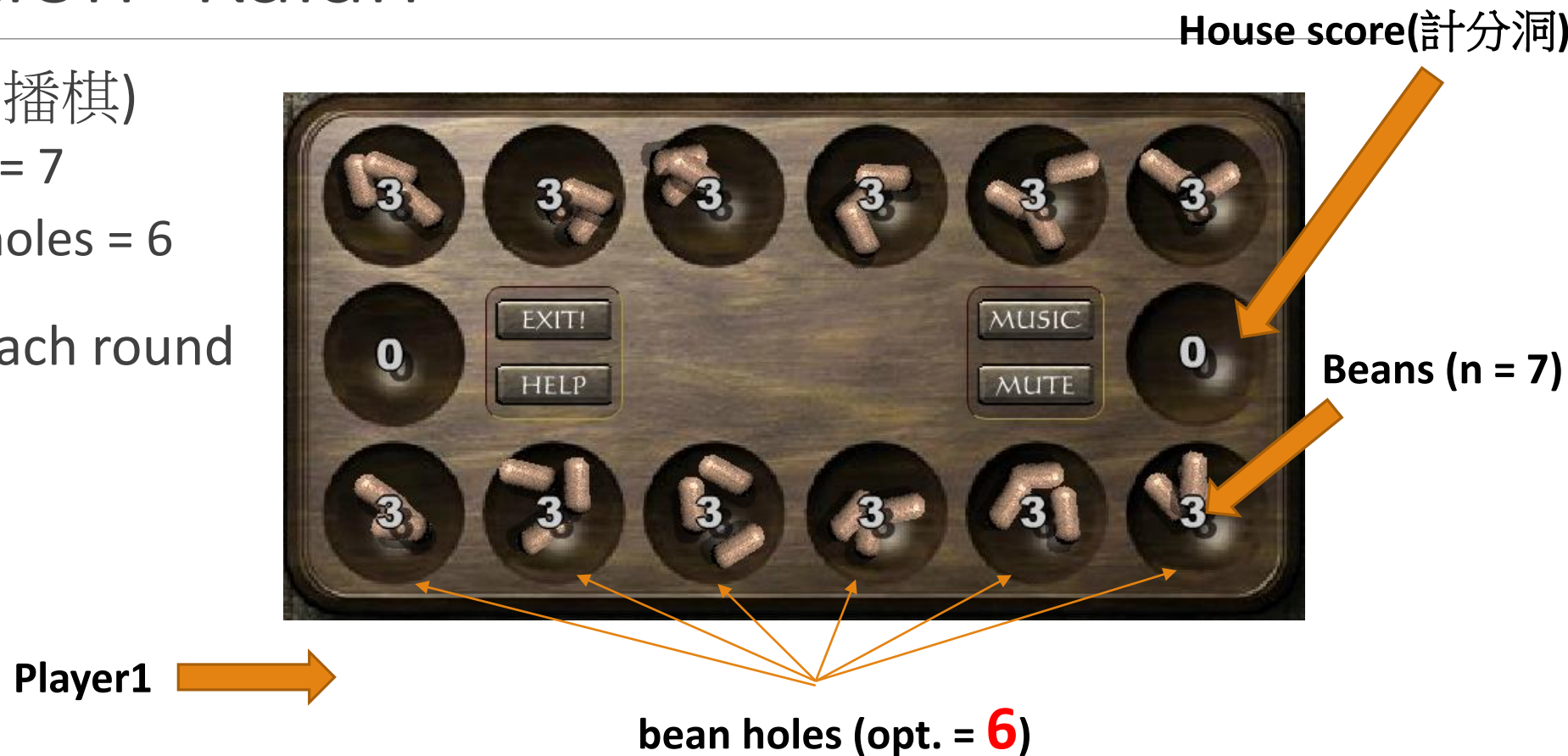
# Outline

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- Introduction- Kalah
- Minimax tree
- Pruned Minimax tree
- New Proposed Method: Advanced parallel method on game tree
- Result and Evaluation
- Conclusion

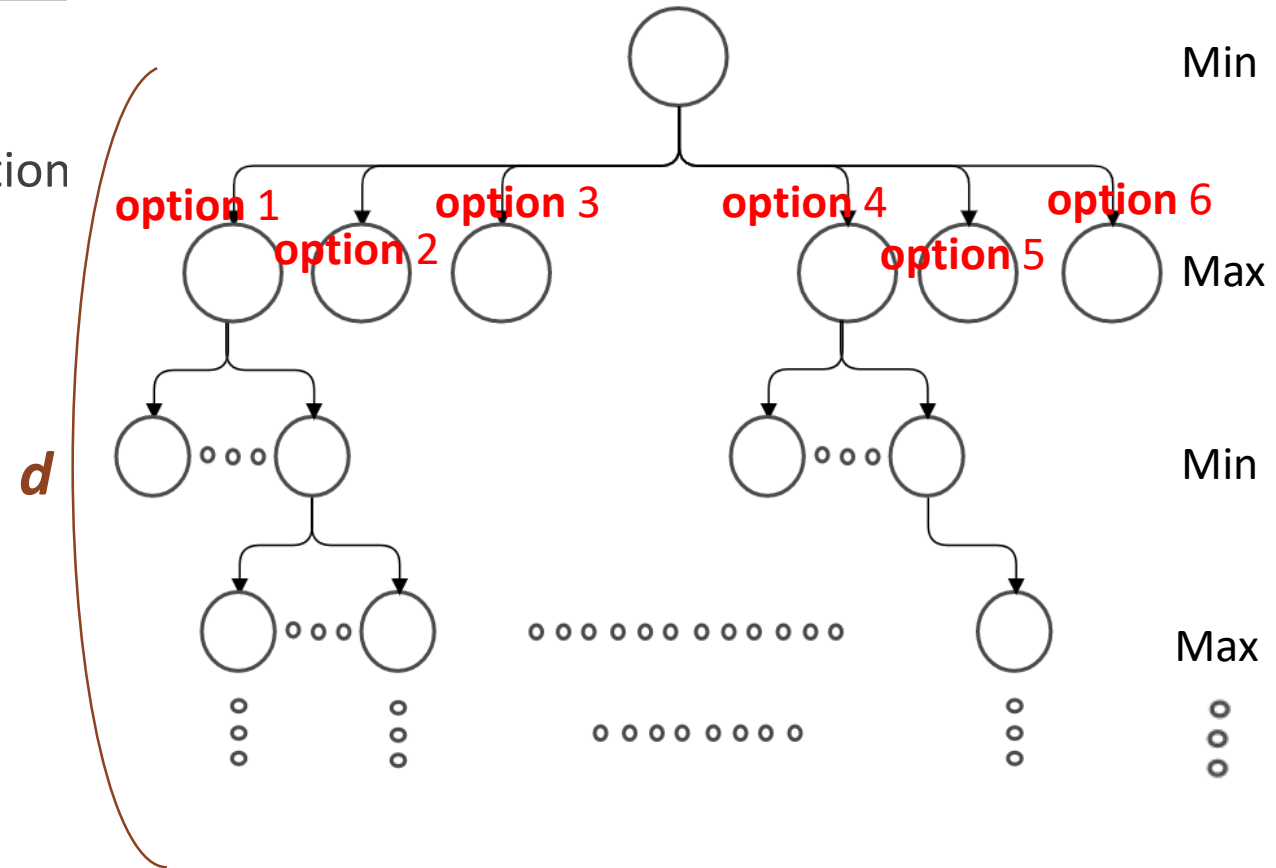
# Introduction -Kalah

- Kalah 、Kalaha(播棋)
  - Assume Beans = 7
  - Assume Bean holes = 6
- **6** options on each round



