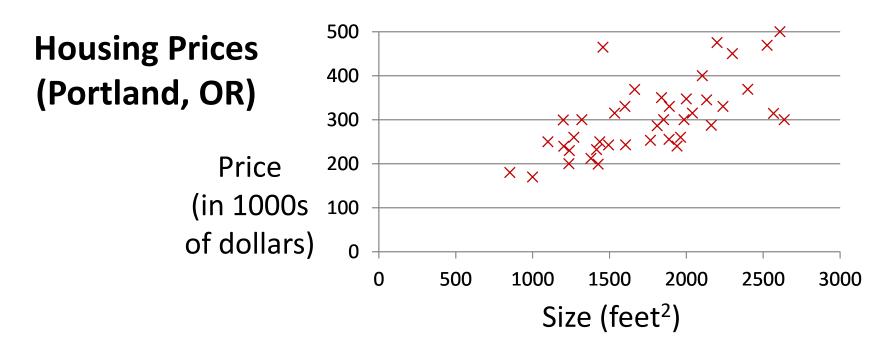


Machine Learning

Model representation



Supervised Learning

Given the "right answer" for each example in the data.

Regression Problem

Predict real-valued output

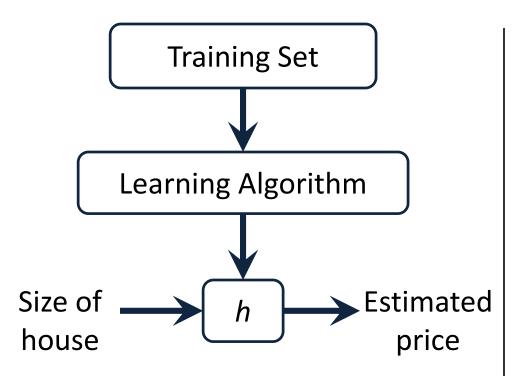
Training set of	Size in feet ² (x)	Price (\$) in 1000's (y)
housing prices	2104	460
(Portland, OR)	1416	232
	1534	315
	852	178

Notation:

```
m = Number of training examples
```

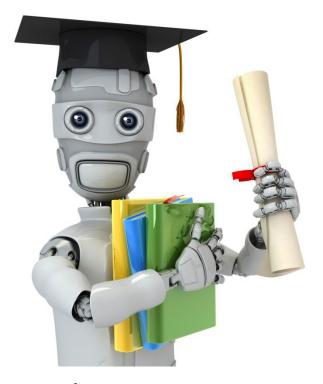
x's = "input" variable / features

y's = "output" variable / "target" variable



How do we represent *h* ?

Linear regression with one variable. Univariate linear regression.



Machine Learning

Linear regression with one variable

Cost function

Training Set

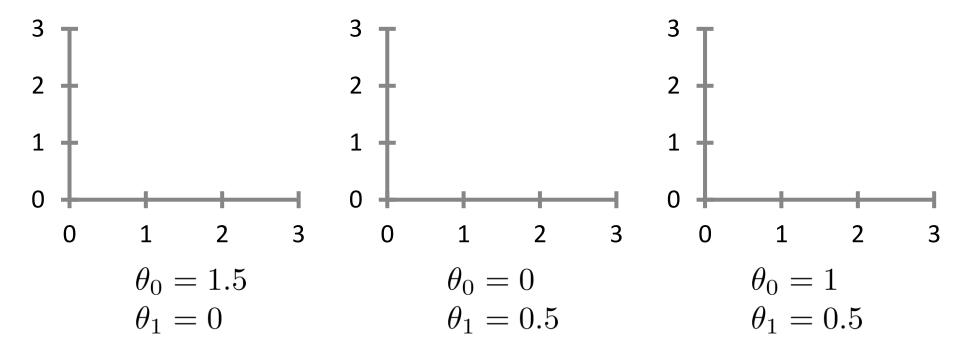
Size	in feet ² (x)	Price (\$) in 1000's (y)
	2104	460
	1416	232
	1534	315
	852	178
	•••	•••

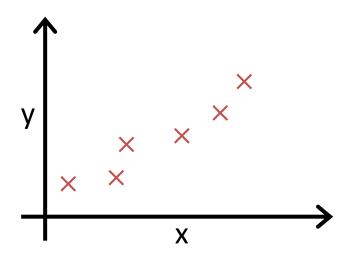
Hypothesis:
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

 θ_i 's: Parameters

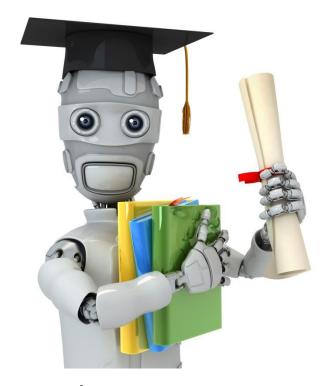
How to choose θ_i 's ?

