Machine Learning HW5

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Transforms: Explicit versus Implicit

1.

•
$$\phi_1(X) = 2x_2^2 - 4x_1 + 1$$
 and $\phi_2(X) = x_1^2 - 2x_2 - 3$

•
$$X_i = (x_1, x_2) \rightarrow Z_i = (\phi_1(X_i), \phi_2(X_i)) = (z_1, z_2)$$

•
$$X_1 = (1,0) \rightarrow Z_1 = (-3,-2), Y_1 = -1$$

$$X_2 = (0, 1) \rightarrow Z_2 = (3, -5), Y_2 = -1$$

$$X_3 = (0, -1) \rightarrow Z_3 = (3, -1), Y_3 = -1$$

$$X_4 = (-1, 0) \rightarrow Z_4 = (5, -2), Y_4 = +1$$

$$X_5 = (0,2) \rightarrow Z_5 = (5,-7), Y_5 = +1$$

$$X_6 = (0, -2) \rightarrow Z_6 = (9, 1), Y_6 = +1$$

$$X_7 = (-2, 0) \rightarrow Z_7 = (9, 1), Y_7 = +1$$

• $z_1 = 4$ is the optimal separting "hyperplane" in Z space

2.

- Polynomial kernel with penalty parameter $C = 10^6$, independent term $\zeta = 2$, kernel coefficient $\gamma = 1$, degree d = 2.
- Optimal $\alpha \approx [0.0, 0.4591, 0.4741, 0.5333, 0.1962, 0.2037, 0.0]$
- Support vectors: [(0,1), (0,-1), (-1,0), (0,2), (0,-2)]

3.

- $b = y_s \sum_{SV \text{ indices } n} \alpha_n y_n K(x_n, x_s)$ with support vector x_s and label y_s .
- $w = \left(\sum_{SV \text{ indices } n} \alpha_n y_n K(x_n, x)\right) + b$ with a new vector x to predict.
- The corresponding nonlinear curve $\approx \frac{8}{15}(x_1)^2 + \frac{2}{3}(x_2)^2 \frac{32}{15}x_1 \frac{5}{3}$

4.

• $z_1 = 2(x_2)^2 - 4x_1 + 1 = 4$ and $\frac{8}{15}(x_1)^2 + \frac{2}{3}(x_2)^2 - \frac{32}{15}x_1 - \frac{5}{3}$ are different because they are learned with respect to different Z space.

Dual Problem of L2-Error Soft-Margin Support Vector Machines

•
$$\mathcal{L}((b, w, \xi), \alpha, \beta) = \frac{1}{2}w^Tw + C\sum_{n=1}^{N} (\xi_n)^2 + \sum_{n=1}^{N} \alpha_n (1 - \xi_n - y_n (w^Tx_n + b)) + \sum_{n=1}^{N} \beta_n (-\xi_n)$$

• Partial differentiated by ξ_n

$$\frac{\partial \mathcal{L}((b, w, \xi), \alpha, \beta)}{\partial \xi_n} = 2C\xi_n - \alpha_n - \beta_n = 0, \Rightarrow 2C\xi_n - \alpha_n = \beta_n \ge 0$$

 $0 \le \alpha_n \le 2C\xi_n \Rightarrow \beta$ can be removed. $\xi \ge 0$ is explicit.

•
$$\mathcal{L}((b, w, \xi), \alpha) = \frac{1}{2}w^{T}w + C\sum_{n=1}^{N} (\xi_{n})^{2} + \sum_{n=1}^{N} \alpha_{n} (1 - \xi_{n} - y_{n} (w^{T}x_{n} + b)) + \sum_{n=1}^{N} (2C\xi_{n} - \alpha_{n}) (-\xi_{n})$$

$$\mathcal{L}((b, w, \xi), \alpha) = \frac{1}{2}w^{T}w + \sum_{n=1}^{N} \alpha_{n} (1 - y_{n} (w^{T}x_{n} + b)) + \sum_{n=1}^{N} C(\xi_{n})^{2} - \alpha_{n}\xi_{n} - 2C\xi_{n} + \alpha_{n}\xi_{n}$$

$$\mathcal{L}((b, w, \xi), \alpha) = \frac{1}{2}w^{T}w + \sum_{n=1}^{N} \alpha_{n} (1 - y_{n} (w^{T}x_{n} + b)) - \sum_{n=1}^{N} C(\xi_{n})^{2}$$

6.