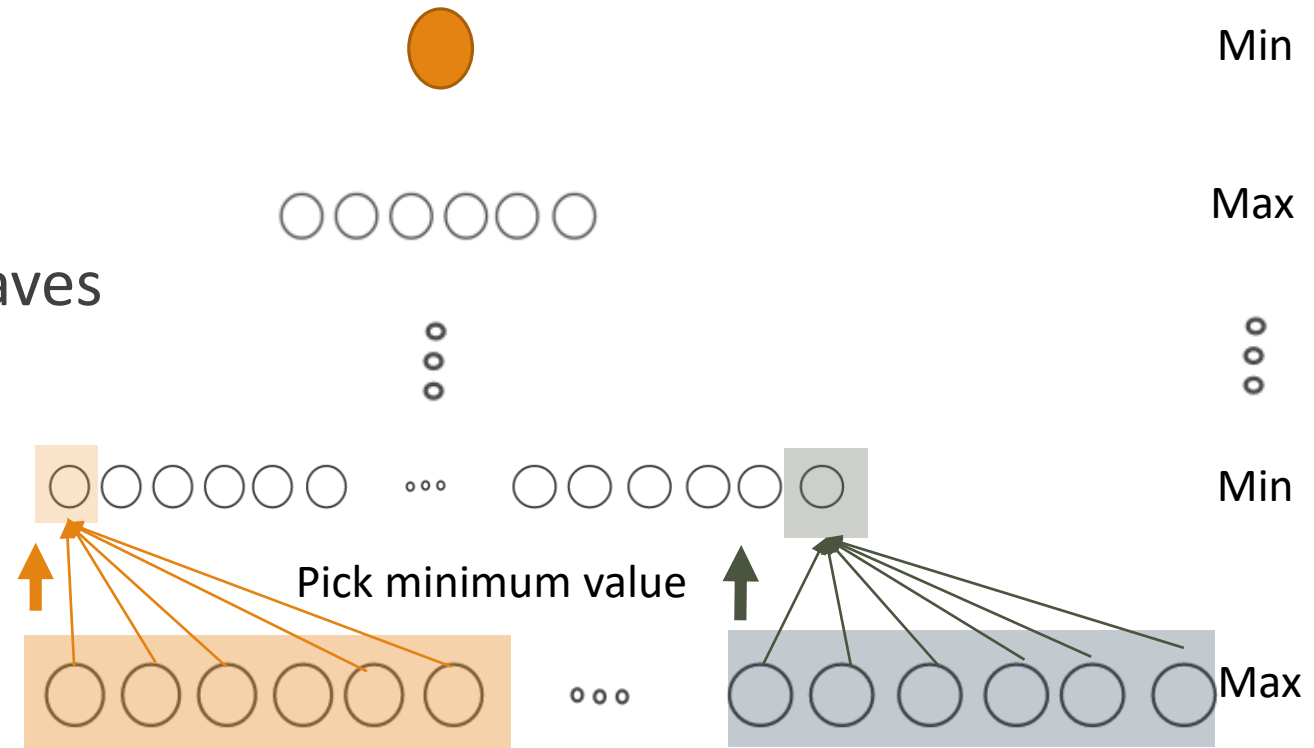
# Minimax tree

- Concept:
  - Best **option** to win opponent's best step
  - Expand further  **$d$**  steps, and predict best option
- complexity:  $O(6^d)$ 
  - Maximum game length ( **$d$** )
  - As far as we know, length can be more than **50**
- Minimax prediction generally use recursion



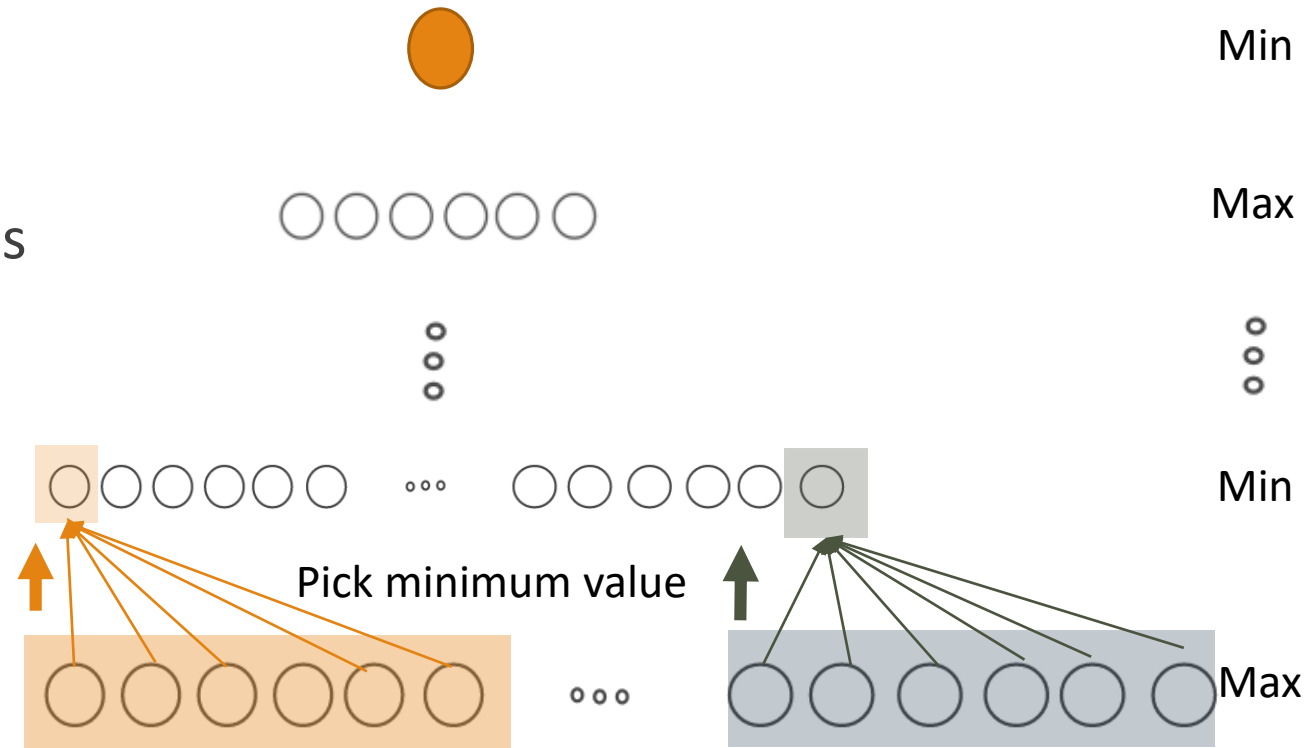
# Experiment- (1)

- Time overhead:
  - Reduction
  - Traverse
- assume  $d = 10$ , yield 362,797,056 leaves
  - Need  $6^{10} + \dots + 6^1$  comparison
  - How much parallelization can improve?



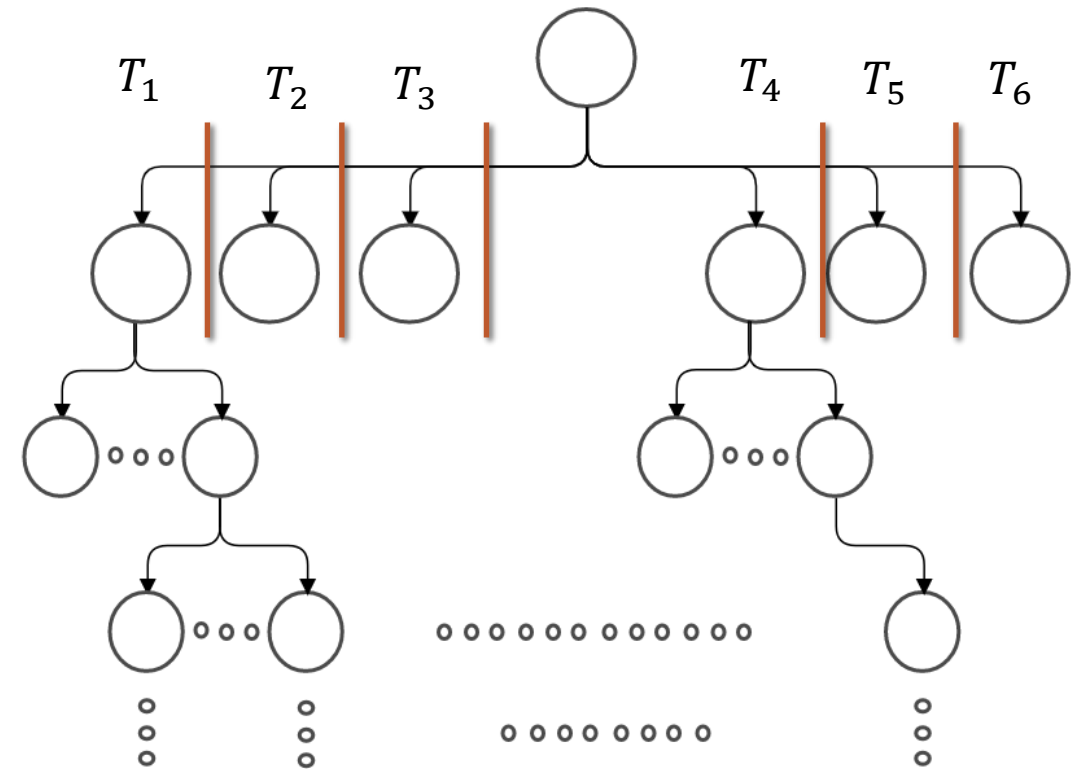
# Experiment- (1)

- Time overhead:
  - Reduction
  - Traverse
- assume  $d = 10$ , yield 362,797,056 leaves
  - Need  $6^{10} + \dots + 6^1$  comparison
- Serial Reduction
  - $Time_{reduction} < 1\%$  of Total time
  - Most of time spend on traverse

