

# **AI 2002**

# **Artificial Intelligence**

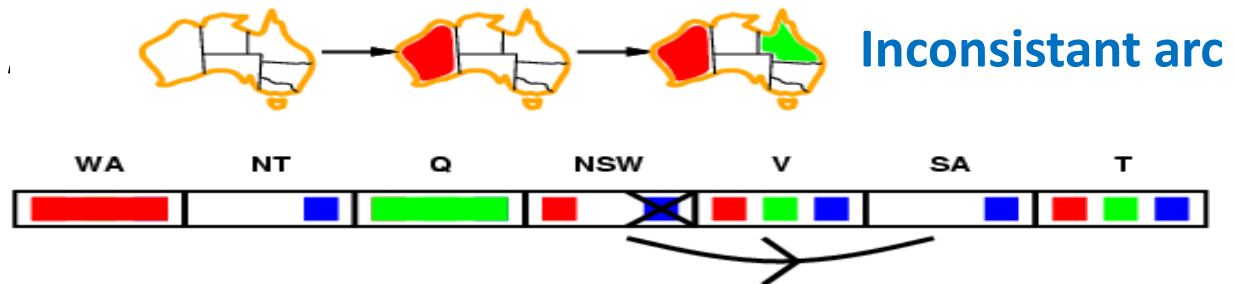
Dr. Hashim Yasin

# Forward Checking

# Arc Consistency

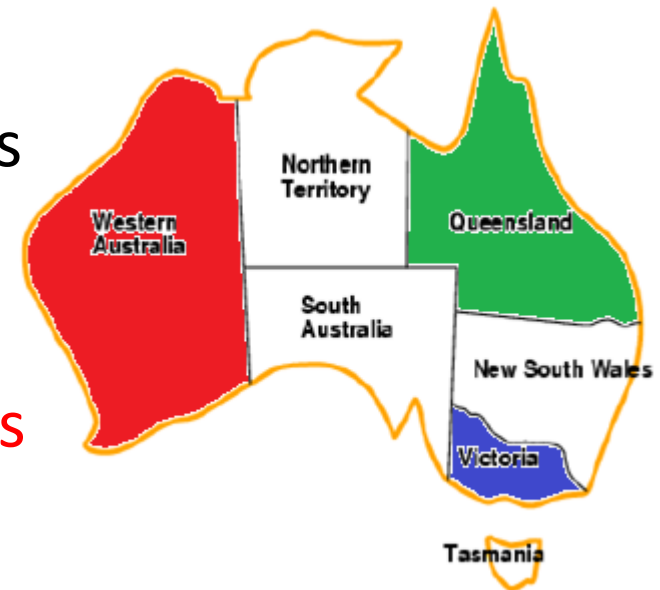
- ▶ A variable in a CSP is **arc-consistent** if every value in its domain satisfies the variable's *binary constraints*.
- ▶ ***Arc consistency** eliminates values from the domain of variables that can never be part of a consistent solution.*
- ▶ Directed arc  $(V_i, V_j)$  is arc consistent if  

$$\forall x \in D_i \quad \exists y \in D_j$$
 such that  $(x, y)$  is allowed by constraint
- ▶ For every value



# Forward Checking

- ▶ Keep track of remaining legal values for unassigned variables
- ▶ Whenever a variable is assigned a value, the **forward-checking process establishes arc consistency** for it:



	WA	NT	Q	NSW	V	SA	T
Initial domains	R G B	R G B	R G B	R G B	R G B	R G B	R G B
After $WA=red$	Ⓡ	G B	R G B	R G B	R G B	G B	R G B
After $Q=green$	Ⓡ	B	Ⓢ	R B	R G B	B	R G B
After $V=blue$	Ⓡ	B	Ⓢ	R	Ⓟ		R G B

# Forward Checking

- Hence, forward checking has detected that the partial assignment {WA=red, Q=green, V=blue} is **inconsistent** and the algorithm will therefore backtrack immediately.

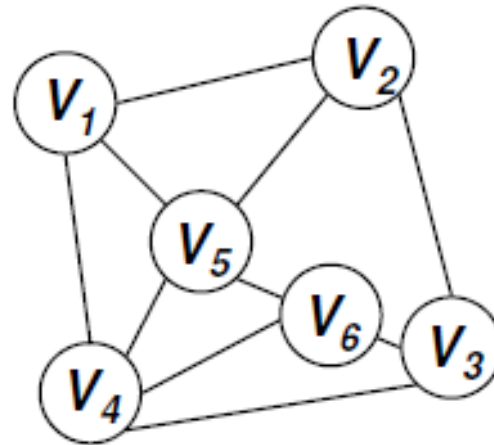


	WA	NT	Q	NSW	V	SA	T
Initial domains	R G B	R G B	R G B	R G B	R G B	R G B	R G B
After WA=red	Ⓐ	G B	R G B	R G B	R G B	G B	R G B
After Q=green	Ⓐ	B	Ⓔ	R B	R G B	B	R G B
After V=blue	Ⓐ	B	Ⓔ	R	Ⓑ		R G B

# Forward Checking ... Example 2

- ▶ Keep track of remaining legal values for unassigned variables
- ▶ Whenever a variable is assigned a value, the forward-checking process establishes **arc consistency** for it:

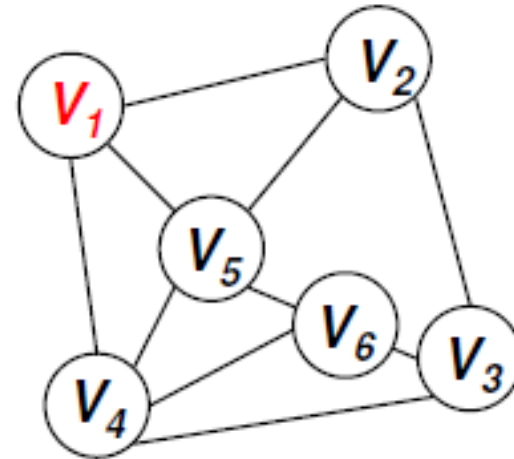
	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	?	?	?	?	?	?
$B$	?	?	?	?	?	?
$G$	?	?	?	?	?	?



