Recorded at time: 159.524 odom Broadcaster: /gazebo Average rate: 100.362 Hz Most recent transform: 159.522 (0.002 sec old) Buffer length: 2.760 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /gazebo Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /gazebo Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 101.087 Hz Average rate: 101.087 Hz Average rate: 10.401 Hz Average rate: 10.401 Hz Most recent transform: 0.000 (159.524 sec old) Most recent transform: 159.522 (0.002 sec old) Most recent transform: 159.522 (0.002 sec old) Most recent transform: 159.428 (0.096 sec old) Most recent transform: 159.428 (0.096 sec old) Buffer length: 0.000 sec Buffer length: 2.596 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.760 sec Buffer length: 2.760 sec Buffer length: 2.596 sec ptu_base_plate_link wheel_right left_arm_base_link wheel_left wheel_front wheel_rear hokuyo_link right_arm_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.365 Hz Average rate: 50.365 Hz Most recent transform: 0.000 (159.524 sec old) Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer length: 2.740 sec Buffer length: 0.000 sec Buffer length: 2.740 sec left_arm_shoulder_roll ptu_base_link right_arm_shoulder_roll Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.365 Hz Average rate: 50.365 Hz Average rate: 50.365 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (159.524 sec old) Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer length: 2.740 sec Buffer length: 2.740 sec Buffer length: 2.740 sec Buffer length: 0.000 sec right_arm_shoulder_pitch left_arm_shoulder_pitch ptu_tilt_link ptu_pan_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.365 Hz Average rate: 50.365 Hz Average rate: 50.365 Hz Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer length: 2.740 sec Buffer length: 2.740 sec Buffer length: 2.740 sec left_arm_shoulder_yaw ptu_mount_link right_arm_shoulder_yaw Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.365 Hz Average rate: 10000.000 Hz Average rate: 50.365 Hz Most recent transform: 159.510 (0.014 sec old) Most recent transform: 0.000 (159.524 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer length: 2.740 sec Buffer length: 0.000 sec Buffer length: 2.740 sec bumblebee_link left_arm_elbow_pitch right_arm_elbow_pitch Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.365 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.365 Hz Most recent transform: 159.510 (0.014 sec old) Most recent transform: 0.000 (159.524 sec old) \Most recent transform: 0.000 (159.524 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer length: 0.000 sec Buffer length: 2.740 sec Buffer length: 0.000 sec Buffer length: 2.740 sec bumblebee_cameras_link xtion_link right_arm_elbow_yaw left_arm_elbow_yaw Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.365 Hz Average rate: 50.365 Hz Most recent transform: 159.510 (0.014 sec old) Most recent transform: 159.510 (0.014 sec old) Buffer 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sec old) Buffer length: 2.740 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.740 sec Buffer length: 2.740 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.740 sec left_arm_virtual_endeffector left_arm_gripper_finger1 left_arm_gripper_finger2 right_arm_virtual_endeffector right_arm_gripper_finger2 left_arm_camera_bracket right_arm_camera_bracket right_arm_gripper_finger1 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (159.524 sec old) Most recent transform: 0.000 (159.524 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec left_arm_camera right_arm_camera

view_frames Result