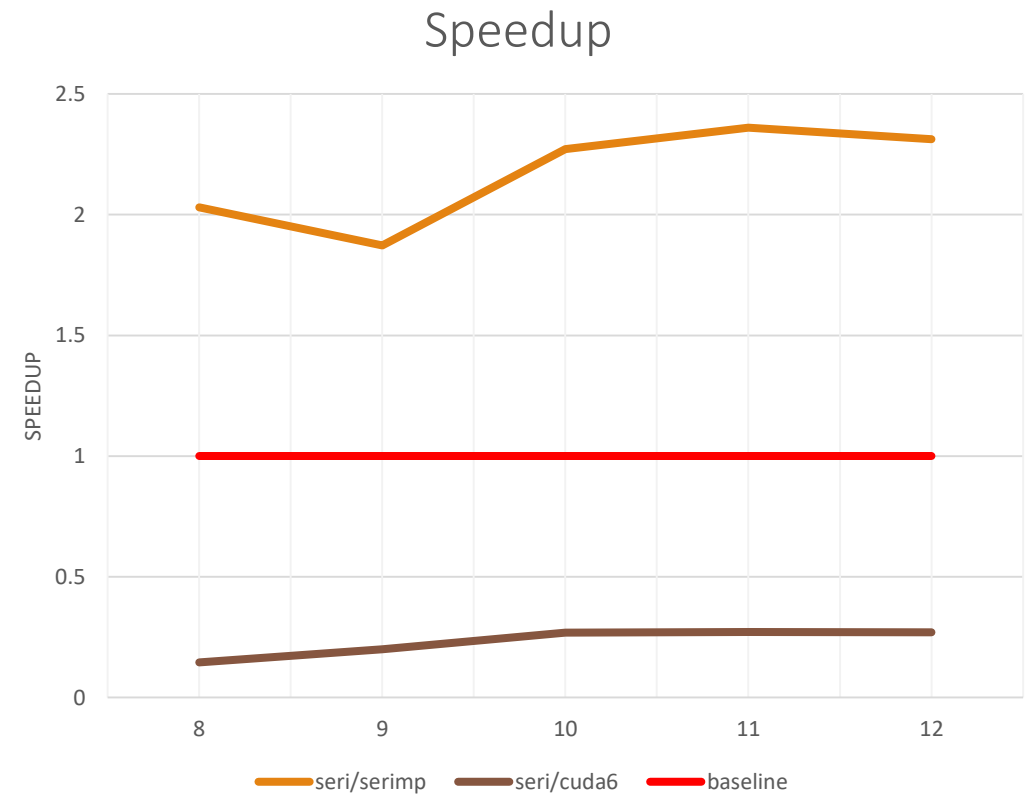
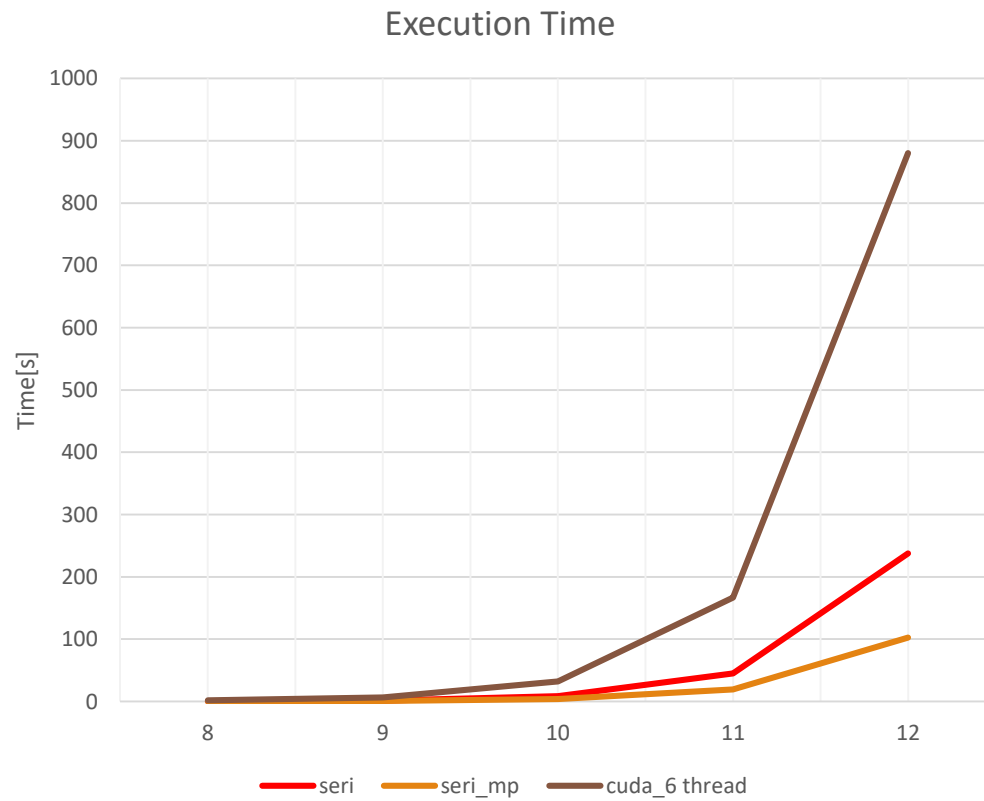