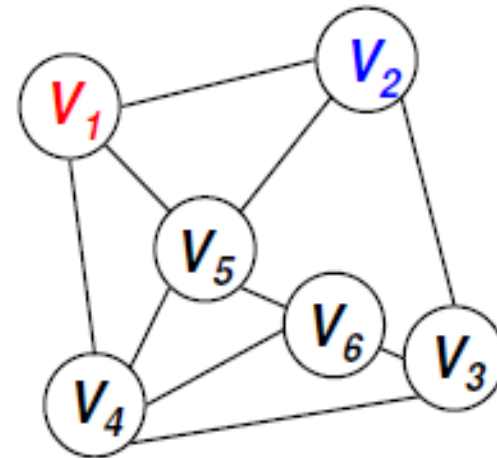


# Forward Checking ... Example 2

	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	$O$	$X$	$?$	$X$	$X$	$?$
$B$		$?$	$?$	$?$	$?$	$?$
$G$		$?$	$?$	$?$	$?$	$?$

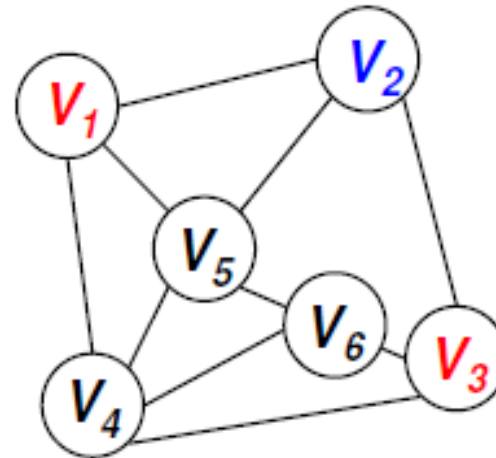


	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	$O$		$?$	$X$	$X$	$?$
$B$		$O$	$X$	$?$	$X$	$?$
$G$			$?$	$?$	$?$	$?$

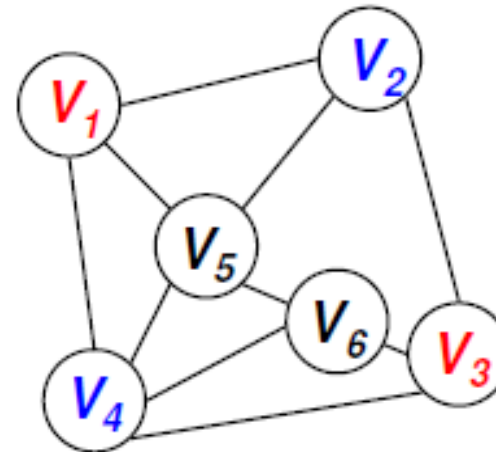


# Forward Checking ... Example 2

	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	$O$		$O$	$X$	$X$	$X$
$B$		$O$		$?$	$X$	$?$
$G$				$?$	$?$	$?$



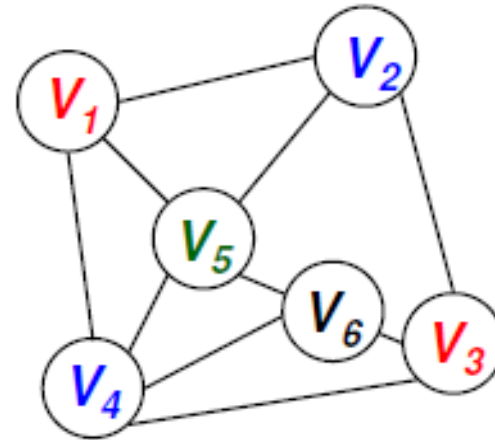
	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	$O$		$O$		$X$	$X$
$B$		$O$		$O$	$X$	$X$
$G$					$?$	$?$