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$





Idea: Choose θ_0, θ_1 so that $h_{\theta}(x)$ is close to y for our training examples (x,y)



Machine Learning

Cost function intuition I

Simplified

Hypothesis:

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

 $h_{\theta}(x) = \theta_1 x$

Parameters:

$$\theta_0, \theta_1$$

 $J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$

Goal:
$$\min_{\theta_0,\theta_1} \sum_{i=1}^{2m} (\theta_0,\theta_1)$$

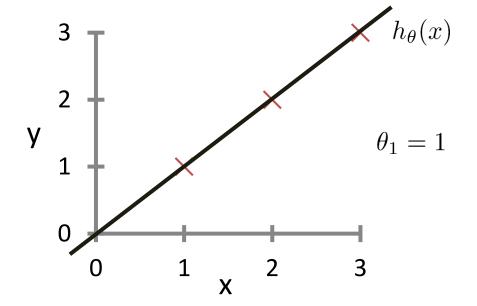
$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

$$\min_{\theta_1} \text{minimize } J(\theta_1)$$

Andrew Ng

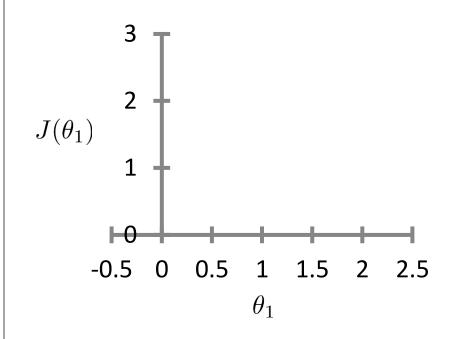
$h_{\theta}(x)$

(for fixed θ_1 , this is a function of x)



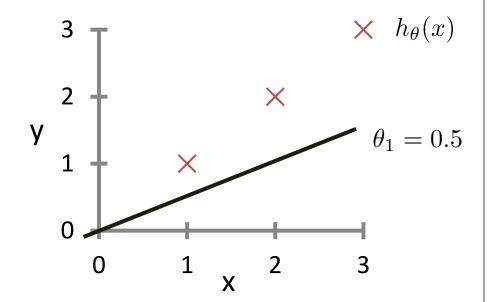


(function of the parameter θ_1)



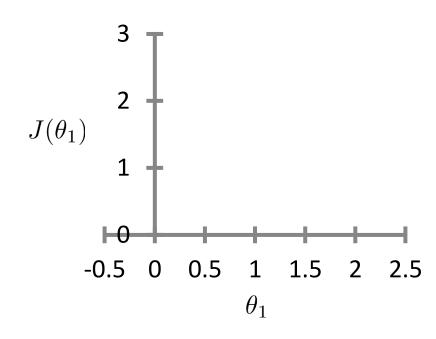
$h_{\theta}(x)$

(for fixed θ_1 , this is a function of x)



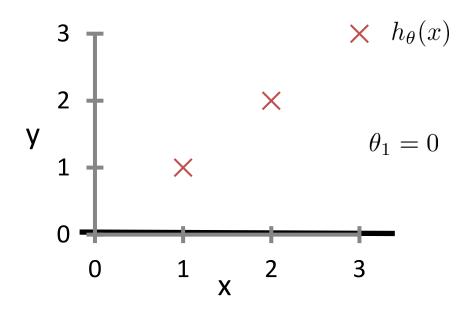


(function of the parameter θ_1)



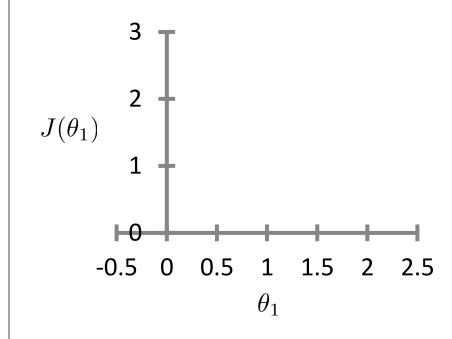
$h_{\theta}(x)$

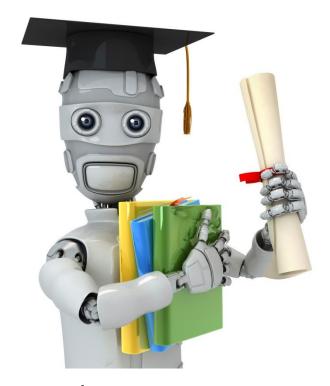
(for fixed θ_1 , this is a function of x)





