

AI 2002

Artificial Intelligence

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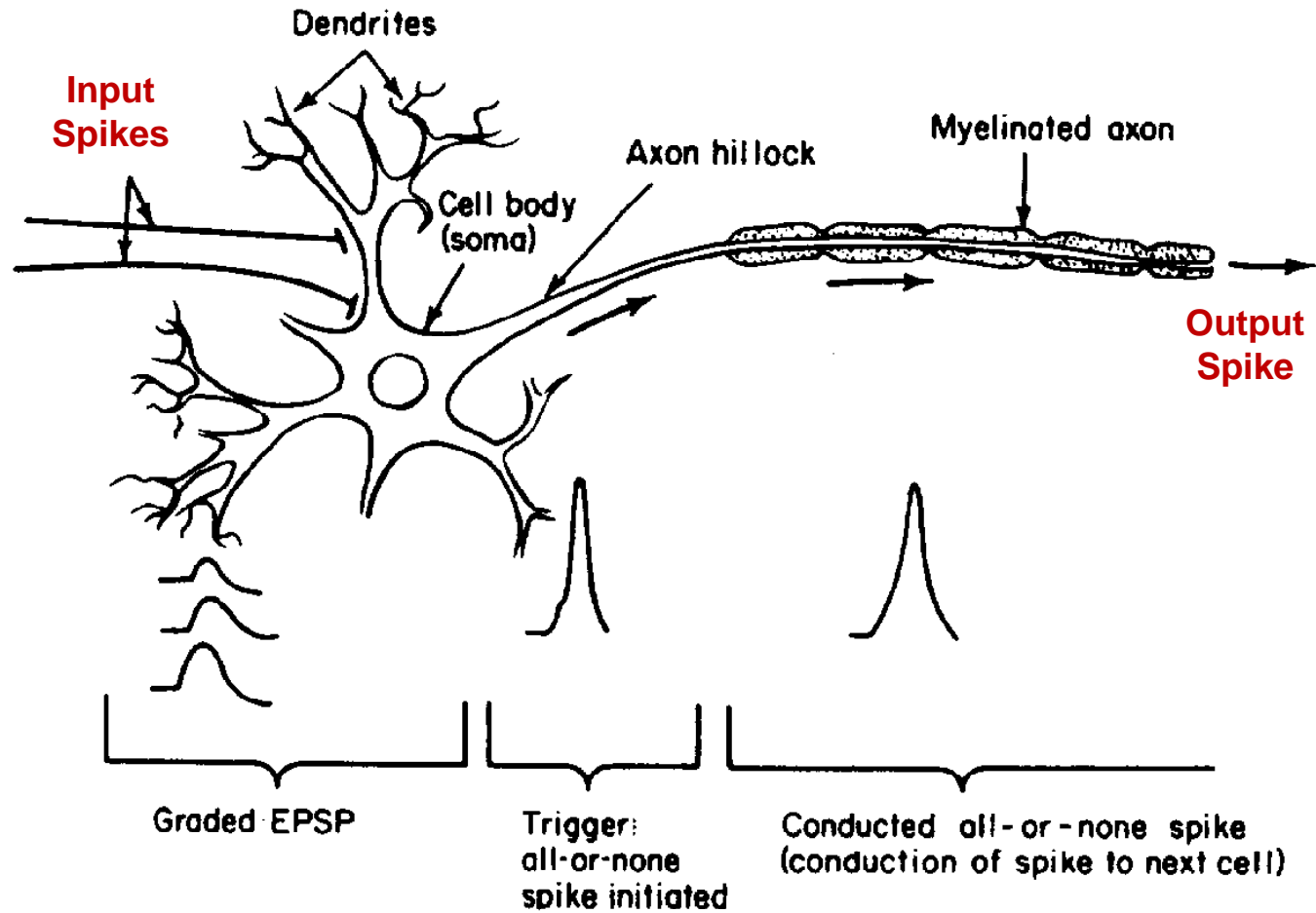
Artificial Neural Network