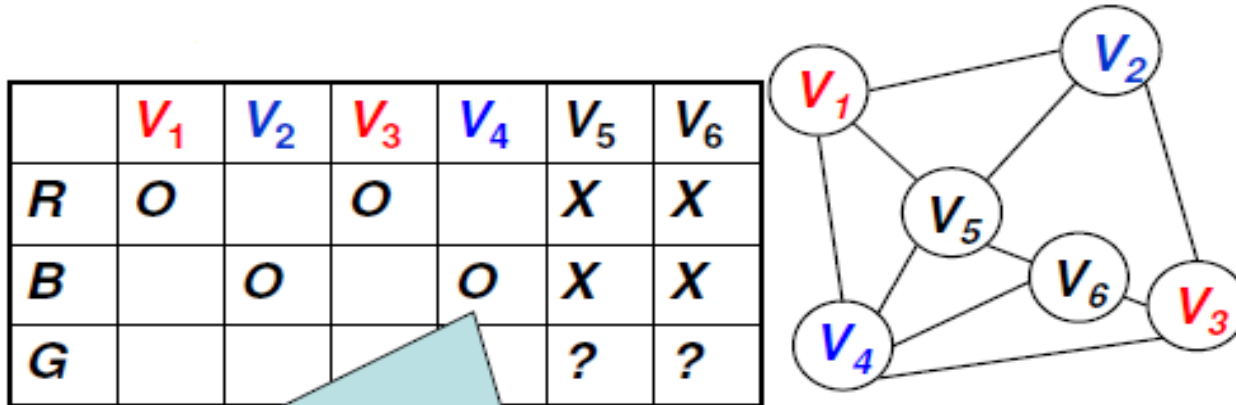
# Forward Checking ... Example 2

	$V_1$	$V_2$	$V_3$	$V_4$	$V_5$	$V_6$
$R$	$O$		$O$			$X$
$B$		$O$		$O$		$X$
$G$					$O$	$X$



There are no valid assignments left for  $V_6$  we need to backtrack

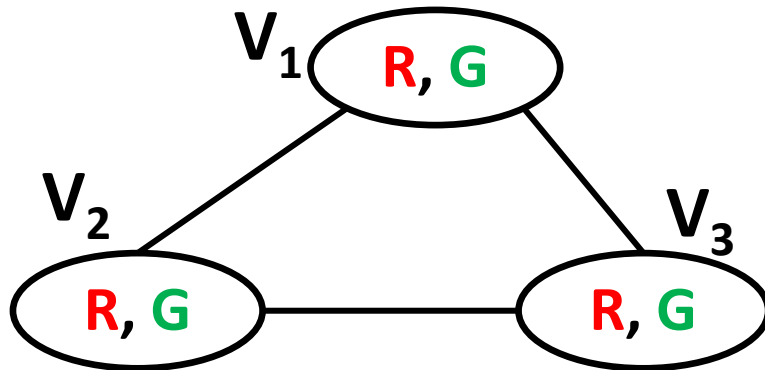
# Forward Checking ... Example 2



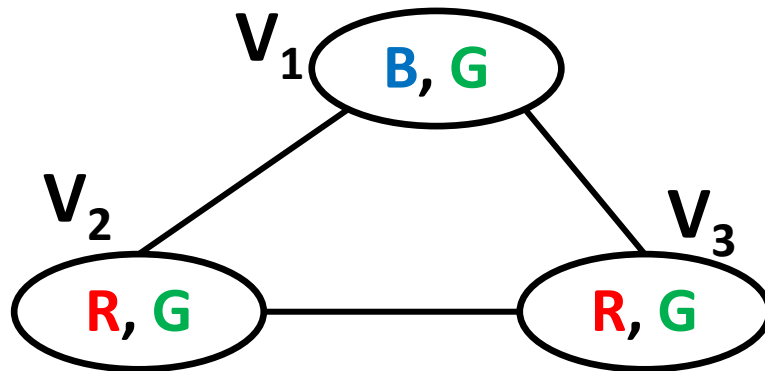
At this point, it is already obvious that this branch will not lead to a solution because there are no consistent values in the remaining domain for  $V_5$  and  $V_6$ .

- ▶ Forward checking **does not detect all the inconsistencies**, only those that can be detected by looking at the constraints which contain the **current variable**.
- ▶ Can we look ahead further?

# Arc consistency is not enough in general



Arc consistent but  
**NO** solutions



Arc consistent but  
TWO solutions

**B, R, G**

**B, G, R**

**Need to do search to find solutions (if any)**

# Constraint Propagation

# Constraint Propagation

- ▶  $V$  = variable being assigned at the current level of the search
- ▶ Set variable  $V$  to a value in  $D(V)$
- ▶ For every variable  $V'$  connected to  $V$ :
  - Remove the values in  $D(V')$  that are inconsistent with the assigned variables
  - For every variable  $V''$  connected to  $V'$ :
    - Remove the values in  $D(V'')$  that are no longer possible candidates
    - And do this again with the variables connected to  $V''$ 
      - .....until no more values can be discarded



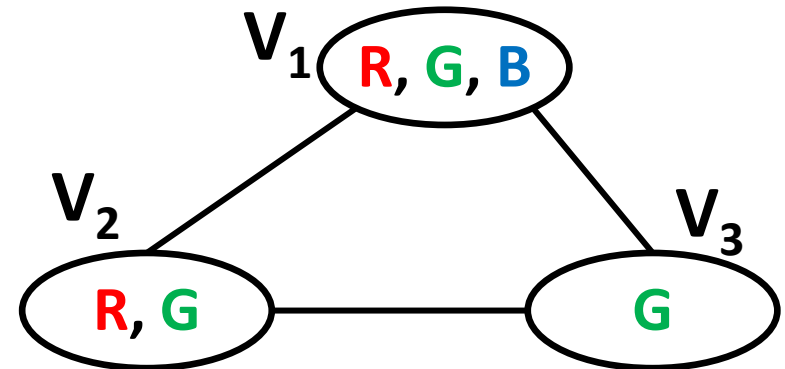
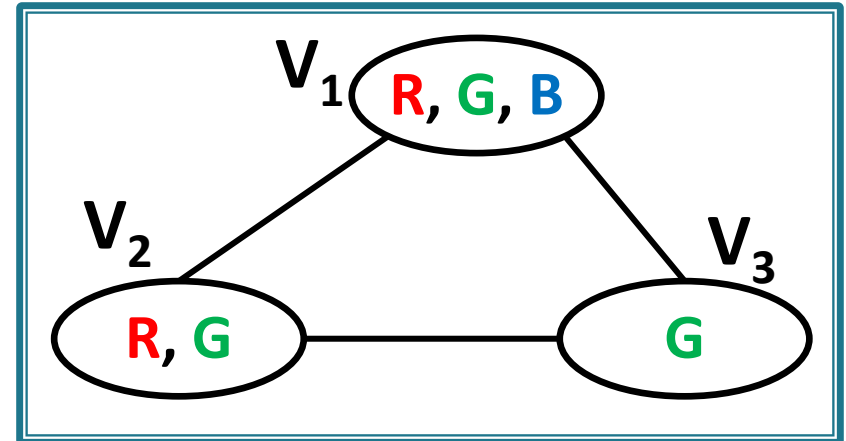
**Forward  
Checking**