# Minimax tree - traverse parallelization

- 6 threads parallel
- CUDA, openMP respectively



# Seri & Seri\_Mp

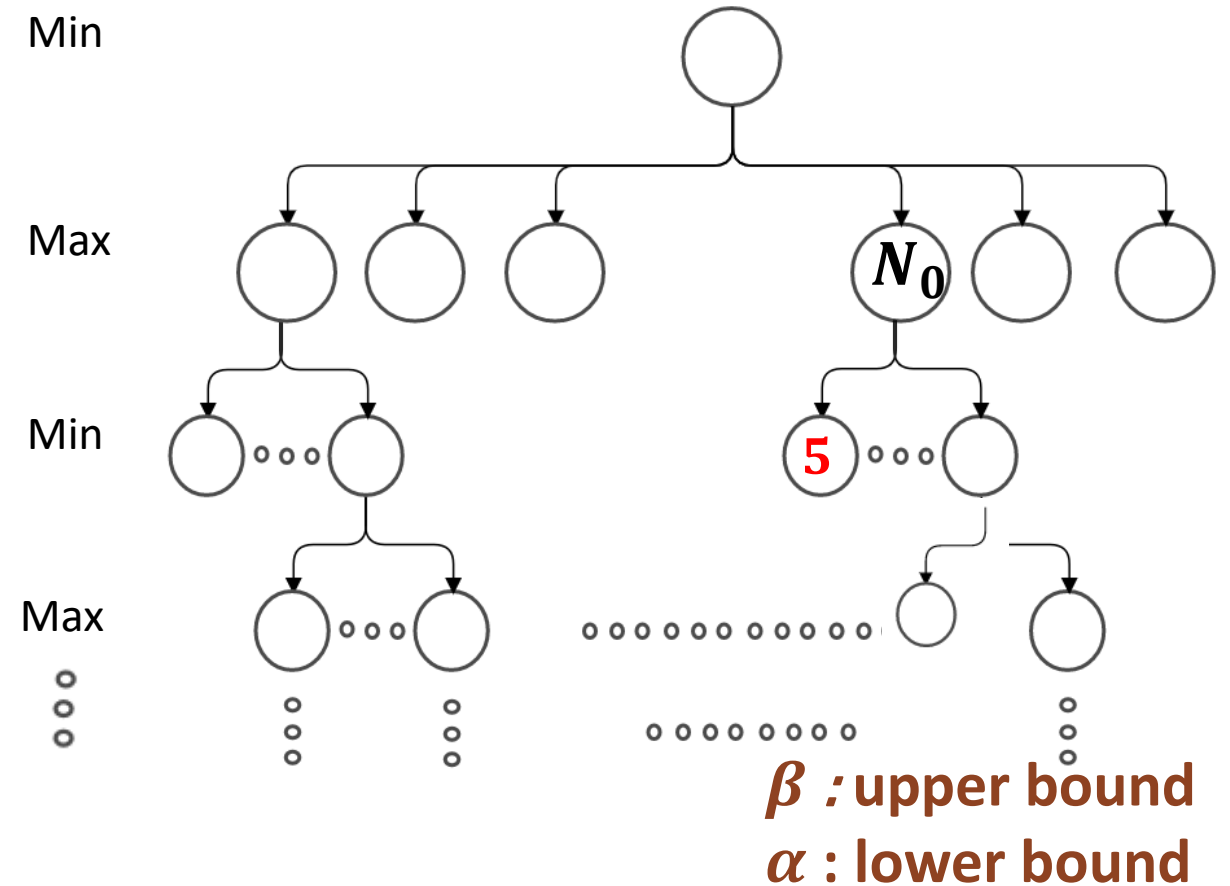




# Pruned Minimax tree

- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

Step1: got min value 5

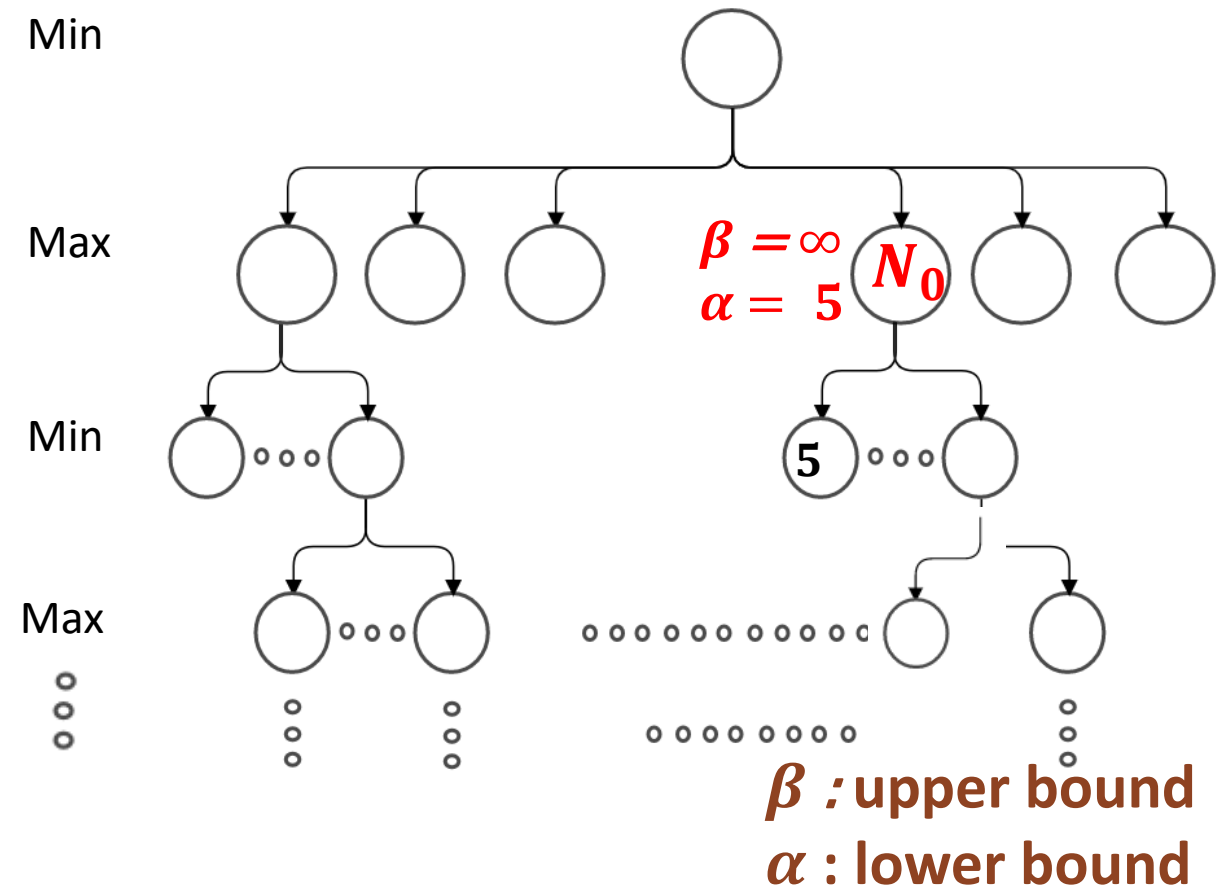


# Pruned Minimax tree

- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

Step1: got min value 5

Step2:  $N_0$  value at least bigger than 5



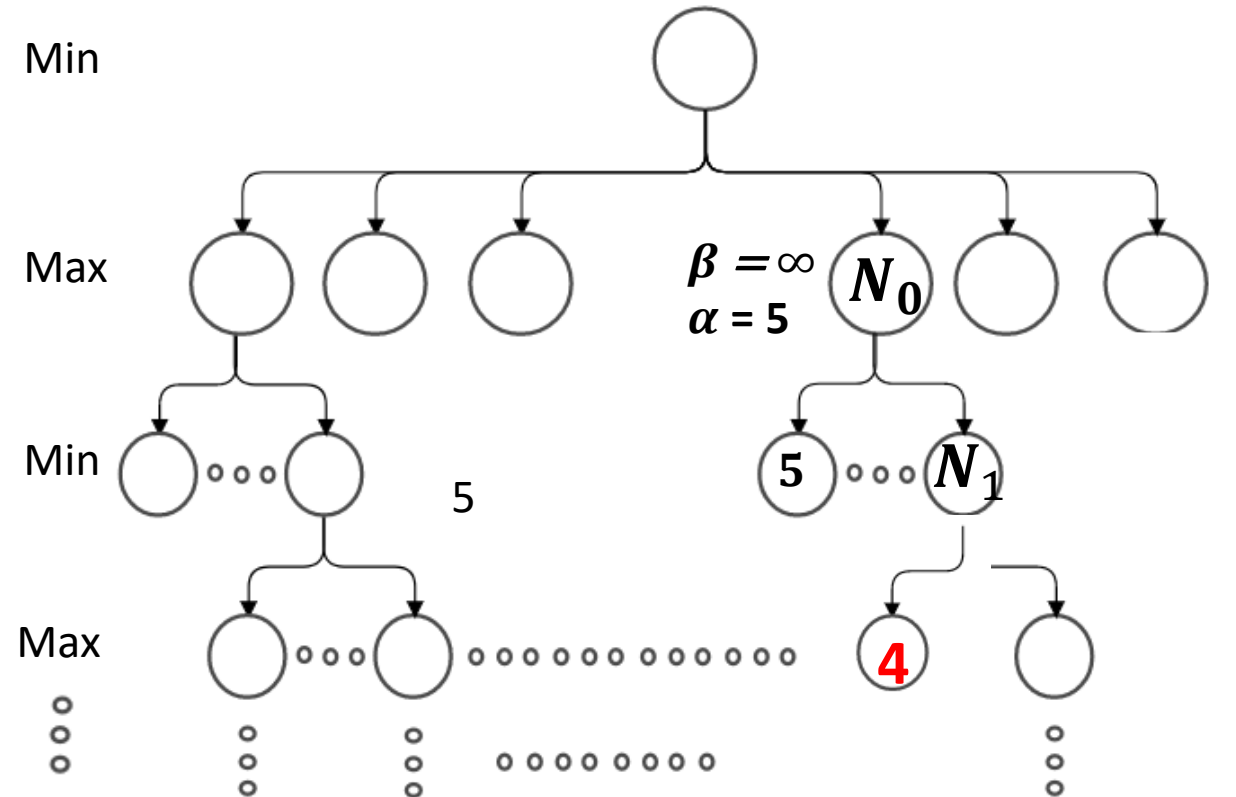
# Pruned Minimax tree

- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

Step1: got min value 5

Step2:  $N_0$  value at least bigger than 5

**Step3: Max value 4 of  $N_1$  child**



# Pruned Minimax tree

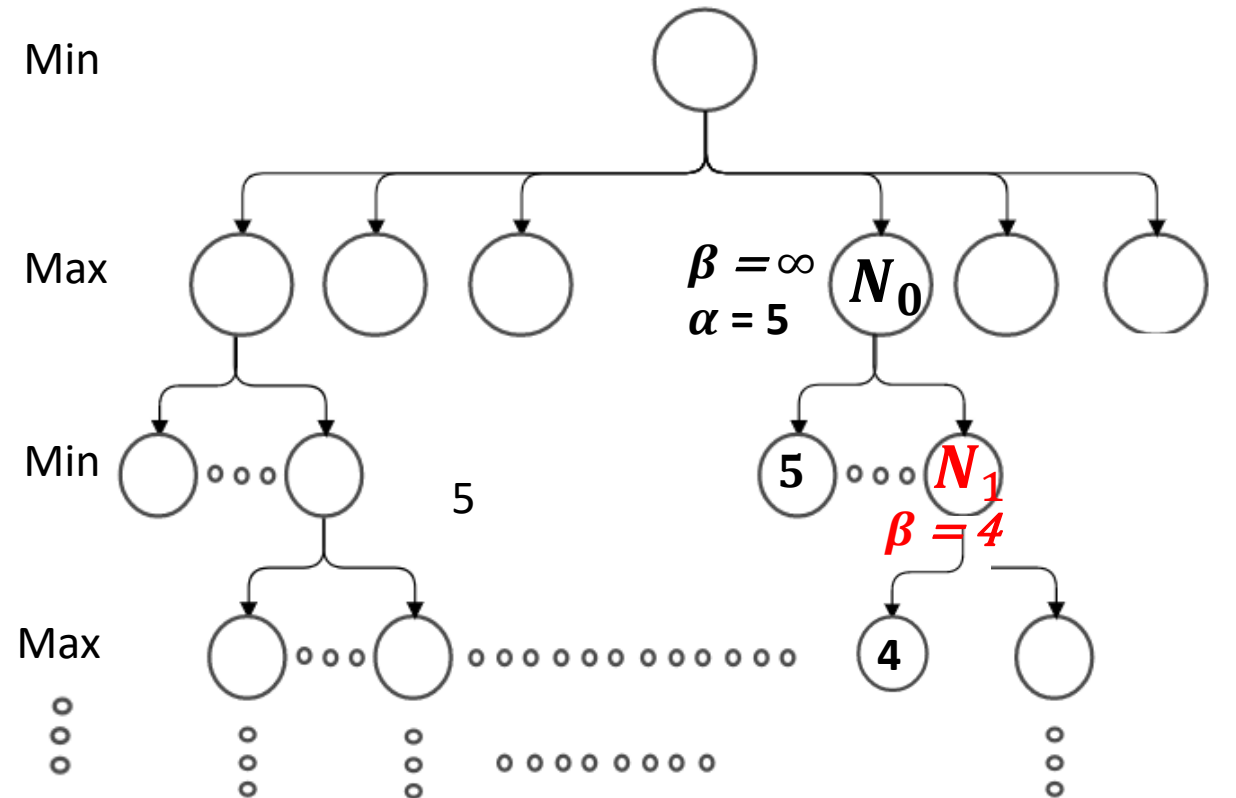
- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