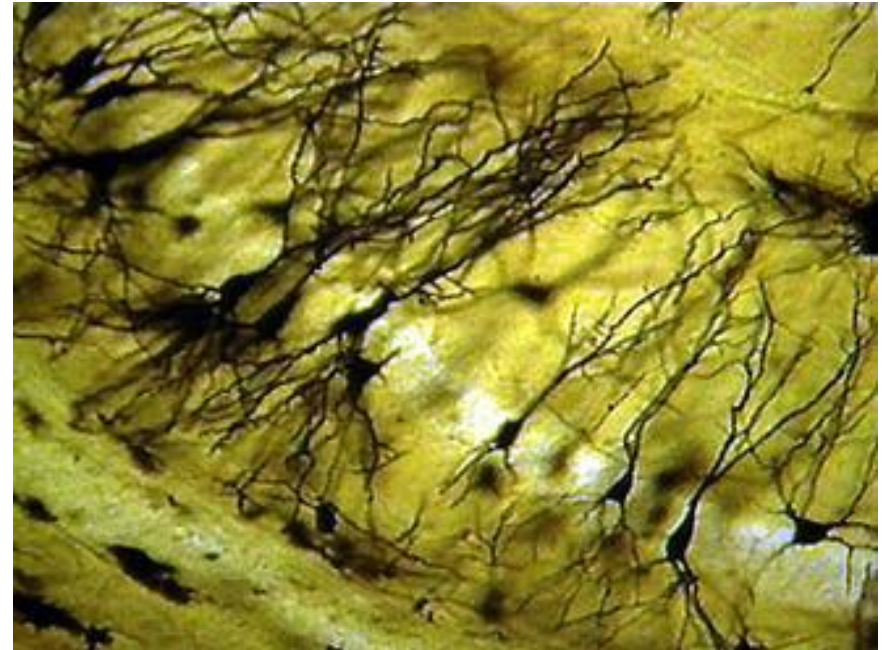
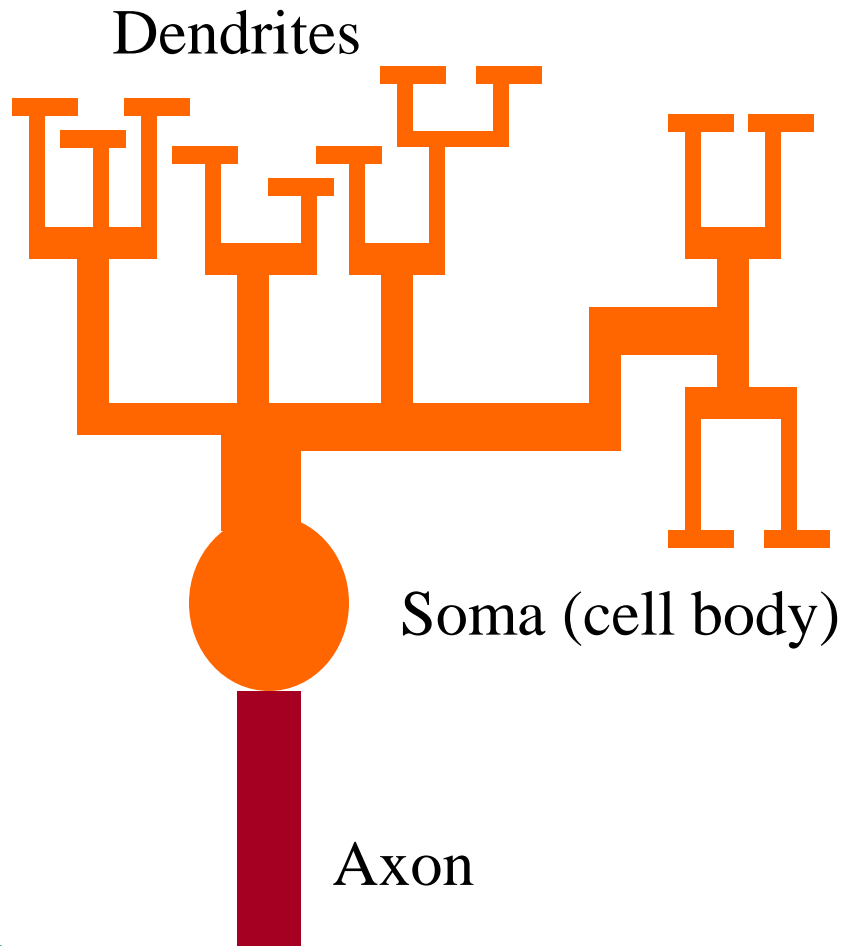
Biological Inspiration

- ▶ Animals are able to **react adaptively to changes** in their external and internal environment, and they use their **nervous system** to perform these behaviours.
- ▶ An appropriate model/simulation of the nervous system should be able to produce similar responses and behaviours in artificial systems.

Biological Inspiration



Biological Inspiration



Biological Inspiration

Four Parts of Typical Nerve Cell:

- ▶ Dendrites:

accepts the inputs

- ▶ Soma:

process the inputs

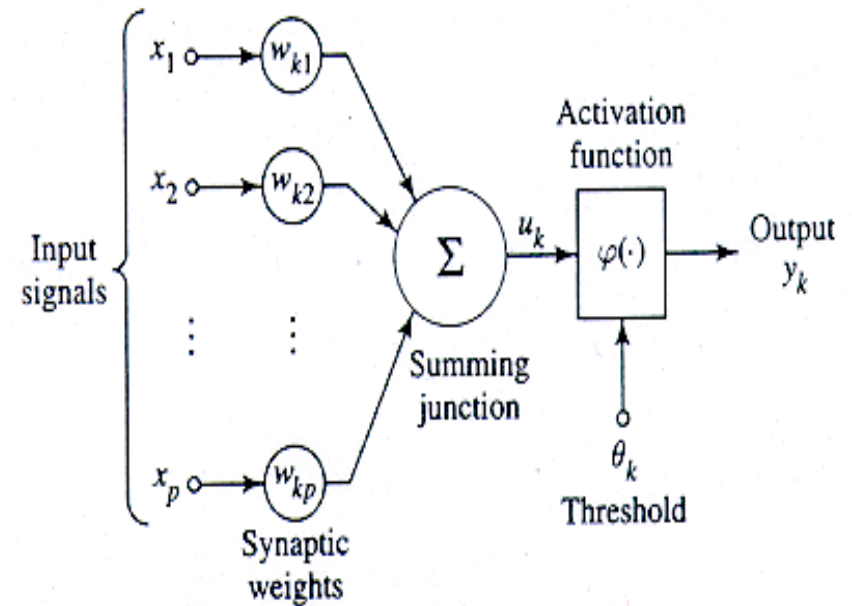
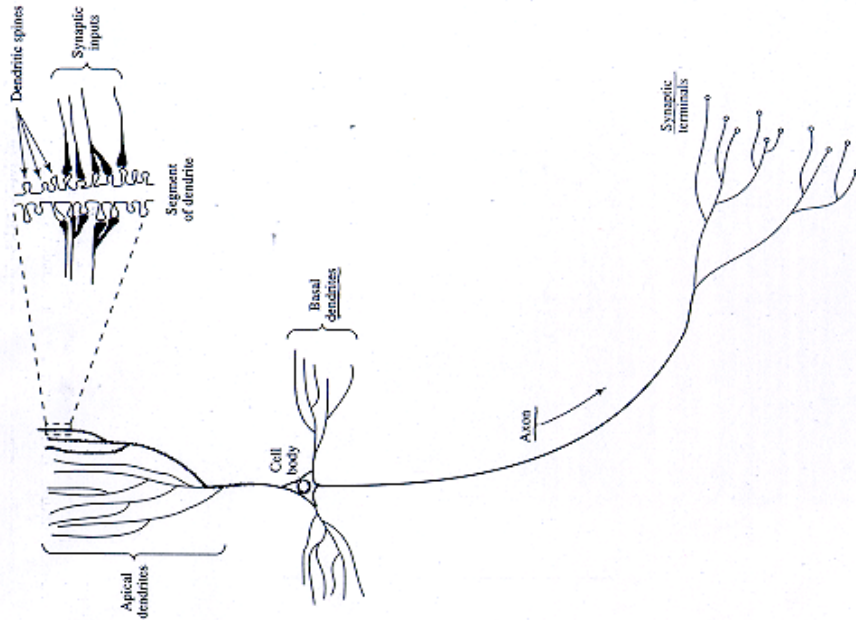
- ▶ Axon:

turns the process input into outputs

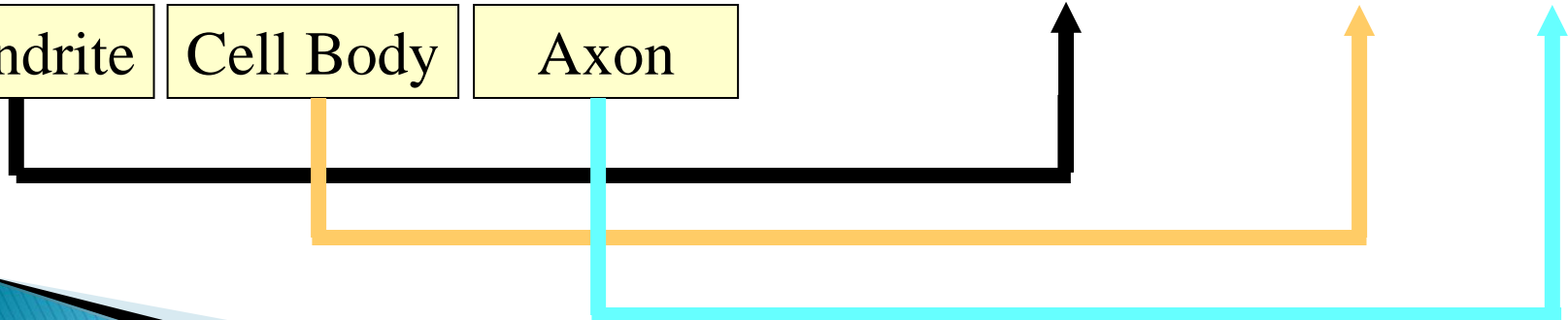
- ▶ Synapses:

the electromechanical contact between the neurons

Biological Inspiration



Dendrite Cell Body Axon



Perceptron

Perceptron

- ▶ A simplest type of ANN system is based on a unit called a **perceptron**.
- ▶ A perceptron
 - takes a **vector of real-valued inputs**,
 - calculates a linear combination of these inputs,
 - then **outputs** a 1 if the result is greater than some **threshold** and -1 otherwise.
- ▶ More precisely, given inputs x_1 through x_n the output $o(x_1, \dots, x_n)$ computed by the perceptron is

$$o(x_1, \dots, x_n) = \begin{cases} 1 & \text{if } w_0 + w_1x_1 + \dots + w_nx_n > 0 \\ -1 & \text{otherwise} \end{cases}$$

Perceptron

$$o(x_1, \dots, x_n) = \begin{cases} 1 & \text{if } w_0 + w_1x_1 + \dots + w_nx_n > 0 \\ -1 & \text{otherwise} \end{cases}$$

- ▶ where each w_i is a real-valued constant, or weight,
 - that determines the contribution of input x_i to the perceptron output.
- ▶ The quantity (w_0) is a threshold
 - the weighted combination of inputs $w_1x_1 + \dots + w_nx_n$ must exceed for the perceptron to output 1.

Perceptron

- ▶ We may imagine an *additional constant input* $x_0 = 1$, allowing to write the above inequality as,

$$\sum_{i=0}^n w_i x_i > 0$$

or in **vector form** as

$$o(\mathbf{x}) = \begin{cases} 1 & \text{if } \mathbf{w} \cdot \mathbf{x} > 0 \\ -1 & \text{otherwise} \end{cases}$$

$$\mathbf{x} = \vec{x}$$

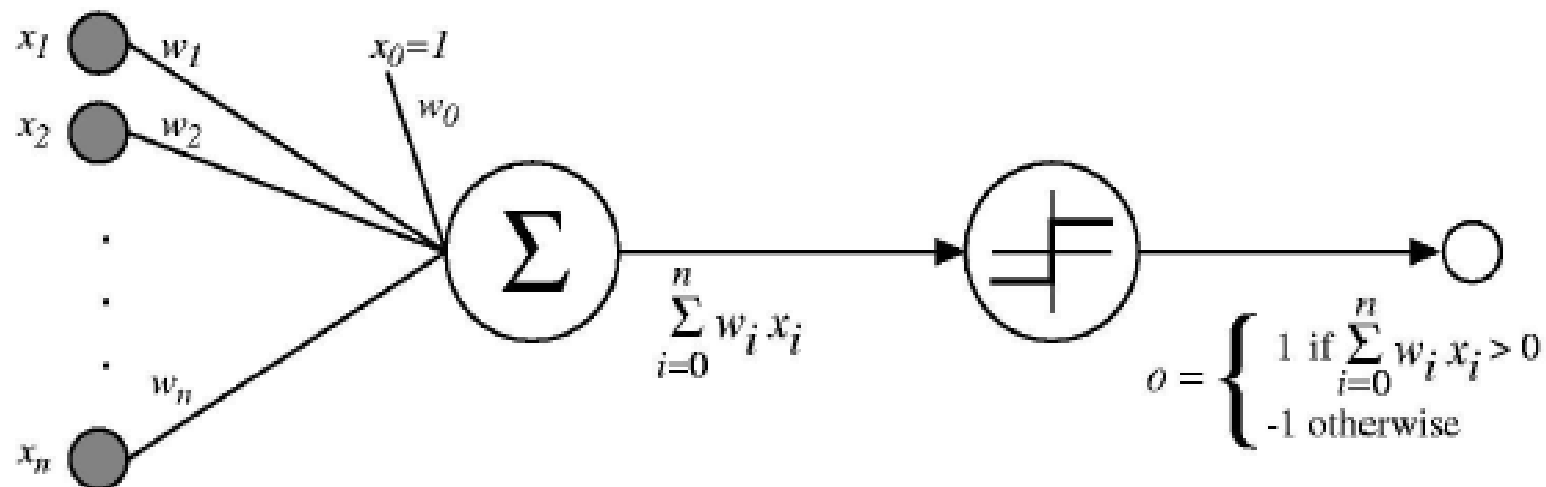
$$\text{sgn}(y) = \begin{cases} 1 & \text{if } y > 0 \\ -1 & \text{otherwise} \end{cases}$$