**Constraint  
Propagation**

# Constraint Propagation

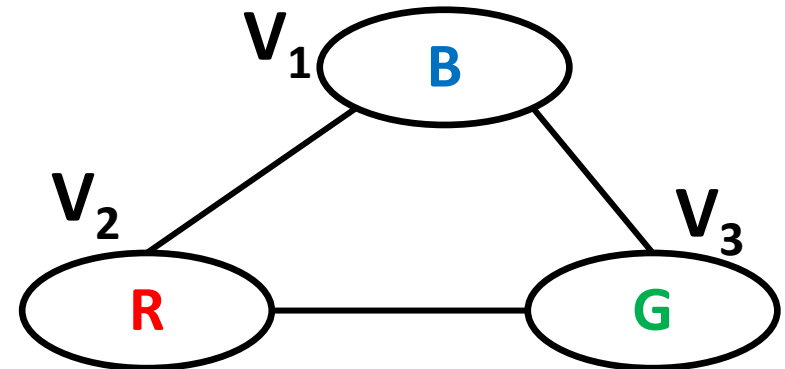
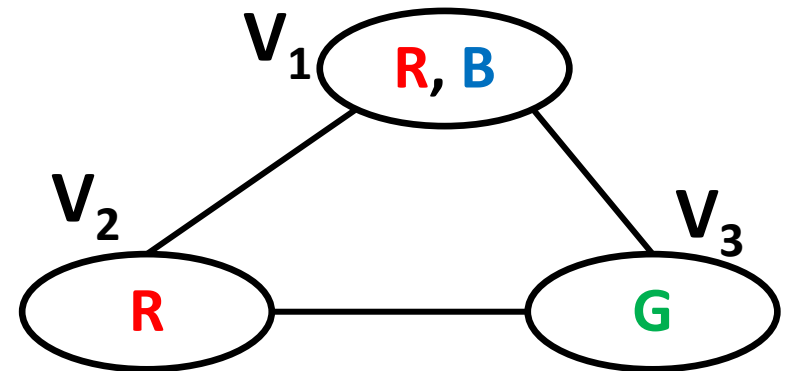
Arc examined	Value deleted
$V_1 - V_2$	None





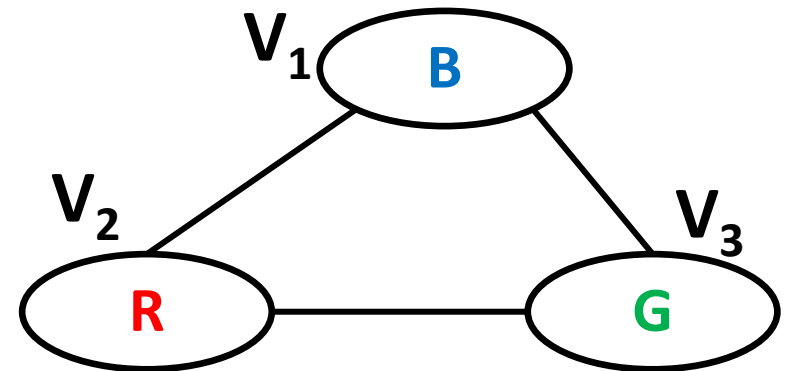
# Constraint Propagation

Arc examined	Value deleted
$V_1 - V_2$	None
$V_1 - V_3$	$V_1$ (G)
$V_2 - V_3$	$V_2$ (G)
$V_1 - V_2$	$V_1$ (R)



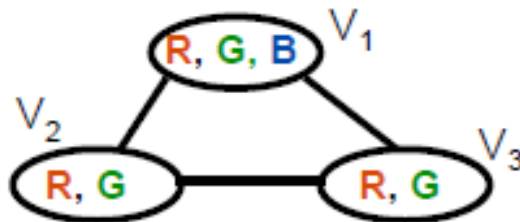
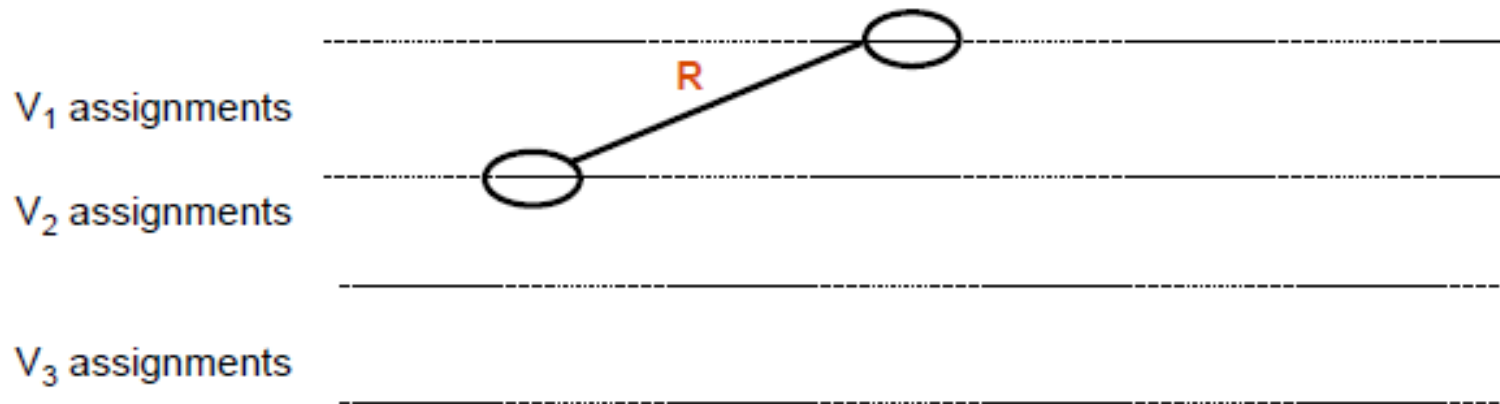
# Constraint Propagation