Step1: got min value 5

Step2:  $N_0$  value at least bigger than 5

Step3: Max value 4 of  $N_1$  child

**Step4:  $N_1$  value at most 5**



$\beta$  : upper bound  
 $\alpha$  : lower bound

# Pruned Minimax tree

- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

Step1: got min value 5

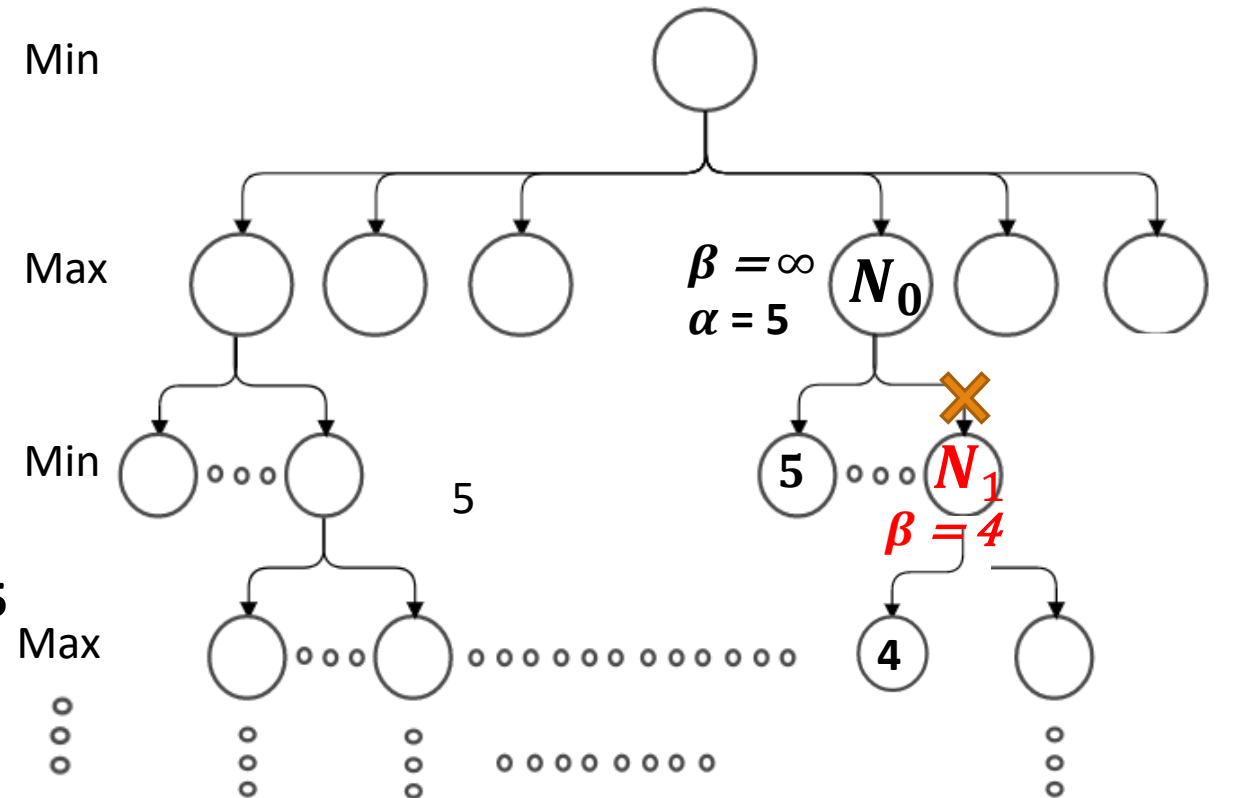
Step2:  $N_0$  value at least bigger than 5

