

AN α -ROBUST DIFFERENCE QUADRATURE METHOD FOR SPACE-TIME CAPUTO-RIESZ FRACTIONAL DIFFUSION EQUATION *

JIANXING HAN

Abstract. This is an example SIAM L^AT_EX article. This can be used as a template for new articles. Abstracts must be able to stand alone and so cannot contain citations to the paper's references, equations, etc. An abstract must consist of a single paragraph and be concise. Because of online formatting, abstracts must appear as plain as possible. Any equations should be inline.

Key words. example, L^AT_EX

MSC codes. 68Q25, 68R10, 68U05

1. Introduction. We study

$$(1.1) \quad \frac{\partial u}{\partial t} + (-\Delta)^{\frac{\alpha}{2}} u = f(x, t), \quad x \in \Omega, t \in (0, T].$$

Implicit scheme: Let $\tau = \frac{T}{M}$, $U^n, F^n \in \mathbb{R}^{2N-1}$,

$$(1.2) \quad \frac{U^{n+1} - U^n}{\tau} + AU^{n+1} = F^{n+1}.$$

Then

$$(1.3) \quad (I + \tau A)E^{n+1} = E^n + \tau R^{n+1}.$$

We will prove the convergence of this scheme.

2. Property of A .

LEMMA 2.1. *The stiffness matrix A has the following properties:*

1. *The eigenvalues of A are positive real numbers.*
2. *The eigenvectors of A form an orthogonal basis of the space of solutions.*
3. *The eigenvectors of A are orthogonal in space where $\langle u, v \rangle := uHv$.*

Proof. Since

$$(2.1) \quad A = H^{-1}D,$$

where $H := \text{diag}\left(\frac{h_i + h_{i+1}}{2}\right)$ and D is symmetric positive definite, $H^{1/2}AH^{-1/2} = H^{-1/2}DH^{-1/2}$ is symmetric positive definite. Thus, the eigenvalues of A are positive real numbers.

The eigenvectors of A form an orthogonal basis of the space of solutions. Let v_i be an eigenvector of A with eigenvalue λ_i . Then,

$$\lambda_i v_i H v_j = v_i H A v_j = v_i D v_j = \lambda_j v_i H v_j,$$

Thus $v_i H v_j = 0$ for $i \neq j$. □

We need to prove $\lambda_1 > c$ for some positive constant c .

*Submitted to the editors DATE.

Funding: This work was funded by the Fog Research Institute under contract no. FRI-454.

33 **3. Convergence.** We prove the scheme in convergence in the meaning of L^2
 34 norm. Both $\|v\|_2^2 := \frac{T}{N} \sum_{i=1}^{2N-1} v_i^2$ and $\|v\|_{2,h}^2 := \sum_{i=1}^{2N-1} v_i^2 \frac{h_i + h_{i+1}}{2}$ are bounded.

$$\begin{aligned} E^n &= (I + \tau A)^{-1} E^{n-1} + (I + \tau A)^{-1} \tau R^n \\ (3.1) \quad &= (I + \tau A)^{-n} E^0 + \sum_{k=1}^n (I + \tau A)^{-k} \tau R^{n-k+1} \end{aligned}$$

36 Assume that $|R^n| \leq C h^{\min\{r\alpha/2, 2\}} (x_i^{-\alpha} + (2T - x_i)^{-\alpha}) + C(r-1)h^2(T - \delta(x_i) +$
 37 $h_N)^{1-\alpha} + C\tau$?

$$\begin{aligned} (3.2) \quad (I + \tau A)^{-k} \tau R^{n-k+1} &= (\tau A)(I + \tau A)^{-k} (\tau A)^{-1} \tau R^{n-k+1} \\ &= (\tau A)(I + \tau A)^{-k} (A^{-1} R^{n-k+1}) \end{aligned}$$

39 Since $A^{-1} R^{n-k+1}$ is bounded, $\|A^{-1} R^{n-k+1}\|_2$ is bounded. Depose it by the basis v_i ,
 40 we have

$$(3.3) \quad \|(I + \tau A)^{-k} \tau R^{n-k+1}\|_2 \leq \frac{\tau \lambda_i}{(1 + \tau \lambda_i)^k} \|A^{-1} R^{n-k+1}\|_2$$

42 Then

$$\begin{aligned} (3.4) \quad \|E^n\|_2 &\leq \|E_0\|_2 + \sum_{k=1}^n \frac{\tau \lambda_1}{(1 + \tau \lambda_1)^k} \|A^{-1} R^{n-k+1}\|_2 \\ &\leq \|E_0\|_2 + \max_k \|A^{-1} R^{n-k+1}\|_2 \end{aligned}$$

44 **Acknowledgments.** We would like to acknowledge the assistance of volunteers
 45 in putting together this example manuscript and supplement.

46 REFERENCES

- 47 [1] G. H. GOLUB AND C. F. VAN LOAN, *Matrix Computations*, The Johns Hopkins University Press,
 48 Baltimore, 4th ed., 2013.