Arc examined	Value deleted
$V_1 - V_2$	None
$V_1 - V_3$	$V_1$ (G)
$V_2 - V_3$	$V_2$ (G)
$V_1 - V_2$	$V_1$ (R)
$V_1 - V_3$	None
$V_2 - V_3$	None

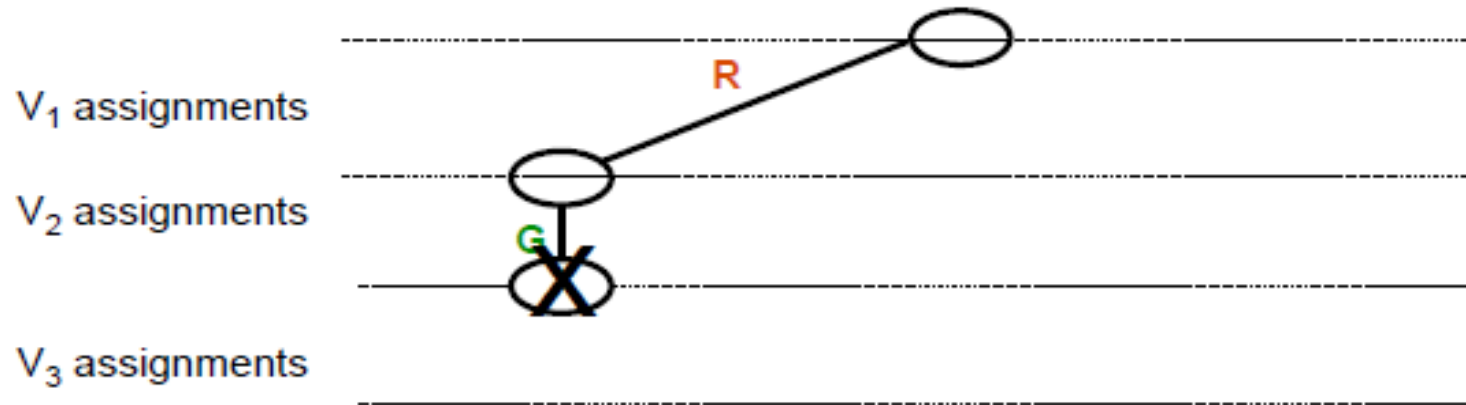


# **Forward Checking with Backtracking**

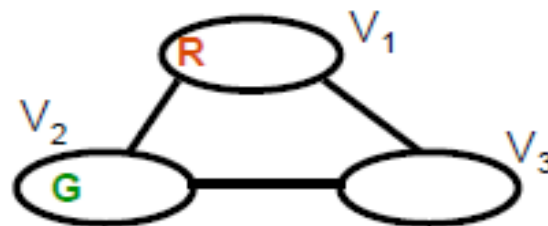
# Forward Checking with Backtracking



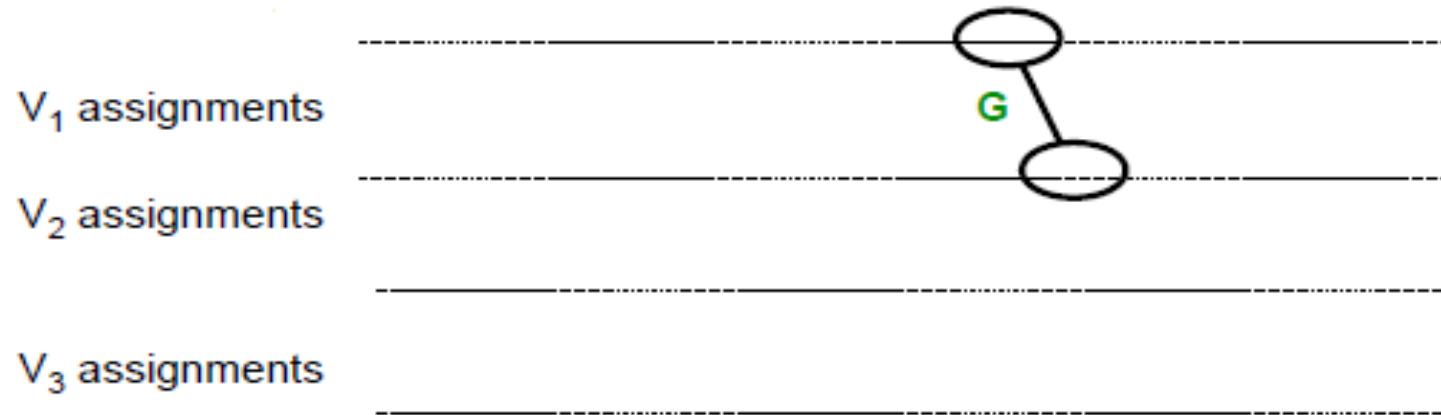
# Forward Checking with Backtracking



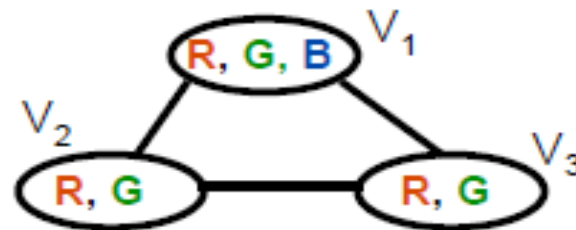