(function of the parameter θ_1)





Machine Learning

Cost function intuition II

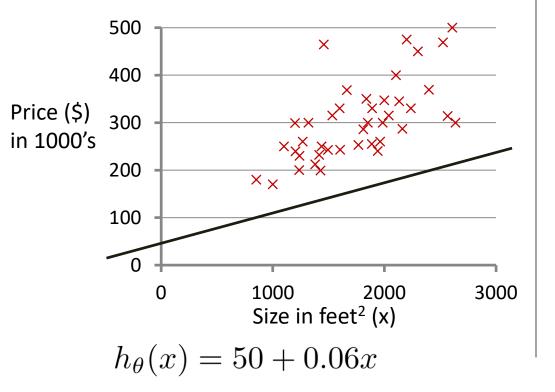
Hypothesis:
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

Parameters:
$$\theta_0, \theta_1$$

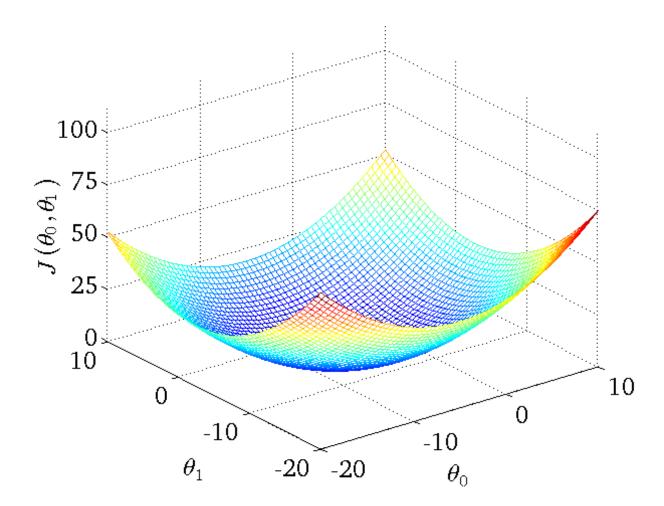
Cost Function:
$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

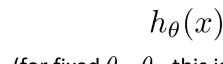
Goal:
$$\min_{\theta_0, \theta_1} \text{minimize } J(\theta_0, \theta_1)$$

