

# Weather Balloon - FYS-MEK1110

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(a)

I define positive directions as in the diagram.

(b)

What is the acceleration of the balloon?

Using Newton's second law of motion. I decompose the forces in  $x, y$  and  $z$  direction, to find the respective accelerations. I see that the only forces acting upon the weather balloon are doing so in the  $z$  direction. So I can already tell that the  $x$  and  $y$  components of  $\vec{a}$  are 0.

$$\begin{aligned}\sum \vec{F} &= m\vec{a} \Rightarrow \vec{a} = \frac{\sum \vec{F}}{m} \\ a_z &= \frac{B - G}{m} = \frac{B}{m} - g \\ \vec{a} &= \left( \frac{B}{m} - g \right) \hat{k}\end{aligned}$$

(c)

Find the position and velocity of the balloon as a function of time.

I will assume that the balloon is let go from ground level, and that it has no initial velocity. This gives:  $v_0 = 0 \text{ m/s}$  and  $x_0 = 0 \text{ m}$ .

$$\begin{aligned}\vec{a}(t) &= a_x(t)\hat{i} + a_y(t)\hat{j} + a_z(t)\hat{k} = \left( \frac{B}{m} - g \right) \hat{k} \\ \vec{v}(t) &= \int_0^t \vec{a}(t) dt = \int_0^t \left( \frac{B}{m} - g \right) \hat{k} dt = t \left( \frac{B}{m} - g \right) \hat{k} \\ \vec{r}(t) &= \int_0^t \vec{v}(t) dt = \int_0^t t \left( \frac{B}{m} - g \right) \hat{k} dt = \frac{t^2}{2} \left( \frac{B}{m} - g \right) \hat{k}\end{aligned}$$

Which seems reasonable, seeing as there are no forces acting upon the weather balloon in the  $x$  and  $y$  direction it follows that there is no acceleration, velocity or displacement in those directions.

(d)

Introducing air resistance:  $\vec{F}_D = -Dv\vec{v}$ .

I again use Newton's second law. Seeing as the air resistance is a force that acts in the opposite direction of the velocity I know that  $a_x$  and  $a_y$  are going to remain 0. The absolute value in the formula is to ensure that the air resistance always works in the opposite direction of the velocity.

$$a_z = \frac{\sum F_z}{m} = \frac{B + F_{Dz} - G}{m} = \frac{B}{m} - g - \frac{D}{m}|v_z|v_z$$

(e)

(f)

Find the asymptotic (terminal) velocity of the balloon.

The balloon is going to reach its terminal velocity when  $B + F_{Dz} - G = 0 \Leftrightarrow B = G - F_{Dz}$ . This implies that:

$$a_z = \frac{B}{m} - g - \frac{D}{m}|v_z|v_z = 0$$

Solving for  $v_z$ :

$$\begin{aligned}\frac{B}{m} - g - \frac{D}{m}|v_z|v_z &= 0 \\ \frac{D}{m}|v_z|v_z &= \frac{B}{m} - g \\ D|v_z|v_z &= B - G \\ |v_z|v_z &= \frac{B - G}{D}\end{aligned}$$

Because of the absolute value of  $v_z$  in  $F_{Dz}$  we have

two different cases, one for  $v_z < 0$  and one for  $v_z \geq 0$ .

$$\begin{array}{ll} v_z < 0 \text{ gives:} & v_z \geq 0 \text{ gives:} \\ -v_z^2 = \frac{B-G}{D} & v_z^2 = \frac{B-G}{D} \\ v_z = \sqrt{\frac{G-B}{D}} & v_z = \sqrt{\frac{B-G}{D}} \end{array}$$

Because we will only be working with positive velocities for now, we can neglect the negative solution  $v_z = \sqrt{\frac{G-B}{D}}$ . Where therefore have an expression for the terminal velocity of the balloon in the  $z$ -direction:

$$v_{Tz} = \sqrt{\frac{B-G}{D}}$$

(g)

We now have to take into account a wind blowing with a velocity  $\vec{w} = w\hat{i} = [w, 0, 0]$  along the horizontal  $x$ -axis. How does this wind modify the air resistance force  $\vec{F}_D$  on the balloon?

The air resistance force  $\vec{F}_D$  is now going to have two non-zero components  $F_D x$  and  $F_D z$

(h)

(i)

Find an expression for the acceleration  $\vec{a}$  of the balloon. What are the initial conditions? Because of the new air resistance, we have to again apply Newton's second law.

$$\begin{aligned} \vec{a} &= \frac{\sum \vec{F}}{m} = \frac{(B-G)\hat{k} + \vec{F}_D}{m} = \frac{1}{m} ([0, 0, B-G] - D|v|\vec{v}) \\ &= \left[ \frac{-D|v_x|v_x}{m}, 0, \frac{B-D|v_z|v_z}{m} - g \right] \end{aligned}$$

The initial conditions is going to be  $\vec{v}_0 = [3, 0, 0]$ ,  $\vec{r}_0 = [0, 0, 0]$  and  $\vec{a}_0 = [0, 0, \frac{B}{m} - g]$

(j)

The motion in the  $z$ - and  $x$ -direction is called coupled because they are dependent on each other. They both occur in each others expressions. I can't see a way for us to find the motion of the ball analytically, unless we have really simple values to work with.

(k)

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```
for i in range(1, len(a)-1):
    # Using numpys matrix and linalg library,
    # where v, a and r are matrices.
    v[i+1] = v[i] + dt*a[i]
    FD = -D*np.linalg.norm(v[i+1])*v[i+1]
    a[i+1] = [0, 0, float(B-G)/m] + FD
    r[i+1] = r[i] + dt*v[i+1]
```

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(l)

(m)

The ball reaches its terminal velocity when  $|\vec{a}| = 0$ . This can be tested for by a simple if test in our python program:

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```
eps = 0.001
termVel = True

for i in range(1, len(a)-1):
    # Using numpys matrix and linalg library,
    # where v, a and r are matrices.
    v[i+1] = v[i] + dt*a[i]
    FD = -D*np.linalg.norm(v[i+1])*v[i+1]
    a[i+1] = [0, 0, float(B-G)/m] + FD
    r[i+1] = r[i] + dt*v[i+1]

    if np.linalg.norm(a[i+1] < eps) \
    and not termVel:
        print "Terminal velocity: ", v[i+1]
        termVel = False
```

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(p)

When the fire is extinguished, the boyancy force  $B$  is going to be reduced to 0. This can easily be implemented in our model by an if test inside our solution-loop that sets  $B = 0$  when our conditions are met.