Perceptron

- ▶ Learning a perceptron involves choosing values for the weights w_0, \dots, w_n .
- ▶ Therefore, the space H of candidate hypotheses considered in perceptron learning is the *set of all possible real-valued weight vectors*

$$H = \{ \vec{w} \mid \vec{w} \in \mathbb{R}^{(n+1)} \}$$

Perceptron



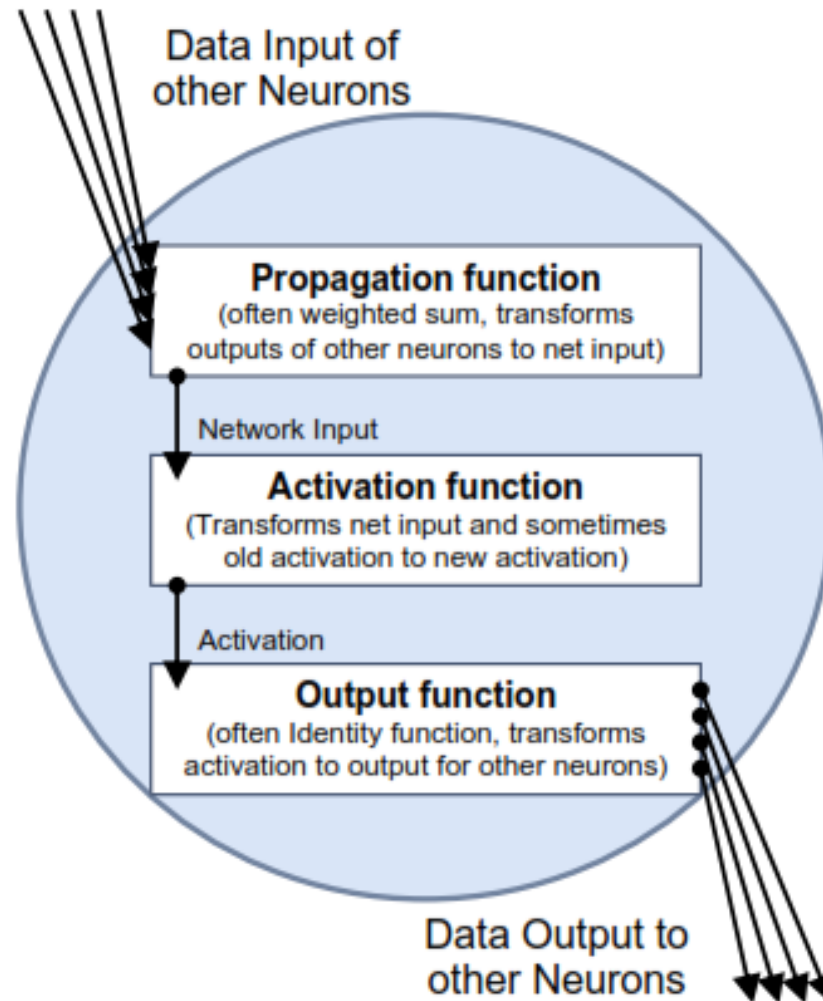
$$o(x_1, \dots, x_n) = \begin{cases} 1 & \text{if } w_0 + w_1 x_1 + \dots + w_n x_n > 0 \\ -1 & \text{otherwise.} \end{cases}$$

Neural Network Components


Neural Network Components

- ▶ A **neural network** is a sorted **triple** (N, V, w) with two sets N, V and a function w ,
 - ▶ whereas N is the set of *neurons* and
 - ▶ V is a sorted set $\{(i, j) | i, j \in N\}$ whose elements are called **connections** between neuron i and neuron j .
- ▶ The function $w : V \rightarrow R$ defines the **weights**, where as $w(i, j)$,
 - The weight of the connection between neuron i and neuron j , is shortly referred to as $w_{i,j}$.

Neural Network Components



Input Neuron

- ▶ An *input neuron* is an **identity neuron**. It exactly forwards the information received.
- ▶ Input neuron only forwards data
- ▶ Thus, it represents the identity function, which can be indicated by the symbol $y = x$
- ▶ The input neuron is represented by the symbol 

Binary Neuron

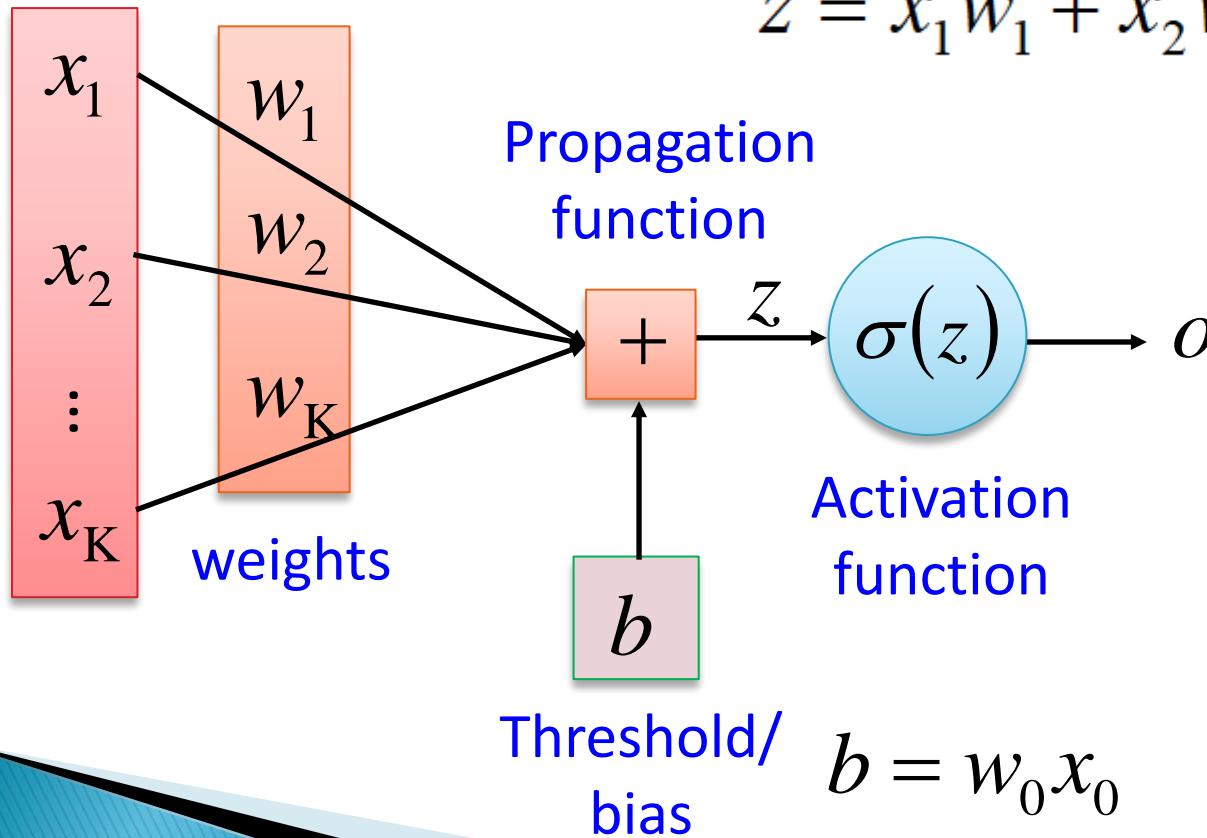
- ▶ **Information processing neurons** process the input information somehow, *i.e.* do not represent the identity function.
- ▶ A **binary neuron** sums up all inputs by using the weighted sum as propagation function, which is illustrate by the sigma sign.