•
$$\mathcal{L}((b, w, \xi), \alpha) = \frac{1}{2}w^Tw + C\sum_{n=1}^{N} (\xi_n)^2 + \sum_{n=1}^{N} \alpha_n (1 - \xi_n - y_n (w^Tx_n + b))$$

• Partial differentiated by ξ_n

$$\frac{\partial \mathcal{L}((b,w,\xi),\alpha)}{\partial \xi_n} = 2C\xi_n - \alpha_n = 0, \Rightarrow C\xi_n - \alpha_n = -C\xi_n$$

• Finally we obtain

$$\mathcal{L}((b, w, \xi), \alpha) = \frac{1}{2} w^{T} w + \sum_{n=1}^{N} \alpha_{n} (1 - y_{n} (w^{T} x_{n} + b)) - C \sum_{n=1}^{N} (\xi_{n})^{2}$$

7.

•
$$L((b, w, \xi), \alpha) = \frac{1}{2}w^Tw + \sum_{n=1}^{N} C(\xi_n)^2 + \sum_{n=1}^{N} \alpha_n (1 - \xi_n - y_n (w^Tx_n + b))$$

•
$$\frac{\partial L((b, w, \xi), \alpha)}{\partial b} = \sum_{n=1}^{N} -\alpha_n y_n = 0 \Rightarrow b \text{ can be removed.}$$

$$\Rightarrow L((b, w, \xi), \alpha) = \frac{1}{2} w^{T} w + \sum_{n=1}^{N} C(\xi_{n})^{2} + \sum_{n=1}^{N} \alpha_{n} (1 - \xi_{n} - y_{n} w^{T} x_{n})$$

•
$$\frac{\partial L((b,w,\xi),\alpha)}{\partial w_i} = w_i - \alpha_n y_n x_{n,i} = 0 \Rightarrow w = \sum_{n=1}^N \alpha_n y_n x_n$$

$$\Rightarrow L((b, w, \xi), \alpha) = -\frac{1}{2} \left\| \sum_{n=1}^{N} \alpha_n y_n x_n \right\|^2 + \sum_{n=1}^{N} C(\xi_n)^2 + \sum_{n=1}^{N} \alpha_n - \sum_{n=1}^{N} \alpha_n \xi_n$$

•
$$\frac{\partial L((b, w, \xi), \alpha)}{\partial \xi_n} = 2C\xi_n - \alpha_n = 0 \Rightarrow \xi_n = \frac{\alpha_n}{2C}$$

$$\Rightarrow L((b, w, \xi), \alpha) = -\frac{1}{2} \left\| \sum_{n=1}^{N} \alpha_n y_n x_n \right\|^2 - \frac{1}{4C} \sum_{n=1}^{N} (\alpha_n)^2 + \sum_{n=1}^{N} \alpha_n$$

KKT conditions

• Primal feasible:
$$y_n (w^T x_n + b) \ge 1 - \xi_n$$

• Dual feasible: $\alpha_n \ge 0$

• Dual-inner optimal:
$$\sum_{n=1}^{N} -\alpha_n y_n = 0, w = \sum_{n=1}^{N} \alpha_n y_n x_n$$

• Primal-inner optimal: $\alpha_n \left(1 - \xi_n - y_n \left(w^T x_n + b \right) \right) = 0$

8.

- If we use $z_n = \phi(x_n)$, it will cost more computation power to calculate $\phi(x_n) \phi(x_m)$. Therefore we use a kernel $K(x_n, x_m)$ to compute the transformation and inner product in an efficient way.
- Optimization problem with kernel trick:
 - Quadratic coefficient: $q_{n,m} = y_n y_m z_n^T z_m = y_n y_m K(x_n, x_m), p = -1_N, (A, c)$ for equation and bound constraints.
 - $\circ \ \alpha = QP(Q_D, p, A, c)$
 - Optimal bias from free SV (x_s, y_s) : $b = y_s \sum_{n=1}^{N} \alpha_n y_n K(x_n, x_s)$
 - Optimal hypothesis g_{svm} for test input x: $g_{svm}(x) = sign\left(\sum_{n=1}^{N} \alpha_n y_n K(x_n, x) + b\right)$

Operation of Kernels

9.

