

# ArcSoft Face Detection

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开发指导文档

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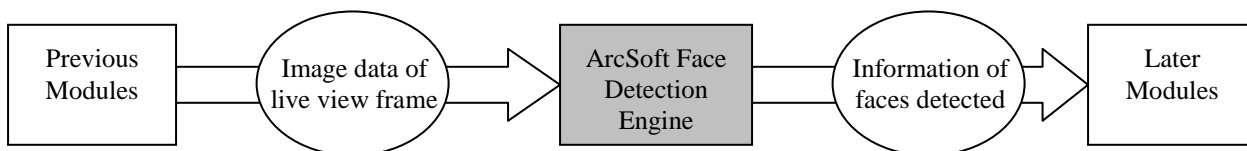
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## Chapter 1: 概述

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虹软人脸检测引擎工作流程图：



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### 1.1. 运行环境

- Windows

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### 1.2. 系统要求

- 32 位系统， Windows7 以上

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### 1.3. 依赖库

- None

## Chapter 2: 结构与常量

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### 2.1. 基本类型

```
typedef MInt32 AFD_FSDK_OrientPriority;  
typedef MInt32 AFD_FSDK_OrientCode;
```

所有基本类型在平台库中有定义。定义规则是在 ANSIC 中的基本类型前加上字母“M”同时将类型的第一个字母改成大写。例如“long”被定义成“MLong”

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### 2.2. 数据结构与枚举

#### 2.2.1. AFD\_FSDK\_FACERES

##### 描述

检测到的脸部信息

##### 定义

```
typedef struct {  
    MLong      nFace;  
    MRECT      * rcFace;  
    AFD_FSDK_OrientCode * lfaceOrient;  
} AFD_FSDK_FACERES, * LPAFD_FSDK_FACERES;
```

##### 成员变量

nFace	人脸个数
rcFace	人脸矩形框信息
lfaceOrient	人脸角度信息

#### 2.2.2. AFD\_FSDK\_Face3Dangle

##### 描述

检测到的脸部角度信息

##### 定义

```
typedef struct {  
    MInt32 nFace;
```

```
MFloat* rollAngle;  
MFloat* yawAngle;  
MFloat* pitchAngle;  
MInt32* status;  
} AFD_FSDK_Face3Dangle, *LPAFD_FSDK_Face3Dangle;
```

### 成员变量

nFace	人脸个数
rollAngle	人脸横滚角 roll
yawAngle	人脸偏航角 yaw
pitchAngle	人脸俯仰角 pitch
status	人脸角度检测成功标志位, 0 正常, 其他值错误

## 2.2.3. AFD\_FSDK\_VERSION

### 描述

SDK 版本信息

### 定义

```
typedef struct  
{  
    MInt32 lCodebase;  
    MInt32 lMajor;  
    MInt32 lMinor;  
    MInt32 lBuild;  
    MPChar Version;  
    MPChar BuildDate;  
    MPChar CopyRight;  
} ArcSoft_Face_Detection_Version;
```

### 成员描述

lCodebase	代码库版本号
lMajor	主版本号
lMinor	次版本号
lBuild	编译版本号, 递增
Version	字符串形式的版本号
BuildDate	编译时间
CopyRight	copyright

## 2.2.4. AFD\_FSDK\_OrientPriority

### 描述

定义脸部检测角度的优先级

### 定义

```
enum _AFD_FSDK_OrientPriority{
    AFD_FSDK_OPF_0_ONLY          = 0x1,
    AFD_FSDK_OPF_90_ONLY         = 0x2,
    AFD_FSDK_OPF_270_ONLY        = 0x3,
    AFD_FSDK_OPF_180_ONLY        = 0x4,
    AFD_FSDK_OPF_0_HIGHER_EXT     = 0x5
};
```