$$\Sigma$$

- ▶ The activation function of the neuron is also binary threshold function, which can be illustrated by \lceil

Neural Network Components

Input
Neurons



$$f: R^K \rightarrow R$$

$$z = x_1 w_1 + x_2 w_2 + x_K w_K + b$$

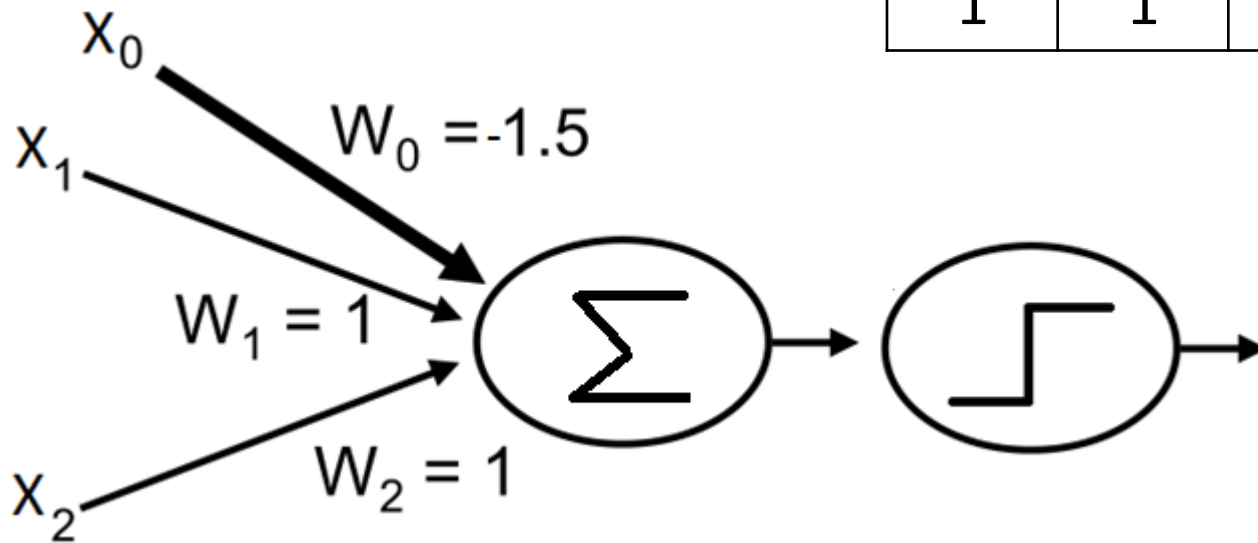
$$b = w_0 x_0$$

AND Function

x_1	x_2	y
0	0	0
0	1	0
1	0	0
1	1	1

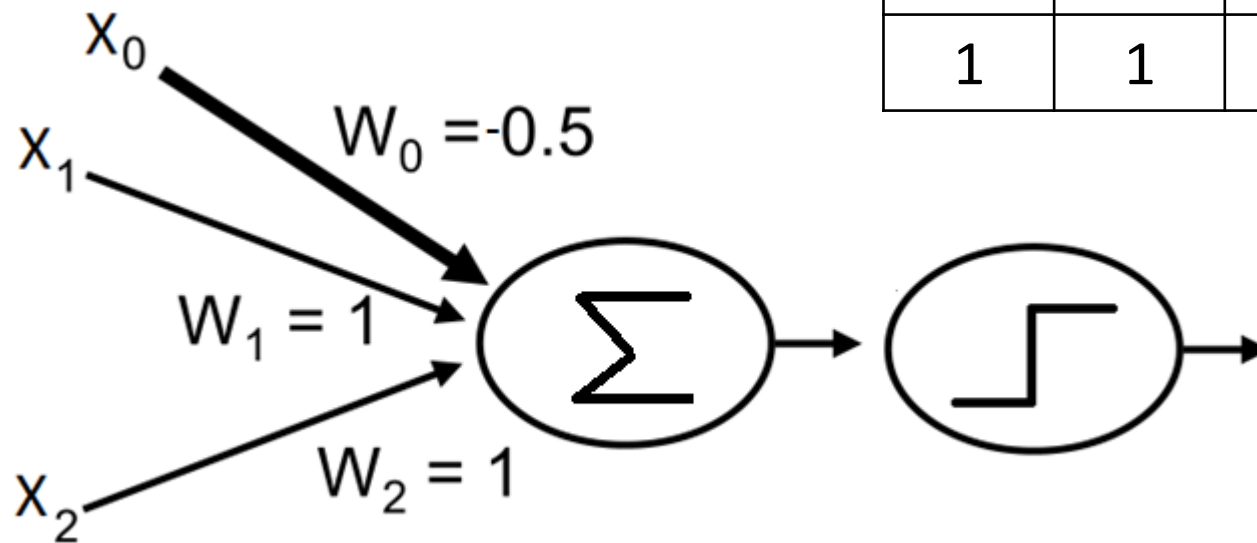
AND Function

x_1	x_2	Y
0	0	0
0	1	0
1	0	0
1	1	1

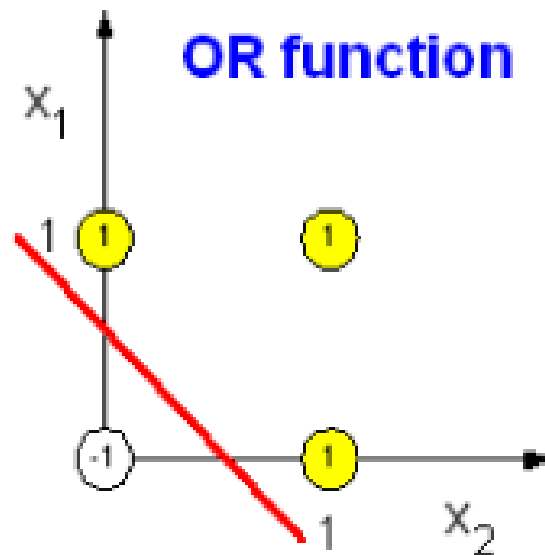
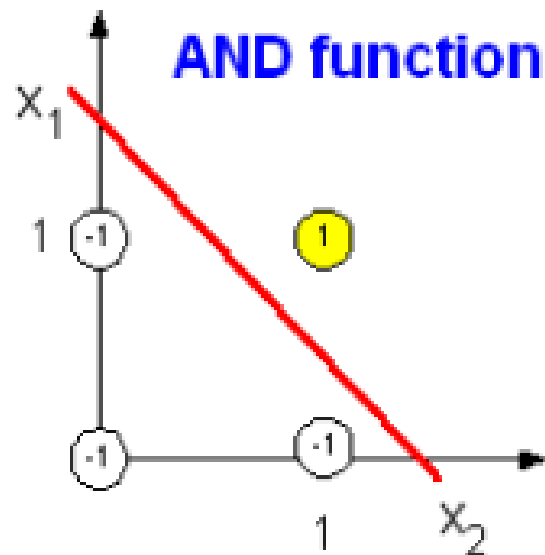


OR Function

x_1	x_2	y
0	0	0
0	1	1
1	0	1
1	1	1



AND OR Function



Perceptron Training Rule

Perceptron Training Rule

- ▶ **How to learn the weights for a single perceptron.**
 - ❑ Begin with random weights,
 - ❑ Iteratively apply the perceptron to each training example,
 - ❑ **Modifying the perceptron weights** whenever it misclassifies an example.
 - ❑ This process is repeated, iterating through the training examples as many times as needed until the perceptron classifies all training examples correctly.
 - ❑ Weights are modified at each step according to the perceptron training rule.

Perceptron Training Rule