Step3: Max value 4 of  $N_1$  child

Step4:  $N_1$  value at most 5

Step5:  $N_1$  would never find number better than 5

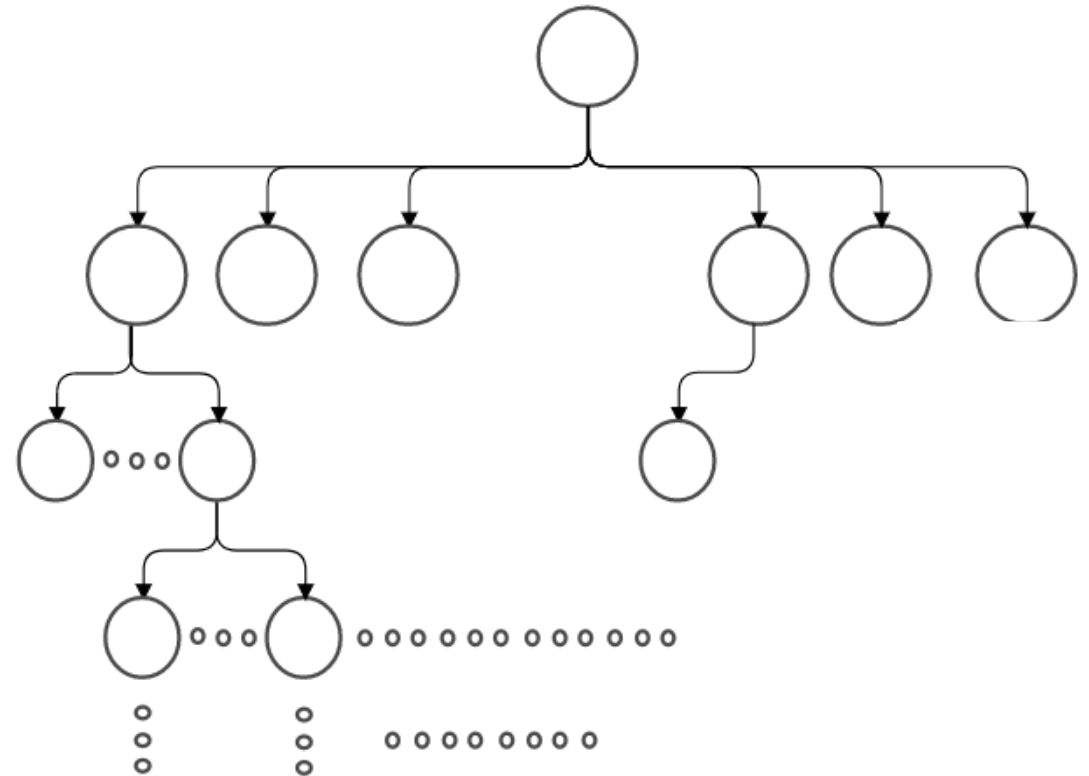
-> prune  $N_1$



# Pruned Minimax tree

- Complexity improvement:
  - $O(6^d) \rightarrow O(6^{d/2})$

**Get a *pruned tree***

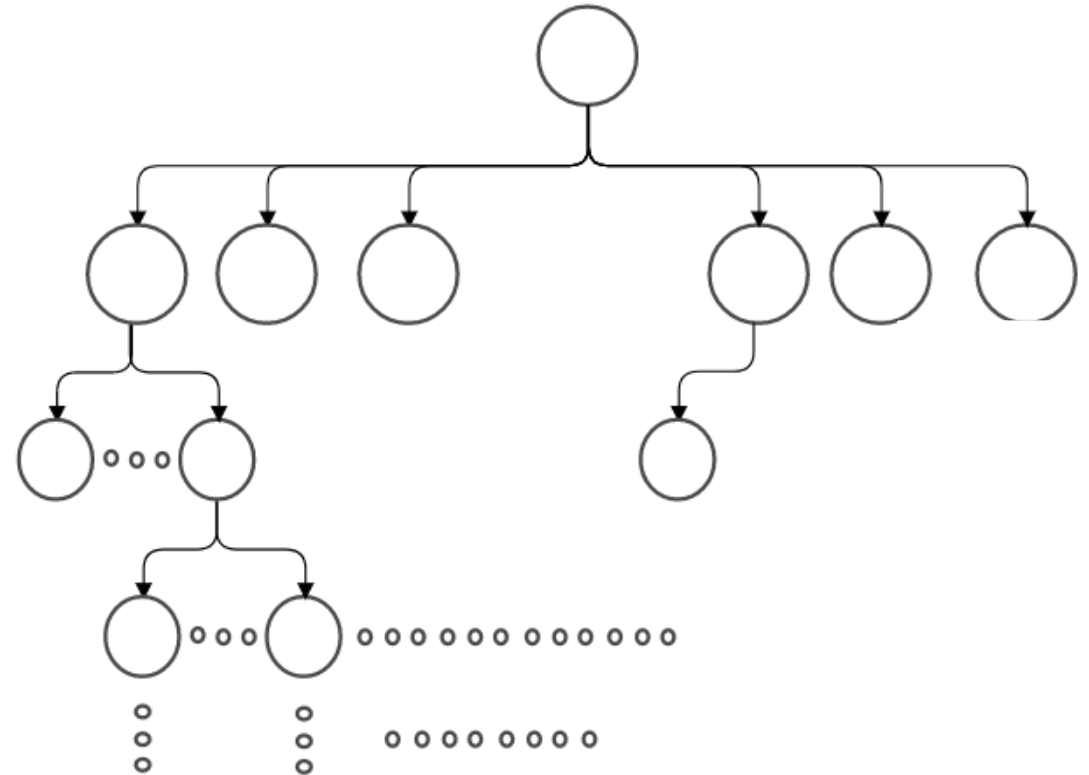


# Pruned Minimax tree

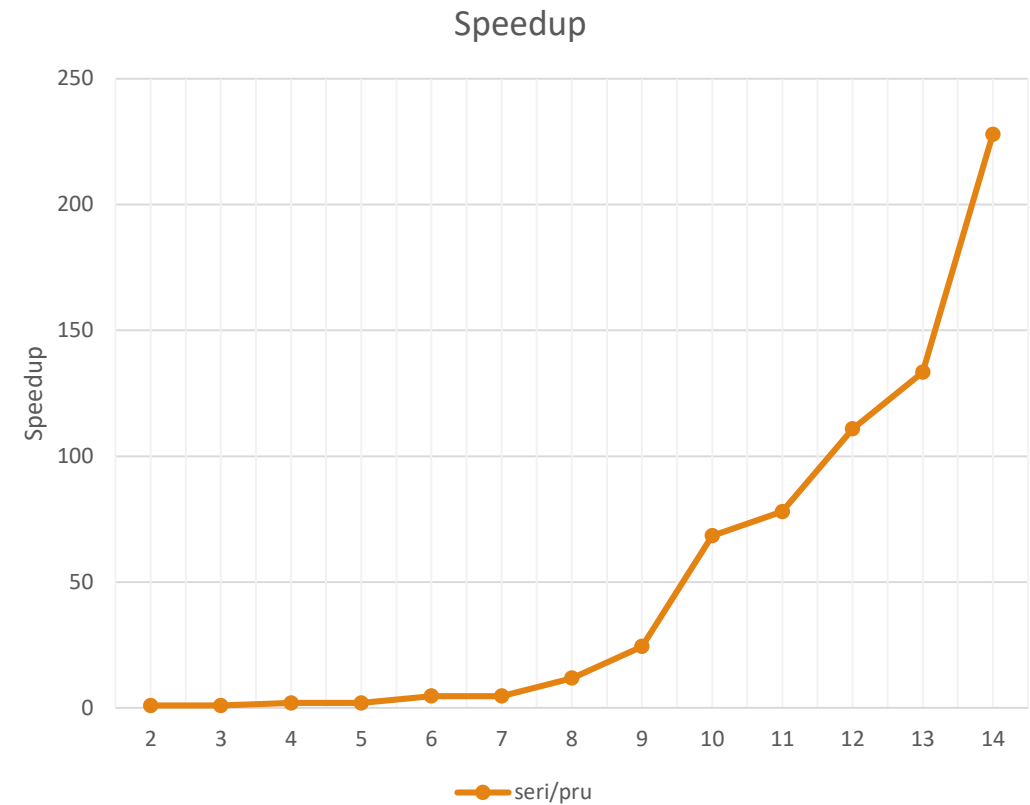
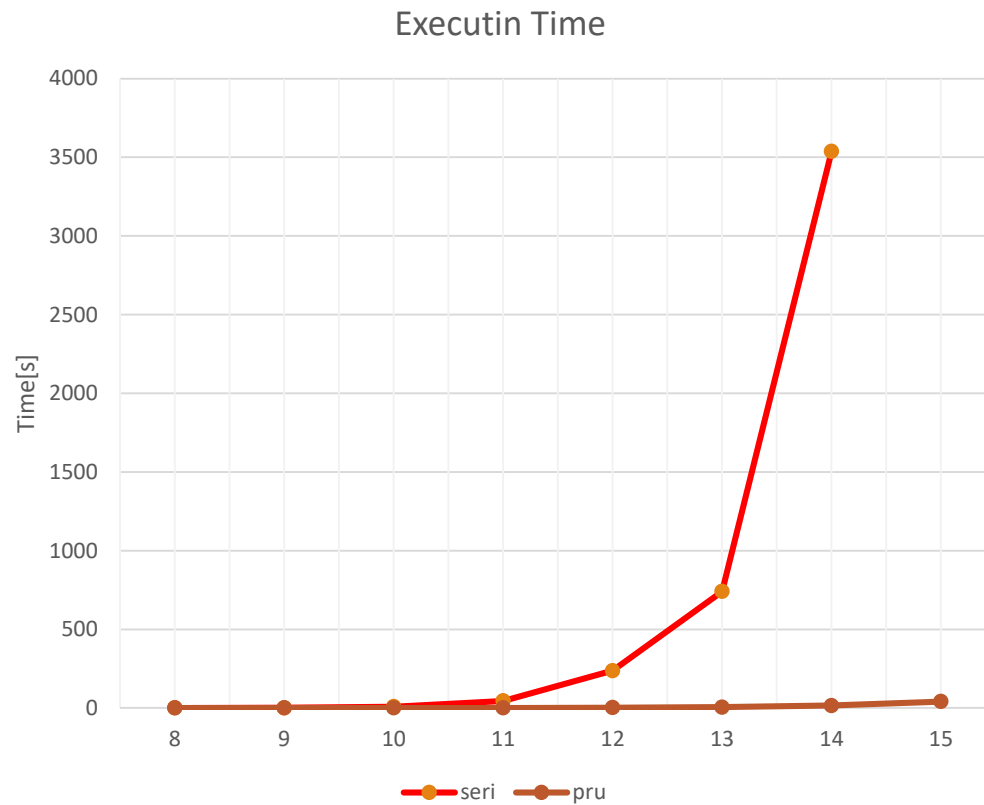
- Complexity improvement:

- $O(6^d) \rightarrow O(6^{d/2})$

Predict layer	original	pruned	save
1	6	6	0%
2	36	11	69%
3	216	42	81%
4	1,296	123	91%
5	7,776	507	93%
6	46,656	1,622	96%
7	279,936	6,348	98%
8	1,679,616	15,400	99%
9	10,077,696	79,274	99%