### 成员描述

AFD_FSDK_OPF_0_ONLY	检测 0 度方向
AFD_FSDK_OPF_90_ONLY	检测 90 度方向
AFD_FSDK_OPF_270_ONLY	检测 270 度方向
AFD_FSDK_OPF_180_ONLY	检测 180 度方向
AFD_FSDK_OPF_0_HIGHER_EXT	检测 0, 90, 180, 270 四个方向, 0 度更优先

## 2.2.5. AFD\_FSDK\_OrientCode

### 描述

定义检测结果中的人脸角度

### 定义

```
enum _AFD_FSDK_OrientCode{
    AFD_FSDK_FOC_0    = 0x1,
    AFD_FSDK_FOC_90   = 0x2,
    AFD_FSDK_FOC_270  = 0x3,
    AFD_FSDK_FOC_180  = 0x4,
    AFD_FSDK_FOC_30   = 0x5,
    AFD_FSDK_FOC_60   = 0x6,
    AFD_FSDK_FOC_120  = 0x7,
    AFD_FSDK_FOC_150  = 0x8,
    AFD_FSDK_FOC_210  = 0x9,
```

```
AFD_FSDK_FOC_240 = 0xa,  
AFD_FSDK_FOC_300 = 0xb,  
AFD_FSDK_FOC_330 = 0xc  
};
```

### 成员描述

AFD_FSDK_FOC_0	0 度
AFD_FSDK_FOC_90	90 度
AFD_FSDK_FOC_270	270 度
AFD_FSDK_FOC_180	180 度
AFD_FSDK_FOC_30	30 度
AFD_FSDK_FOC_60	60 度
AFD_FSDK_FOC_120	120 度
AFD_FSDK_FOC_150	150 度
AFD_FSDK_FOC_210	210 度
AFD_FSDK_FOC_240	240 度
AFD_FSDK_FOC_300	300 度
AFD_FSDK_FOC_330	330 度

## 2.2.6. 支持的颜色格式

### 描述

颜色格式及其对齐规则

### 定义

ASVL_PAF_I420	8-bit Y 层，之后是 8-bit 的 2x2 采样的 U 层和 V 层
ASVL_PAF_YUYV	Y0, U0, Y1, V0
ASVL_PAF_RGB24_B8G8R8	BGR24, B8G8R8



## Chapter 3: API 说明

---

### 3.1. AFD\_FSDK\_InitialFaceEngine

#### 原型

```
MRESULT AFD_FSDK_InitialFaceEngine(  
    MPChar                AppId,  
    MPChar                SDKKey,  
    MByte                 *pMem,  
    MInt32                lMemSize,  
    MHandle               *pEngine,  
    AFD_FSDK_OrientPriority iOrientPriority,  
    MInt32                nScale,  
    MInt32                nMaxFaceNum  
);
```

#### 描述

初始化脸部检测引擎

#### 参数

AppId	[in]	用户申请 SDK 时获取的 App Id
SDKKey	[in]	用户申请 SDK 时获取的 SDK Key
pMem	[in]	分配给引擎使用的内存地址
lMemSize	[in]	分配给引擎使用的内存大小
pEngine	[out]	引擎 handle
iOrientPriority	[in]	期望的脸部检测角度的优先级
nScale	[in]	用于数值表示的最小人脸尺寸 有效值范围 [2, 50] 推荐值 16
nMaxFaceNum	[in]	用户期望引擎最多能检测出的人脸数 有效值范围 [1, 100]

#### 返回值

成功返回 MOK，否则返回失败 code。失败 codes 如下所列：

MERR_INVALID_PARAM	参数输入非法
MERR_NO_MEMORY	内存不足

---

### 3.2. AFD\_FSDK\_StillImageFaceDetection

#### 原型

```
MRESULT AFD_FSDK_StillImageFaceDetection(  

```

```
MHandle          hEngine,  
LPASVLOFFSCREEN  pImgData,  
LPAFD_FSDK_FACERES *pFaceRes  
);
```

