

Part 1

AK-0003-MOY

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + c + \epsilon_t \quad (1)$$

1. ^{4/4} The AR(2) process is stationary, if its corresponding difference equation is stable.

The AR(2) model can be written as

$$(1 - \phi_1 L - \phi_2 L^2) Y_t = c + \epsilon_t \quad (2)$$

The difference equation (1) is stable provided that the roots of (3) lie outside the unit circle.

$$(1 - \phi_1 z - \phi_2 z^2) = 0 \quad (3) \quad \checkmark$$

2. ^{4/4} $E(Y_t) = \phi_1 E(Y_{t-1}) + \phi_2 E(Y_{t-2}) + c + E(\epsilon_t)$
which gives us

$$E(Y_t) = \mu = \phi_1 \mu + \phi_2 \mu + c + 0 \Rightarrow$$

$$\Rightarrow c = \mu - \phi_1 \mu - \phi_2 \mu = \mu(1 - \phi_1 - \phi_2) \Rightarrow$$

$$\Rightarrow \mu = \frac{c}{(1 - \phi_1 - \phi_2)} \quad \checkmark$$

3. ^{4/4} $(1 - 0,3z - 0,1z^2) = (1 - 0,5z)(1 + 0,2z)$

It is weakly stationary since the eigenvalues 0,5 and 0,2 are both inside the unit circle. ✓

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3. 4/4

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4. ^{4/4} The stationarity of an ARMA(1,1) process depends entirely on the autoregressive parameter ϕ_1 . The roots needs to lie outside the unit circle.

5. ^{6/6}
$$Y_t = \phi Y_{t-1} + \epsilon_t + \theta \epsilon_{t-1}$$

$$E(Y_t \epsilon_t) = \phi E(Y_{t-1} \epsilon_t) + E(\epsilon_t \epsilon_t) + \theta E(\epsilon_{t-1} \epsilon_t) =$$

$$= 0 + \sigma^2 + 0 = \sigma^2$$

No, it does not depend on time t .

6. ^{0/6}
$$E(Y_t \epsilon_{t-1}) = \phi E(Y_{t-1} \epsilon_{t-1}) + E(\epsilon_t \epsilon_{t-1}) + \theta E(\epsilon_{t-1} \epsilon_{t-1}) =$$

$$= \phi E(Y_{t-2} \epsilon_{t-1} + \epsilon_{t-1}^2 + \theta \epsilon_{t-2} \epsilon_{t-1}) + E(\epsilon_t \epsilon_{t-1}) + \theta E(\epsilon_{t-1}^2) =$$

$$= \phi \sigma^2 + \sigma^2 = \sigma^2(\phi + 1)$$

Yes, it depends on time t .

7.
$$E(Y_t \epsilon_{t-k}) = \phi E(Y_{t-k-1} \epsilon_{t-k} + \epsilon_{t-k}^2 + \theta \epsilon_{t-k-1} \epsilon_{t-k}) +$$

$$+ E(\epsilon_t \epsilon_{t-k}) + \theta E(\epsilon_{t-1} \epsilon_{t-k}) = 0$$

No, it does not depend on time t .

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Part 1

AX-0003-MDY

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Unconditional mean:

$$E(Y_t) = C + \phi E(Y_{t-1}) + \theta E(\epsilon_{t-1}) + E(\epsilon_t) \Rightarrow \\ \Rightarrow (1 - \phi) E(Y_t) = C \Rightarrow E(Y_t) = \frac{C}{1 - \phi} = 0$$

variance:

$$\gamma_0 = \text{Var}(Y_t) = E(Y_t - \mu)^2 = \int_{-\infty}^{\infty} (y_t - \mu)^2 f_{Y_t}(y_t) dy_t$$

$$\gamma_0 = E(Y_t - \mu)^2 = E(\epsilon_t^2) = \sigma^2 = 1$$

covariances

$$\gamma_1 = \phi \gamma_0 = \phi$$

$$\gamma_2 = \phi \gamma_0 + \gamma_1 = 2\phi$$

autocorrelations

$$\rho_1 = \frac{\gamma_1}{\gamma_0} = \frac{\phi}{1} = \phi$$

$$\rho_2 = \frac{\gamma_2}{\gamma_0} = \frac{2\phi}{1} = 2\phi$$

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Part 2

AK-0003-MDY

2. We want to test if Y_t has a unit root.
 Our null hypothesis will then be

$$H_0: \rho = 1 \quad \rho = 0$$

and the alternative

$$H_1: |\rho| < 1$$

Assumptions

$$\alpha = 0$$

$$\delta = 0$$

Our t-value for Y_{t-1} is -1,67 which is bigger than the results for the ^{no constant} no trend test on the 1% and 5% significance level. And therefore we cannot reject the null that there exists a unit root on any significance level.

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3. From 2 we find that the order of integration for Y_t is $I(1)$. The theory then suggests that Z_t should also be $I(1)$.

What about the cointegration vector?

Part 2

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4. Well if we take a look at the t -value for X_{t-7} we can see that it is $-2,54$ which is actually less than the $-1,95$ for the no constant ADF test on the 5% significance level ^{why?} which means that we can reject the null that there is a unit root. And it is therefore in accordance with the theoretical prediction

2.4

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