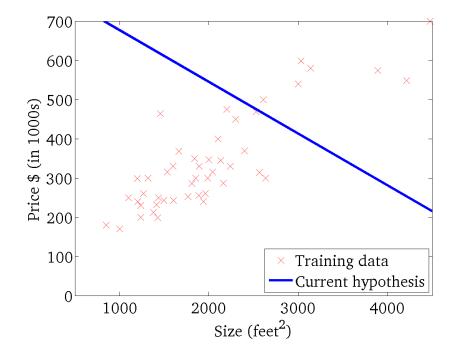




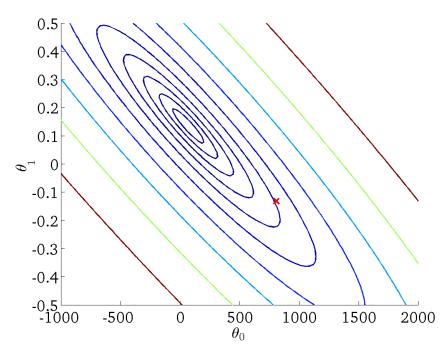
 $J(\theta_0,\theta_1)$



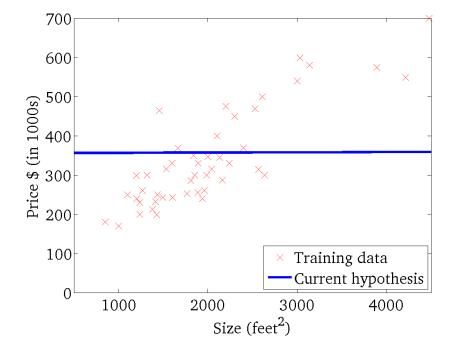




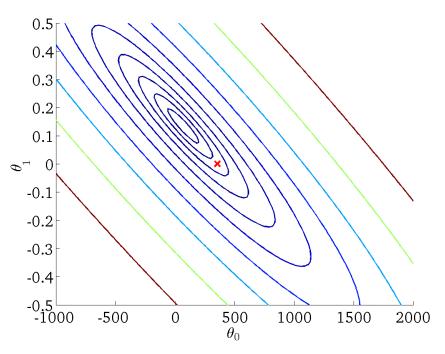
 $J(\theta_0, \theta_1)$



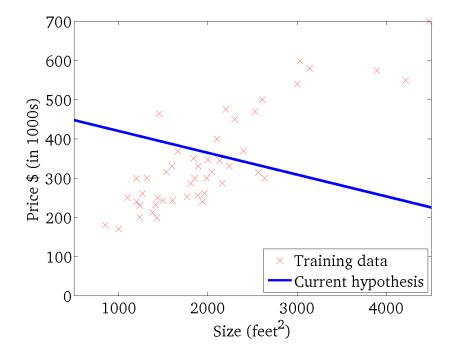




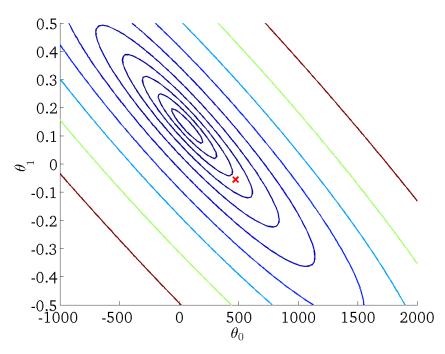
 $J(\theta_0, \theta_1)$



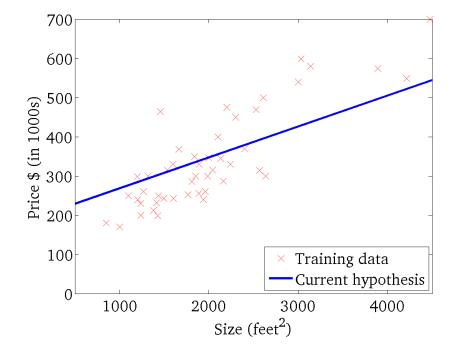




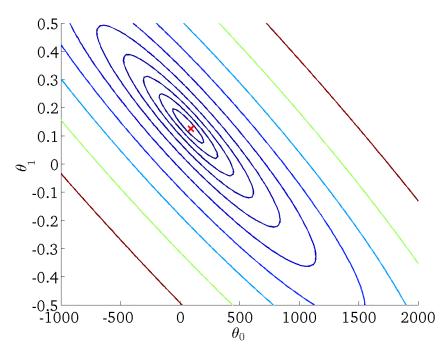
 $J(\theta_0, \theta_1)$

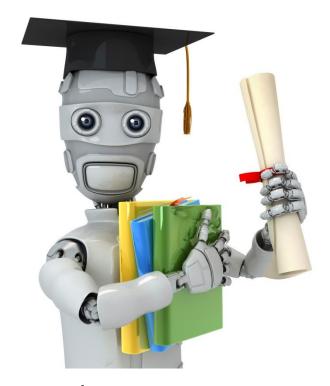






 $J(\theta_0, \theta_1)$





Machine Learning

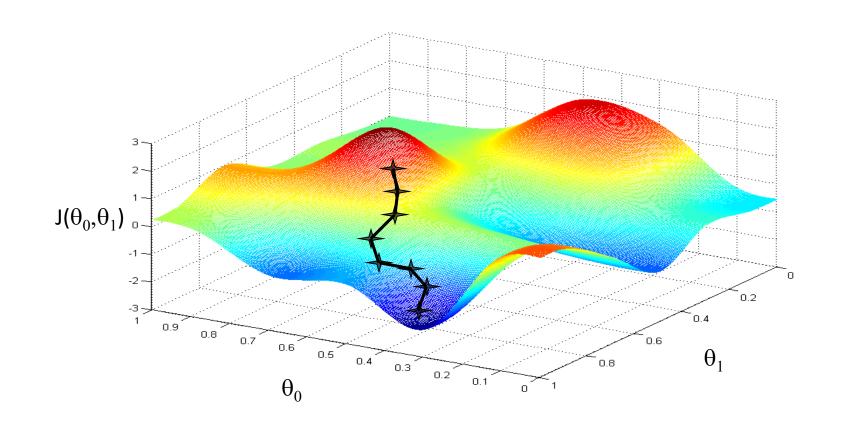
Gradient descent

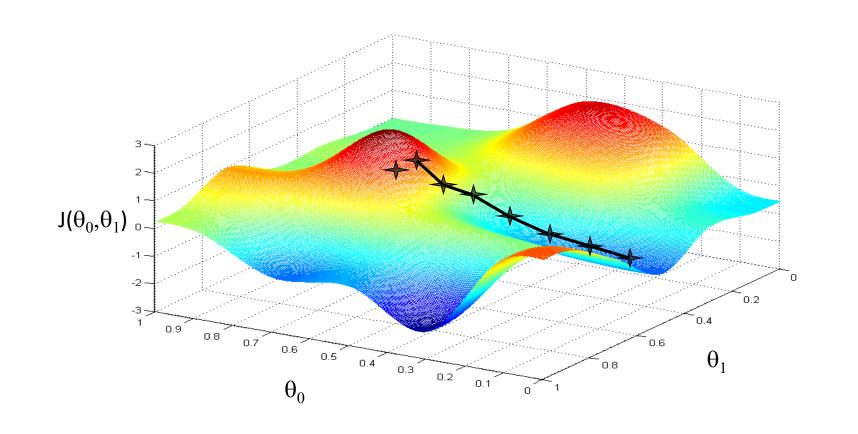
Have some function $J(\theta_0, \theta_1)$