We have a conflict whenever a domain becomes empty.



# Forward Checking with Backtracking

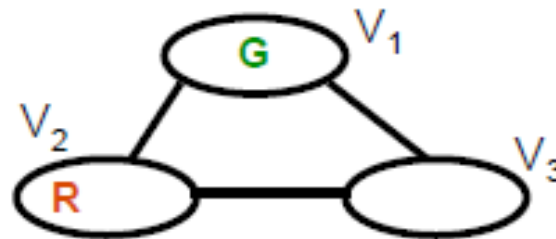
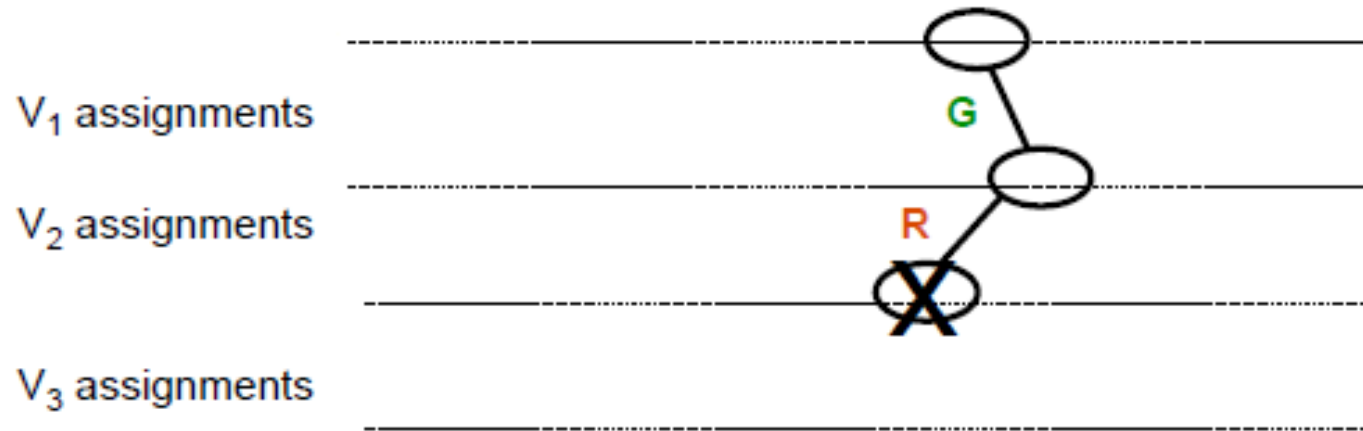


When backing up, need to restore domain values, since deletions were done to reach consistency with tentative assignments considered during search.

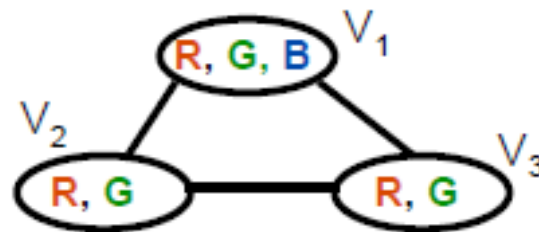
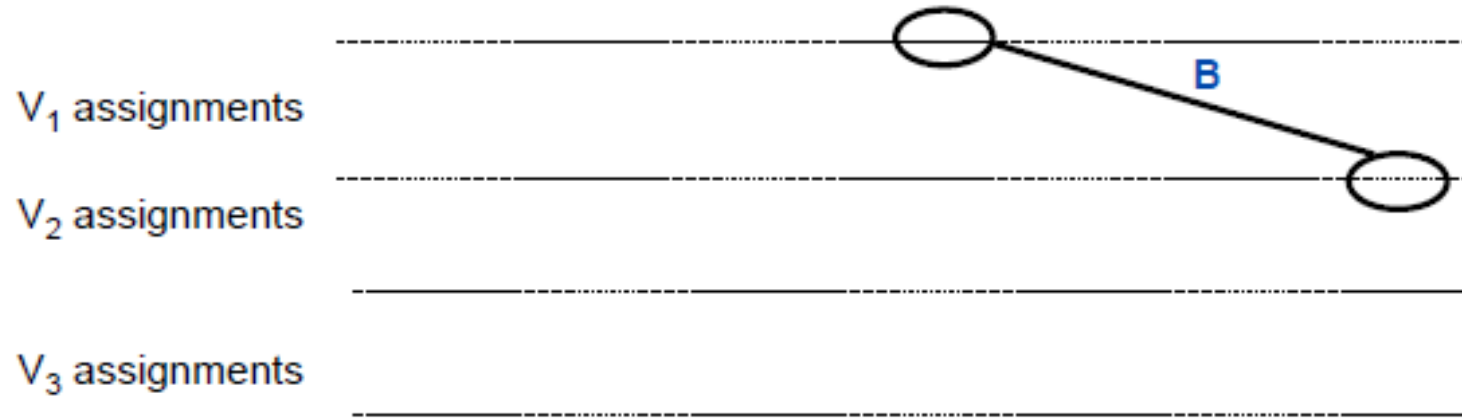