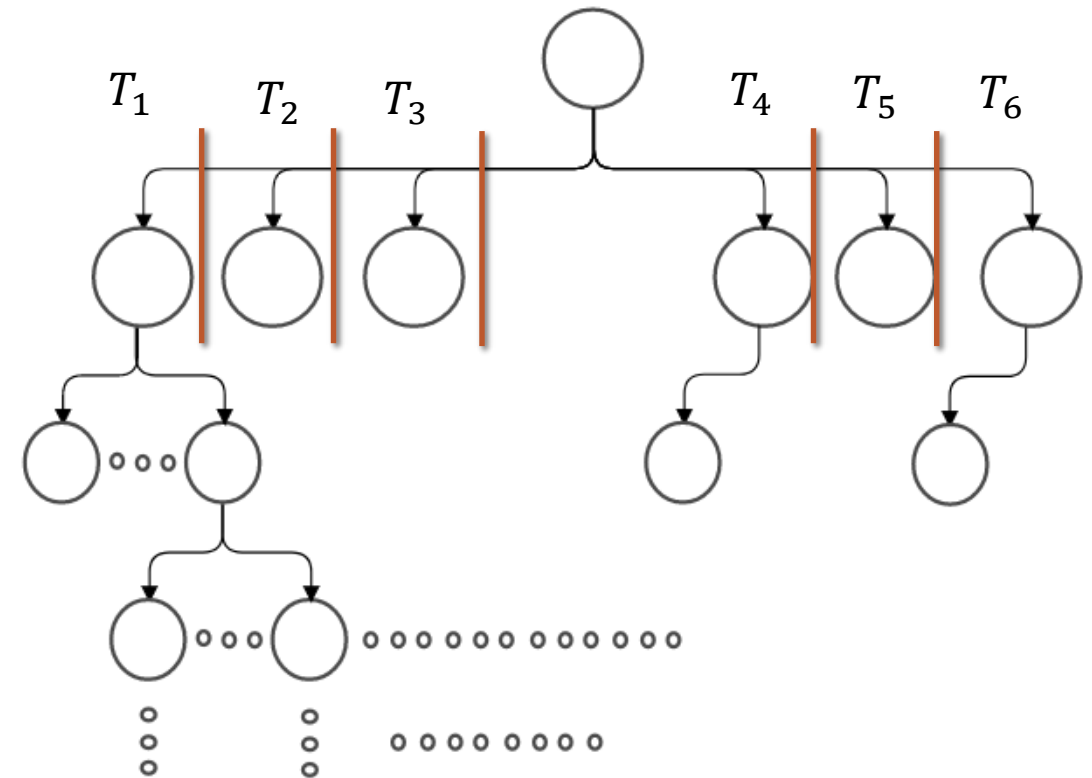
# Min-max & min-max prune



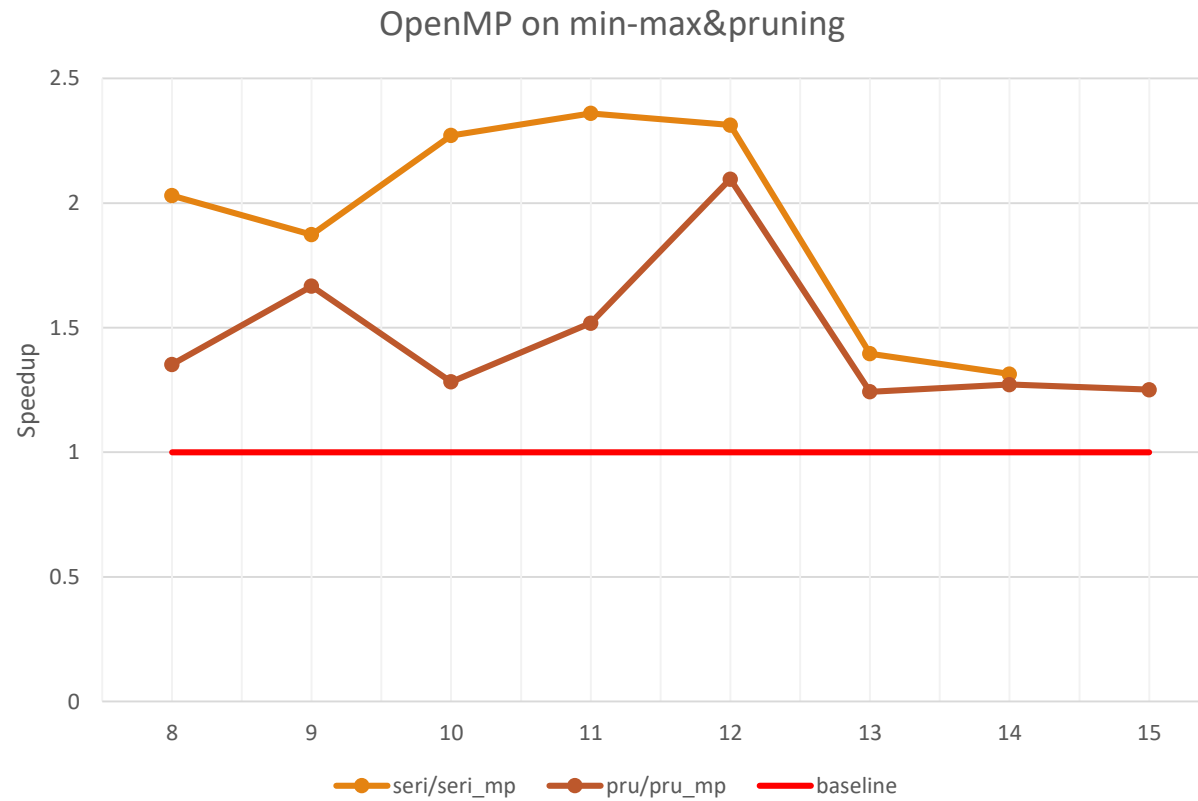


# Pruned Minimax tree – Parallelization

- Hard to parallelize recursive algorithm
  - Thread number: 6



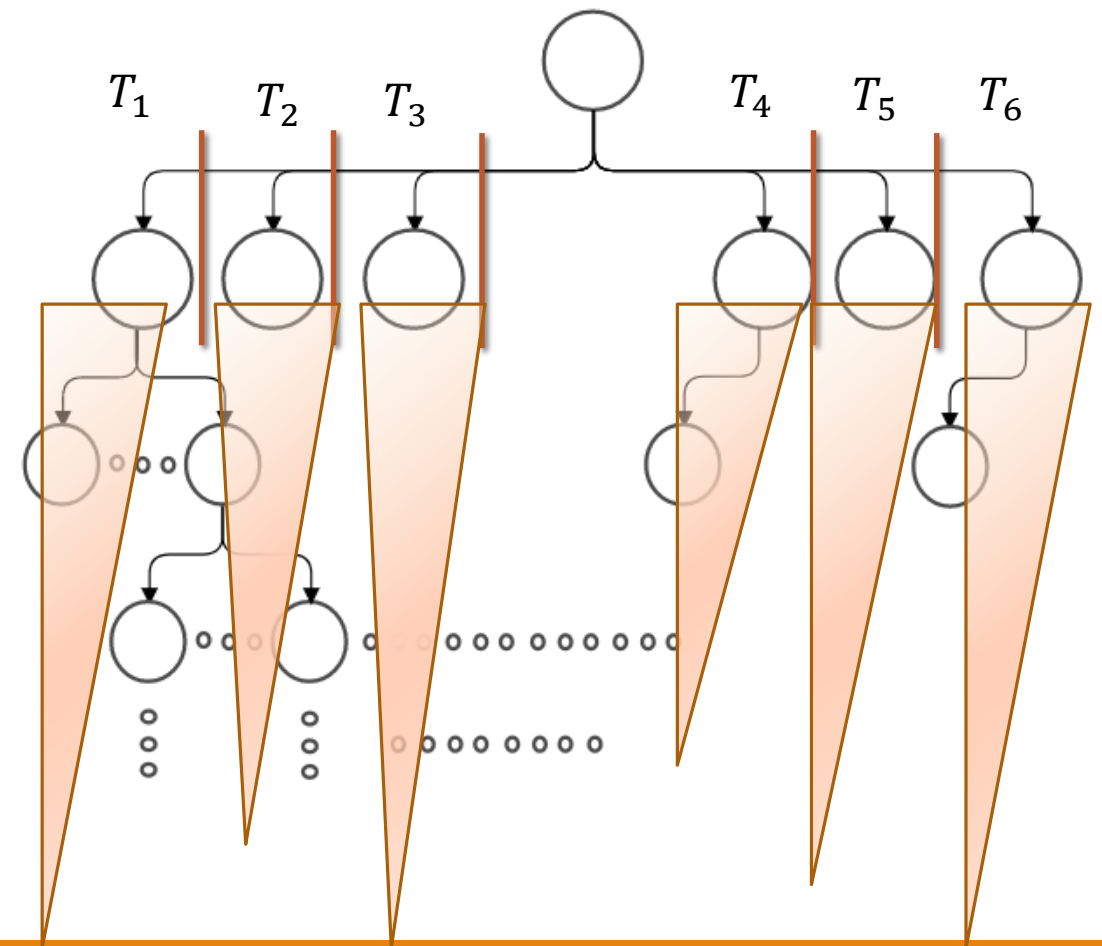
# Min-max\_mp & prune\_mp speedup



# Pruned Minimax tree – Parallelization

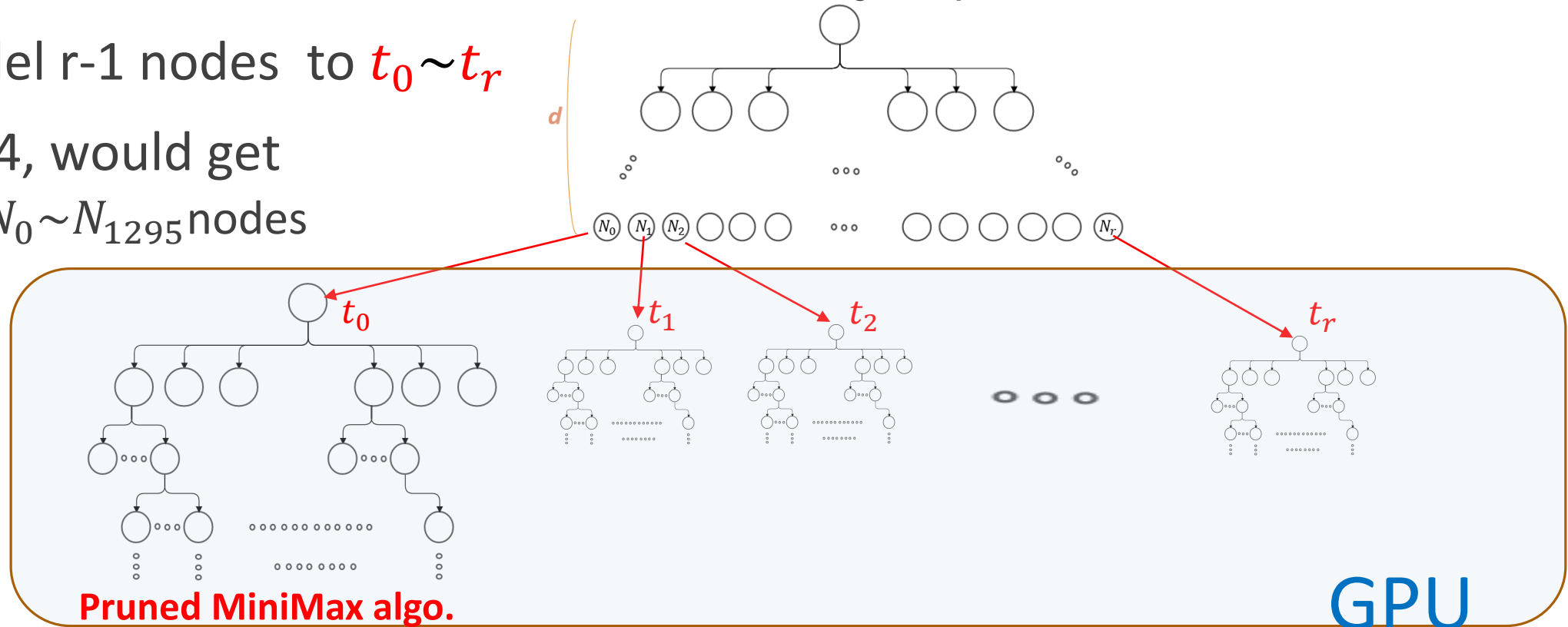
- Hard to parallelize recursive algorithm
  - Thread number: 6
- Still face with load imbalance.
  - Note: htop