- ▶ The ***perceptron training rule***, which revises the weight w_i associated with input x_i according to the rule:

$$w_i \leftarrow w_i + \Delta w_i$$

where

$$\Delta w_i = \eta(t - o)x_i$$

Where:

- t is target value
- o is perceptron output
- η is small constant (e.g., 0.1) called *learning rate*

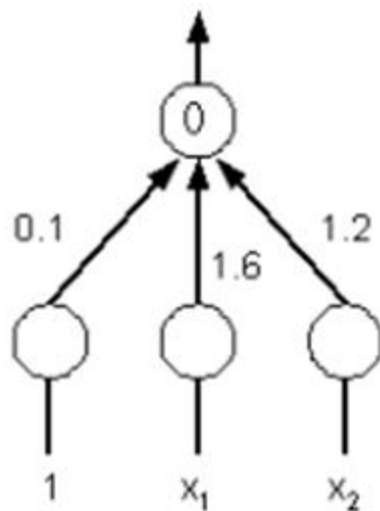
Perceptron Training Rule

training set: $x_1 = 1, x_2 = 1 \rightarrow 1$ $\eta = 0.5$

$x_1 = 1, x_2 = -1 \rightarrow -1$

$x_1 = -1, x_2 = 1 \rightarrow -1$

$x_1 = -1, x_2 = -1 \rightarrow -1$



using these updated weights:

$x_1 = 1, x_2 = 1: 0.1*1 + 1.6*1 + 1.2*1 = 2.9 \rightarrow 1$ OK

$x_1 = 1, x_2 = -1: 0.1*1 + 1.6*1 + 1.2*(-1) = 0.5 \rightarrow 1$ WRONG

$x_1 = -1, x_2 = 1: 0.1*1 + 1.6*(-1) + 1.2*1 = -0.3 \rightarrow -1$ OK

$x_1 = -1, x_2 = -1: 0.1*1 + 1.6*(-1) + 1.2*(-1) = -2.7 \rightarrow -1$ OK

$$w_i \leftarrow w_i + \Delta w_i$$

$$\Delta w_i = \eta(t - o)x_i$$

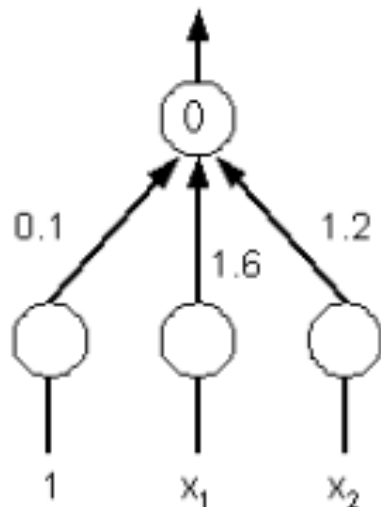
Perceptron Training Rule

training set: $x_1 = 1, x_2 = 1 \rightarrow 1$ $\eta = 0.5$

$x_1 = 1, x_2 = -1 \rightarrow -1$

$x_1 = -1, x_2 = 1 \rightarrow -1$

$x_1 = -1, x_2 = -1 \rightarrow -1$



using these updated weights:

$x_1 = 1, x_2 = 1: 0.1*1 + 1.6*1 + 1.2*1 = 2.9 \rightarrow 1$ OK

$x_1 = 1, x_2 = -1: 0.1*1 + 1.6*1 + 1.2*-1 = 0.5 \rightarrow 1$ WRONG

$x_1 = -1, x_2 = 1: 0.1*1 + 1.6*-1 + 1.2*1 = -0.3 \rightarrow -1$ OK

$x_1 = -1, x_2 = -1: 0.1*1 + 1.6*-1 + 1.2*-1 = -2.7 \rightarrow -1$ OK

new weights: $w_0 = 0.1 - 1 = -0.9$

$w_1 = 1.6 - 1 = 0.6$

$w_2 = 1.2 + 1 = 2.2$

$$w_i \leftarrow w_i + \Delta w_i$$

$$\Delta w_i = \eta(t - o)x_i$$

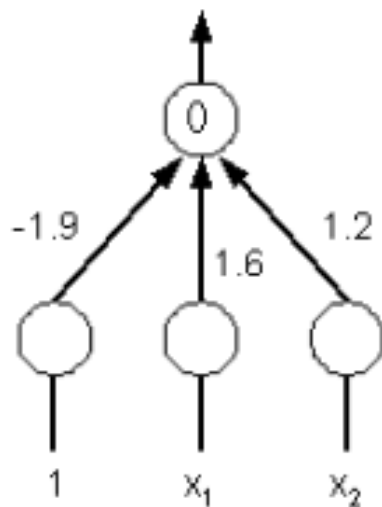
Perceptron Training Rule

training set: $x_1 = 1, x_2 = 1 \rightarrow 1$

$x_1 = 1, x_2 = -1 \rightarrow -1$

$x_1 = -1, x_2 = 1 \rightarrow -1$

$x_1 = -1, x_2 = -1 \rightarrow -1$



using these updated weights:

$x_1 = 1, x_2 = 1: -1.9*1 + 1.6*1 + 1.2*1 = 0.9 \rightarrow 1$ OK

$x_1 = 1, x_2 = -1: -1.9*1 + 1.6*1 + 1.2*-1 = -1.5 \rightarrow -1$ OK

$x_1 = -1, x_2 = 1: -1.9*1 + 1.6*-1 + 1.2*1 = -2.3 \rightarrow -1$ OK

$x_1 = -1, x_2 = -1: -1.9*1 + 1.6*-1 + 1.2*-1 = -4.7 \rightarrow -1$ OK

DONE!

Perceptron Training Rule

Example:

- The training rule **will increase w** , if $(t - o)$, η and x_i **are all positive**.

- ❑ if $x_i = 0.8$, $\eta = 0.1$, $t = 1$, and $o = -1$, then the weight update will be

$$\Delta w_i = \eta(t - o)x_i = 0.1(1 - (-1))0.8 = 0.16.$$

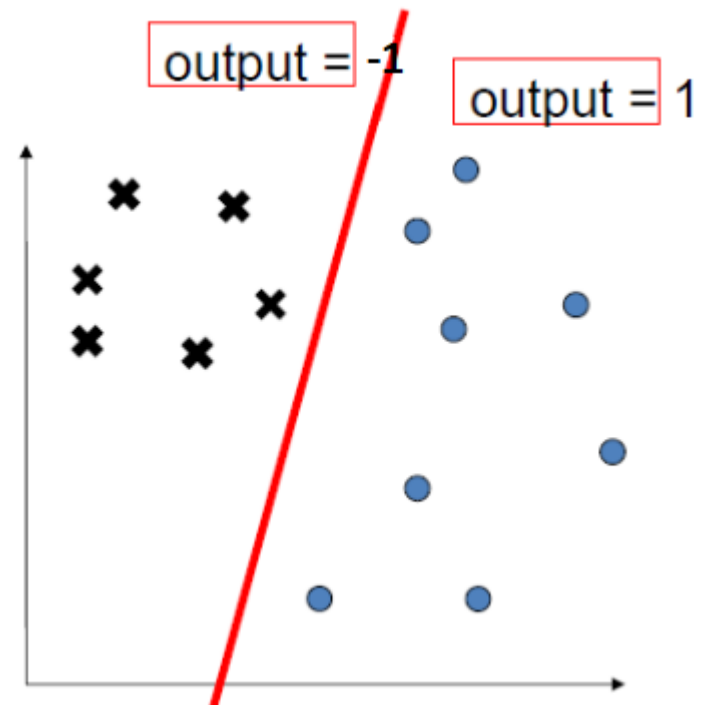
- On the other hand,

- ❑ if $x_i = 0.8$, $\eta = 0.1$, $t = -1$ and $o = 1$, then weights associated with positive x_i will be decreased rather than increased.

$$\Delta w_i = \eta(t - o)x_i = 0.1(-1 - (1))0.8 = -0.16.$$

Perceptron Training Rule

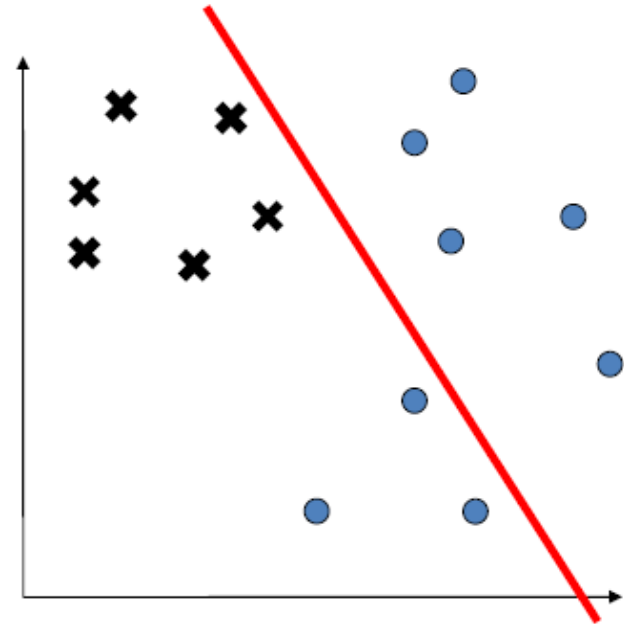
$$\begin{cases} \sum_{i=1}^M w_i x_i > 0 & \text{output} = 1 \\ \text{else} & \text{output} = -1 \end{cases}$$



Perceptron Training Rule

$$\begin{cases} \sum_{i=1}^M w_i x_i > 0 & \text{output} = 1 \\ \text{else} & \text{output} = -1 \end{cases}$$