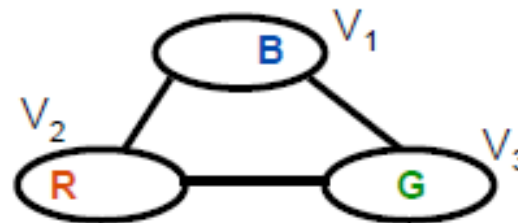
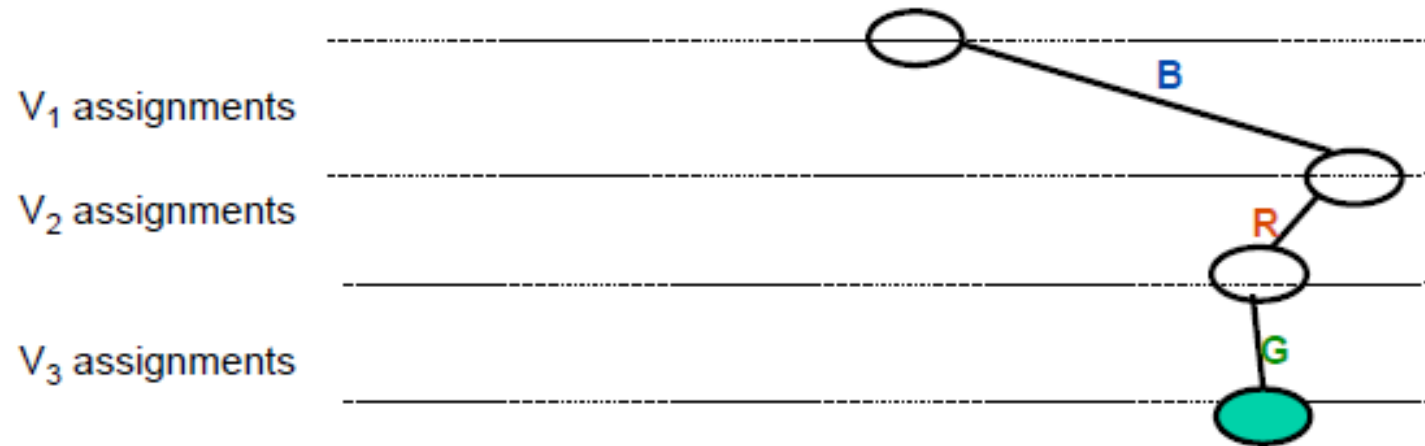
# Forward Checking with Backtracking



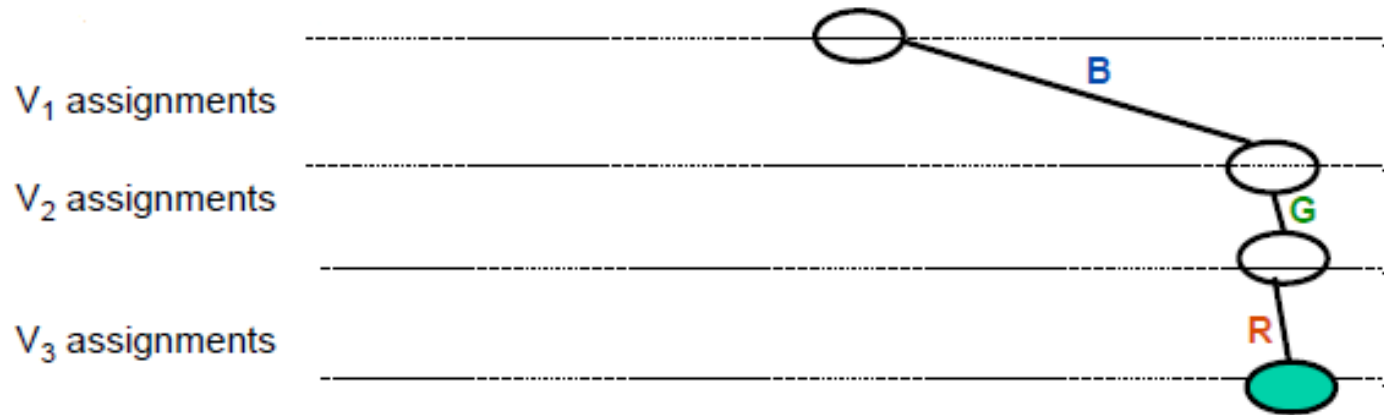
# Forward Checking with Backtracking



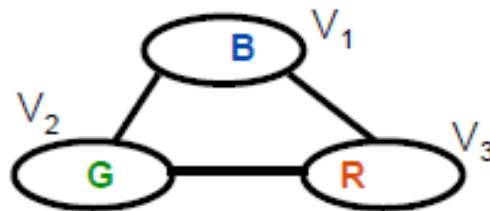
# Forward Checking with Backtracking



# Forward Checking with Backtracking



No need to check  
previous assignments



# FC-BT with dynamic ordering

- ▶ Traditional **backtracking uses fixed ordering** of variables & values.
- ▶ The simplest strategy for selecting unassigned variable is to choose the next unassigned variable in order,  $\{X_1, X_2, \dots\}$ .
- ▶ Other is the random order or place variables with many constraints first.
- ▶ Can be modified by choosing an **order dynamically** as the search proceeds.