Want
$$\min_{ heta_0, heta_1} J(heta_0, heta_1)$$

Outline:

- Start with some θ_0, θ_1
- Keep changing $heta_0, heta_1$ to reduce $J(heta_0, heta_1)$ until we hopefully end up at a minimum





Gradient descent algorithm

repeat until convergence {
$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad \text{(for } j = 0 \text{ and } j = 1)$$
 }

Correct: Simultaneous update

$$temp0 := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

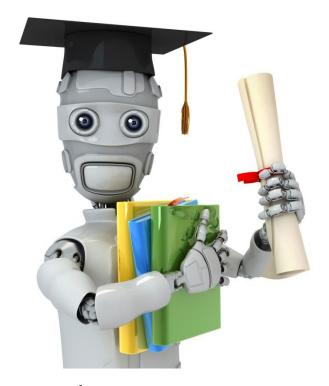
$$temp1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\theta_0 := temp0$$

$$\theta_1 := temp1$$

Incorrect:

$$\begin{array}{l} \operatorname{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) \\ \theta_0 := \operatorname{temp0} \\ \operatorname{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1) \\ \theta_1 := \operatorname{temp1} \end{array}$$

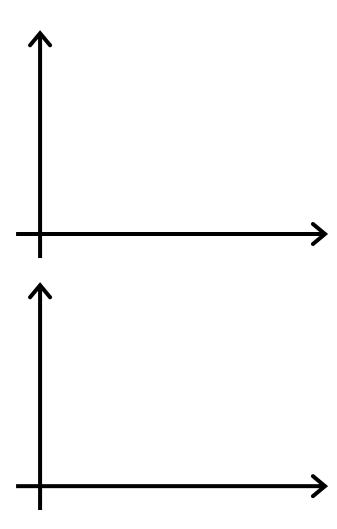


Machine Learning

Gradient descent intuition

Gradient descent algorithm

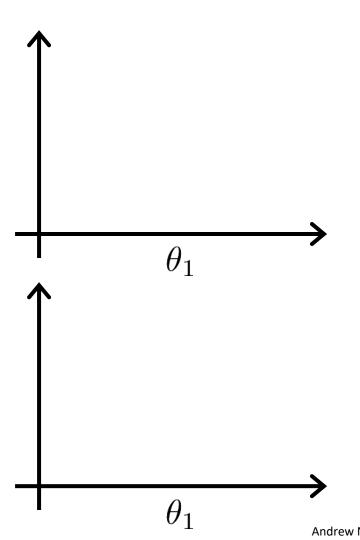
```
repeat until convergence { \theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) \quad \text{(simultaneously update } j = 0 \text{ and } j = 1) }
```

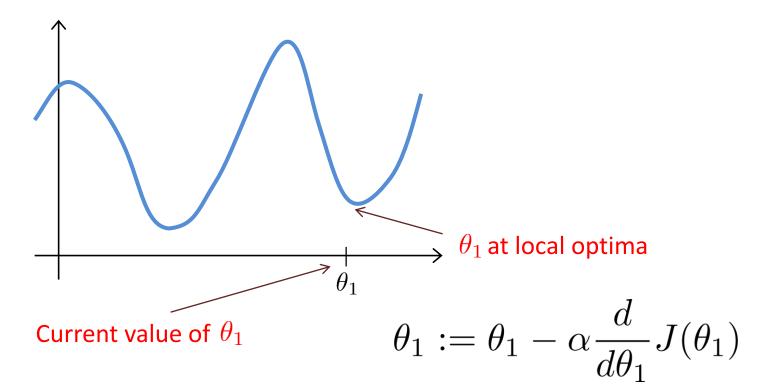


$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If α is too small, gradient descent can be slow.

If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.

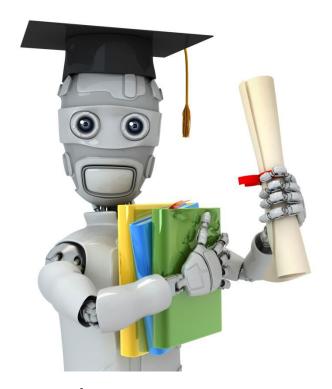




Gradient descent can converge to a local minimum, even with the learning rate α fixed.

time.