### 描述

根据输入的图像检测出人脸位置，一般用于静态图像检测

### 参数

hEngine	[in]	引擎 handle
pImgData	[in]	带检测图像信息
pFaceRes	[out]	人脸检测结果

### 返回值

成功返回 MOK，否则返回失败 code。

---

## 3.3. AFD\_FSDK\_FaceAngleDetect

### 原型

```
MRESULT AFD_FSDK_FaceAngleDetect(  
    MHandle hEngine,  
    LPASVLOFFSCREEN pImgData,  
    LPAFD_FSDK_FACERES pFaceRes,  
    LPAFD_FSDK_Face3Dangle pFace3Dangle  
);
```

### 描述

根据输入的图像和人脸框，得到人脸角度信息

### 参数

hEngine	[in]	引擎 handle
pImgData	[in]	带检测图像信息
pFaceRes	[in]	输入人脸信息
pFace3Dangle	[out]	人脸角度检测结果

### 返回值

成功返回 MOK，否则返回失败 code。

---

## 3.4. AFD\_FSDK\_UninitialFaceEngine

### 原型

```
MRESULT AFD_FSDK_UninitialFaceEngine(  
    MHandle      hEngine  
);
```

### 描述

销毁引擎，释放相应资源

### 参数

hEngine                      [in]          引擎 handle

### 返回值

成功返回 MOK，否则返回失败 code。失败 codes 如下所列：

MERR\_INVALID\_PARAM          参数输入非法

---

## 3.5. AFD\_FSDK\_GetVersion

### 原型

```
const AFD_FSDK_Version * AFD_FSDK_GetVersion(  
    MHandle      hEngine  
);
```

### 描述

获取 SDK 版本信息

### 参数

hEngine                      [in]          引擎 handle

## Chapter 4: 示例代码

---

注意,使用时请替换申请的 **APPID SDKKEY**, 并设置好文件路径和图像尺寸

```
#include <stdio.h>
#include <stdlib.h>
#include <stdint.h>
#include "arcsoft_fsdk_face_detection.h"
#include "merror.h"

#pragma comment(lib,"libarcsoft_fsdk_face_detection.lib")

#define WORKBUF_SIZE      (30*1024*1024)
#define APPID             ""           //APPID
#define SDKKey            ""           //SDKKey

int main()
{
    /* 初始化引擎和变量 */
    MRESULT nRet = MERR_UNKNOWN;
    MHandle hEngine = nullptr;
    MInt32 nScale = 16;
    MInt32 nMaxFace = 10;
    MByte *pWorkMem = (MByte *)malloc(WORKBUF_SIZE);
    if (pWorkMem == nullptr)
    {
        return -1;
    }
    nRet = AFD_FSDK_InitialFaceEngine(APPID, SDKKey, pWorkMem, WORKBUF_SIZE,
    &hEngine, AFD_FSDK_OPF_0_HIGHER_EXT, nScale, nMaxFace);
    if (nRet != MOK)
    {
        return -1;
    }
    /* 打印版本信息 */
    const AFD_FSDK_Version * pVersionInfo = nullptr;
    pVersionInfo = AFD_FSDK_GetVersion(hEngine);
    printf("%d %d %d %d\n", pVersionInfo->lCodebase, pVersionInfo->lMajor,
    pVersionInfo->lMinor, pVersionInfo->lBuild);
    printf("%s\n", pVersionInfo->Version);
    printf("%s\n", pVersionInfo->BuildDate);
    printf("%s\n", pVersionInfo->CopyRight);

    /* 读取静态图片信息, 并保存到ASVLOFFSCREEN结构体 (以ASVL_PAF_RGB24_B8G8R8格式
    为例) imagedata为BGR原始数据 */
    ASVLOFFSCREEN offInput = { 0 };
    offInput.u32PixelFormat = INPUT_IMAGE_FORMAT;
    offInput.i32Width = INPUT_IMAGE_WIDTH;
    offInput.i32Height = INPUT_IMAGE_HEIGHT;
    offInput.ppu8Plane[0] = imagedata;
    if (ASVL_PAF_I420 == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width;
        offInput.pi32Pitch[1] = offInput.i32Width/2;
    }
}
```

```

        offInput.pi32Pitch[2] = offInput.i32Width/2;
        offInput.ppu8Plane[1] = offInput.ppu8Plane[0] + offInput.pi32Pitch[0] *
offInput.i32Height;
        offInput.ppu8Plane[2] = offInput.ppu8Plane[1] + offInput.pi32Pitch[1] *