S	CPU%	MEM
R	1.3	0
S	0.7	0
S	0.7	0



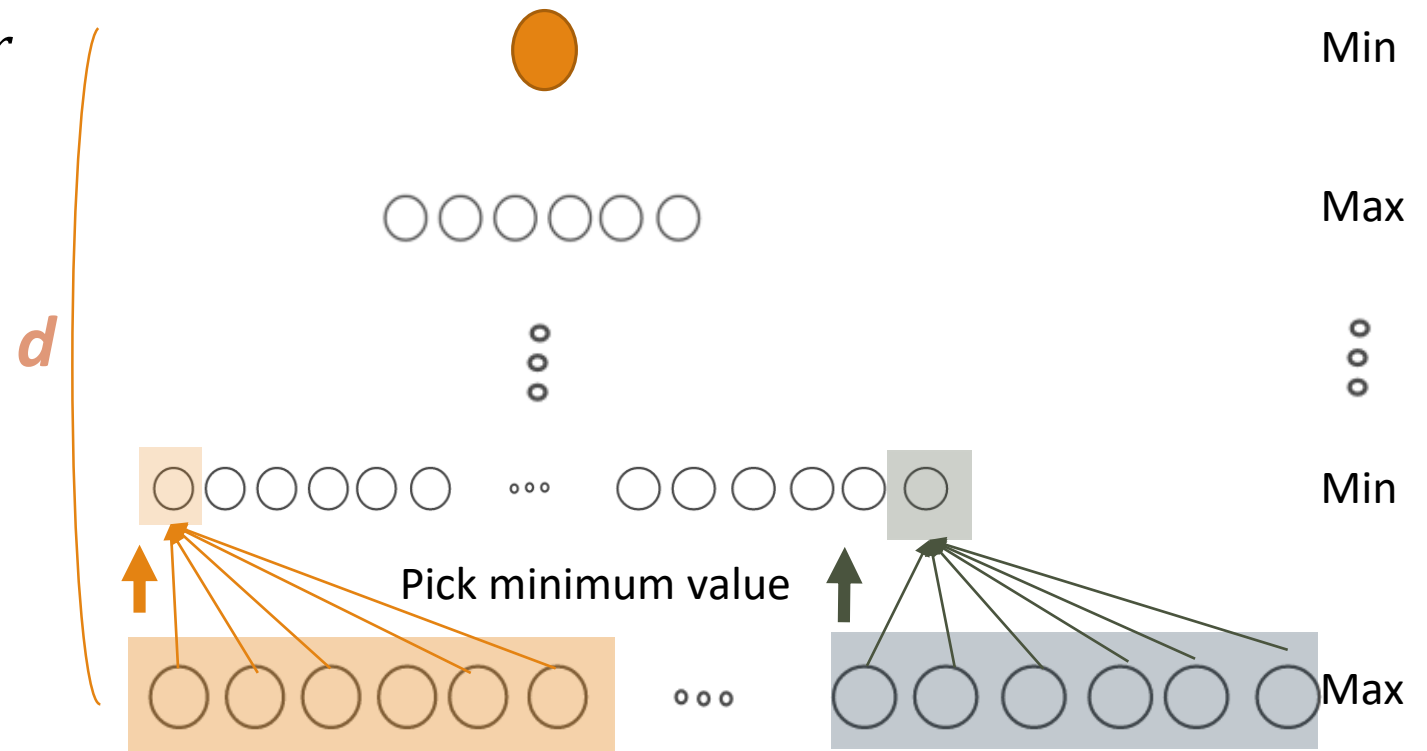
# Pruned Minimax tree parallel method with GPU

- Brutely expand  $d$  layer tree, yield nodes  $N_0 \sim N_r$ , ( $r = 6^d$ )
- Parallel  $r-1$  nodes to  $t_0 \sim t_r$
- If  $d = 4$ , would get  $N_0 \sim N_{1295}$  nodes

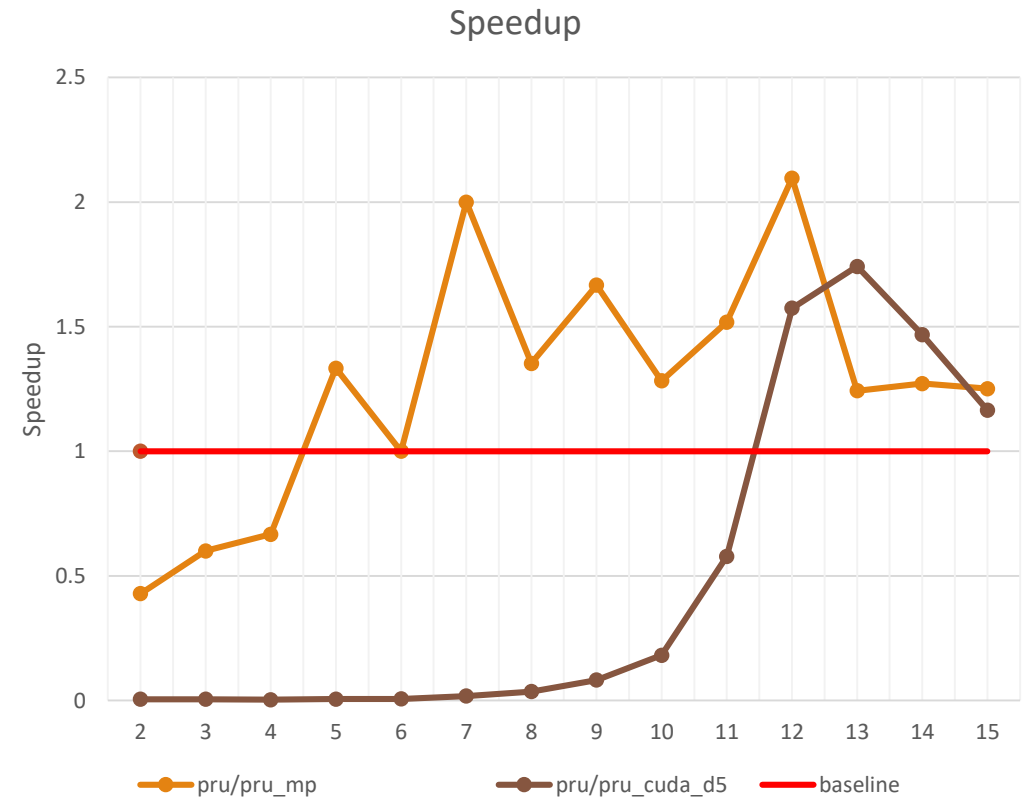
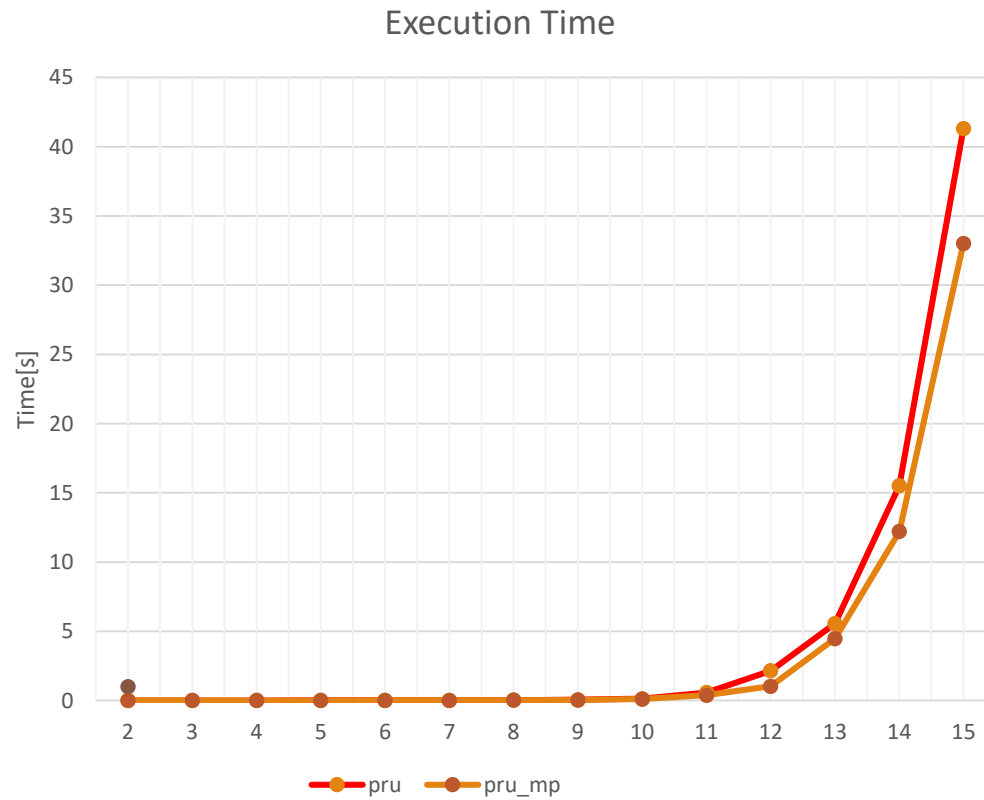


# Proposed Method: Advanced Pruned Minimax tree parallel method with GPU

- Brutely expand  $d$  layer tree, yield nodes  $N_0 \sim N_r$ , ( $r = 6^d$ )
- Parallel  $r-1$  nodes to  $t_0 \sim t_r$
- Collect predictions and get best **option**.



# Pruned Minimax tree parallel method with GPU



# Conclusion

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- When we are design a parallel algorithm. The issues firstly come to our mind are synchronization problem and dependency problem. However, picking a good algorithm to parallelize is also a big deal.

e.q. recursion.