$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$
 As we approach a local $J(\theta_1)$ minimum, gradient descent will automatically take smaller steps. So, no need to decrease α over θ_1



Machine Learning

Linear regression with one variable

Gradient descent for linear regression

Gradient descent algorithm

repeat until convergence { $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$ (for j = 1 and j = 0)

Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

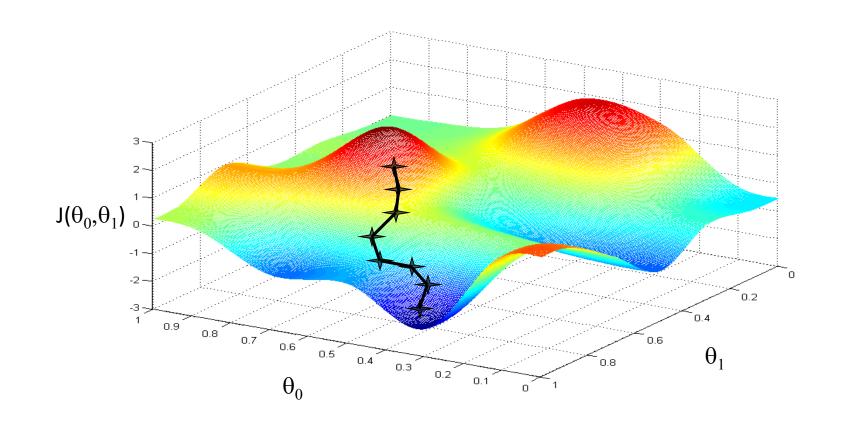
$$\frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1) =$$

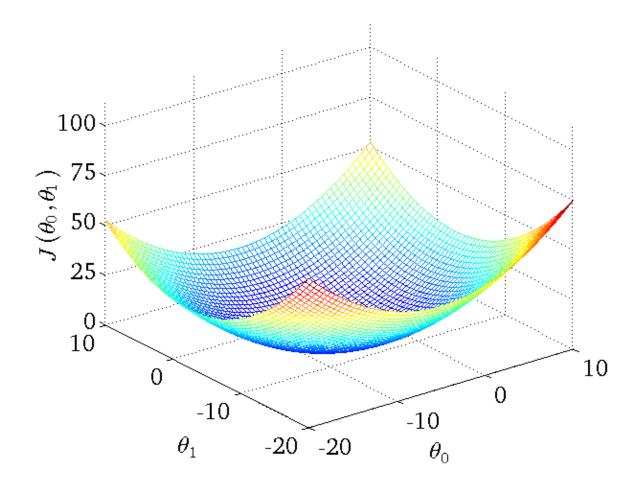
$$j = 0 : \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1) =$$

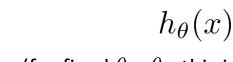
$$j=1: \frac{\partial}{\partial \theta_1} J(\theta_0,\theta_1) =$$

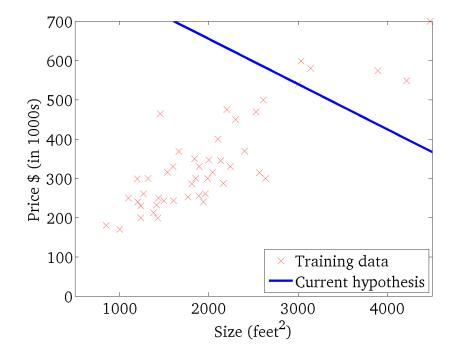
Gradient descent algorithm

 $\begin{array}{l} \text{repeat until convergence } \{ \\ \theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right) \\ \theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m \left(h_\theta(x^{(i)}) - y^{(i)} \right) \cdot x^{(i)} \end{array} \right] \begin{array}{l} \text{update} \\ \theta_0 \text{ and } \theta_1 \\ \text{simultaneously} \end{array}$