# FC-BT with dynamic ordering

## Most Constrained Variable (Minimum Remaining Values (MRV)):

- ▶ when doing forward-checking, ***pick variable with fewest “legal” values*** to assign next (minimizes branching factor)
  - The MRV heuristic usually performs better than a random or static ordering, sometimes by a factor of 1,000 or more.

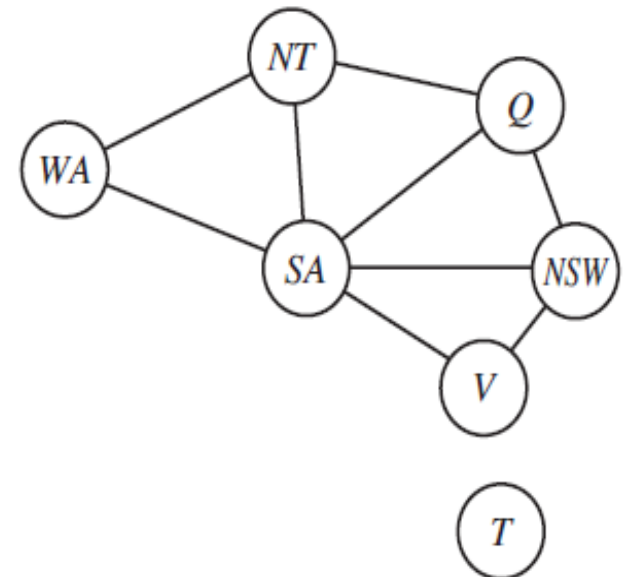
	WA	NT	Q	NSW	V	SA	T
Initial domains	R G B	R G B	R G B	R G B	R G B	R G B	R G B
After WA=red	Ⓡ	G B	R G B	R G B	R G B	G B	R G B



# FC-BT with dynamic ordering

## Degree Heuristic:

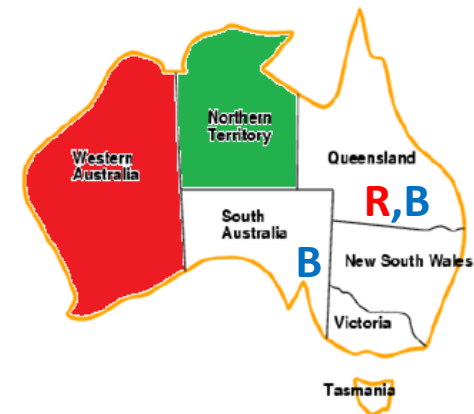
- ▶ It attempts to reduce the branching factor on future choices by *selecting the variable* that is involved in the *largest number of constraints*.
  - SA is the variable with highest degree, 5.



# FC-BT with dynamic ordering

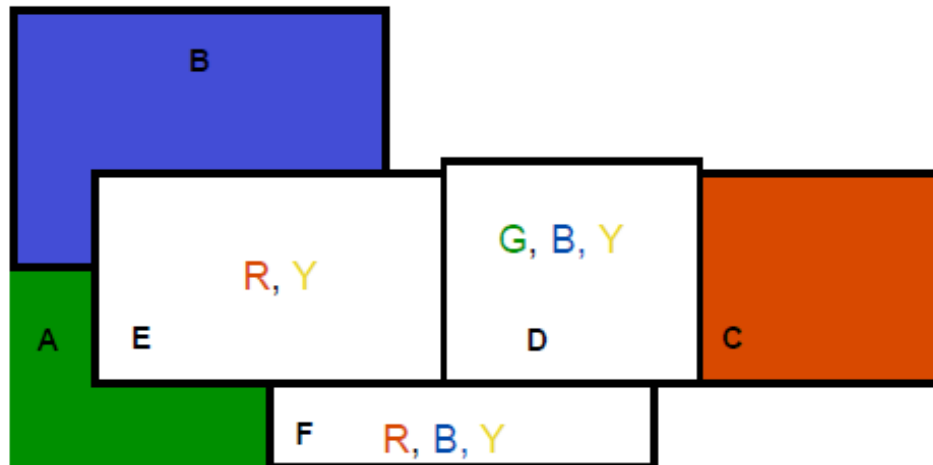
## Least Constrained Value:

- ▶ choose value that rules out the *smallest number* of values in variables connected to the chosen variable by constraints.
- ▶ We have generated the partial assignment for **WA=red** and **NT=green**. What would be our next choice for Q. Blue would be a bad choice because it eliminates the last legal value left for Q's neighbor, SA. *The least-constraining-value heuristic therefore prefers red to blue. (eliminates fewest values from neighbouring domains)*
  - This combination improves feasible n-queens performance from about  $n = 30$  with just FC to about  $n = 1000$  with FC & ordering.



# FC-BT with dynamic ordering

Colors: R, G, B, Y



- ▶ Which **country** should we colour next
- ▶ What **colour** should we pick for it?

**E** most-constrained variable (smallest domain)

**RED** least-constraining value (eliminates fewest values from neighbouring domains)

# Reading Material

- ▶ **Artificial Intelligence, A Modern Approach**  
**Stuart J. Russell and Peter Norvig**
  - Chapter 6.