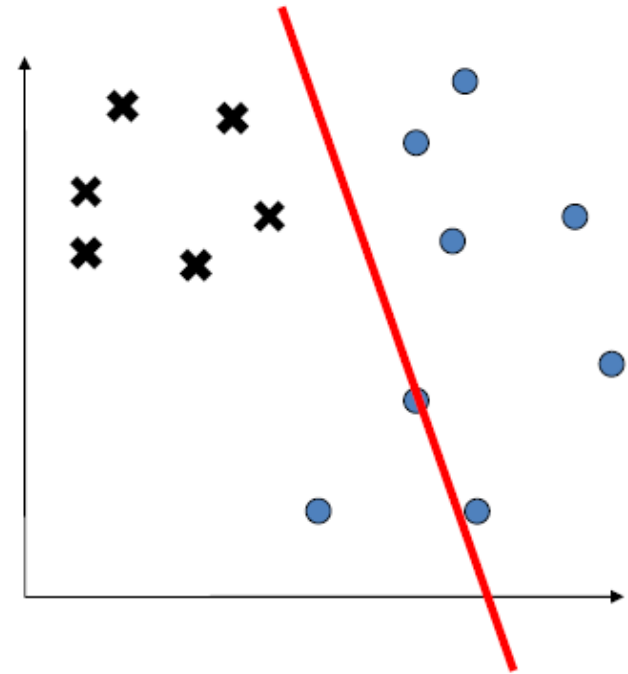
$$w_1 = 1, w_2 = 0.2, w_0 = 0.05$$



Perceptron Training Rule

$$\begin{cases} \sum_{i=1}^M w_i x_i > 0 & \text{output} = 1 \\ \text{else} & \text{output} = -1 \end{cases}$$

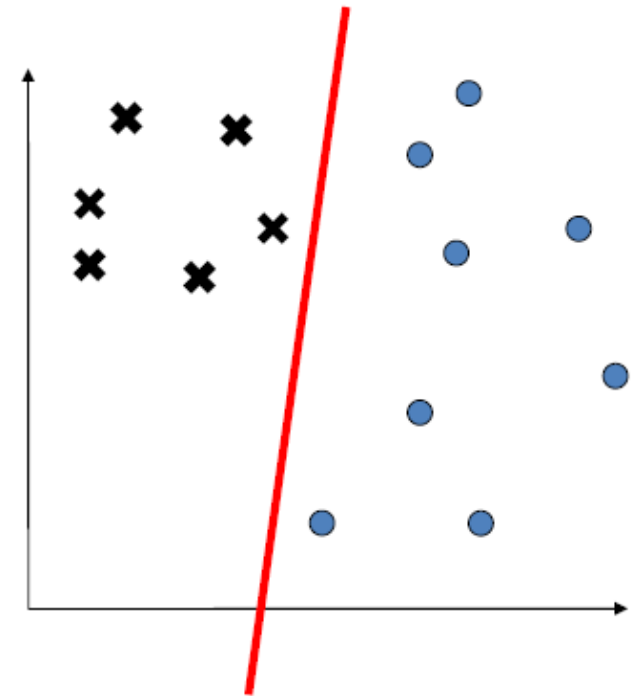
$w_1 = 2.1, w_2 = 0.2, w_0 = 0.05$



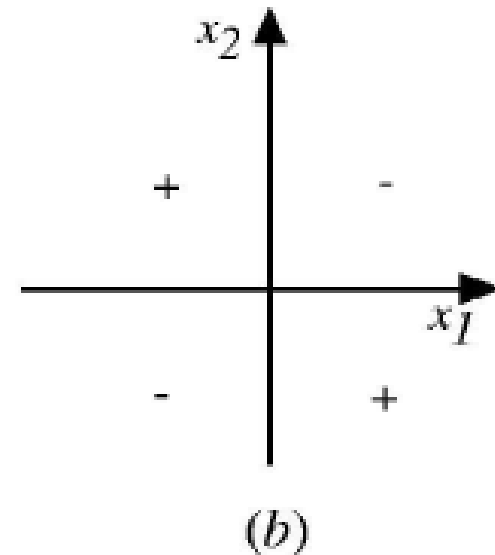
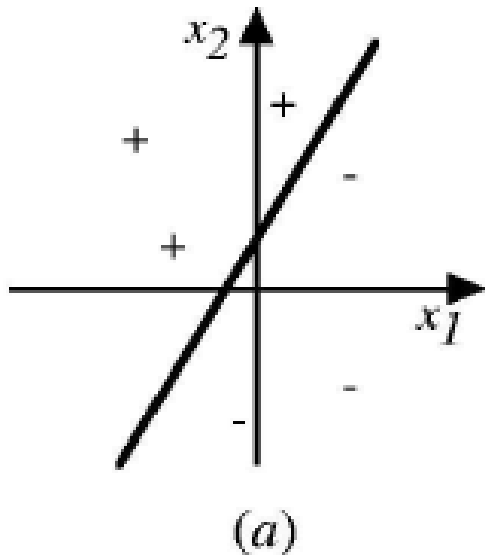
Perceptron Training Rule

$$\begin{cases} \sum_{i=1}^M w_i x_i > 0 & \text{output} = 1 \\ \text{else} & \text{output} = -1 \end{cases}$$

$$w_1 = -0.8, w_2 = 0.03, w_0 = 0.05$$



Perceptron



The **decision surface** represented by a **two-input perceptron x_1 and x_2** .
(a) A set of training examples and the decision surface of a perceptron that classifies them correctly. (b) A set of training examples that is not linearly separable.

Perceptron Training Rule

- ▶ The **perceptron rule** finds a successful weight vector when the training examples are **linearly separable**,
- ▶ It fails to converge if the examples are **not linearly separable**.
- ▶ The solution is ... **Delta Rule** also known as (**Widrow-Hoff Rule**)

Delta Rule

- ▶ use ***gradient descent*** to search the hypothesis space of possible weight vectors to find the weights that best fit the training examples.

Reading Material

- ▶ **Artificial Intelligence, A Modern Approach**
Stuart J. Russell and Peter Norvig
 - Chapter 18.
- ▶ **Machine Learning**
Tom M. Mitchell
 - Chapter 4.