offInput.i32Height/2;
    } else if (ASVL_PAF_NV12 == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width;
        offInput.pi32Pitch[1] = offInput.i32Width;
        offInput.ppu8Plane[1] = offInput.ppu8Plane[0] + (offInput.pi32Pitch[0] *
offInput.i32Height);
    } else if (ASVL_PAF_NV21 == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width;
        offInput.pi32Pitch[1] = offInput.i32Width;
        offInput.ppu8Plane[1] = offInput.ppu8Plane[0] + (offInput.pi32Pitch[0] *
offInput.i32Height);
    } else if (ASVL_PAF_YUYV == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width*2;
    } else if (ASVL_PAF_I422H == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width;
        offInput.pi32Pitch[1] = offInput.i32Width / 2;
        offInput.pi32Pitch[2] = offInput.i32Width / 2;
        offInput.ppu8Plane[1] = offInput.ppu8Plane[0] + offInput.pi32Pitch[0] *
offInput.i32Height;
        offInput.ppu8Plane[2] = offInput.ppu8Plane[1] + offInput.pi32Pitch[1] *
offInput.i32Height;
    } else if (ASVL_PAF_LPI422H == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width;
        offInput.pi32Pitch[1] = offInput.i32Width;
        offInput.ppu8Plane[1] = offInput.ppu8Plane[0] + (offInput.pi32Pitch[0] *
offInput.i32Height);
    } else if (ASVL_PAF_RGB24_B8G8R8 == offInput.u32PixelFormat) {
        offInput.pi32Pitch[0] = offInput.i32Width*3;
    } else {
        printf("unsupported Image format: 0x%x\r\n",offInput.u32PixelFormat);
        AFD_FSDK_UninitialFaceEngine(hEngine);
        free(pWorkMem);
        return -1;
    }
}

/* 人脸检测 */
LPAFD_FSDK_FACERES FaceRes = nullptr;
AFD_FSDK_Face3Dangle face3dAngle = { 0 };
nRet = AFD_FSDK_StillImageFaceDetection(hEngine, &offInput, &FaceRes);
if (nRet != MOK)
{
    printf("Face Detection failed, error code: %d\r\n", nRet);
}
else
{
    printf("The number of face: %d\r\n", FaceRes->nFace);
    for (int i = 0; i < FaceRes->nFace; ++i)
    {
        printf("Face[%d]: rect[%d,%d,%d,%d], Face orient: %d\r\n", i,
FaceRes->rcFace[i].left, FaceRes->rcFace[i].top, FaceRes->rcFace[i].right,
FaceRes->rcFace[i].bottom, FaceRes->lfaceOrient[i]);
    }
}

```

```
        if(FaceRes->nFace > 0)
        {
            nRet = AFD_FSDK_FaceAngleDetect(hEngine, &offInput, FaceRes,
&face3dAngle);
            if(nRet != MOK)
            {
                printf("AFD_FSDK_FaceAngleDetect failed, error
code: %d\n", nRet);
            }
            else
            {
                for (int i = 0; i < face3dAngle.nFace; ++i)
                {
                    printf("Face[%d]: roll:%f, yaw:%f, pitch:%f\n",
i, face3dAngle.rollAngle[i], face3dAngle.yawAngle[i], face3dAngle.pitchAngle[i]);
                }
            }
        }
    }
    /* 释放引擎和内存 */
    nRet = AFD_FSDK_UninitialFaceEngine(hEngine);
    if (nRet != MOK)
    {
        printf("UninitialFaceEngine failed , errorcode is %d \n", nRet);
    }
    free(pWorkMem);
    return 0;
}
```