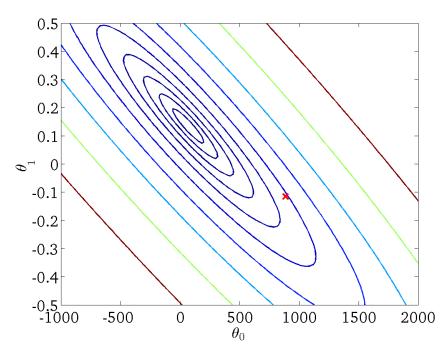




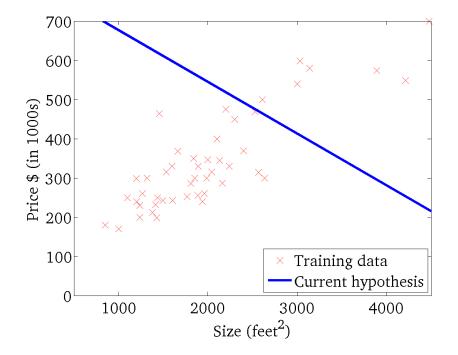




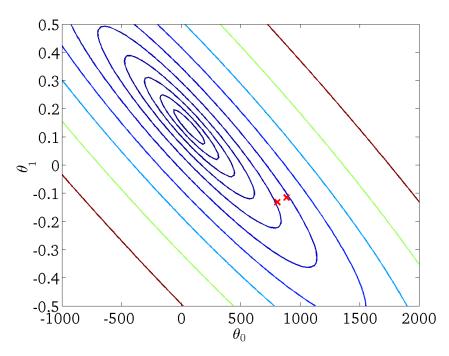
 $J(\theta_0, \theta_1)$

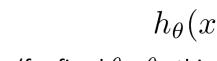


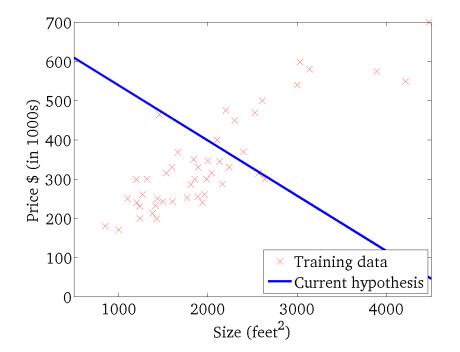




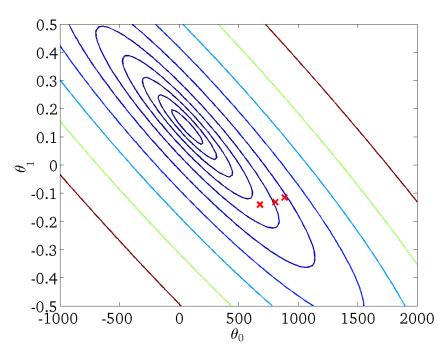
 $J(\theta_0, \theta_1)$

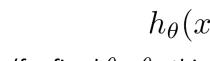


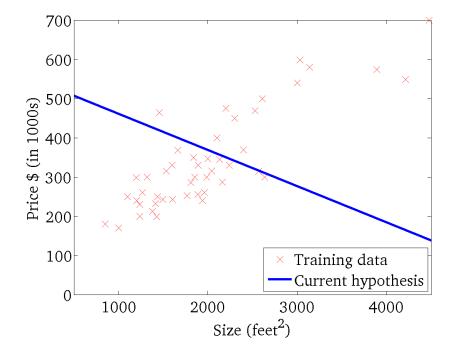




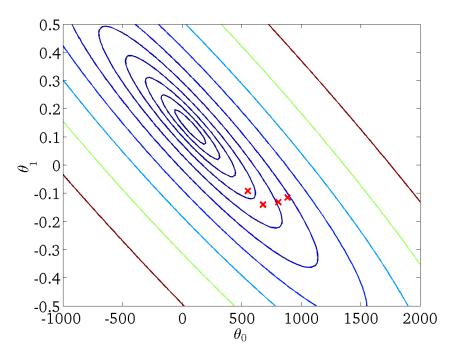
 $J(\theta_0, \theta_1)$



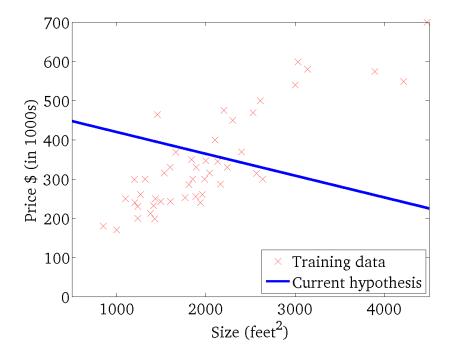




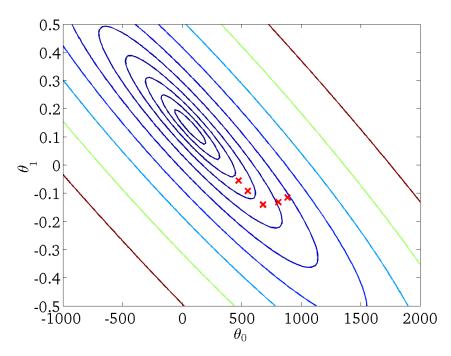
 $J(\theta_0, \theta_1)$