• Valid kernel \Rightarrow positive-semidefinite matrix \Rightarrow eigenvalue non-negative

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix}, K = \begin{bmatrix} K_{11} & \cdots & K_{1N} \\ \vdots & \ddots & \vdots \\ K_{N1} & \cdots & K_{NN} \end{bmatrix}$$

We need to prove $x^T K x = \sum_{i=1}^N \sum_{j=1}^N x_j K_{ij} x_j \ge 0$

- Denote K as $K_1(x, x')$, and set $K = 0.5I = \begin{bmatrix} 0.5 & 0 \\ 0 & 0.5 \end{bmatrix}$, $eigen(K) = \begin{bmatrix} 0.5 \\ 0.5 \end{bmatrix}$
- [a] $eigen((1-K)^1) = \begin{bmatrix} 1.5 \\ -0.5 \end{bmatrix} \Rightarrow \text{not valid kernel}$
- [b]

Any matrix with 0-th power always results into matrix filled with ones.

$$eigen\left((1-K)^0\right) = eigen\left(\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 0 \end{bmatrix} \Rightarrow valid kernel$$

• [c]

Positive semi-definite matrix is closed under addition and multiplication

$$\Rightarrow I + K^1 + K^2 + K^3 + \dots + K^n$$
 is valid kernel.

We have known that
$$0 < K < 1 \Rightarrow \lim_{n \to \infty} K^n = 0$$
, thus:
$$\lim_{n \to \infty} I + K^1 + K^2 + K^3 + \dots + K^n = \frac{(I - K^n) \cdot I}{I - K} = (I - K)^{-1} \text{ is also a valid kernel.}$$

• [d]

From [c], we have known is a valid kernel, and we known its closeness under multiplication and addition.

$$(I - K)^{-1}(I - K)^{-1} = (I - K)^{-2}$$
 is also a valid kernel.

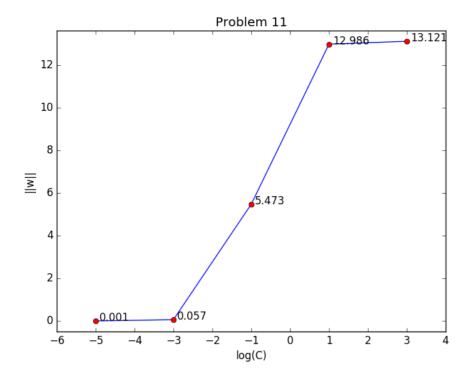
10. Kernel Scaling and Shifting

• $\tilde{K}(x,x') = pK(x,x') + q$ • We need to prove $\tilde{g}_{svm}(x) = g_{svm}(x)$ • $b = y_s - \sum_{SV \text{ indices } n}^{N} \alpha_n y_n K(x_n, x_s)$ on bounded SV (x_s, y_s) $g_{svm}(x) = sign\left(\left(\sum_{SV \text{ indices } n}^{N} \alpha_n y_n K(x_n, x)\right) + b\right)$ $= sign\left(\left(\sum_{SV \text{ indices } n}^{N} \alpha_n y_n K(x_n, x)\right) + y_s - \sum_{SV \text{ indices } n}^{N} \alpha_n y_n K(x_n, x_s)\right)$ $= sign\left(\left(\sum_{SV \text{ indices } n}^{N} \alpha_n y_n K(x_n, x) - K(x_n, x_s)\right) + y_s\right)$ • $\tilde{b} = y_s - \sum_{SV \text{ indices } n}^{N} \tilde{\alpha}_n y_n \tilde{K}(x_n, x_s) = y_s - \sum_{SV \text{ indices } n}^{N} \tilde{\alpha}_n y_n \left(pK(x_n, x_s) + q\right)$ on bounded SV (x_s, y_s) $\tilde{g}_{svm}(x) = sign\left(\left(\sum_{SV \text{ indices } n}^{N} \tilde{\alpha}_n y_n \tilde{K}(x_n, x)\right) + \tilde{b}\right)$ $= sign\left(\left(\sum_{SV \text{ indices } n}^{N} \tilde{\alpha}_n y_n \left(pK(x_n, x) + q\right)\right) + y_s - \sum_{SV \text{ indices } n}^{N} \alpha_n y_n \left(pK(x_n, x_s) + q\right)\right)$ $= sign\left(\left(\sum_{SV \text{ indices } n}^{N} \tilde{\alpha}_n y_n \left(pK(x_n, x) - K(x_n, x_s)\right)\right) + y_s\right)$