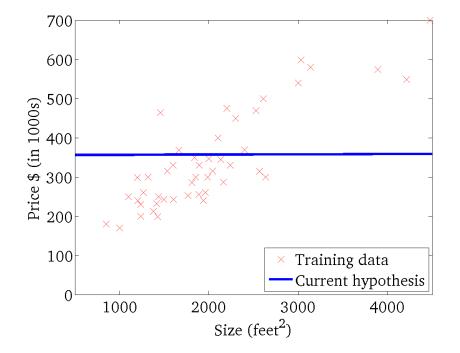




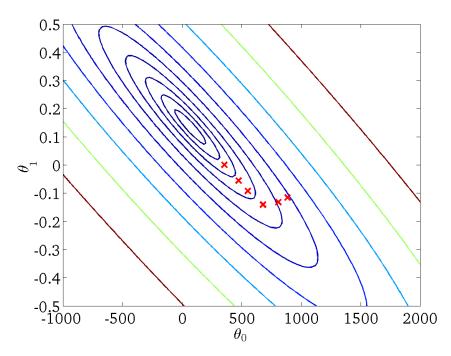
 $J(\theta_0, \theta_1)$



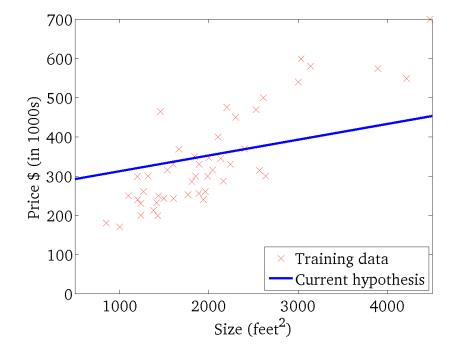




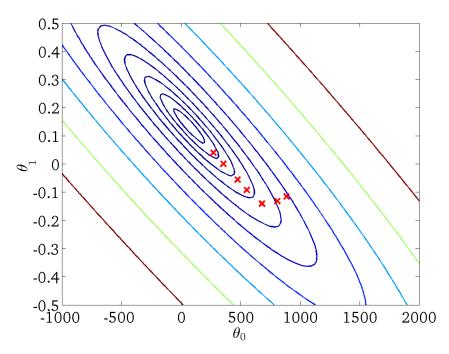
 $J(\theta_0, \theta_1)$



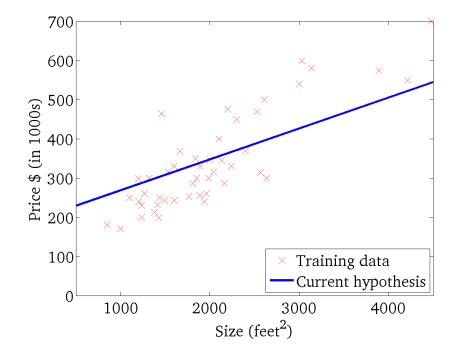




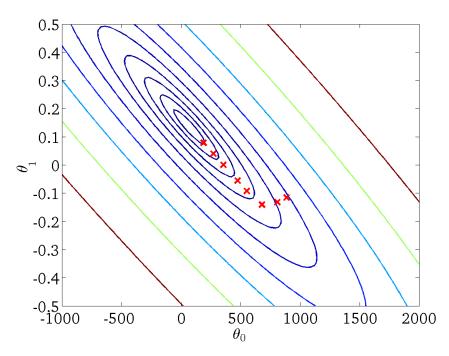
 $J(\theta_0, \theta_1)$



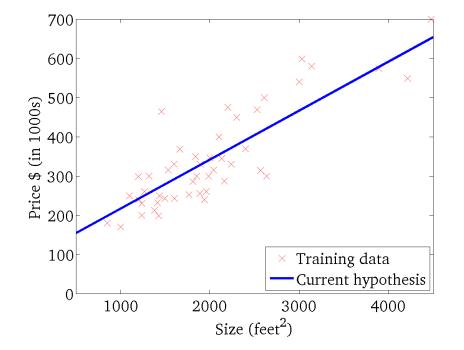




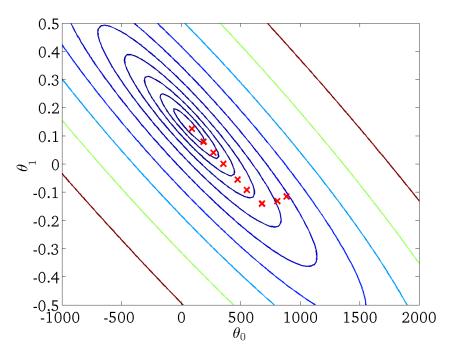
 $J(\theta_0, \theta_1)$







 $J(\theta_0, \theta_1)$



"Batch" Gradient Descent

"Batch": Each step of gradient descent uses all the training examples.