Experiments with Soft-Margin Support Vector Machine

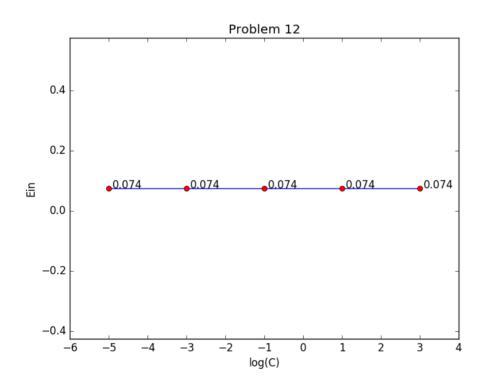
11.

• $\tilde{\alpha}_n = \frac{1}{n}\alpha_n \Rightarrow \tilde{C} = \frac{1}{n}C$



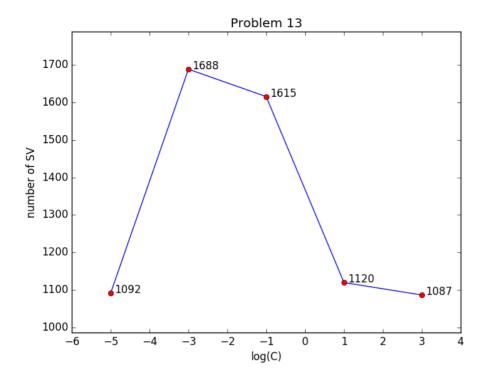
• Larger C will cause larger ||w||.

12.



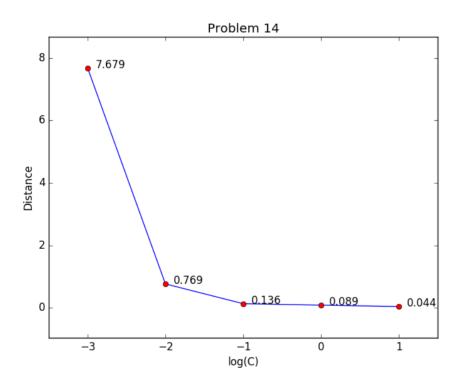
• All E_{in} are the same.

13.

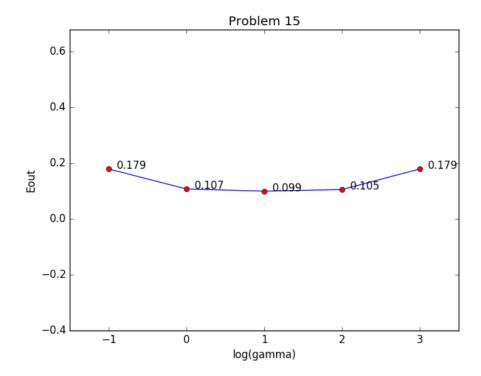


• When $\log_{10} C$ is around $-3 \sim -1$, the number of SVs is higher.

14.

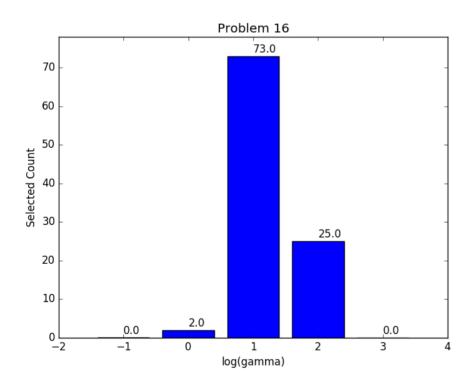


 \bullet Larger C will cause smaller distance between free SVs and hyperplane.



• When $\log_{10} \gamma = 1$, E_{out} is the lowest.

16.



• By 100 iteration of validation, we found $\log_{10} \gamma = 1$ has the lowest E_{val} .